

1. Să se reducă la forma canonică următoarele forme pătratice.

2) $q(x) = x_1^2 - 4x_1x_2 + 2x_1x_3 + 2x_2^2 + 5x_3^2$

Metoda 1:

$$\begin{aligned} q(x) &= x_1^2 - 4x_1x_2 + 2x_1x_3 + 2x_2^2 + 5x_3^2 \\ &= (x_1^2 - 4x_1x_2 + 2x_1x_3) + 2x_2^2 + 5x_3^2 \\ &= (x_1^2 - 4x_1x_2 + 2x_1x_3 - 4x_2x_3 + 4x_2^2 + x_3^2) + 4x_2x_3 - 4x_2^2 - x_3^2 + 2x_2^2 + 5x_3^2 \\ &= (x_1 - 2x_2 + x_3)^2 + 4x_2x_3 - 2x_2^2 + 4x_3^2 \\ &= (x_1 - 2x_2 + x_3)^2 + (-2)(x_2^2 - 2x_2x_3 + x_3^2) + 4x_3^2 \\ &= (x_1 - 2x_2 + x_3)^2 - 2(x_2^2 - 2x_2x_3 + x_3^2) + 2x_3^2 + 4x_3^2 \\ &= \underbrace{(x_1 - 2x_2 + x_3)^2}_{\varphi_1^2} - 2 \underbrace{(x_2 - x_3)^2}_{\varphi_2^2} + \underbrace{6x_3^2}_{\varphi_3^2} \end{aligned}$$

$$\Rightarrow q(\varphi) = \varphi_1^2 - 2\varphi_2^2 + 6\varphi_3^2$$

Metoda 2

$$A = \begin{pmatrix} 1 & -2 & 1 \\ -2 & 2 & 0 \\ 1 & 0 & 5 \end{pmatrix}; \begin{pmatrix} \boxed{1} & 2 & 1 \\ -2 & 2 & 0 \\ 1 & 0 & 5 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & 1 \\ 0 & \boxed{-2} & 2 \\ 0 & 2 & 4 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & \boxed{6} \end{pmatrix}$$

$$\Rightarrow q(x) = 1 \cdot (x_1 - 2x_2 + x_3)^2 - 2(x_2 - x_3)^2 + 6x_3^2$$

$$\Rightarrow q(\varphi) = \varphi_1^2 - 2\varphi_2^2 + 6\varphi_3^2$$

Metoda 3

$$A = \begin{pmatrix} \boxed{1} & -2 & 1 \\ -2 & 2 & 0 \\ 1 & 0 & 5 \end{pmatrix}; \quad D_0 = 1; \quad D_1 = 1; \quad D_2 = \begin{vmatrix} 1 & -2 \\ -2 & 2 \end{vmatrix} = -2$$

$$D_3 = 10 - 2 - 20 = -12$$

$$\Rightarrow q(\varphi) = \frac{D_1}{D_0} \varphi_1^2 + \frac{D_2}{D_1} \varphi_2^2 + \frac{D_3}{D_2} \varphi_3^2 = \varphi_1^2 - 2\varphi_2^2 + 6\varphi_3^2$$

3) $q(x) = -2x_1x_2 + x_2x_3 - x_1x_3$

Se face schimbarea de variabilă:

$$\begin{cases} x_1 = y_1 - y_2 \\ x_2 = y_1 + y_2 \\ x_3 = y_3 \end{cases}$$

Metoda 1

$$\begin{aligned} Q(x) &= -2(\gamma_1 - \gamma_2)(\gamma_1 + \gamma_2) + (\gamma_1 + \gamma_2) \cdot \gamma_3 - \gamma_3(\gamma_1 - \gamma_2) \\ &= -2\gamma_1^2 + 2\gamma_2^2 + \gamma_1\gamma_3 + \gamma_2\gamma_3 - \gamma_1\gamma_3 + \gamma_2\gamma_3 \\ &= -2\gamma_1^2 + 2\gamma_2^2 + 2\gamma_2\gamma_3 \\ &= -2\gamma_1^2 + 2\left(\gamma_2^2 + \gamma_2\gamma_3 + \frac{1}{4}\gamma_3^2\right) - \frac{1}{2}\gamma_3^2 \\ &= -2\underbrace{\gamma_1^2}_{\gamma_1^2} + 2\underbrace{\left(\gamma_2 + \frac{1}{2}\gamma_3\right)^2}_{\gamma_2^2} - \frac{1}{2}\underbrace{\gamma_3^2}_{\gamma_3^2} \Rightarrow Q(y) = -2y_1^2 + 2y_2^2 - \frac{1}{2}y_3^2. \end{aligned}$$

