

COURSEWORK REPORT

CS7052 Machine Learning

Case Study:

Glaucoma Disease Detection

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Machine Learning

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Glaucoma Disease Detection - Deep Learning Base Methodology

1. Abstract

To categorize Glaucoma illnesses, we built an architecture based on the Deep Learning (DL) approach, namely a Convolution Neural Network (CNN). We employed two deep learning algorithms, MobileNetV2 and DensNet201, for identifying and classifying Glaucoma. We used Kaggle dataset for 938 photos of Glaucoma illness from 10 different classes. The Glaucoma dataset was assessed based on the val_loss and val_accuracy of both models. In addition, we gave the classification report in which we compared the accuracy, recall, and f1-score of the two illness classification models. DensNet201 has the lowest val_loss rate and the highest val_accuracy, which are 0.31 and 91.62 %, respectively.

Introduction

Glaucoma is the second leading cause of blindness worldwide, with 75 million cases in 2020, and it is expected to increase by 30 million in 2040 (Abdullah et al., 2021), (Aamir et al., 2020). Glaucoma can be broadly classified into two categories: Open Angle Glaucoma and Closed Angular Glaucoma. Among them, Open-Angle Glaucoma has a greater number of registered cases all over the world and has no symptoms (Mayro et al., 2020). Open-Angle Glaucoma is a chronic Eye disease that is caused due to the blockage in the flow of liquid called Aqueous humor (Li et al., 2019). Aqueous humor flows inside the eye directly below the optic nerve and keeps the eye pressure low. The blockage in the eye creates an accumulation of liquid and destroys the optic nerve, which carries the information to the brain. When information from the eye to the brain is lost, it results in permanent blindness (Saxena et al., 2020). Glaucoma has no permanent solution in the current medical field, so early detection is the only possibility. Due to its risk of spreading and diagnosis complexity, my research mainly focuses on addressing the glaucoma diagnosis. Figure 1 shows the difference between the normal and Glaucoma eyes (Open Angle Glaucoma) (Gupta et al., 2022).

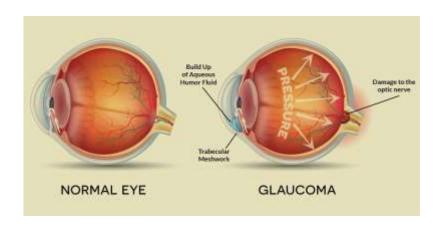


Figure 1 Difference between a Normal Eye and an Eye Affected by Glaucoma

To detect Glaucoma in its earliest stages, the patient is subjected to various tests, such as the Field Examination, Optic head examination, and Pressure Checkup. Among these, the Optic head Examination is the most reliable and efficient method for detecting the presence of Glaucoma due to its cost-effectiveness and simple structure (Thakoor et al., 2019). In the Optic Head Examination, the doctor takes a picture of the human eye structure in the form of a Fundus image (Medical image containing information about eye structure) using a Fundus Camera (Krishna Adithya et al., 2021). Then the doctor tries to estimate the boundaries of the Optic

Disc and Optic Cup to calculate the Optic Cup-to-Disc ratio to predict whether a patient has Glaucoma.

Figure 2 and Figure 3 shows the visual representation of the Fundus image and Optic Disc and Optic Cup boundaries.

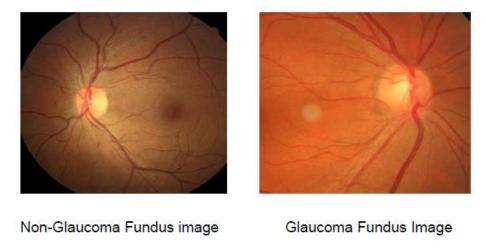


Figure 2 Illustration of Fundus images of a Glaucoma eye and a normal eye

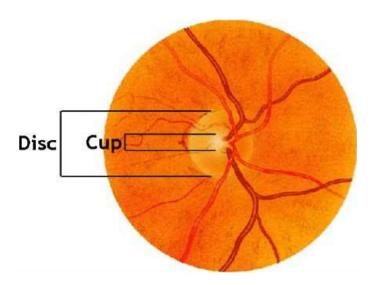


Figure 3 Example of Optic Disc and Cup labeled in a Fundus image

The leading cause of blindness and visual impairment worldwide, Glaucoma currently has no effective cure. The possibility that this condition may be the root cause of blindness wasn't first accepted, but years of study have provided conclusive evidence to support this hypothesis (Vaghjiani et al., 2020). Vision loss from Glaucoma may be avoided if the disease is caught early enough. So, we may state that Glaucoma is the salient chronic eye condition that is the reason for blindness. The urban population is where this chronic illness is having the most

impact. Recent studies have predicted that by 2020, 79 million people will have fallen prey to this illness (Gheisari et al., 2021). Since detecting Glaucoma is so crucial, it's vital to conduct screening eye exams. However, this is laborious and time-consuming when applied to a population as vast as the general population.

