

The dinner party

Suppose you are at a dinner party. The host wants to give out a door prize that is wrapped in a box. Everyone (including the host) sits around a circular table and each person is given a fair coin. Initially the host is holding the box. He/she flips his coin. If it is heads, the box is passed to the right; if it is tails, it is passed to the left. The process is repeated by whichever guest is holding the box. (Heads, they pass right; tails, they pass left.) The game ends when the last person to receive the box finally gets it for the first time. That person gets to keep the box as the winner of the game.

How do you work out where should you sit in order to maximize your probability of winning?

PM 520 - Lecture 3

Finding roots and fixed points
Chapter 10 of Jones et al.

Assignment1: Randomization tests - golf balls - due midnight today

- Allan Rossman used to live along a golf course and collected the golf balls that landed in his yard. Most of these golf balls had a number on them.



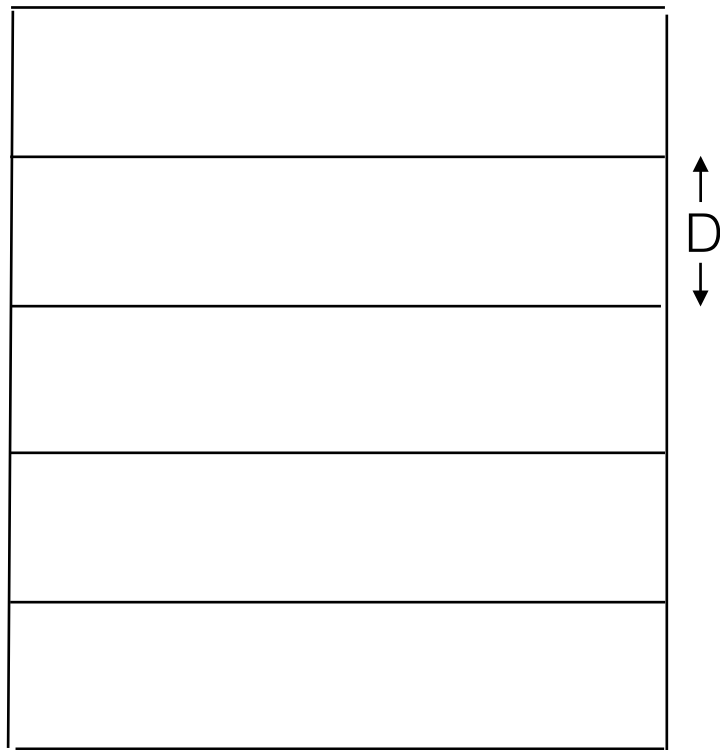
- Question: What is the distribution of these numbers?
- In particular, are the numbers 1, 2, 3, and 4 equally likely?

[Originally due to Allan Rossman - via Randall Pruim]

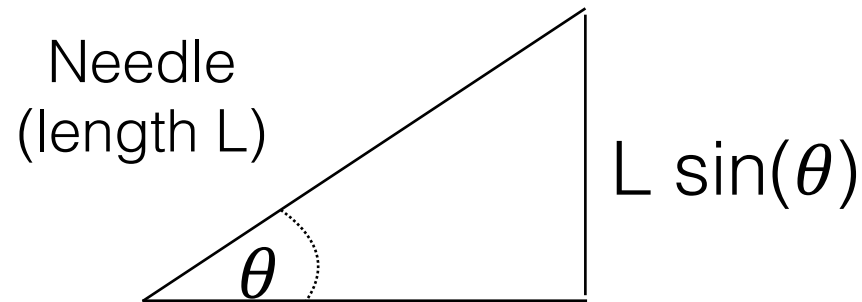
Assignment notes

- I cannot read your answers if you upload an html file (annoying fact of life with Github).
- So please knit your answers to either:
 - A pdf (ideal, but requires you to install a latex editor. I recommend tinytex)
 - A markdown (.md) file, but note that you also need to upload the folder that contains the graphics for any figures that are included.
- I will go through these tomorrow to make sure we can see everything we need to see.
- Thanks to those of you who have confirmed your (non-obvious) GitHub IDs. I think I know who everybody is now, but I'll confirm once we have graded the assignments.

Monte Carlo Simulation: Calculating π - Buffon's needle



Table



$$\text{So, } P(\text{cross line}) = \min(1, L \sin(\theta)/D)$$

If N = number of trials, lines are distance **$D=1$** apart,
 C = number of times needle crosses line,
 and **$L \leq D$** , then:

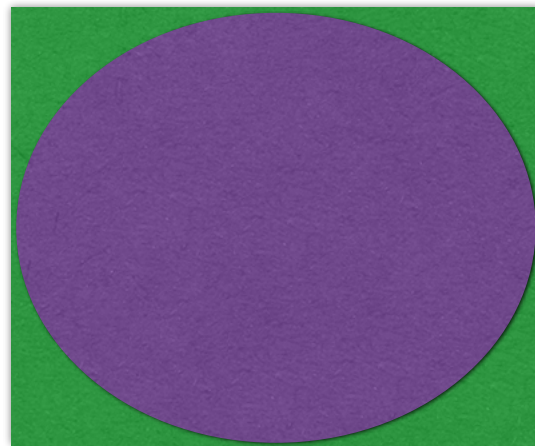
$$C/N \sim \int L \sin(\theta) (1/\pi) d\pi \quad [\text{integral goes from } 0 \text{ to } \pi \text{ in radians}]$$

$$\text{So } C/N \sim L[-\cos(\pi) - (-\cos(0))]/\pi = 2L/\pi$$

$$\text{So } \pi \sim 2LN/C$$

Monte Carlo Simulation: Calculating π - 'dart board' approach

- Estimate (not calculate) π using Monte Carlo methods.
- So, you need to think of something you can simulate in which the probability of success depends upon π .



In-class exercise: Exponential task 1

- Generate 1000 $\text{Exp}(\lambda)$ rvs. conditional on them each being greater than y , for some y (Try $\lambda=1$, $y=1$, say). Let's call those r.v.s X .
- Plot a histogram showing the distribution of $(x-y)$, for $y=1$ and $\lambda=1$, and compare it to 1000 $\text{Exp}(1)$ rvs. [or superimpose the exponential density function using the command `curve($\lambda \cdot \exp(-\lambda \cdot x)$)`]
- How do we generate exponential rvs conditional on them being greater than y ?

In-class exercise: Exponential task 2: Waiting for a bus

- Suppose times between bus arrivals are distributed as $T \sim \text{exp}(1)$.
 1. Suppose we arrive at a bus-stop at some fixed time during the day (say after 10 hours). How long, on average, do we have to wait for a bus? [What if we arrive at a random time each day?]
 2. If we get off one bus and wait for the next one to arrive on the same route, how long, on average, do we have to wait?
 3. How long on average was the time between the arrival of the bus we caught and the one before it.
 4. What is the expected time between any two buses?

Note: the mean of an $\text{exp}(\lambda)$ r.v. is $1/\lambda$.

