

Sensitivity of phytoplankton primary production estimates to available irradiance under heterogeneous sea-ice conditions

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Key Points:

- Phytoplankton primary production under heterogeneous sea ice is highly spatially variable.
- Transmittance sampled with profiling platforms improves the accuracy of primary production estimates.
- Upscaling estimates at larger spatial scales using satellite sea-ice concentration further reduced the error.

Abstract

The Arctic icescape is becoming an increasingly complex mosaic composed of ridges, hummocks, melt ponds, leads and snow. Under such heterogeneous surfaces, drifting phytoplankton communities are experiencing a wide range of irradiance conditions and intensities that cannot be sampled representatively using single-point measurements. Combining experimentally derived photosynthetic parameters with transmittance measurements acquired at spatial scales ranging from hundreds of meters (using a Remotely Operated Vehicle, ROV) to thousands of meters (using a Surface and Under-Ice Trawl, SUIT), we assessed the sensitivity of water-column primary production estimates to multi-scale under-ice light measurements. Daily primary production calculated from transmittance from both the ROV and the SUIT ranged between 0.004 and 939 mgC m⁻² d⁻¹. Upscaling these estimates at larger spatial scales using satellite-derived sea-ice concentration reduced the variability by 22% (0.004-731 mgC m⁻² d⁻¹). The relative error in primary production estimates was two times lower when combining remote sensing and in situ data compared to ROV-based estimates alone. These results suggest that spatially extensive in situ measurements must be combined with large-footprint sea-ice coverage sampling (e.g., remote sensing, aerial imagery) to accurately estimate primary production in ice-covered waters. Also, the results indicated a decreasing error of primary production estimates with increasing sample size and the spatial scale of in situ measurements. Conversely, existing estimates of spatially integrated phytoplankton primary production in ice-covered waters using single-point measurements may be associated with large statistical errors. Considering these implications is important for modelling scenarios and interpretation of existing measurements in a changing Arctic ecosystem.

1 Introduction

The Arctic sea icescape is characterized by a mosaic composed of sea ice, snow, leads, melt ponds and open water. During the last decades, this arctic icescape has been undergoing major changes, including a reduction of sea ice cover and thickness (?), and increased drift speed (?). A greater frequency of storm events is also making this icescape more prone to deformation (?) and promotes lead formation. Because of this surface heterogeneity, light transmittance can be highly variable in space, even over short distances (???). For example, ? showed that ice and snow transmittance at 440 nm could vary by a factor of two over horizontal distances of 25 m. The relative contribution of various sea-ice features to under-ice light variability depends on the spatial scale under consideration and has significant implications for their application in physical and ecological studies and also determines the context in which results can be interpreted. For instance, at small scales (<100 m), local features such as melt ponds and leads have a strong influence on light penetration and fluctuations (???). At larger scales (>100 m), it was argued that the variability of transmittance is mainly controlled by sea ice thickness (?).

Calculation of primary production based on incubations or photosynthetic parameters derived from photosynthesis vs. irradiance curves (P vs. E curves) requires adequately measured or estimated values of irradiance. Because phytoplankton is exposed to a highly variable light regime while drifting under a spatially heterogeneous, and sometimes dynamic sea-ice surface, local irradiance measurements are not representative of the average irradiance experienced by phytoplankton over a large area (??). One major challenge in obtaining adequate irradiance estimates under spatially heterogeneous sea ice is that observations are often limited to time-consuming spot measurements made through boreholes. To overcome this drawback, different underwater technologies have been developed to study the spatial variability of light transmission under spatially heterogeneous sea surfaces.

For the last decade, radiometers have been attached to remotely operated vehicles (ROV). Small sized ROVs can be deployed through small holes (<2 m) to cover areas in the order of a few hundreds of meters (?????). Navigating directly under sea ice, ROVs

allow covering various types of sea ice, such as newly formed, ponded and snow-covered sea ice, as well as pressure ridges (?). More recently, radiometers have been attached to the Surface and Under Ice Trawl (SUIT) net. The SUIT is a trawl developed for sampling meso- and macrofauna in the ice-water interface layer, allowing for greater spatial coverage on the order of a few kilometres (??).