When ophthalmologists use a computer-aided system (CADx) to do eye screenings, they can save time and money while improving the quality of care they provide. The diagnosis and analysis of Glaucoma, a chronic eye illness, may be streamlined with these tools, saving time and energy. Because the border of CUP is impacted by glaucoma eye illness, it is difficult for ophthalmologists to distinguish between Glaucoma retinal images and normal glaucoma images, which is why the CADx system should be adopted in clinics and hospitals (Bisneto et al., 2020). A cup-to-disc ratio (CDR) may be used to measure this impact. Retinal fundus imaging and glaucoma stage categorization are challenging because of high-volume screening as shown in Figure 4.

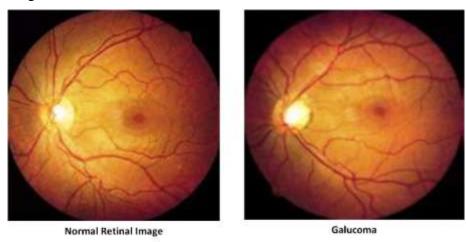


Figure 4 Glaucoma manifesting itself visually: "(a) normal retinal image, (b) glaucoma"

Reduction in the size of the periphery of the retina (PPA). It is, moreover, a sensor for the detection of ocular Glaucoma. In the event of peripapillary atrophy (PPA), the border of the disc shifts when neighboring intensities do (Serte and Serener, 2019). The figure displays the result of PPA on a region-of-interest (ROI) picture of the retinal fundus in a patient with glaucomatous optic nerve damage. PP manifests as a disc boundary variant analogous to rim thinning as shown in Figure 5.

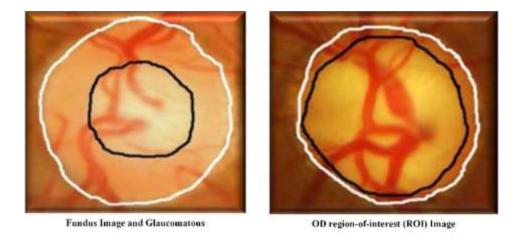


Figure 5 Representative Normal Sample "(a) fundus image and glaucomatous (b) OD regionof-interest (ROI) image"

An early study gave a mechanized answer and classified this chronic illness based on the cupto-disc ratio (CDR) (Bechar et al., 2018). Therefore, it may be challenging to segregate CUP and Od areas near the disc's edge. Therefore, several image processing methods should be available after feature extraction if we are not planning on segmenting the OD and CUP areas. After creating the picture features, we may use them without further knowledge or training to choose the discriminative features (Kausu et al., 2018). Therefore, it is safe to state that ophthalmologists will have difficulty detecting Glaucoma utilizing CADx devices.

Instead of relying on segmentation methods, Glaucoma may be identified by analyzing the picture characteristics in and around the OD area. Therefore, a method where it may be presupposed that morphological change in OD produced by the illness might lessen the requirement to precisely detect cup and disc boundaries (Raja et al., 2022). Because of this, deep learning's foundational characteristics may be recovered automatically, even by those who lack specialized knowledge in a certain area of image processing.

In this research, we have used the python programming language with the Google Co-lab Platform, where we have developed our models. We have used resources of dataset from google, and for the implementation, we have used the online platform of Google Colab.

3 Demonstration of the technique

This experiment shows that deep tuning, or fine-tuning all the trainable layers in the CNN, is the optimal strategy for improving performance. To test how well the CNN performs after being fine-tuned for a period ranging from 1 to 30 iterations, we also conduct a more basic experiment in which all layers are set to trainable mode. It should be noted that this experiment's performance was evaluated using the validation set.

3.1 Experiments Result

In the implementation of the CNN models, we have used python programming. In the initial phase, we imported several libraries from Kera's. After this, we mounted our dataset with google drive. In the dataset, we have 938 images based on the 10 glaucoma disease classes. We have used the google colab platform for the implementation. In the co-lab, we used the 12GB RAM resource during the training and testing of the dataset. We have divided our dataset into the 70% for training and 30% for testing of the dataset, 30 epochs, and 30 batch sizes for training time.

