

7. Să se verifice cu ajutorul unei substituții dacă următoarele sisteme de vectori formează baze și în caz afirmativ să se det. coord. vect. \vec{x} în aceste baze:

b) $B = \{(1, 2, -1)^T, (1, 5, 0)^T, (6, 3, -3)^T\}$, $\vec{x} = (0, 3, 2)^T$.

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{x}
\vec{e}_1	1	1	6	0
\vec{e}_2	2	5	3	3
\vec{e}_3	-1	0	-3	2
\vec{v}_1	1	1	6	0
\vec{e}_2	0	3	-9	3
\vec{e}_3	0	1	3	2
\vec{v}_1	1	0	9	-1
\vec{v}_2	0	1	-3	1
\vec{e}_3	0	0	6	1
\vec{v}_1	1	0	0	-15/6
\vec{v}_2	0	1	0	9/6
\vec{v}_3	0	0	1	1/6

Deoarece obt $I_3 \Rightarrow B$ formează o bază, iar
 $\vec{x}_B = \left(-\frac{15}{6}, \frac{9}{6}, \frac{1}{6}\right)$

c) $B = \{(1, -2, 3)^T, (-2, 5, 0)^T, (2, -3, 2)^T\}$, $\vec{x} = (0, -3, 8)^T$.

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{x}
\vec{e}_1	1	-2	2	0
\vec{e}_2	-2	5	-3	-3
\vec{e}_3	3	0	2	8
\vec{v}_1	1	-2	2	0
\vec{e}_2	0	9	7	-3
\vec{e}_3	0	6	-4	8
\vec{v}_1	1	0	20/9	-2/3
\vec{v}_2	0	1	7/9	-1/3
\vec{e}_3	0	0	-74/3	70
\vec{v}_1	1	0	0	86/27
\vec{v}_2	0	1	0	-2/27
\vec{v}_3	0	0	1	-15/7

Deoarece am obtinut $I_3 \Rightarrow$

B formează o bază, iar

$$\vec{x}_B = (86/27, -2/27, -15/7).$$

d) $B = \{(1, -2, 1)^T, (2, 5, 4)^T, (3, -7, 2)^T\}$, $\vec{x} = (0, 3, 1)^T$.

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{x}
\vec{r}_1	1	2	3	0
\vec{r}_2	-2	5	-1	3
\vec{r}_3	1	4	2	1
\vec{v}_1	1	2	2	0
\vec{r}_2	0	5	5	3
\vec{r}_3	0	2	-1	1
\vec{v}_1	1	0	11/9	-2/3
\vec{v}_2	0	1	5/9	1/3
\vec{r}_3	0	0	-19/9	7/3
\vec{v}_1	1	0	0	-7/19
\vec{v}_2	0	1	0	8/19
\vec{v}_3	0	0	1	-3/19

Decore se am obținut $I_3 \Rightarrow B$ formază o bază,
 iar $\vec{x}_B = \left(\frac{-7}{19}, \frac{8}{19}, \frac{-3}{19} \right)$

e) $B = \{(1, 5, 1)^T, (0, 1, 3)^T, (1, 6, 5)^T\}$, $\vec{x} = (1, 2, 3)^T$.

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{x}
\vec{r}_1	1	0	1	1
\vec{r}_2	5	1	6	2
\vec{r}_3	1	3	5	3
\vec{v}_1	1	0	1	1
\vec{r}_2	0	1	1	-3
\vec{r}_3	0	3	4	2
\vec{v}_1	1	0	1	1
\vec{v}_2	0	1	1	-3
\vec{r}_3	0	0	1	11
\vec{v}_1	1	0	0	-10
\vec{v}_2	0	1	0	-14
\vec{v}_3	0	0	1	11

Decore se am obținut $I_3 \Rightarrow B$ form. o bază
 iar $\vec{x}_B = (-10, -14, 11)$.