See 'Week2-BusWaitingTimesExercise' on Github

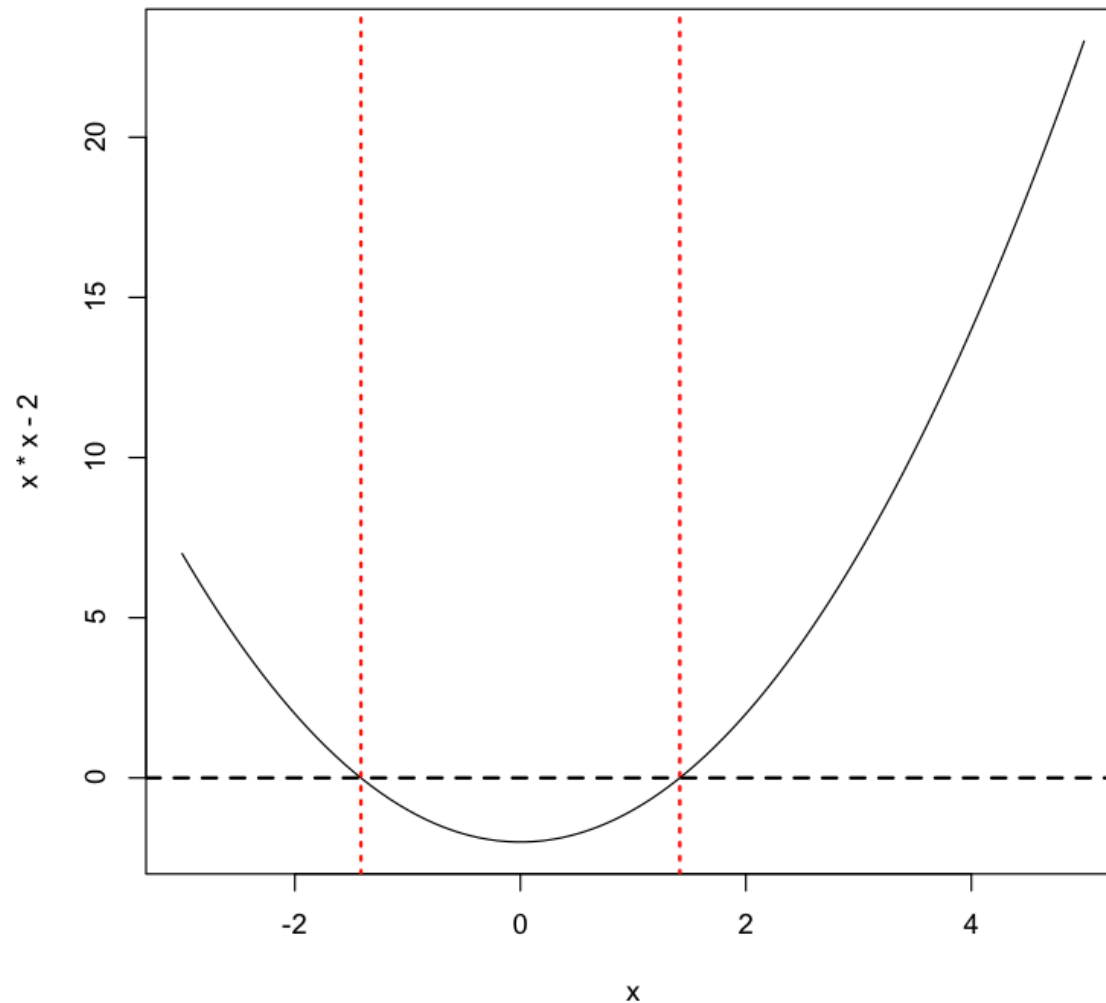
Admin

- Solutions:
 - Solutions to week 2 problems have been uploaded to <https://github.com/PM520-Spring2021/Solutions-public>
- Lecture:
 - No class next Monday (Presidents' Day)
 - I will still run office hours on the Friday
- TA email: sgugliel@usc.edu (Shane Guglielmo)
- Lecture recordings: ZoomPro tab on Blackboard.

Finding roots and fixed points

“Root-finding” Chapter 10 of Jones
et al.

Finding roots and fixed points



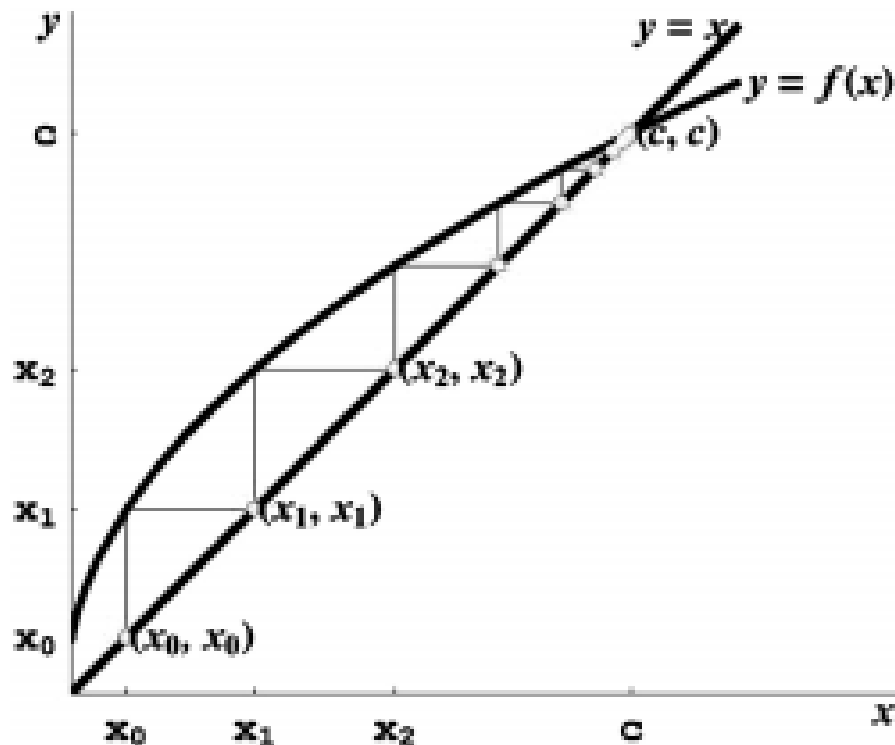
```
curve(x*x-2,-3,5)
abline(h=0,col=1,lwd=2,lty=2)
abline(v=sqrt(2),col=2,lwd=2,lty=3)
abline(v=-sqrt(2),col=2,lwd=2,lty=3)
```

Roots are important

1. As part of optimization (derivative of a function is 0 at its optima).
2. For finding **fixed-points**, i.e., an x such that $f(x)=x$ (because then, $g(x) = f(x) - x = 0$).

Fixed point iteration

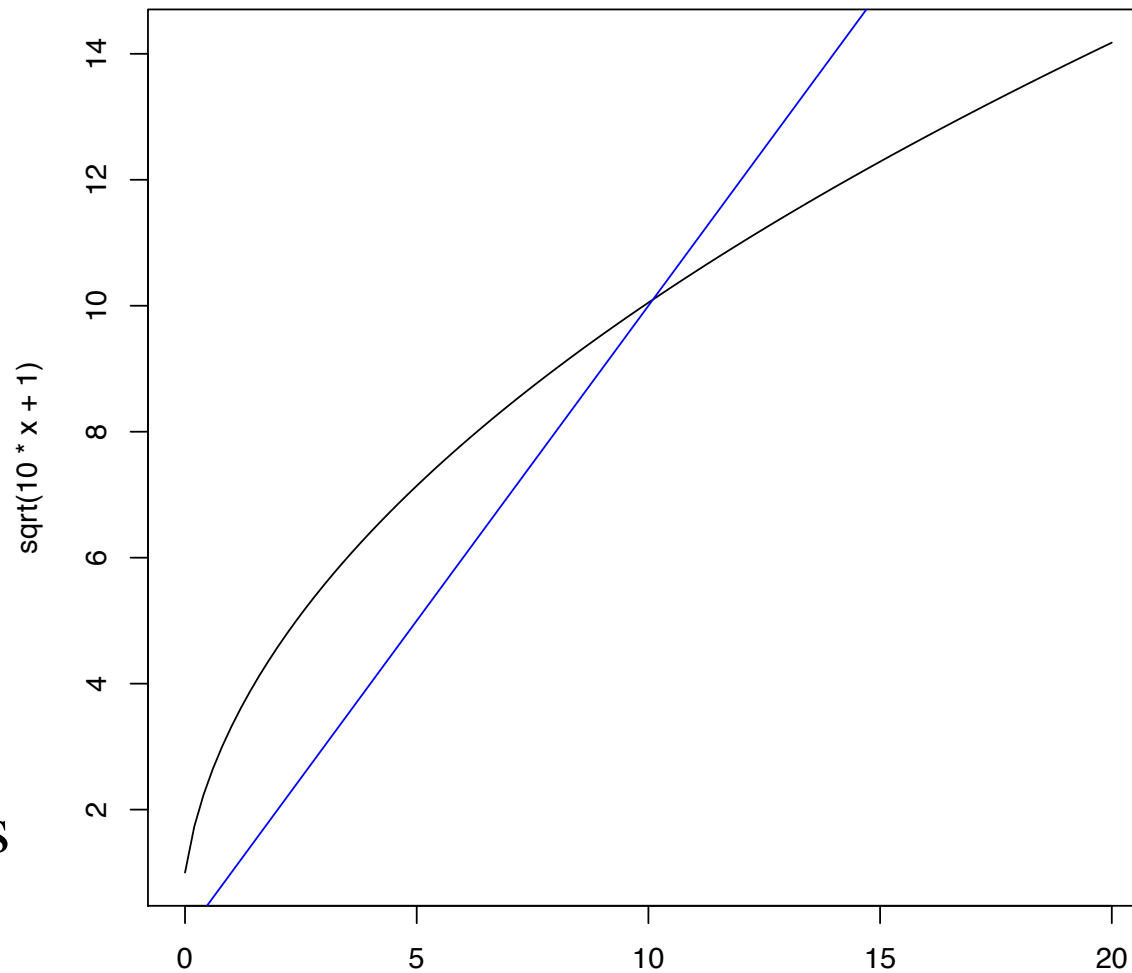
- The fixed point(s) are the points at which the graph of the function intercepts the line $y=x$



- Start at x_0 .
- For $i=1,2,3,\dots$
 - Set $x_i = f(x_{i-1})$
- When should we stop?

