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ADR220-B235-P-K-H9D-0.5-FB-S305-P25

Customization description: Biss-c Absolute Encoder 23bit

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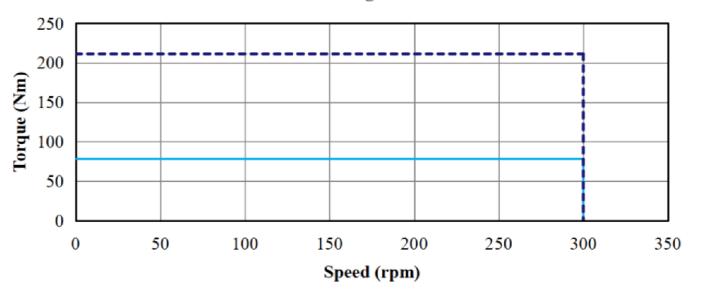
Rev0	SJ	2022/6/24	
Approved		2022/6/25	
Performance Parameters	Symbol	Unit	Value
Continuous Torque (NC)@100°C ^[1]	Ten	Nm	78.2
Peak Torque	T_{pk}	Nm	211.2
Torque Constant ±10%	\mathbf{K}_{t}	Nm/Arms	7.90
Back EMF Constant ±10%	Ke	Vpeak/rpm	0.68
Motor Constant @25°C	K _m	Nm/Sqrt(W)	5.89
Resistance (L-L) @25°C ±10% ^[2]	R ₂₅	О	1.2
Inductance (L-L) $\pm 20\%^{[3]}$	L	mH	11.9
Electrical Time Constant	t _e	ms	9.92
Continuous Current (NC)@100°C ^[1]	I_{cn}	Arms	9.9
Peak Current	I_{pk}	Arms	29.7
Continuous Power Dissipation (NC)@100°C ^[1]	P _{cn}	W	227.4
Max. Coil Temperature	t _{max}	°C	100
Thermal Dissipation Constant (NC) ^[1]	K _{thn}	W/°C	3.0
Max. Bus Voltage	U _{bus}	Vdc	600
Pole Number	2p	-	24
Rec. Max Speed @Peak Torque (415V AC) ^[4]	O _{max}	rpm	300
Rec. Max Speed @Continuous Torque (415V AC) ^[4]	O _{max}	rpm	300
Mechanical Parameters	_		
Overall Mass (NC)	$\mathbf{m}_{\mathbf{n}}$	kg	TBD
Rotor Inertia	J_{r}	kg·m ²	TBD
Axial Runout	-	μm	25
Radial Runout	-	μm	25
Max. Axial Load (Upright Mounting) ^[5]	-	N	1669
Max Axial Load (Inverted / Wall mounting)	-	N	105
Max Moment Load (Upright Mounting)	-	Nm	85
Max Moment Load (Inverted / Wall Mounting)	-	Nm	9.4
Enco der Parameters			
Absolute Encoder	-	bit	23
Accuracy after Error Mapping ^[6]	-	arc sec	±3
Accuracy without error mapping ^[6]		arc sec	±15
Repeatability ^[6]	_	arc sec	±1.5

- [1] Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment. Abbreviations: NC-Natural Cooling
- [2] Resistance is measured by DC current with standard 0.5 m cable.
- [3] Inductance is measured by current frequency of 1 kHz.
- [4] The value is based on absolute encoder under max. bus voltage.
- [5] Please refer to the illustration for different mountings.
- [6] Based on absolute encoder with standard runout.

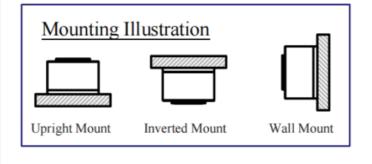
The contents of datasheet are subject to change without prior notice.