In a recent study, ? showed, that under spatially heterogeneous sea ice and snow surfaces, propagating measured surface downward irradiance just below sea ice $E_d(0^-)$ into the water column using upward attenuation coefficient (K_{L_u}) calculated from radiance profiles is a better choice compared to the traditional downward vertical attenuation coefficient K_{E_d} because it is less influenced by surface heterogeneity. However, while the method allows propagation of irradiance to depth from $E_d(0^-)$ more accurately, estimation of representative $E_d(0^-)$ remains difficult. Both ROV and SUIT aim to better describe the horizontal variability of $E_d(0^-)$ under heterogeneous sea ice. Since these technologies are designed to operate at different scales and in different conditions, they are likely to provide complementary information on the light regime experienced by drifting phytoplankton. In this study, we investigated the spatial variability of light transmittance measured from these two devices and combined them with satellite-derived sea ice concentrations. We further used these transmittance data measured at different horizontal spatial scales to quantify how they influence primary production estimates derived from photosynthetic parameters. The results provide new guidance on how to derive more representative primary production estimates under a heterogeneous and changing icescape.

2 Materials and Methods

2.1 Sampling campaign and study sites

Process studies on biological productivity and ecosystem interactions were carried out north of Spitsbergen during the international Transitions in the Arctic Seasonal Sea Ice Zone (TRANSSIZ) expedition aboard the RV Polarstern (PS92, ARK-XXIX/1) between the 19th of May and the 26th June of 2015. In total, eight process studies (stations 19 27, 31, 32, 39, 43, 46 and 47) were carried out where the ship was anchored to an ice floe, typically for 36 hours (Figure 1, Table 1). While the ship drifted anchored to ice floe on the port side of the ship, winch-operated instruments were deployed in the open water on the starboard side. Water samples for P vs. E curves were collected using a CTD/Rosette. On-ice station work included the deployment of a small observation class ROV under the ice to investigate the small-scale irradiance variability. Prior to arriving or directly after leaving each ice station, the SUIT was deployed for larger scale characterization of the under-ice irradiance field. Due to instrument failure, no SUIT data are available for station 32.

2.2 Sea-ice and snow thicknesses and concentrations

Ground-based multi-frequency electromagnetic induction soundings from a GEM-2 (Geophex Ltd., Raleigh, NC, USA) were used to measure the total thickness of both sea ice and snow following the ROV survey grid. The snow thickness during GEM-2 surveys was measured with a Snow-Hydro Magna Probe instrument (SnowHydro LLC, Fairbanks, Alaska, USA) with a precision of 3 mm (?). The instrument was inserted in the snow approximately every 2 m. The combined GEM-2 and Magna Probe measurements started immediately after the ROV light transmission measurements were finished to ensure that the snow surface was undisturbed. Due to instrument failure of the Magna Probe, no snow measurements were available for stations 46 and 47. Sea-ice thickness was calculated as the difference between total snow and -ice thickness and snow depth. Sea ice concentration (SIC) data were obtained from www.meereisportal.de and processed according to algorithms in ?.

2.3 Underwater light measurements

2.3.1 ROV measurements

ROV observations were taken using similar procedures as presented in ? and ? using a V8 Sii ROV (Ocean Modules, Atvidaberg, Sweden) and RAMSES-ACC-VIS (TriOs GmbH, Rastede, Germany) spectroradiometers mounted both on the ROV and in a fixed location above the sea-ice surface. The ROV was deployed through a hole drilled through the ice at a distance of more than 300 m from the ship. Optical measurements were performed along two perpendicular 100-m transects and in a push-broom pattern over a 100 m by 100 m area. Spectral downward irradiance (E_d , W m^{-2}) between 320 and 950 nm was recorded above and below the surface to calculate spectral light transmittance as the ratio of irradiance transmitted through the snow/ice to incident irradiance. The sensors were triggered in *burst* mode with the sensors acquiring data as fast as possible. To account for ROV movement, all data with ROV roll and pitch angles larger than 10 degrees and with a distance of more than 3 m depth to the ice cover were rejected from further analysis. To account for light attenuation between the ice-water interface and the sensor, an exponential function was used to obtain the transmission at the ice-water interface:

$$T(z_{\text{int}}) = \frac{T(z)}{e^{-K_{E_d}(\text{PAR}) \times -z}} \quad (1)$$