3.2 Compiling Model

In this section, we have evaluated the val_loss and val_accuracy of the CNN models used in this report, such as MobileNetV2 and DensNet201. After evaluation, we have found that DensNet201 finds less val_loss and gains the best accuracy compared to another CNN model (MobileNetV2), which is 0.0899 and 98.58%, respectively, as shown in Table 1.

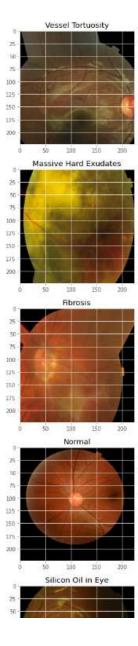
Table 1 The evaluated results of CNN models

	MobileNe	etV2	DensNet201				
epoch	val_loss	val_accuracy	epoch	val_loss	val_accuracy		
1	1.3372	0.6418	1	1.4089	0.6738		
2	0.6876	0.7943	2	0.8630	0.7979		
3	0.4683	0.9078	3	0.5858	0.8759		
4	0.3157	0.9362	4	0.4574	0.8901		
5	0.2422	0.9504	5	0.3516	0.9220		
6	0.2012	0.9610	6	0.2539	0.9574		
7	0.1905	0.9645	7	0.2091	0.9574		
8	0.1587	0.9610	8	0.1933	0.9539		
9	0.1597	0.9681	9	0.1763	0.9681		
10	0.1277	0.9645	10	0.1669	0.9610		
11	0.1444	0.9504	11	0.1554	0.9681		
12	0.1273	0.9574	12	0.1468	0.9681		
13	0.1145	0.9681	13	0.1499	0.9645		
14	0.1188	0.9681	14	0.1476	0.9610		
15	0.1097	0.9716	15	0.1283	0.9787		
16	0.1061	0.9752	16	0.1553	0.9716		
17	0.1228	0.9681	17	0.1210	0.9858		
18	0.0966	0.9716	18	0.1225	0.9823		
19	0.1079	0.9716	19	0.1264	0.9752		
20	0.1353	0.9574	20	0.1152	0.9787		
21	0.0979	0.9752	21	0.1204	0.9787		
22	0.1043	0.9681	22	0.1155	0.9823		
23	0.1273	0.9610	23	0.1165	0.9787		
24	0.0973	0.9681	24	0.1116	0.9752		
25	0.1079	0.9752	25	0.1108	0.9752		
26	0.1025	0.9716	26	0.1053	0.9787		
27	0.1452	0.9574	27	0.1099	0.9716		
28	0.0824	0.9752	28	0.0963	0.9858		
29	0.0921	0.9681	29	0.1116	0.9716		
30	0.0920	0.9787	30	0.0899	0.9858		

Below is the accuracy and loss after 10 epochs:

```
+ Code + Text
     Epoch 3/18
 0
                                      --] - 299s 14s/step - loss: 0.9560 - accuracy: 0.6951 - val_loss: 0.7165 - val_accuracy: 0.8440
     21/21 [----
Epoch 4/10
 D-
     21/21 [ ---
                                        - 306s 14s/step - loss: 0.6978 - accuracy: 0.7805 - val_loss: 0.5356 - val_accuracy: 0.8901
     Epoch 5/10
21/21 [====
                                        - 294s 14s/step - loss: 0.6358 - accuracy: 0.8110 - val_loss: 0.4741 - val_accuracy: 0.8972
     23/21 [****
Epoch 7/18
                                        - 200s 13s/step - loss: 0.5407 - accuracy: 0.0552 - val_loss: 0.3597 - val_accuracy: 0.9255
     21/21 [---
                                         - 284s 13s/step - Ioss: 0.4340 - accuracy: 0.8650 - val_loss: 0.3021 - val_accuracy: 0.9326
     Epoch 8/18
                                     ---] - 282s 13s/step - loss: 8.3925 - accuracy: 8.8841 - val_loss: 8.2926 - val_accuracy: 8.9291
     21/21 [---
     Epoch 9/10
     21/21 [---
                                      --] - 236s lis/step - loss: 0.3627 - accuracy: 0.8811 - val_loss: 0.2741 - val_accuracy: 0.9326
     Epoch 10/10
     21/21 [----
                                    ----] - 237s 11s/step - loss: 0.3113 - accuracy: 0.9162 - val_loss: 0.2357 - val_accuracy: 0.9362
```

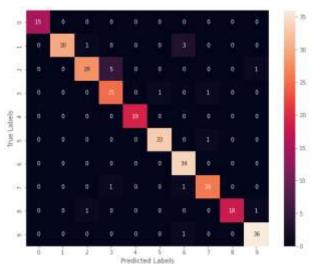
The output of few images from the dataset is shown below.