Metoda 2

$$A = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix}; \begin{pmatrix} \boxed{-2} & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & \boxed{2} & 1 \\ 0 & 1 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1/2 \\ 0 & 0 & \boxed{-1/2} \end{pmatrix}$$

$$\Rightarrow Q(y) = -2y_1^2 + 2\left(y_2^2 + \frac{1}{2}y_3\right)^2 - \frac{1}{2}y_3^2$$

$$\Rightarrow Q(y) = -2y_1^2 + 2y_2^2 - \frac{1}{2}y_3^2$$

Metoda 3

$$A = \left(\begin{array}{c|c|c} \boxed{-2} & 0 & 0 \\ \hline 0 & 2 & 1 \\ 0 & 1 & 0 \end{array} \right); D_0 = 1; D_1 = -2; D_2 = -4; D_3 = 2.$$

$$Q(y) = -2y_1^2 + 2y_2^2 - \frac{1}{2}y_3^2$$

$$b) Q(x) = 2x_1^2 - 5x_2^2 + 4x_1x_3 - 4x_1x_4 + 6x_2x_3 - 8x_3x_4.$$

Metoda 1

$$\begin{aligned} Q(x) &= (2x_1^2 + 4x_1x_3 - 4x_1x_4) - 5x_2^2 + 6x_2x_3 - 8x_3x_4 \\ &= 2(x_1^2 + 2x_1x_3 - 2x_1x_4 - 2x_3x_4 + x_3^2 + x_4^2) + 4x_3x_4 - 2x_3^2 - 2x_4^2 - 5x_2^2 + \\ &\quad + 6x_2x_3 - 8x_3x_4 \\ &= 2(x_1 + x_3 - x_4)^2 - 5\left(x_2^2 - \frac{6}{5}x_2x_3 + \frac{9}{25}x_3^2\right) + \frac{9}{5}x_3^2 - 2x_3^2 - 2x_4^2 - 4x_3x_4. \\ &= 2(x_1 + x_3 - x_4)^2 - 5\left(x_2 - \frac{3}{5}x_3\right)^2 - \frac{1}{5}x_3^2 - 2x_4^2 - 4x_3x_4 \\ &= 2(x_1 + x_3 - x_4)^2 - 5\left(x_2 - \frac{3}{5}x_3\right)^2 - \frac{1}{5}(x_3^2 + 20x_3x_4 + 100x_4^2) + 20x_4^2 - 2x_4^2 \\ &= 2\underbrace{(x_1 + x_3 - x_4)^2}_{\gamma_1^2} - 5\underbrace{\left(x_2 - \frac{3}{5}x_3\right)^2}_{\gamma_2^2} - \frac{1}{5}\underbrace{(x_3 + 10x_4)^2}_{\gamma_3^2} + \underbrace{78x_4^2}_{\gamma_4^2} \end{aligned}$$

$$\Rightarrow Q(y) = 2y_1^2 - 5y_2^2 - \frac{1}{5}y_3^2 + 78y_4^2$$

Metoda 2

$$A = \begin{pmatrix} \boxed{2} & 0 & 2 & -2 \\ 0 & -5 & 3 & 0 \\ 2 & 3 & 0 & -4 \\ \boxed{2} & 0 & -4 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & \boxed{-5} & 3 & 0 \\ 0 & 3 & -2 & -2 \\ 0 & 0 & -2 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -3/5 & 0 \\ 0 & 0 & \boxed{-1/5} & -2 \\ 0 & 0 & -2 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -3/5 & 0 \\ 0 & 0 & 1 & 10 \\ 0 & 0 & 0 & \boxed{18} \end{pmatrix}$$

$$\Rightarrow q(x) = 2(x_1 + x_3 - x_4)^2 - 5(x_2 - \frac{3}{5}x_3)^2 - \frac{1}{5}(x_3 + 10x_4)^2 + 18x_4^2$$

$$\Rightarrow q(y) = 2y_1^2 - 5y_2^2 - \frac{1}{5}y_3^2 + 18y_4^2$$

Metoda 4

$$A = \begin{pmatrix} \boxed{2} & 0 & 2 & -2 \\ 0 & \boxed{-5} & 3 & 0 \\ 2 & 3 & 0 & -4 \\ -2 & 0 & -4 & 0 \end{pmatrix}$$

$$D_0 = 1;$$

$$D_1 = 2;$$

$$D_2 = -10;$$

$$D_3 = 20 - 18 = 2;$$

$$D_4 = 36;$$

$$\Rightarrow q(y) = 2y_1^2 - 5y_2^2 - \frac{1}{5}y_3^2 + 18y_4^2$$