where $T(z_{\text{int}})$ is the transmittance of the ice and snow at the ice-water interface, $T(z)$ the PAR transmittance measured by the ROV at depth z (m) and $K_{E_d}(\text{PAR})$ is the downward diffuse attenuation coefficient of photosynthetically available radiation (PAR; m^{-1}) calculated from $E(\text{PAR})$ vertical profiles (equation 2). At each station, at some point during the survey, the ROV measured a vertical irradiance profile between the surface and at least 20 m depth. Photosynthetically available radiation downwelling irradiance ($E(\text{PAR}, z)$, $\mu\text{mol m}^{-2} \text{s}^{-1}$), was calculated as follow:

$$E(\text{PAR}, z) = \frac{1}{hc} \frac{1}{N} \int_{400}^{700} \lambda E_d(\lambda, z) d\lambda \quad (2)$$

where h is Planck's constant, describing the energy content of quanta ($6.623 \times 10^{-34} \text{ J s}$), c is the constant speed of light ($299\,792\,458 \text{ m s}^{-1}$), N is the Avogadro's number ($6.022 \times 10^{23} \text{ mol}^{-1}$) and $E_d(\lambda, z)$ is the measured irradiance at wavelength λ (nm) at depth z . Conversion from mol to μmol has been done using a factor of 1×10^6 . Note that planar, $E(\text{PAR})$, was converted to scalar irradiance, $\dot{E}(\text{PAR})$, using a conversion factor of 1.2 (?). For each vertical $\dot{E}(\text{PAR})$ profile, $K_{\dot{E}_d}(\text{PAR})$ was calculated by fitting the following equation to the measured irradiance data:

$$\dot{E}(\text{PAR}, z) = \dot{E}(\text{PAR}, z_{\text{int}}) e^{K_{\dot{E}_d}(\text{PAR})z} \quad (3)$$

where $\dot{E}(\text{PAR}, z_{\text{int}})$ is PAR at the ice-water interface and $K_{\dot{E}_d}(\text{PAR})$ is the diffuse vertical attenuation coefficient (m^{-1}) describing the rate at which $\dot{E}(\text{PAR})$ decreases with increasing depth. It is assumed constant for a given station in all our calculations. The determination coefficients (R^2) of the non-linear fits (equation 3) varied between 0.936 and 0.998.

2.3.2 SUIT measurements

On the SUIT, transmittance (T) and sea ice draft observations were made using a mounted environmental sensors array that included a RAMSES-ACC irradiance sensor (Trios, GmbH, Rastede, Germany), a conductivity-temperature-depth probe (CTD; Sea

and Sun Technology, Trappenkamp, Germany), a PA500/6S altimeter (Tritech International Ltd., Aberdeen, UK), and an Aquadopp acoustic doppler current Profiler (ADCP; Nortek AS, Rud, Norway). A complete and detailed description of the full sensor array can be found in ? and ?. Sea ice draft was calculated from the CTD depth and altimeter measurements of the distance to the ice and corrected for sensor attitude using the ADCP's pitch and roll measurements according to ?. Irradiance above the ice was measured with a RAMSES spectroradiometer mounted on the ship's crow's nest. Consistent with the ROV spectral measurements, the transmittance was calculated as the ratio of under-ice irradiance to incoming irradiance. SUIT-mounted downwelling irradiance measurements were acquired every 11 seconds during the haul. To account for SUIT movement, all data with SUIT roll and pitch angles larger than 15 degrees were rejected from further analysis. Note that we did not correct for the light attenuation between the ice-water interface and the sensor because contrary to the ROV, the SUIT frame is equipped with floats that keep it at the surface in open water or in contact with the sea ice.