Saving plots to file

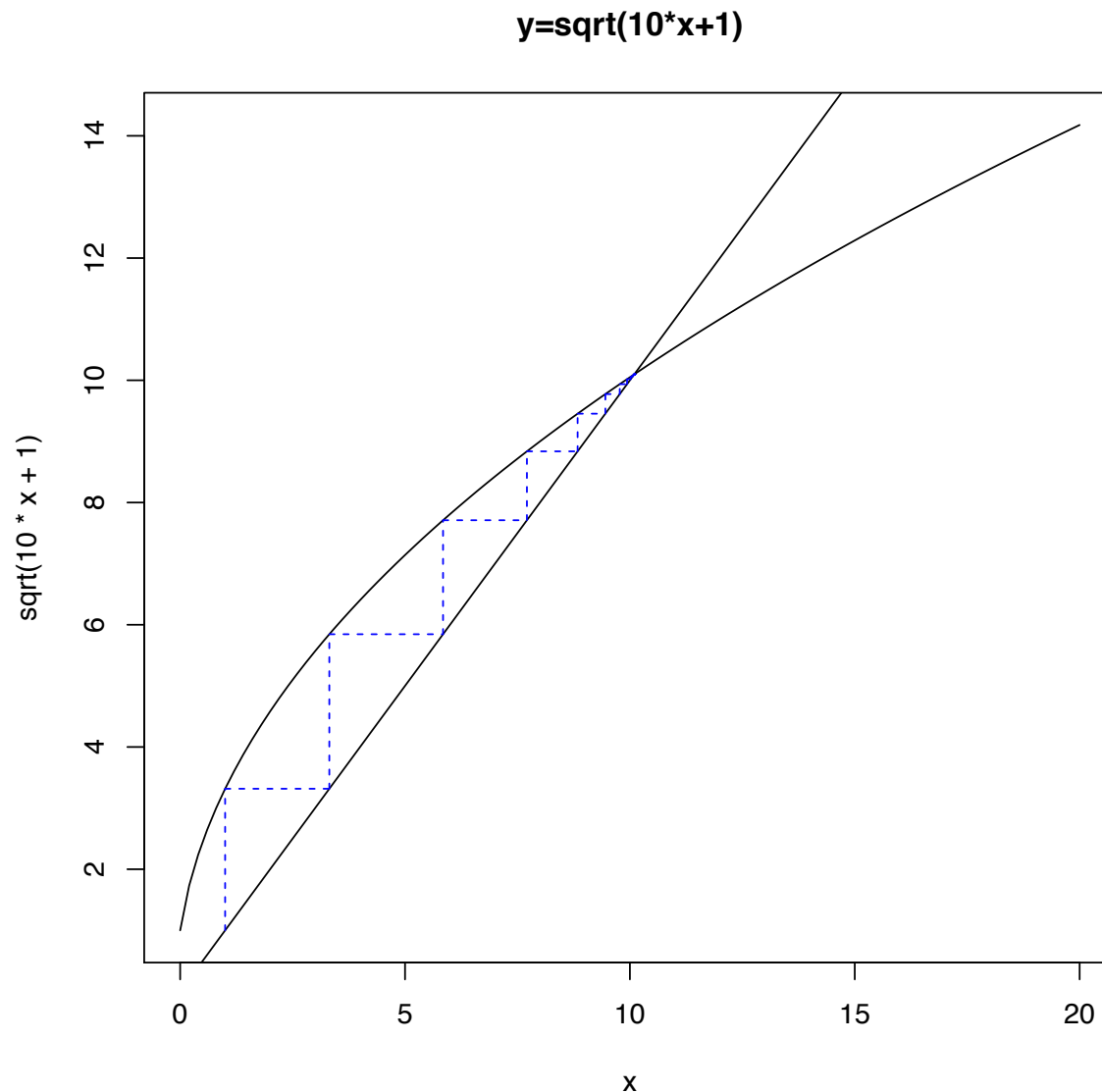
$$y = \sqrt{10x+1}$$



Plots functions

```
pdf("Fig2.pdf")  
curve(sqrt(10*x+1),0,20,main="y=sqrt(10*x+1)")  
abline(coef=c(0,1),col="blue")  
dev.off()
```

A version that plots progress

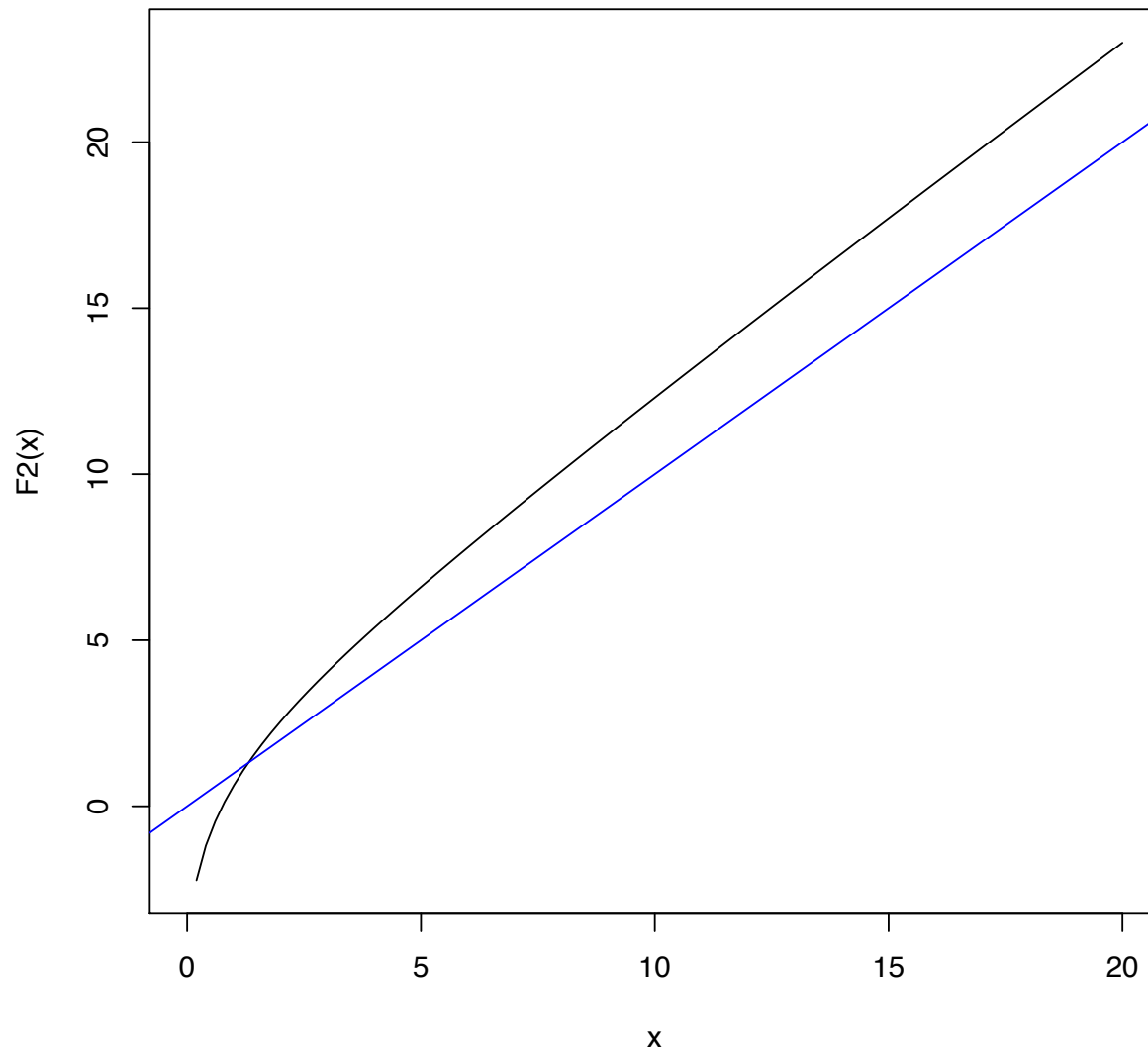


```
segments(X,X,X,Xprime,col="blue",lty=2)
```