2. Se re determine matricas de la B_1 la B_2 :

b) $B_1 = \{(2, -1, 0)^T, (1, 1, 1)^T, (0, 2, 3)^T\}$

$B_2 = \{(-1, 0, 1)^T, (0, 1, 1)^T, (3, 1, -1)^T\}$

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{w}_1	\vec{w}_2	\vec{w}_3
\vec{e}_1	2	-1	0	-1	0	3
\vec{e}_2	-1	1	1	0	1	1
\vec{e}_3	0	1	3	1	1	1
\vec{v}_1	1	1/2	0	-1/2	0	3/2
\vec{v}_2	0	3/2	2	-1/2	1	5/2
\vec{v}_3	0	1	3	1	1	-1
\vec{v}_1	1	0	2/3	-1/3	-1/3	2/3
\vec{v}_2	0	1	4/3	-1/3	2/3	5/3
\vec{v}_3	0	0	5/3	4/3	1/3	-8/3
\vec{v}_1	1	0	0	-1/5	-7/5	26/5
\vec{v}_2	0	1	0	-1/5	2/5	19/5
\vec{v}_3	0	0	1	4/5	1/5	-8/5

$\underbrace{\begin{matrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \end{matrix}}_{I_3} \quad \underbrace{\begin{matrix} \vec{w}_1 & \vec{w}_2 & \vec{w}_3 \end{matrix}}_{M_{B_1, B_2}}$

c) $B_1 = \{(1, 1, 2)^T, (1, 0, 3)^T, (3, -1, 2)^T\}$

$B_2 = \{(-1, 4, 2)^T, (1, 3, -2)^T, (0, 7, 5)^T\}$

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{w}_1	\vec{w}_2	\vec{w}_3
\vec{e}_1	1	1	2	-1	4	2
\vec{e}_2	1	0	3	1	3	-2
\vec{e}_3	3	-1	2	2	-2	5
\vec{v}_1	1	1	2	-1	4	2
\vec{v}_2	0	-1	-1	5	2	-7
\vec{v}_3	0	1	-4	4	-4	9
\vec{v}_1	1	0	-1	4	3	-2
\vec{v}_2	0	1	4	-5	-2	-7
\vec{v}_3	0	0	-8	9	-2	12
\vec{v}_1	1	0	0	-23/8	13/4	17/2
\vec{v}_2	0	1	0	-4/8	-3	-7
\vec{v}_3	0	0	1	-9/8	1/4	3/2

$\underbrace{\begin{matrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \end{matrix}}_{I_3} \quad \underbrace{\begin{matrix} \vec{w}_1 & \vec{w}_2 & \vec{w}_3 \end{matrix}}_{M_{B_1, B_2}}$

d) $B_1 = \{(1, 3, 2)^T, (0, 1, 5), (1, 2, 4)^T\}$

$B_2 = \{(1, 2, 4)^T, (2, 4, 5)^T, (4, -1, 2)^T\}$

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{w}_1	\vec{w}_2	\vec{w}_3
\vec{e}_1	1	0	1	1	2	4
\vec{e}_2	3	1	2	2	4	-1
\vec{e}_3	2	5	4	4	5	2
\vec{v}_1	1	0	1	1	2	4
\vec{v}_2	0	1	-1	-1	-2	-13
\vec{v}_3	0	5	2	2	1	-6
\vec{v}_1	1	0	1	1	2	4
\vec{v}_2	0	1	-1	-1	-2	-13
\vec{v}_3	0	0	7	7	8	59
\vec{v}_1	1	0	0	0	6/7	-37/7
\vec{v}_2	0	1	0	0	-6/7	150/7
\vec{v}_3	0	0	1	1	8/7	59/7

$\left. \begin{matrix} \vec{v}_1 \\ \vec{v}_2 \\ \vec{v}_3 \end{matrix} \right\} M_{B_1 B_2}$

e) $B_1 = \{(1, 4)^T, (2, -3)^T\}$; $B_2 = \{(3, -1)^T, (4, 2)^T\}$.

	\vec{v}_1	\vec{v}_2	\vec{w}_1	\vec{w}_2
\vec{e}_1	1	2	3	4
\vec{e}_2	4	-3	-1	2
\vec{v}_1	1	2	3	4
\vec{v}_2	0	-7	-13	-14
\vec{v}_1	1	0	7/11	96/11
\vec{v}_2	0	1	13/11	74/11

$\left. \begin{matrix} \vec{v}_1 \\ \vec{v}_2 \end{matrix} \right\} M_{B_1 B_2}$

f) $B_1 = \{(4, -3)^T, (1, 5)^T\}$; $B_2 = \{(3, 2)^T, (4, -3)^T\}$

	\vec{v}_1	\vec{v}_2	\vec{w}_1	\vec{w}_2
\vec{e}_1	4	1	3	4
\vec{e}_2	-3	5	2	-3
\vec{v}_1	1	1/4	3/4	1
\vec{v}_2	0	23/4	7/4	0
\vec{v}_1	1	0	13/23	1
\vec{v}_2	0	1	17/23	0