2.4 Incident in-air $\dot{E}(\text{PAR})$

A CM 11 global radiation pyranometer (Kipp & Zonen, Delft, Netherlands) installed next to the above mentioned RAMSES spectroradiometer in the crowsnest onboard the Polarstern was used for measuring incident solar photosynthetically available radiation, ($\dot{E}(\text{PAR})$, W m^{-2}), at 10 minutes intervals. Conversion from shortwave flux in energy units to $\dot{E}(\text{PAR})$ in quanta ($\mu\text{mol m}^{-2} \text{s}^{-1}$) was achieved using a conversion factor of 4.49 (?). Data were then hourly averaged. Calculated hourly $\dot{E}(\text{PAR}, 0^+)$ were vertically propagated in the water column between 0 and 40 meters with 1-meter increments using the following equation:

$$\begin{aligned}\dot{E}(\text{PAR}, z, t) &= \dot{E}(\text{PAR}, 0^+, t)T(z_{\text{int}})e^{-K_{\dot{E}_d}(\text{PAR})z} \\ &= \dot{E}(\text{PAR}, z_{\text{int}})e^{-K_{\dot{E}_d}(\text{PAR})z}\end{aligned}\quad (4)$$

where $\dot{E}(\text{PAR}, 0^+, t)$ is the incident in-air hourly PAR derived from the pyranometer ($\mu\text{mol m}^{-2} \text{s}^{-1}$), $K_{\dot{E}_d}(\text{PAR})$ is derived from the ROV (see Table 1 and equation 3), z the water depth (m) and $T(z_{\text{int}})$ the snow and sea ice transmittance estimated using either the ROV or the SUIT data.

2.5 Photosynthetic parameters derived from P vs. E curves

To calculate photosynthetic parameters, seawater samples were taken from six depths between 1 and 75 m and incubated at different irradiance levels in presence of ^{14}C -labelled sodium bicarbonate using a method derived from ?. Incubations were carried out in a dimly lit radiation van under the deck to avoid any light stress on the algae. Three replicates of 50 mL samples were inoculated with inorganic ^{14}C ($\text{NaH}^{14}\text{CO}_3$, approximately $2 \mu\text{Ci mL}^{-1}$ final concentration). Exact total activity of added bicarbonate was determined by three 20 μL aliquots of inoculated samples added to 50 μL of an organic base (ethanolamine) and 6 mL of scintillation cocktail (EcoLumeTM, Costa Mesa, US) into glass scintillation vials. One mL aliquots of the inoculated sample were dispensed into twenty-eight 7 mL glass scintillation vials. The samples were cooled to 0°C in thermo-regulated alveoli. Within the array, the vials were exposed to 28 different irradiance levels provided by separate LEDs (LUXEON Rebel, Philips Lumileds, USA) from the bottom of each alveolus. Scalar PAR irradiance was measured in each alveolus prior to the incubation with an irradiance quantum meter (Walz US-SQS + LI-COR LI-250A, USA) equipped with a 4π spherical collector. The incubation lasted for 120 minutes and the incubations were terminated by adding with 50 μL of buffered formalin to each sample. Thereafter, the aliquots were acidified (250 μL of HCl 50%) in a glove box (radioactive $^{14}\text{CO}_2$ was trapped in a NaOH solution before opening the glove box) to remove the excess inorganic carbon (three hours, ?). In the end, 6 mL of scintillation

cocktail was added to each vial prior to counting in a liquid scintillation counter (Tri-Carb, PerkinElmer, Boston, USA). The carbon fixation rate was finally estimated according to ?. Photosynthetic parameters were estimated from P vs. E curves by fitting non-linear models based on the original definition proposed by ? using equation 5 (see below).

2.6 Estimating primary production

Two different approaches were used to calculate primary production from estimated photosynthetic parameters.

Method 1: under-ice only primary production - This first approach relied on using $\hat{E}(\text{PAR})$ propagated in the water column only under the ice using the transmittance values derived from either the ROV or the SUIT, the $K_{E_d}(\text{PAR})$ from the ROV and the hourly incident irradiance from the pyranometer. Primary production was calculated every hour at each sampling depth using $\hat{E}(\text{PAR}, z, t)$ measurements derived from both ROV and SUIT transmittance as follows:

$$P_{\text{underice}}^{\text{device}}(z, t) = P(z)(1 - e^{-\alpha(z, t) \frac{\hat{E}(\text{PAR}, z, t)}{z}}) \times e^{-\beta(z, t) \frac{\hat{E}(\text{PAR}, z, t)}{z}} + P0 \quad (5)$$