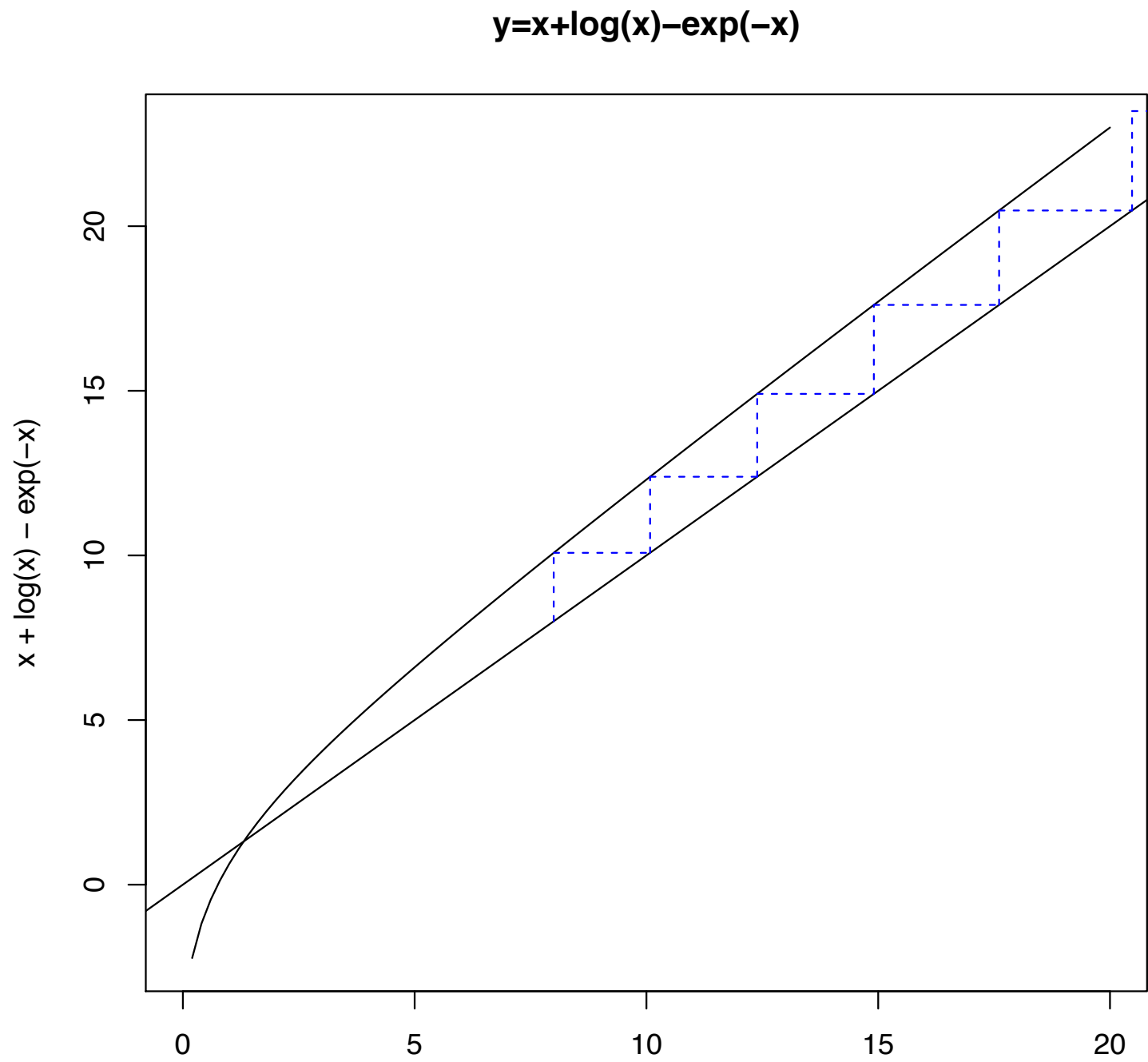
On Github in “FixedPoints”
repo

Let's try a tougher function

$$x + \log(x) - \exp(-x)$$



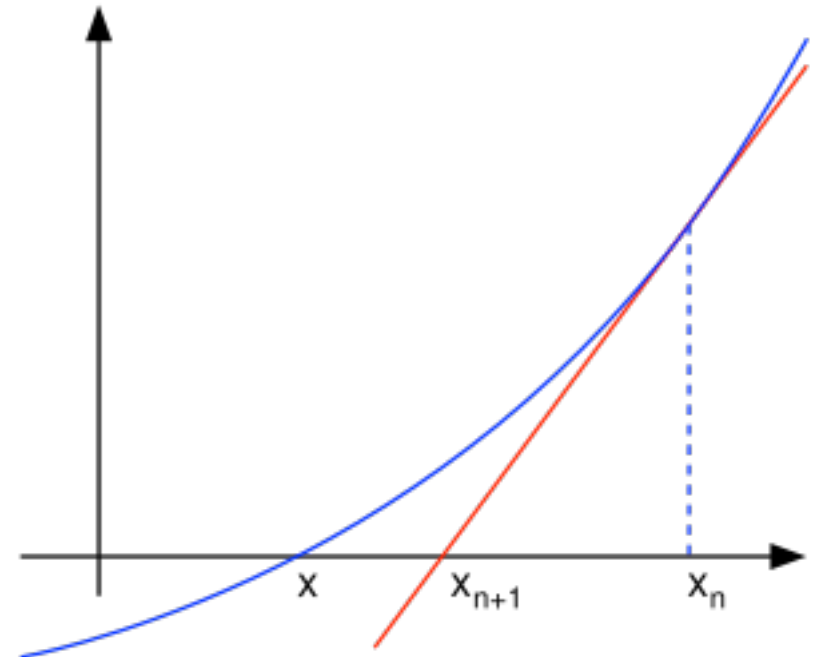
```
F2<-function(x){  
  return(x+log(x)-exp(-x))  
}
```

Root finding: The Newton-Raphson method

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

- Newton-Raphson to find roots
- Start at an arbitrary value
- Sequence $\{x_n\}$ converges to a root

