view_frames Result Recorded at time: 1574656914.255 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /link1_broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.189 Hz Most recent transform: 1574656914.314 (-0.059 sec old) Most recent transform: 0.000 (1574656914.255 sec old) Most recent transform: 0.000 (1574656914.255 sec old) Buffer length: 4.907 sec Buffer length: 0.000 sec Buffer length: 0.000 sec D435base_link link0 camera_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (1574656914.255 sec old) Most recent transform: 1574656914.192 (0.063 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec D435_link link1 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574656914.192 (0.063 sec old) Buffer length: 4.900 sec link2 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574656914.192 (0.063 sec old) Buffer length: 4.900 sec link3 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574656914.192 (0.063 sec old) Buffer length: 4.900 sec link4 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574656914.192 (0.063 sec old) Buffer length: 4.900 sec link5 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1574656914.192 (0.063 sec old) Buffer length: 4.900 sec link6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1574656914.255 sec old) Buffer length: 0.000 sec **EEFlink** Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1574656914.192 (0.063 sec old) Most recent transform: 1574656914.192 (0.063 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec left_gripper right_gripper