where $P_{\text{underice}}^{\text{device}}$ device is primary production ($\text{mgC m}^{-3} \text{h}^{-1}$) calculated using the $\hat{E}(\text{PAR}, z, t)$ from the transmittances measured from a specific device (ROV, $P_{\text{underice}}^{\text{ROV}}$ or SUIT, $P_{\text{underice}}^{\text{SUIT}}$) as in equation 4, P is the photosynthetic rate ($\text{mgC m}^{-3} \text{h}^{-1}$) at light saturation, α is the photosynthetic efficiency at irradiance close zero ($\text{mgC m}^{-3} \text{h}^{-1} (\mu\text{mol photon m}^{-2} \text{s}^{-1})^{-1}$), β is a photoinhibition parameter (same unit as α). The superscript *device* can be either ROV or SUIT. While fits allowed a variable intercept ($P0$), which tended to be positive, we did not use $P0$ in the primary production computations as we assumed that it was due to methodological issues (e.g., light absorbed before incubation started for example). Daily primary production ($\text{mgC m}^{-3} \text{h}^{-1}$) at each depth was calculated by integrating $P_{\text{underice}}^{\text{device}}(z, t)$ over a 24h period. Depth-integrated primary production ($\text{mgC m}^{-2} \text{d}^{-1}$) was then calculated by integrating daily primary production over the water column.

Method 2: average production under ice and adjacent open waters - The second approach consisted of using a mixing model based on sea ice concentration (SIC) derived from satellite imagery to upscale at a larger spatial scale the estimates of primary production derived from the ROV and the SUIT. This approach was motivated by the fact that, even far away from the marginal ice zone, there were often large leads that increased the amount of light available to drifting phytoplankton and may have contributed to under-ice blooms in the vicinity as observed by ?. To account for this additional light source available for phytoplankton, primary production was calculated as follows:

$$P_{\text{mixing}}^{\text{device}} = \text{SIC} \times P_{\text{underice}}^{\text{device}} + (1 - \text{SIC}) \times P_{\text{openwater}} \quad (6)$$

where $P_{\text{mixing}}^{\text{device}}$ is the primary production calculated using the mixing model approach with the transmittance values from a specific device, SIC is the sea ice concentration averaged over an area of $\approx 350 \text{ km}^2$ (the mean of a 9-pixels square with the station within the center pixel). $P_{\text{underice}}^{\text{device}}$ is the primary production calculated under ice using transmittance measurements (equation 5 & method 1 above) and $P_{\text{openwater}}$ the primary production calculated in open water by using a transmittance of 100%. For the mixing-model based SUIT-derived primary production, $P_{\text{mixing}}^{\text{SUIT}}$, transmittance observations higher than 10% were discarded to remove measurements made under very thin ice and in open leads to avoid accounting twice for open water. In the end, four types of primary production were considered (2 devices \times 2 approaches, Table 2).

2.7 Error on primary production estimates

For each of the four scenarios, the average primary production derived from all the transmittance values was viewed as an adequate description of the average primary production produced by drifting phytoplankton cells for a given area. The relative deviation of each individual primary production estimate to the average primary production over all stations was viewed as the error that one would make when sampling at a single point location. This relative error was calculated as follow:

$$\delta_P^{\text{device}} = \frac{|P^{\text{device}} - \bar{P}^{\text{device}}|}{\bar{P}^{\text{device}}} \times 100 \quad (7)$$

where δ_P^{device} is the relative error (%) associated to a specific device (ROV or SUIT), P^{device} the primary production estimate and \bar{P}^{device} the average primary production of the device (both in $\text{mgC m}^{-2} \text{ d}^{-1}$).

2.8 Impacts of the number of in situ spot measurements on primary production estimates

Because of the sea surface heterogeneity in the field, one needs to carefully choose the number of spot measurements in order to obtain representative values of primary production over a given area. Averaging a high number of local measurements is likely to give a better approximation of the average primary production over a given area. However, in the Arctic, it is difficult to sample a high number of uniformly dispersed sampling points due to logistical constraints. Using primary production estimates derived from the ROV and the SUIT, we calculated how the error would decrease on average when increasing the number of measurements uniformly sampled over a given area. To calculate this error, between 1 and 250 values were randomly drawn from the full distribution of primary production values calculated with individual transmittance data from the ROV or SUIT, and used to calculate average primary production. One can view each of these 250 numerical experiments as possible number of spot measurements that one would perform in the field. Each numerical experiment was repeated 100 times to calculate an average and the standard deviation of the absolute difference between a given estimate of primary production and the reference primary production calculated with all transmittance measurements.