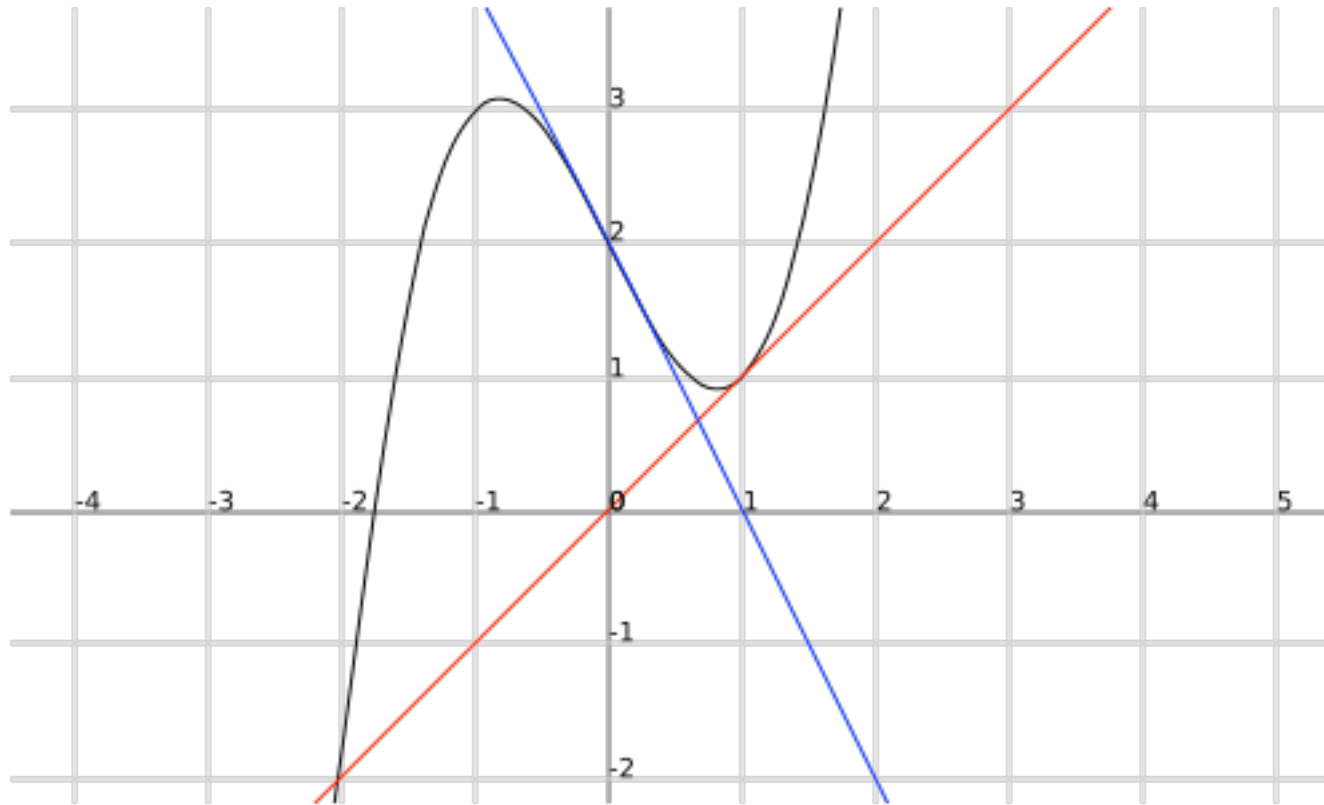


An illustration of one iteration of Newton's method (the function f is shown in blue and the tangent line is in red). We see that x_{n+1} is a better approximation than x_n for the root x of the function f .

Informally

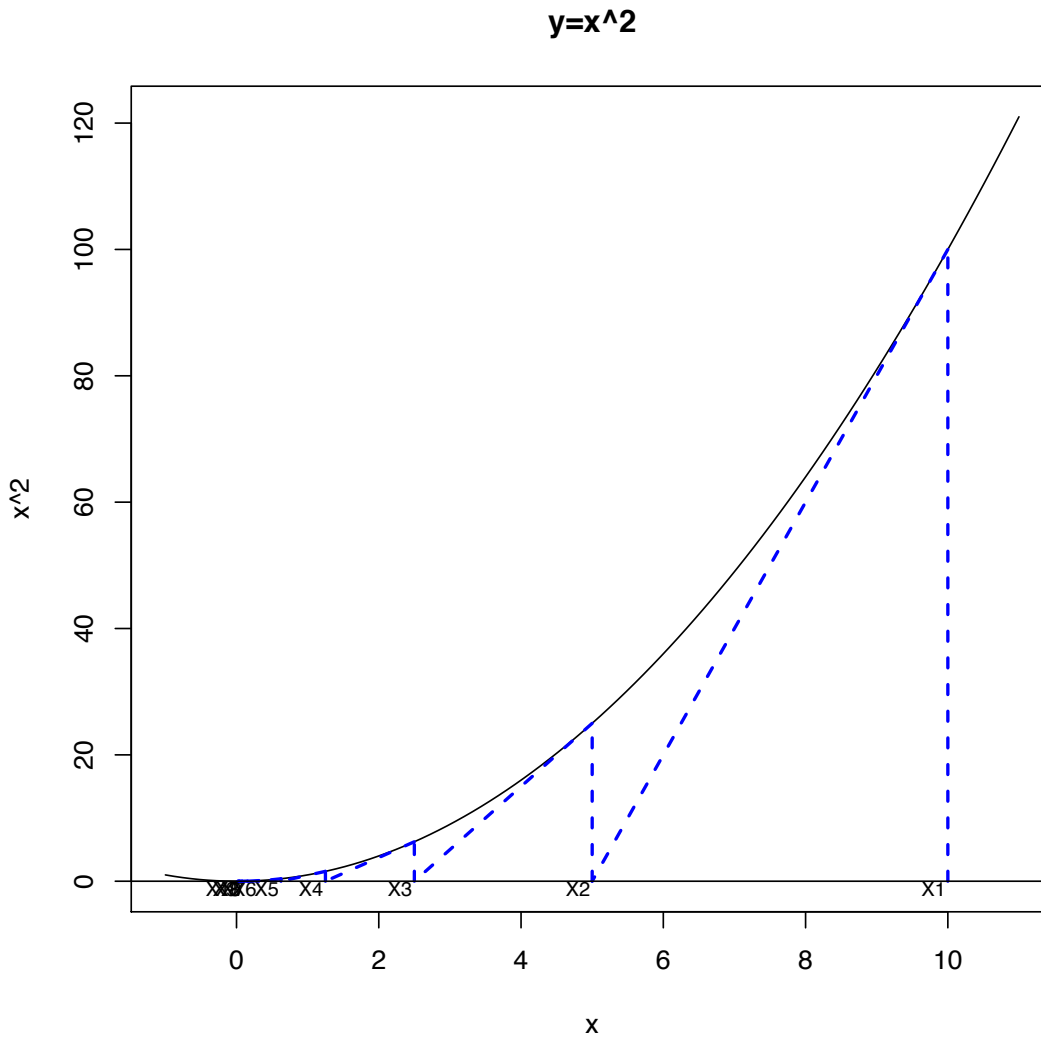
- If we are at x_i
 - Take the tangent to $f(x)$ at $x = x_i$
 - Find where the tangent intercepts the x -axis. Set this to be x_{i+1}
 - Iterate

Which is not to say that it always works...



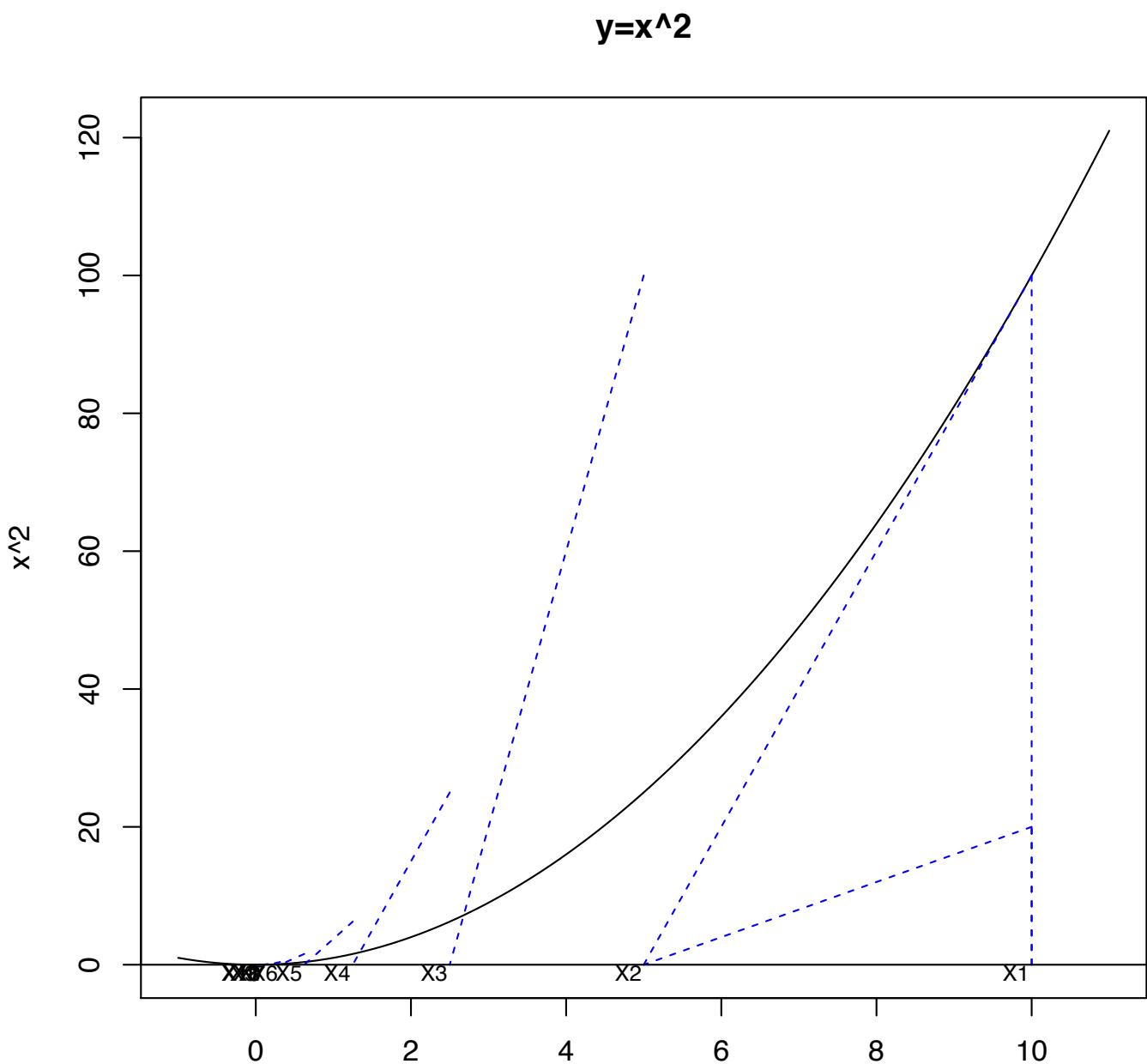
The tangent lines of $x^3 - 2x + 2$ at 0 and 1 intersect the x -axis at 1 and 0 respectively, illustrating why Newton's method oscillates between these values for some starting points.