$\left. \begin{matrix} \vec{v}_1 \\ \vec{v}_2 \end{matrix} \right\} M_{B_1 B_2}$

3. Găsiți și determinați cu ajutorul bazei substituției inversele matricelor.

b) $A = \begin{pmatrix} 1 & 1 & 2 \\ 3 & 0 & -1 \\ 4 & 1 & 5 \end{pmatrix}$

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{l}_1	\vec{l}_2	\vec{l}_3
\vec{l}_1	1	1	2	1	0	0
\vec{l}_2	3	0	-1	0	1	0
\vec{l}_3	4	1	5	0	0	1
\vec{v}_1	1	1	2	1	0	0
\vec{l}_2	0	-3	-1	-3	1	0
\vec{l}_3	0	-3	-3	-4	0	1
\vec{v}_1	1	0	-1/3	0	1/3	0
\vec{v}_2	0	1	2/3	1	-1/3	0
\vec{l}_3	0	0	1	-1	-1	-1
\vec{v}_1	1	0	0	-1/4	1/4	-1/4
\vec{v}_2	0	1	0	19/12	1/4	-1/12
\vec{v}_3	0	0	1	-1/4	-1/4	-1/4

$\underbrace{\begin{matrix} \vec{v}_1 \\ \vec{v}_2 \\ \vec{v}_3 \end{matrix}}_{I_3} \quad \underbrace{\begin{matrix} \vec{l}_1 \\ \vec{l}_2 \\ \vec{l}_3 \end{matrix}}_{A^{-1}}$

c) $A = \begin{pmatrix} 1 & 0 & 5 \\ 6 & 1 & -2 \\ 1 & 1 & 0 \end{pmatrix}$

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{l}_1	\vec{l}_2	\vec{l}_3
\vec{l}_1	1	0	5	1	0	0
\vec{l}_2	6	1	-2	0	1	0
\vec{l}_3	1	1	0	0	0	1
\vec{v}_1	1	0	5	1	0	0
\vec{l}_2	0	1	-32	-6	1	0
\vec{l}_3	0	0	27	-1	0	1
\vec{v}_1	1	0	5	1	0	0
\vec{v}_2	0	1	-32	-6	1	0
\vec{l}_3	0	0	27	5	-1	1
\vec{v}_1	1	0	0	2/27	-5/27	-5/27
\vec{v}_2	0	1	0	-2/27	-5/27	32/27
\vec{v}_3	0	0	1	5/27	-1/27	1/27

$\underbrace{\begin{matrix} \vec{v}_1 \\ \vec{v}_2 \\ \vec{v}_3 \end{matrix}}_{I_3} \quad \underbrace{\begin{matrix} \vec{l}_1 \\ \vec{l}_2 \\ \vec{l}_3 \end{matrix}}_{A^{-1}}$

d) $A = \begin{pmatrix} 1 & 3 & 1 \\ 2 & 6 & 5 \\ 2 & 7 & -1 \end{pmatrix}$

	\vec{v}_1	\vec{v}_2	\vec{v}_3	\vec{l}_1	\vec{l}_2	\vec{l}_3
\vec{l}_1	1	3	1	1	0	0
\vec{l}_2	2	6	5	0	1	0
\vec{l}_3	2	7	-1	0	0	1
\vec{v}_1	1	3	1	1	0	0
\vec{l}_2	0	0	3	-2	1	0
\vec{l}_3	0	1	-3	-2	0	1
\vec{v}_1	1	3	1	1	0	0
\vec{l}_2	0	1	-3	-2	0	1
\vec{l}_3	0	0	3	-2	1	0
\vec{v}_1	1	0	9	7	0	-3
\vec{v}_2	0	1	-3	-2	0	1
\vec{l}_3	0	0	3	-2	1	0

	\vec{l}_1	\vec{l}_2	\vec{l}_3	\vec{l}_1	\vec{l}_2	\vec{l}_3
\vec{v}_1	1	0	0	1/3	-1/3	-1/3
\vec{v}_2	0	1	0	-4	1	1
\vec{v}_3	0	0	1	-2/3	1/3	0

$\underbrace{\begin{matrix} \vec{v}_1 \\ \vec{v}_2 \\ \vec{v}_3 \end{matrix}}_{I_3} \quad \underbrace{\begin{matrix} \vec{l}_1 \\ \vec{l}_2 \\ \vec{l}_3 \end{matrix}}_{A^{-1}}$