2.9 Statistical analysis

All statistical analysis and graphics were carried out with R 3.5.2 (?). The non-linear fitting for the P vs. E curves was done using the Levenberg-Marquardt algorithm implemented in the minpack.lm R package (?).

3 Results

3.1 Characterization of the sea-ice and snow cover

GEM-2 and Magna Probe surveys along and across the ROV transects showed distinct differences in sea ice and snow thickness between the sampled stations. An overview of the total thickness (i.e., combined snow and ice thickness) is presented in Figure 2A. Overall, the mean ice thickness was 1.01 ± 0.52 m (mean \pm s.d.), the mean snow thickness was 0.32 ± 0.16 m and the mean total thickness was 1.33 ± 0.49 m (Figure 2B). Stations 19 and 47 were characterized by an average total thickness over the ROV transect of approximately 1 m, whereas the average total thickness at station 39 was approximately 2 m. For other stations, average total thickness varied around 1.4 m.

3.2 ROV and SUIIT transmittance measurements

A total of 9211 and 817 transmittance measurements distributed over the seven stations were collected from the ROV and SUIIT devices, respectively (Figure 3). Transmittance values ranged between 0.001% and 68% for the ROV and between 0.002% and 92% for the SUIIT (Figure 3). The transmittances measured by the SUIIT were generally higher (mean = 35%) by approximately one order magnitude than those measured with the ROV (mean = 2%). The SUIIT measurements were also covering greater ranges of transmittances compared to the ROV. Histograms showed that transmittance generally followed a bimodal distribution (most of the time occurring within the SUIIT data) with often one overlapping mode between the ROV and SUIIT values (Figure 3).

3.3 Photosynthetically active radiation (PAR)

Incident hourly $\dot{E}(\text{PAR})$, $\dot{E}(\text{PAR}, 0^+, t)$, measured by the pyranometer ranged between 190 and 1400 $\mu\text{mol m}^{-2} \text{s}^{-1}$ (Figure 4). Stations 32 and 39 experienced the highest incident $\dot{E}(\text{PAR}, 0^+, t)$ whereas stations 27 and 43 received the lowest amount of light. Over 24h periods, $\dot{E}(\text{PAR}, z_{\text{int}})$ calculated using SUIIT and ROV transmittances ranged between 0.005-1358 and 0.005-1012 $\mu\text{mol m}^{-2} \text{s}^{-1}$ respectively. Due to relatively high attenuation coefficients (Table 1), $\dot{E}(\text{PAR})$ decreased rapidly with depth and generally reached the asymptotic regime at maximum 30 m depth. The PAR diffuse vertical attenuation coefficients, $K_{E_d}(\text{PAR})$, estimated from the ROV vertical profiles varied between 0.07 and 0.59 m^{-1} (Table 1).

3.4 Estimated primary production

Daily areal primary production derived from photosynthetic parameters and transmittance values ranged between 0.004 and 939 $\text{mgC m}^{-2} \text{d}^{-1}$ for P_{underice} and between 0.004 and 731 $\text{mgC m}^{-2} \text{d}^{-1}$ for P_{mixing} (Figure 5). In ROV-based estimates, daily areal primary productions calculated using the two different approaches (P_{underice} and P_{mixing}) generally showed consistency especially when SIC was high. At stations 19 and 27, greater differences between P_{underice} and P_{mixing} were observed in ROV-based estimates due to lower sea ice concentrations (Table 1) which allowed for a greater weight of $P_{\text{openwater}}$ on the calculations. In SUIIT-based estimates, mean daily P_{underice} values were higher than P_{mixing} values at stations 19, 39 and 43, similar values at stations 27, 46 and 47, and lower values at station 31 (Figure 5). The differences between the two approaches in SUIIT data were related to the varying proportions of thin ice and open water during SUIIT hauls, which were reflected in the P_{underice} estimates. Overall, both ROV- and SUIIT based estimates agreed well with each other when the mixing approach (P_{mixing}) was applied.