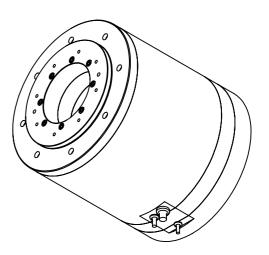
Torque Speed Curve ADR220-B235 Parallel Connection DC Bus Voltage 600V

INITIAL RELEASE



- Continuous Torque --- Peak Torque





DESCRIPTION

RELEASED DATE: 2025/2/5

DATE

21-10-2022

APPD

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	GENERAL TOLERANCE X ± 0.25mm X.X ± 0.1mm X.XX ± 0.05mm X.XXX ± 0.025mm X.XXX ± 0.025mm	Drawn	WYW	20-10-2022		Akribis Systems Pte Ltd ©2004. All rights reserved.		
		Checked	SJ	21-10-2022				
		Approved	YX	21-10-2022	***			
		Material	NA		Model:	ADR220-B235		
		Surface Treatment	NA		Title :	ADR220-B235		
		Heat Treatment	NA		Dwg No:	ADR220-B235		
		Quantity	NA		Sheet:	2 OF4	Rev: 0	

8 7 6 5 4 3 2 1

8 7 3 2

250

150

100

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Upright Mount

Torque (Nm)

ADR220-B235-S-K-H9D-0.5-FB-S305-P25

Customization description: Biss-c Absolute Encoder 23bit

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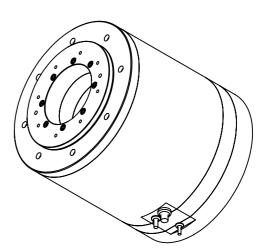
REV	DESCRIPTION	BY	DATE	APPD
00	INITIAL RELEASE	WYW	21-10-2022	YX

Rev0	SJ	2022/6/24	
Approved	Manager	2022/6/25	
Performance Parameters	Symbol	Unit	Value
Continuous Torque (NC)@100°C ^[1]	T _{cn}	Nm	77.9
Peak Torque	T_{pk}	Nm	210.3
Torque Constant ±10%	Kt	Nm/Arms	23.60
Back EMF Constant ±10%	Ke	Vpeak/rpm	2.02
Motor Constant @25°C	K _m	Nm/Sqrt(W)	6.0
Resistance (L-L) @25°C ±10% ^[2]	R ₂₅	О	10.32
Inductance (L-L) ±20% ^[3]	L	mH	106.7
Electrical Time Constant	t _e	ms	10.34
Continuous Current (NC)@100°C ^[1]	I _{cn}	Arms	3.3
Peak Current	I_{pk}	Arms	9.9
Continuous Power Dissipation (NC)@100°C ^[1]	P _{cn}	w	217.3
Max. Coil Temperature	t _{max}	°C	100
Thermal Dissipation Constant (NC) ^[1]	K _{thn}	W/°C	2.9
Max. Bus Voltage	U _{bus}	Vdc	600
Pole Number	2p	-	24
Rec. Max Speed @Peak Torque (415V AC) ^[4]	O _{max}	rpm	125
Rec. Max Speed @Continuous Torque (415V AC) ^[4]	O _{max}	rpm	190
Mechanical Parameters			
Overall Mass (NC)	m_n	kg	TBD
Rotor Inertia	$J_{\rm r}$	kg·m ²	TBD
Axial Runout	-	μm	25
Radial Runout	-	μm	25
Max. Axial Load (Upright Mounting) ^[5]	-	N	1669
Max Axial Load (Inverted / Wall mounting)	-	N	105
Max Moment Load (Upright Mounting)	-	Nm	85
Max Moment Load (Inverted / Wall Mounting)	-	Nm	9.4
Encoder Parameters			
Absolute Encoder	-	bit	23
Accuracy after Error Mapping ^[6]	-	arc sec	±3
Accuracy without error mapping ^[6]		arc sec	±15
Repeatability ^[6]	-	arc sec	±1.5

50 Continuous Torque --- Peak Torque Mounting Illustration

Inverted Mount

Wall Mount



150

- [1] Measurement is taken at ambient temperature 25°C. Value depends on the thermal environment. Abbreviations: NC-Natural Cooling
- [2] Resistance is measured by DC current with standard 0.5 m cable.
- [3] Inductance is measured by current frequency of 1 kHz.
- [4] The value is based on absolute encoder under max. bus voltage.
- [5] Please refer to the illustration for different mountings.
- [6] Based on absolute encoder with standard runout.
- The contents of datasheet are subject to change without prior notice.