Performance measurement technique

The confusion matrix's code is shown below. It aids in testing recall, accuracy, false positives, true positives, and false negatives, true negatives.

```
+ Code + Text
      from sklearn.metrics import confusion_matrix
      y_test = np.argmax(testY, axis=1)
      conf_mtrx = confusion_matrix(y_test, y_pred)
 [9] # Functions to compute True Positives, True Negatives, False Positives and False Negatives
      def true_positive(y_true, y_pred):
          tp = 0
          for yt, yp in zip(y_true, y_pred):
              if yt == 1 and yp == 1:
                 tp += 1
          return tp
      def true_negative(y_true, y_pred):
          tn = 0
          for yt, yp in zip(y_true, y_pred):
              if yt == 0 and yp == 0:
                  tn += 1
          return tn
      def false_positive(y_true, y_pred):
          for yt, yp in zip(y_true, y_pred):
              if yt == 0 and yp == 1:
                  fp += 1
          return fp
      def false_negative(y_true, y_pred):
          for yt, yp in zip(y_true, y_pred):
              if yt == 1 and yp == 0:
                  fn += 1
          ceturn fo
```



Confusion matrix

3.3 Classification Report

Precision-recall is utilized to evaluate both the MobileNetV2 and DenseNet201 CNN models' classification precision and their ability to generalize across distinct datasets. Regarding golf swings, precision is the rate at which the classifier retrieves correct Disc Swelling and Elevation. At the same time, recall is the rate at which the classifier retrieves true Disc Swelling and Elevation and thus indicates the classifier's sensitivity when faced with plausibly incorrect Disc Swelling and Elevation. When considering both accuracy and recall, the synthesized F1-score assesses classification quality (see Table 2). The figure is generated using two-line graphs representing the loss and classification learning curves on the train and test sets, respectively. There seems to be a good match between the issue and the model, as shown by the Figure 6.

Table 2 Classification report of CNN Models with all glaucoma diseases

Model Name	MobileNetV2				DensNet201			
Glaucoma	precision	recall	f1-	support	precision	recal1	f1-	support
Diseases Name			score	11			score	
Congenital Disc	1.00	1.00	1.00	29	1.00	1.00	1.00	29
Abnormality								
Disc Swelling and	0.97	0.95	0.96	37	1.00	0.97	0.99	37
Elevation			0.50					
Fibrosis	0.4	1.00	0.97	34	0.94	1.00	0.97	34
Fundus Neoplasm	1.00	0.92	0.96	26	1.00	0.96	0.98	26
Laser Spots	1.00	1.00	1.00	33	1.00	1.00	1.00	33
Massive Hard	1.00	1.00	1.00	29	1.00	1.00	1.00	29
Exudates		1.00						
Normal	0.97	1.00	0.98	31	0.97	1.00	0.98	31
Preretinal	0.94	0.94	0.94	16	0.94	1.00	0.97	16
Hemorrhage	0.51	0.51	0.51	10	0.51	1.00	0.57	10
Silicon Oil in Eye	1.00	0.95	0.97	20	1.00	0.95	0.97	20
Vessel Tortuosity	0.96	1.00	0.98	27	1.00	0.96	0.98	27
accuracy			0.98	282			0.99	282
macro avg	0.98	0.98	0.98	282	0.99	0.98	0.98	282
weighted avg	0.98	0.99	0.99	282	0.99	0.99	0.99	282