Example



Iteration 1 : X= 5 Y= 25
 Iteration 2 : X= 2.5 Y= 6.25
 Iteration 3 : X= 1.25 Y= 1.5625
 Iteration 4 : X= 0.625 Y= 0.390625
 Iteration 5 : X= 0.3125 Y= 0.09765625
 Iteration 6 : X= 0.15625 Y= 0.0244140625
 Iteration 7 : X= 0.078125 Y= 0.006103515625
 Iteration 8 : X= 0.0390625 Y= 0.00152587890625
 Iteration 9 : X= 0.01953125 Y= 0.0003814697265625
 Found the root point: 0.01953125 after 9 iterations

My first attempt looked like this...



Newton-Raphson Pseudocode

a function we will work with

```
F1<-function(x){  
  return(c(x^2,2*x)) # note that the function returns two numbers. The first is f(x); the second is the derivative, f'(x)  
}
```

#define a function $F2(x)=\sin(x)$

#define $F3(x)=(x-2)^3-6x$

#define $F4(x)=\cos(x)-x$

(All functions need to return $f(x)$ and $f'(x)$)

#Define your Newton-Raphson function ...

Newton-Raphson Pseudocode

Define your Newton-Raphson function

```
NewtonRaphson<-function(func,StartingValue,Tolerance,MaxNumberOfIterations){
  #initialize a variable, Deviation (say), to record |f(x)| so that you know how far away you are from 0.
  #(So initialize it to some arbitrary large number)
  #Set up a counter, i, to record how many iterations you have performed. Set it equal to 0
  # Initialize the values of x and f(x)

  #Set up a while loop until we hit the required target accuracy or the max. number of steps
  while ((i<MaxNumberOfIterations)&&(Deviation>Tolerance))
  {
    # Record the value of f(x) and f'(x), for the current x value.
    # I put them in a variable Z. Z[1]<-x; Z[2]<-f(x)
    # To be safe, check that the function and it's derivative are defined at X (either could be NaN if you are unlucky)
    if ((Z[1]=="NaN")||(Z[2]=="NaN")){
      cat("Function or derivative not defined error.\n")
      break
    }

    #Find the next X-value using Newton-Raphson's formula. Let's call that value X
    # calculate Deviation<- |f(x)-0|
    # increase the value of your iteration counter
    i<-i+1

    # if you like, have the program write out how it is getting on
    cat(paste("\nIteration ",i,": X=",X," Y=",Y))
  }

  # output the result
  if (Deviation<Tolerance){
    cat(paste("\nFound the root point: ",X, "after ", i, "iterations"))
  }else{
    cat(paste("\nConvergence failure. Deviation: ",Deviation, "after ", i, "iterations"))
  }
  # have the function return the answer
  return(X)
}
```

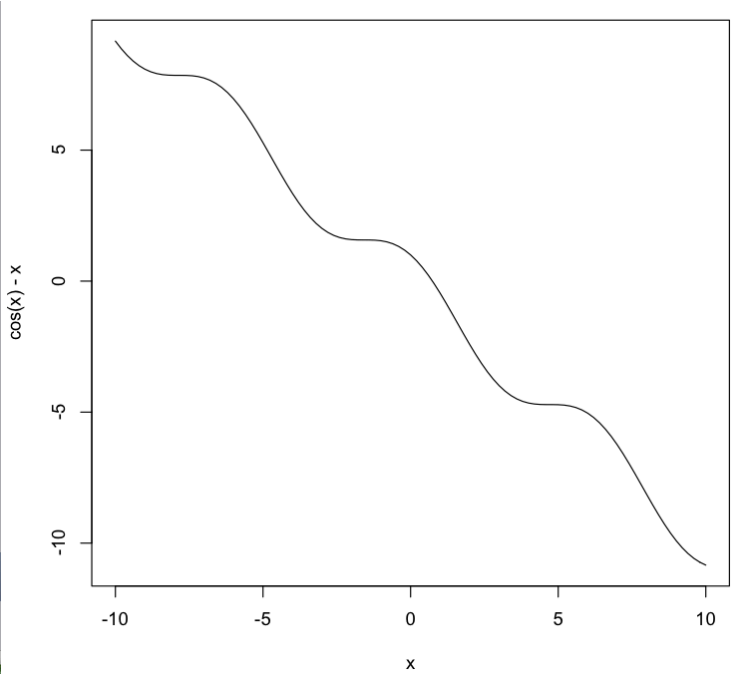
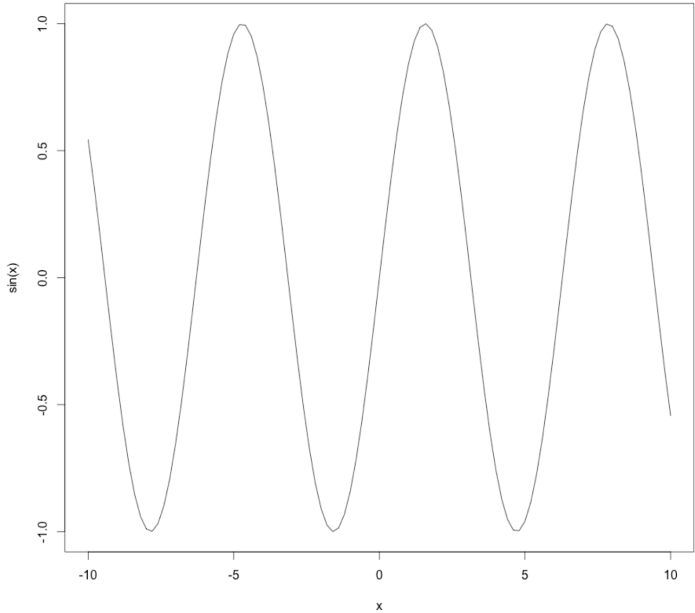
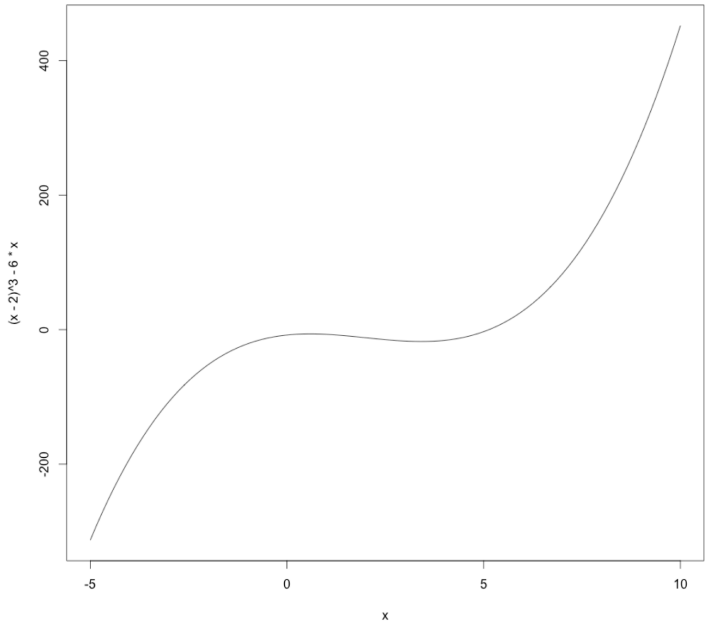
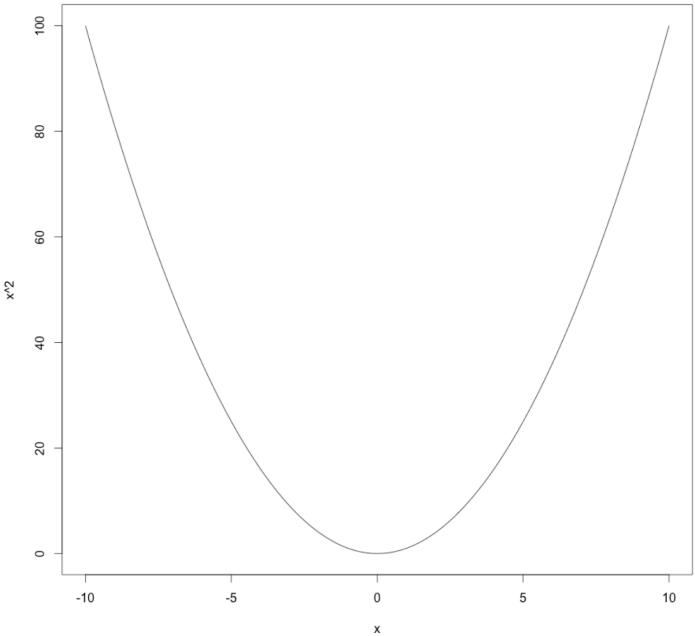