3.5 Error on primary production estimates

Figure 6 shows the distributions of the relative errors around the calculated average of areal primary production (see black dots in Figure 5). Overall, the absolute relative errors (δ_P) were distributed over a range covering four orders of magnitude, between 0.1% and 1000% which is corresponding to absolute primary production error varying between 0.0001 and 640 $\text{mgC m}^{-2} \text{d}^{-1}$. The lowest absolute errors (average $\approx 50\%$) were associated with primary production estimates made using the mixing model approach (P_{mixing}). Larger absolute errors were made with P_{underice} derived from only using ROV (mean = 88%) and the SUIIT (mean = 71%) transmittances.

3.6 Impacts of the number of in situ spot measurements on primary production estimates

Figure 7 shows the average relative error that one would make when averaging samples at a number of random locations varying between 1 and 250. For all scenarios, the mean

relative error decreased exponentially with increasing number of chosen observations. The variability around the means also decreased with increasing number of observations (shaded areas in Figure 7). The greatest relative mean error ($\approx 60\text{--}100\%$) occurred when only one primary production estimate was randomly selected from the distributions. The number of randomly selected observations to reach mean relative errors of 10%, 15%, 20% and 25% are presented in Table 3. Overall, about 25% the number of observations were needed to reach those targets when sampling from the distribution for P_{mixing} compared to the distribution of P_{underice} . Additionally, the number of observations required when using the SUIT transmittance to derive primary production estimation was also about 25% of the number of corresponding ROV-based measurements to reach the same error threshold.

4 Discussion

4.1 Multi-scale spatial variability of light transmittance

In the context of obtaining meaningful measurements of transmittance to accurately estimate $\dot{E}(\text{PAR}, 0^-)$, the challenge is to define the spatial extent at which light should be sampled. Based on a spatial autocorrelation analysis conducted in the central Arctic ocean, it was determined that transmittance values were uncorrelated (i.e., randomly spatially distributed) to each other after a horizontal lag distance of 65 m (?). This range is likely to be much smaller than the distance covered by drifting phytoplankton over a 24h period. Indeed, water currents around Svalbard have been found to vary between 0.14 and 0.21 m s⁻¹ (?). These speeds are on the same order of magnitude as the sea ice drift speeds of 0.10 m s⁻¹ observed during the expedition. Assuming passive transport, this corresponds to a displacement varying between 8 and 18 km over a 24h period which is much greater than the 65 m distance at which transmittance was found to be randomly spatially distributed. Under such a large area, drifting phytoplankton is experiencing a wide range of irradiance conditions that can be hardly characterized by single-spot measurements or even with ROV and SUIT devices sampling over larger distances. In such context, measured transmittances should be upscaled at the spatial scale that is meaningful for the studied process. An easily applicable approach to upscale in-situ transmittance measurements consists of using sea ice concentration (SIC) derived from satellite imagery. A simple mixing model (equation 6), combining both in-situ transmittance measurements and SIC, can be used to upscale observations acquired locally to larger scales. Our results showed that using this approach reduced the relative error by approximately a factor of two when spatially integrating devices such as ROVs or SUIT are used to measure transmittance (Figure 5). Furthermore, this error was lower when using in-situ measurements acquired on a larger spatial scale using the SUIT. This strengthens the idea that one needs to characterize the light field over an area as large as reasonably possible so the full irradiance variability is captured.

Our study confirms earlier suggestions that estimating primary production from photosynthetic parameters and transmittance measured at a single location does not provide a representative description of the spatial variability of the primary production occurring under a heterogeneous sea surface (Figure 6, Figure 7). Depending on the scale at which transmittance was measured, it was found that deriving primary production from photosynthetic parameters using under-ice profile measurements alone would produce on average relative errors varying between 47% and 88% (Figure 6). In contrast, much lower errors (25%) were made when primary production estimates were upscaled using satellite-derived SIC (P_{mixing}). For stations with lower SIC (stations 19, 27, 31 and 39), primary production estimates were more constrained around the average (Figure 4) because $P_{\text{openwater}}$ had a greater weight in the calculation of P_{mixing} (see equation 5). For stations 43, 46 and 47 where SIC was 100%, the spread around the mean was higher because only P_{underice} was contributing to the calculation of P_{mixing} . These results suggest that using a distribution of measured transmittances allows calculating a more representative transmittance average for a given area, but also provides additional knowledge on its spatial variability.