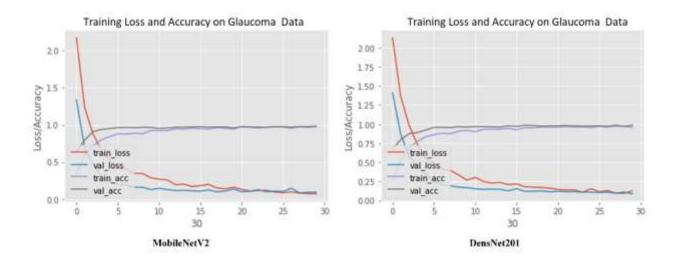
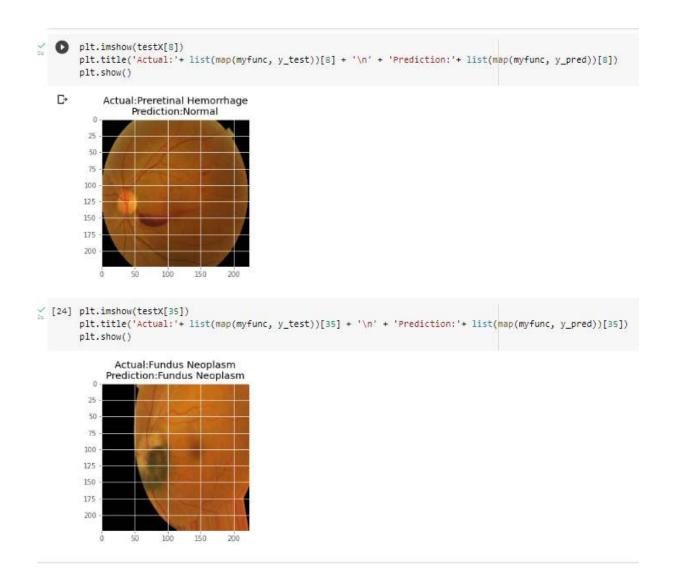


Figure 6 Precision-Recall curve of classification from all glaucoma diseases



As can be observed from the aforementioned code and output, a small number of errors were made when predicting the model, and a small number of the dataset's images were incorrectly forecasted. Additionally, the actual forecast and anticipated value are provided together with the slight discrepancy that can't be predicted correctly in this model. Therefore, by giving the model more precise and thoroughly cleaned images and information, which will eventually assist the model to train and perform better, this model can demonstrate further development.

4 Conclusion

The retinal nerve fiber layer (RNFL) thickness seen in normal people necessitates routine monitoring for accurate glaucoma diagnosis (Shabbir et al., 2021). That's why it's recommended to check up with a doctor every six months. However, it is difficult to conduct such comprehensive medical examinations in countries with less access to advanced imaging technology like OCT. However, qualitative evaluations based on fundus photos have a low sensitivity for diagnosing early-stage progressive optic neuropathy because of the substantial training necessary. While our method has the potential to greatly increase the usefulness of qualitative and subjective data derived from fundus pictures alone, it still requires refinement before it can be used in clinical settings. Additional data for the training model is something we think can help RNFL thickness prediction become even more precise. However, the quality of the fundus image plays a crucial role in determining the discrepancy between OCT measurement and CNN-based estimate, even if a trained CNN can predict quantitative retinal deformation correctly.

As per my view this report helped me in understanding a CNN deep learning method which can be applied to various hospitals and ophthalmologists as it is cost-efficient, time-saving and easily accessible to small clinics and hospitals. In contrast to other methods, the suggested method primarily focuses on precisely extracting the optic cup and disc from the fundus image. It enables medical professionals to diagnose glaucoma without the need for extra examinations which not only saves time and cost to the doctor but for the patient as well.

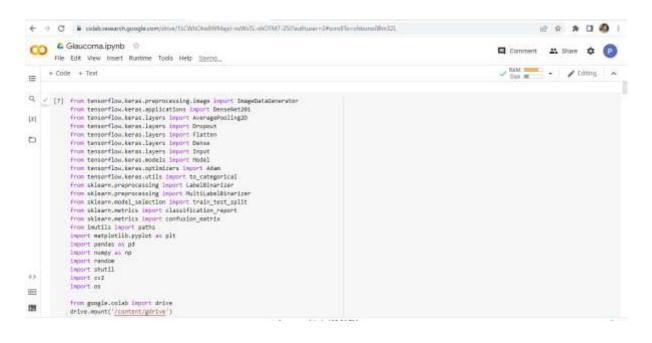
To sum up, a good fundus shot is essential for a precise prediction. More risk factors, like intraocular pressure, a history of diabetes, hypertension, and extreme myopia, can be incorporated into the DL model to increase screening efficacy.