How to use the function:

```
pdf("Fig6.pdf")  
curve(x^2,-1,11,main="y=x^2")  
NewtonRaphson(F1,10,1e-3,40)  
abline(h=0)  
dev.off()
```

‘Week3-NewtonRaphson’ on Github

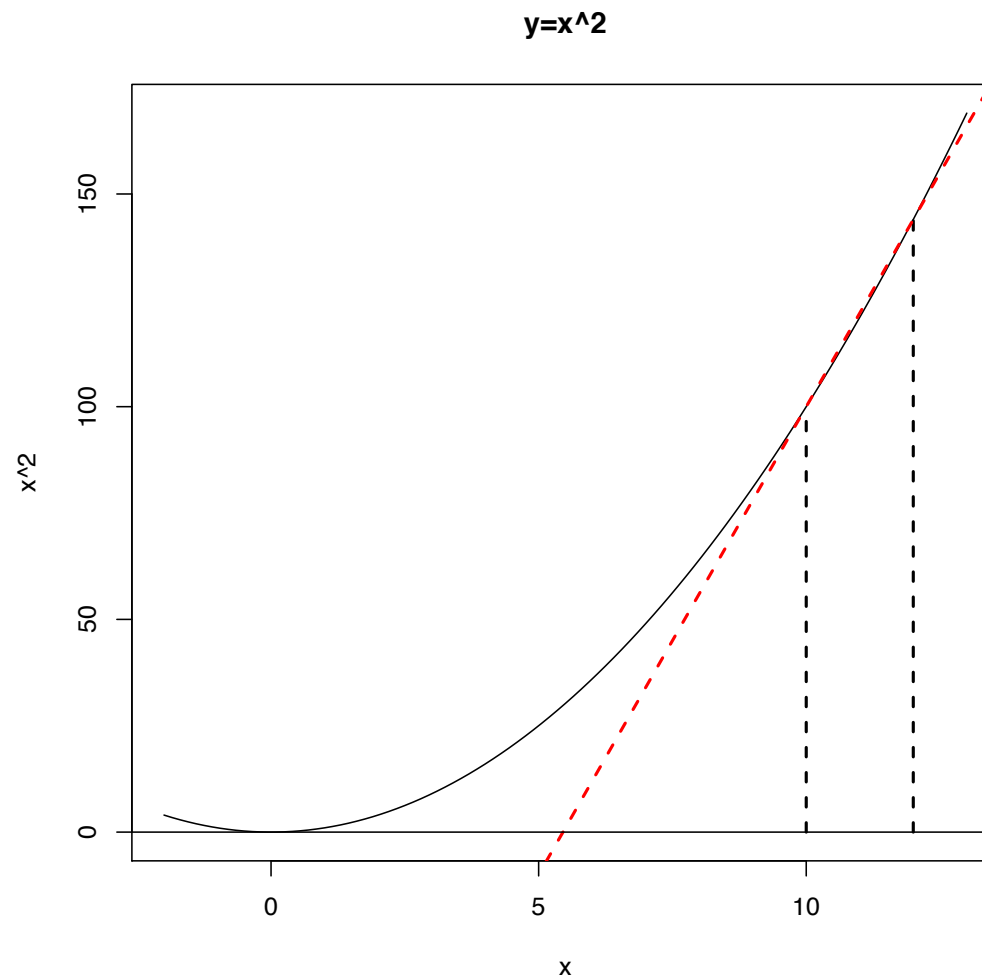
Lab task (~30 minutes)

- Implement Newton-Raphson in R
- Test it on the following functions:
 - $f(x)=x^2$
 - $f(x)=(x-2)^3-6x$
 - $f(x)=\sin(x)$
 - $f(x)=\cos(x)-x$
- Draw plots showing progress of the algorithm
- When you have something that works, or that is giving you problems, push it to GitHub with @pmarjora in your commit message. Or come visit my lab to talk it over.



Secant method for root finding

- Newton-Raphson needs the derivative f' .
- What if f' is impossible to compute?
- Use an approximation to the derivative formed by a straight line put through the last two 'guesses'



```
pdf("Fig5.pdf")
curve(x^2,-2,13,main="y=x^2")
segments(10,0,10,100,lty=2,col="black",lwd=2)
segments(12,0,12,144,lty=2,col="black",lwd=2)
abline(-120,22,col="red",lty=2,lwd=2)
abline(h=0)
dev.off()
```

The Bisection method

- Previous methods don't always work.
- Bisection method is more reliable, but slower.

- Pseudo-code:

Start with X_L , X_R such that $f(X_L)f(X_R) < 0$

while ($|X_L - X_R| > \text{tolerance}$) {

$X_M = (X_L + X_R)/2$

 if $f(X_L)f(X_M) < 0$ then set $X_R = X_M$, else set $X_L = X_M$

}

What happens if there are 3 roots between x_L and x_R ?

Non-examinable lab task

- Implement the bisection method
- Test it on the following functions:
 - $f(x)=x^3$
 - $f(x)=x^3-2x^2+x$
 - $f(x)=\sin(x)$

Examinable Assignment 2a

- To be turned in by 11am, **THREE** week's from now (i.e. Monday March 1st).
- (Exercise 6, from Root-finding Chapter of Jones et al.)
 - See following slide for details.

1. Write a program to implement the Secant method.

2. Test it, using $x_0=1$ and $x_1=2$ on:

1. $\cos(x)-x$

2. $\log(x)-\exp(-x)$

Compare it with the performance of Newton-Raphson on the same functions.

3. Write a function to show a plot of the iterations of the algorithm.

4. Turn it in as an Rmd document, along with a compiled pdf or .md file (along with figures folder).

Lab break ~ 45-60 mins

- We will now break for a lab session on gather town.
- You can work on any of the problems introduced so far.