Although our results indicate that it is necessary to properly characterize the light field under the heterogeneous sea surface, the physiological state of the phytoplankton community also plays a major role on the sensitivity of the estimates to incoming irradiance. An important parameter of the physiological state of the phytoplankton community is the light-saturated photosynthesis regime, E_k an index of photoadaptation. When the phytoplankton community is adapted to low light intensity (e.g., ?), it is likely that variations in the surface light field have reduced impacts on the estimates because phytoplankton primary production is already near saturation. The degree of photoadaptation of the phytoplankton communities and their ability to adjust rapidly to a variable light field still remains to be evaluated.

4.2 Influence of the number of sampling locations on primary production estimation

It was pointed out by ? that it is difficult to characterize light conditions under sea ice over large areas and to quantify spatial variability on different scales due to important requirements in logistical and instrumental efforts. As with any missions in remote environments such as the Arctic, careful planning is needed to find the right balance between the sampling effort and the right amount of acquired information to study a particular phenomenon. Our results suggested that errors made by estimating primary production using photosynthetic parameters decreased exponentially with increasing number of transmittance measurements (Figure 7). Depending on the extent of the spatial scale at which transmittance is measured (order of meters for the ROV, order of kilometres for the SUIT) and the targeted error thresholds (10%, 15%, 20% or 25%), a number of measurements varying between four and 359 were sufficient to reasonably capture the spatial variability of sea ice transmittance to derive average primary production estimates over a given area. This shows, that local primary production estimated from just a single or even a handful of light observations has limited value.

4.3 Implications for Arctic primary production estimates

It is known that the annual primary production in the ice-covered Arctic is among the lowest of all oceans worldwide because both light and limited nutrient availability are the main limiting factors for phytoplankton growth under the ice. In a changing Arctic icescape, efforts have been devoted to better understand how phytoplankton primary productivity is responding to increasing light availability. Many studies have been conducted in the vicinity of an ice edge to characterize primary production occurring under the ice sheet (???). However, in such studies, due to logistical constraints, the underwater light field was often characterized by a limited number of light measurements. Other approaches, based on 24h ship-board incubations performed under incident light, have provided local estimates that were simply scaled to an assessment of percent ice-cover in the vicinity of the ship (???). Therefore, depending on whether light is measured under bare ice or in open water, the estimated primary production is either under- or overestimated. Different approaches based on remote sensing techniques and modelling have been used to reduce the high uncertainties associated with estimates derived from local in-situ measurements. However, in an ecosystem model intercomparison study, ? showed that under-ice primary production was very sensitive to the light availability computed by atmospheric and sea ice models, reinforcing the need to develop new integrative strategies to adequately characterize the light field at large scale under heterogeneous sea surfaces. Our results showed that upscaling primary production estimates derived from fine-scale local measurements using SIC derived from satellite imagery allowed reducing the error at larger spatial scales. Furthermore, it was found that even when SIC was high (>95%), the use of a mixing-model approach helped to obtain better estimates (Figure 5).

5 Conclusions

Advances in underwater technologies made it easier to characterize surface transmittance over large areas. Our results showed that combining photosynthetic parameters measured in laboratory experiments with spatially representative transmittance values sampled with under-ice profiling platforms can significantly improve the accuracy of primary production estimates under heterogeneous sea surfaces. A good way forward to sample the under-ice light field on a large enough scale without the inherent biases of the ROV and SUIT deployment techniques would be the use of long-range autonomous underwater vehicles. Furthermore, upscaling in-situ measurements at larger scales using remote sensing data becomes necessary when the spatial scale of the studied process (e.g., a phytoplankton bloom) is greater than that which is realistically possible to measure in the field. This emphasizes the need for spatially integrated observation approaches to characterize the light field in ice-covered regions in order to provide more representative primary production estimates.

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- ROV data (<https://doi.pangaea.de/10.1594/PANGAEA.861048>)
- Incident radiation (<https://doi.pangaea.de/10.1594/PANGAEA.849663>)
- Station list (<https://doi.pangaea.de/10.1594/PANGAEA.848841>),
- SUIT data (submitted to Pangaea)
- Photosynthetic parameters (submitted to Pangaea)
- Sea-ice/snow thickness (submitted to Pangaea)