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Appendix I



```
** Food ** Test

** From google.cold# Import drive

** (F) drive.mount('/content/gorive')

** file path ** Frontient/gorive')

** file path ** Frontient/gorive'

** file path ** Frontient/gorive/machine tearning/Wraject Glaucima/'

dataset_path ** os.path.join(os.path.dirname(file path), "elaucima Dataset')

** BNIT_LReled**

** EPOCHS ** IN

** B year the list of images in our dataset directory, then initialize

** # the list of data (i.e., Images) and class Images

** print("IMPO) loading louges...")

** shangepaths ** list(paths.list_images(dataset_path))

** imagePaths ** list(paths.list_images(dataset_path)'))

** data ** []

** loop over the image paths

** for imagePath silst(out).path.sep[-2]

** load the image, many column channels, and resize it to be a fload

** # Idaazza pixals while ignaring aspect ratio

** leage ** evz.imread(imagePath)

** Image ** evz.imread(imagePath)

** Image ** evz.imread(imagePath)

** image ** evz.evtcolor(image, cvz.COLOM_BERZERSE)

** image ** evz.evtcolor(image, cvz.colom_Gerzerse)

** image *** image ** evz.evtcolor(image, cvz.colom_Gerzerse)

** image *** image *** image *** image **
```

+ Code + Text

```
opt=Adam()
        model.compile(loss = "categorical_crossentropy", optimizer = opt, metrics=["accuracy"])
        print("[INFO] training head...")
        H = model.fit(
            trainAug.flow(trainX, trainY, batch_size=BS),
            steps_per_epoch=len(trainX)/BS,
            validation_data=(testX, testY),
            validation_steps=len(testX),
            epochs=EPOCHS )
        # plot the training loss and accuracy
        N = EPOCHS
        plt.style.use("ggplot")
        plt.figure()
        plt.plot(np.arange(0, N), H.history["loss"], label="train_loss")
        \verb|plt.plot(np.arange(0, N), H.history["val_loss"], label="val_loss")|\\
        plt.plot(np.arange(0, N), H.history["accuracy"], label="train_acc")
        plt.plot(np.arange(0, N), H.history["val accuracy"], label="val acc")
        plt.title("Training Loss and Accuracy on Glaucoma Data")
        plt.xlabel(N)
        plt.ylabel("Loss/Accuracy")
        plt.legend(loc="lower left")
        plt.savefig("plot.png")
```

```
+ Code + Text
        from sklearn.datasets import make_circles
[7] from sklearn.metrics import accuracy_score
        from sklearn.metrics import precision_score
        from sklearn.metrics import recall_score
        from sklearn.metrics import f1_score
        from sklearn.metrics import cohen_kappa_score
        from sklearn.metrics import roc_auc_score
        from sklearn.metrics import confusion_matrix
        def myfunc(a):
         return lb.classes_[a]
        y_predz = model.predict(testX, batch_size=BS, verbose=1)
        y_pred = np.argmax(y_predz, axis=1)
        predicted_Labels = map(myfunc, y_pred)
        print(list(lb.inverse_transform(testY))[:])
        #print(np.fromiter(predicted_Labels))
        print(classification_report(list(lb.inverse_transform(testY))[:],list(predicted_Labels)[:]))
 + Code + Text
       from sklearn.metrics import confusion_matrix
       y_test = np.argmax(testY, axis=1)
       conf_mtrx = confusion_matrix(y_test, y_pred)
```

```
[9] # Functions to compute True Positives, True Negatives, False Positives and False Negatives
    def true_positive(y_true, y_pred):
        tp = 0
        for yt, yp in zip(y_true, y_pred):
            if yt == 1 and yp == 1:
                tp += 1
        return tp
    def true_negative(y_true, y_pred):
        tn = 0
        for yt, yp in zip(y_true, y_pred):
            if yt == 0 and yp == 0:
                tn += 1
        return tn
    def false_positive(y_true, y_pred):
        fp = 0
         for yt, yp in zip(y_true, y_pred):
            if yt == 0 and yp == 1:
                fp += 1
        return fp
    def false_negative(y_true, y_pred):
         fn = 0
         for yt, yp in zip(y_true, y_pred):
            if yt == 1 and yp == 0:
                fn += 1
        return fo
```

```
Dict={}
for i in range(30):
    if list(map(myfunc, y_test))[i] not in Dict:
        Dict[list(map(myfunc, y_test))[i]] = list(map(myfunc, y_test))[i]
        plt.imshow(testX[i])
        plt.title(list(map(myfunc, y_test))[i])
        plt.show()
```