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CONTAINED IN IT ARE CONFIDENTIAL. AND	GENERAL		Approved	YX	21-10-2022	***	©2004. All rights re	servea.
CANNOT BE CÓPIED OR	TOLERAN	4	Material	NA		Model:	ADR220-B235	
OR IN PART WITHOUT	X ± 0.25m X.X ± 0.1m	3rd ANGLE	Surface Treatment	NA		Title :	ADR220-B235	
WRITTEN CONSENT OF	$X.XX \pm 0.0$	•	Heat Treatment	NA		Dwg No:	ADR220-B235	
AKRIBIS SYS PTE LTD	X.XXX ± 0	.025mm	Quantity	NA		Sheet:	3 OF4	Rev: 0

Torque Speed Curve ADR220-B235 Series Connection DC Bus Voltage 600V

100

Speed (rpm)

7 8 2

ADR220-B235-P/S-J/K-NH-0.5-FB-S305-P25

Customization description: Biss-c Absolute Encoder 23bit

WIRING DIAGRAM AND CABLE INFORMATION:

Table 1:

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Motor Power Cable Information

Specification	Unit		Remarks
Cable Diameter	mm	9.5	See Note 1
Cable Length	m	0.5	See Note 1
Number of Cores	-	4×2.5mm^2	
Cable Colour	-	Grey	
Minimum Bending	mm	Moving:Cable ∅ x 12	
Radius		Fixed: Cable ∅x6	
Rated Voltage	-	3-phase 415Vac	
Termination Type	-	Flying Leads	
Ferrite Bead	-	Yes	
CE Compliance	-	Yes	

Table 2: **Hall Sensor Cable Information**

Specification	Unit		Remarks
Cable Diameter	mm	5.2	See Note 1
Cable Length	m	0.5	See Note 1
Number of Cores	ı	2×0.14mm^2	
Cable Colour	-	Grey	
Minimum Bending	mm	Moving:Cable ∅ x 12	
Radius		Fixed: Cable ∅x6	
Temperature Option	-	Provided	J-Type(thermostat) K-Type(PT100)
CE Compliance	-	Yes	

Table 3: **Encoder Cable Information**

Specification	Unit		Remarks	
Cable Diameter	mm	4.0	See Note 1	
Cable Length	m	0.5	See Note 1	
Number of Cores	-	6		
Cable Colour	-	Black		
Minimum Bending		Moving:Cable ∅ x 12		
Radius	mm	Fixed: Cable ∅x6		

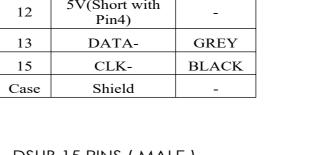
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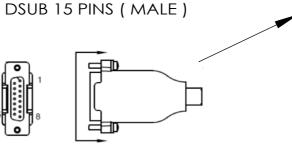
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- 1. Cable diameter within +/-0.3mm tolerance, cable length within +/-60.0mm tolerance;
- 2. Certain specifications in the drawing are subject to change.

Encoder Cable

PIN	DESCRIPTION	COLOUR
2	GND	WHITE
4	5V	RED
5	DATA+	YELLOW
8	CLK+	BROWN
10	GND(Short with Pin2)	-
12	5V(Short with Pin4)	-
13	DATA-	GREY
15	CLK-	BLACK
Case	Shield	_





Thermal Sensor Cable

THERMAL SENSOR

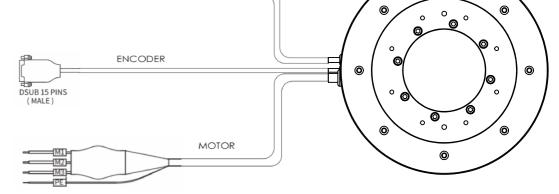
INITIAL RELEASE

PIN	DESCRIPTION	COLOUR	
-	T1	PINK	
-	T2	BLUE	
		(KTYPE-	SENSOR WIRE PT100) THERMOSTAT)

21-10-2022

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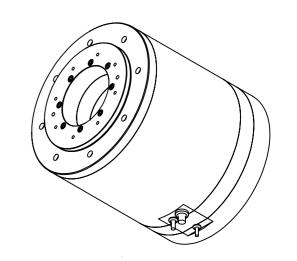
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Motor Cable

PIN	DESCRIPTION	COLOUR
-	M1	BLACK 1
-	M2	BLACK 2
-	M3	BLACK 3
-	PE	YELLOW / GREEN

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20-10-2022 20-10-2022 21-10-2022 Checked 21-10-2022 YX Surface Treatment NA

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	Model:	ADR220-B235		
	Title :	ADR220-B235		
	Dwg No:	ADR220-B235		
	Sheet:	4 OF4	Rev: 0	
			Rev: 0	_

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