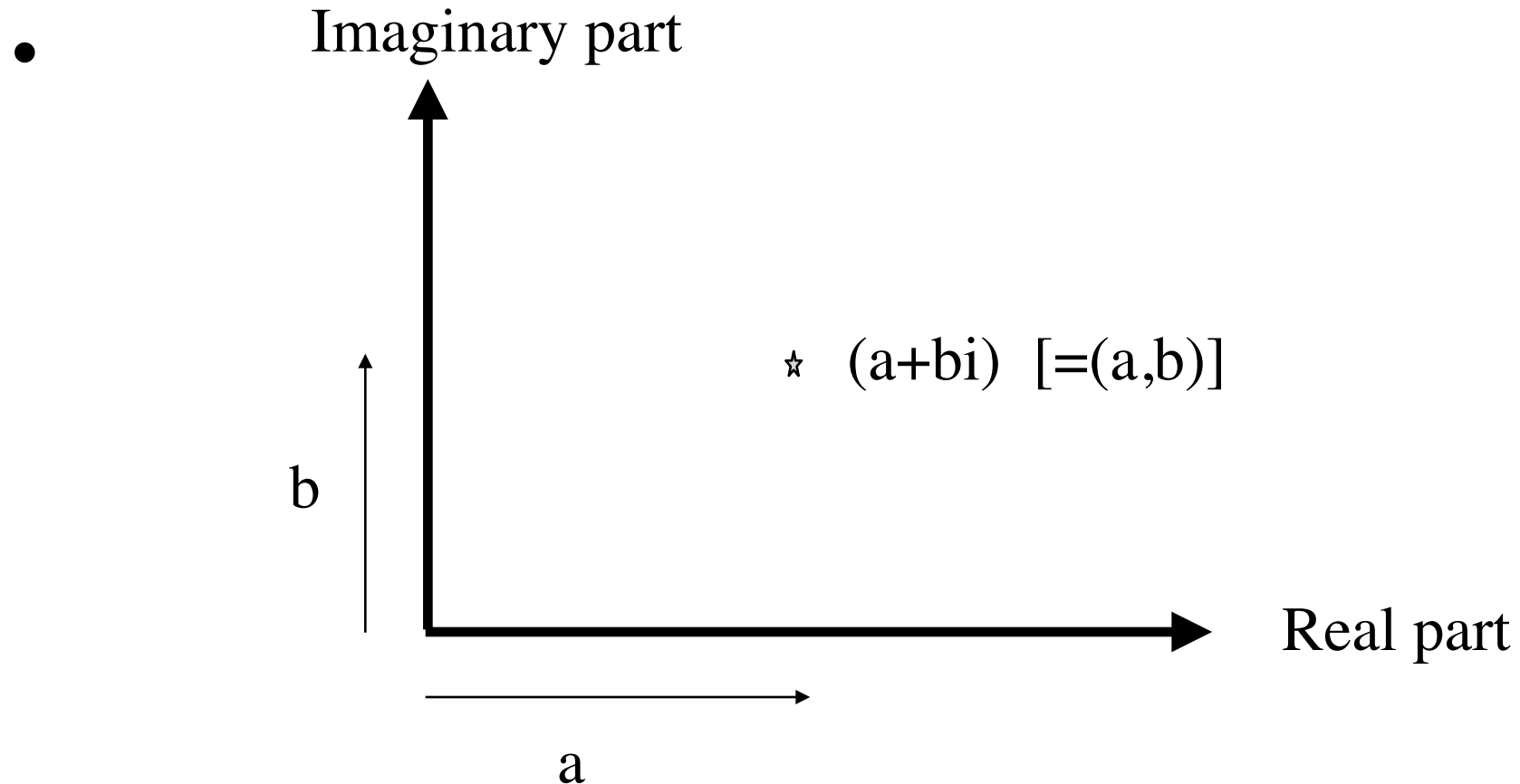
Newton-Raphson (continued)

- We have seen Newton-Raphson on 1-dimensional space
- It works on higher-dimensional space.
 - e.g. Complex numbers
- Complex numbers:
 - $(a+bi)$
 - $(c+di)$
 - $(a+bi)(c+di)=ac+bdi^2+adi+bci=(ac-bd)+(ad+bc)i$

Recall $i^2 = -1$

Complex numbers on the plane

- $a+bi$:



Complex math

- $(a+bi)(c+di)=(ac-bd)+(ad+bc)i$
- $(a+bi)/(c+di)=?$

$$\frac{a+bi}{c+di} = \left(\frac{a+bi}{c+di} \right) \left(\frac{c-di}{c-di} \right) = \frac{(a+bi)(c-di)}{c^2+d^2}$$

- Derivatives work the same way as for real numbers:
 - e.g. If z is a complex number, then the derivative of cz^n is ncz^{n-1} .

Newton-Raphson on complex plane

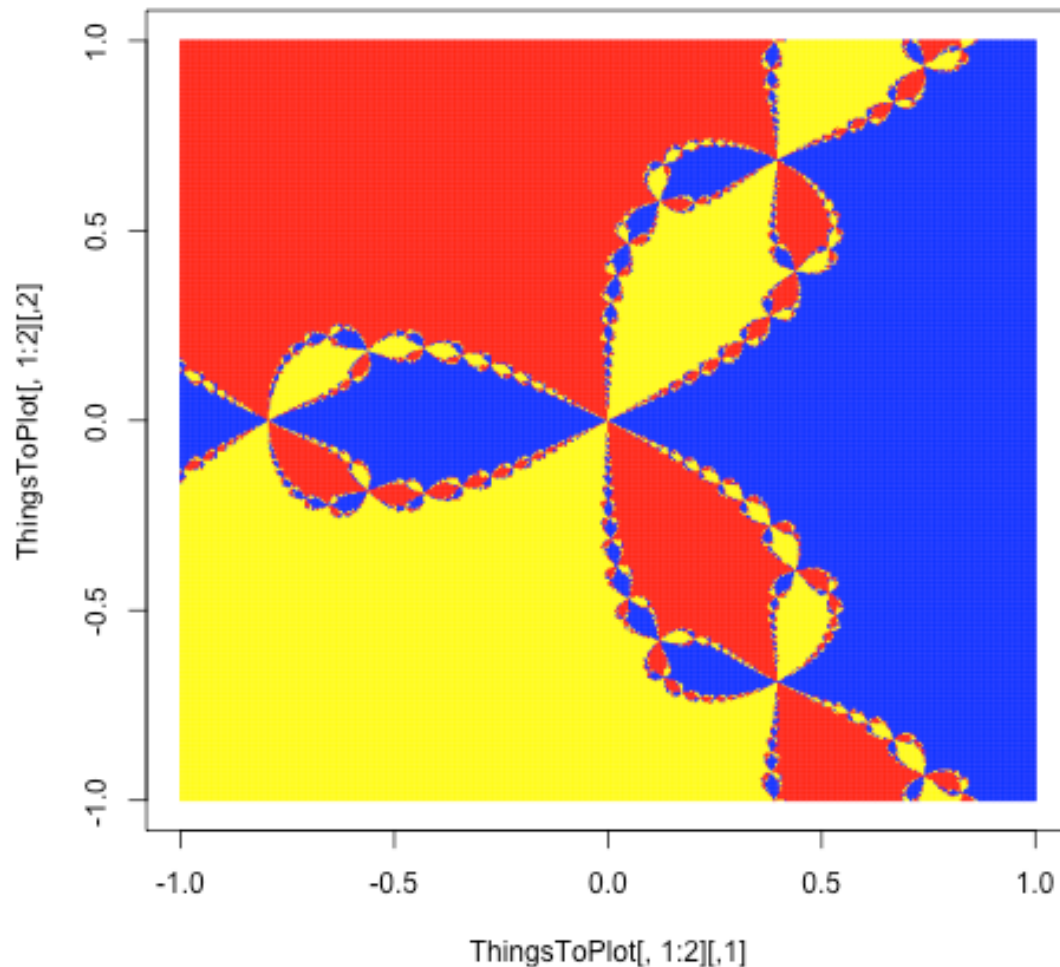
- Works the same way, but using complex derivatives. Complex derivatives work in much the same way as the derivatives you are familiar with.
- Try the function z^3-1 (It has three roots).
- Try z^4-1 .
-

Newton-Raphson task:

Newton-Raphson on complex plane

- Construct a plot in which you sample start values for Newton-Raphson on a 2D grid. eg., let x go from -1 to +1, and y go from -1 to +1
- Color each start point by either:
 - a) How many iterations are needed to reach a root starting from that point.
 - a) Which root you reach from that start point.
- What does the resulting plot look like?
- R has built-in support of complex numbers:
 - `complex(length.out = 0, real = numeric(), imaginary = numeric(), modulus = 1, argument = 0)`
 - `> x<-complex(1,3,4)`
 - `> y<-complex(1,3,-4)`
 - `> x+y`
 - `[1] 6+0i`
 - `> x*y`
 - `[1] 25+0i`

Example: $F(z)=z^3-1$, coloring according to the root you reach



```
png("FigFrac1.png")  
A<-RootPlotter(F6,-1,1,500,-1,1,500,0.2)  
dev.off()
```