POLS/CS&SS 503: Advanced Quantitative Political Methodology

LINEAR REGRESSION ESTIMATOR

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Jeffrey B. Arnold







Overview

Regression Coefficient Anatomy

Linear Regression Population Model

Sampling Distribution

Estimators and mean squared error

Gauss-Markov Theorem

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Coeficients of a simple regression

$$Y_i = A + BX_i + E_i$$

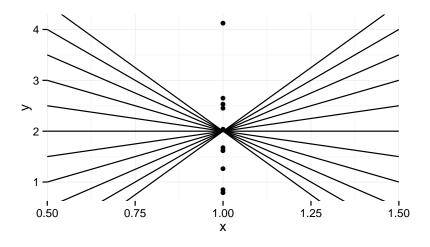
The least squares coefficients are

$$A = \bar{Y} + B\bar{X}$$

$$B = \frac{\sum_{i} (X_i - \bar{X})(Y_i - \bar{Y})}{\sum_{i} (X_i - \bar{X})^2}$$

- State B in terms of covariance of X and Y and variance?
- State B in terms of correlation of X and Y and standard deviations?
- What values can B take if SD(X) = SD(Y) = 1?
- What is \hat{Y} for $X = \bar{X}$?
- What happens to B as V(X) decreases? V(Y) decreases? If V(X) = 0

Least squares when VX = 0



Least squares coefficients are unidentified if V x = 0

- If Vx = 0 then least squares solution is unidentified
- There is no unique value of A, B that $\arg\min_{A,B} \sum_i E_i^2$

```
y \leftarrow c(1, 2, 3, 4, 5)
x <- 1
ybar <- mean(y)</pre>
ybar
## [1] 3
\# A = 2, B = 1
sum((y - 2 - 1 * x) ^ 2)
## [1] 10
\# A = -7, B = 10
sum((v + 7 - 10 * x) ^ 2)
## [1] 10
```

Coefficients of a multiple regression

$$\vec{Y} = Xb + e$$

- $b = (X'X)^{-1}X'y$. Not that intuitive!
- Coefficient b_i is

$$b_k = \frac{\mathsf{C}(y, \tilde{x}_j)}{\mathsf{V}(\tilde{x}_k)}$$

• Where \tilde{x}_j are the residulals of x_j on all X_h where $h \neq j$

$$\tilde{X}_{j,i} = X_{j,i} - \tilde{A} - \sum_{h \neq i} \tilde{B}_h X_h$$

Regression example

See $multiple_regression_anatomy.R$

Least Squares coefficients are unidentified if $(X'X)^{-1}$ does not exist

- Common cases in which $(X'X)^{-1}$ does not exist:
 - Number of observations less than k+1
 - X_k is constant
 - X_k is a linear function of other variables: $X_k = \sum_{i \neq k} c_j X_j$.
 - dummy variables for all categories of a categorical variable
 - variable multiplied by the constant of another variable

Which of these would be cases of collinearity and why?

- There is a variable that takes values "white", "black", "hispanic", "asian", "other". You include a dummy variable for each category.
- · GDP, GDP per capita, and population
- Log GDP, log GDP per capita, and log population
- GDP in millions of dollars: GDP in trillions of dollars
- · GDP measured in nominal value; GDP measured in real terms
- · Regression with 3 variables and 4 observations

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Population model in a simple regression

$$Y_i = \alpha + \beta X_i + \epsilon_i$$

Assumptions for statistical inference

- 1. *X* is not invariant: V(X) > 0
- 2. *Linearity*. Average value of error given x is 0. $E(\epsilon_i) = E(\epsilon_i|x_i) = 0$

$$\mu_i = E(Y_i) = E(Y|X_i) = E(\alpha + \beta X_i + \epsilon_i) = \alpha + \beta x_i$$

3. Constant variance Variance of the errors is the same regardless of the value of \boldsymbol{X}

$$V(Y|x_i) = E(\epsilon_i^2) = \sigma_\epsilon^2$$

- 4. *Independence:* Observations are sampled independently. $Cor(\epsilon_i, \epsilon_j) = 0$ for all $i \neq j$.
- 5. Fixed X or X measured without error and independent of the error.
- 6. Errors are normally distributed $\epsilon_{i} \sim N\left(0,\sigma_{\epsilon}^{2}\right)$

Population model in a multiple regression

$$Y_i = \alpha + \beta_1 x_{i,1} + \beta_2 x_{i,2} + \dots + \beta_k x_{i,k} + \epsilon_i$$

Assumptions for statistical inference

- 1. X is not invariant and no X is a perfect linear function of the others.
- 2. Linearity. $E(\epsilon_i) = 0$
- 3. Constant variance $V(\epsilon_i) = \sigma_{\epsilon}^2$
- 4. Independence Observations are sampled independently. $Cor(\epsilon_i, \epsilon_j) = 0$ for all $i \neq j$.
- 5. Fixed X or X measured without error and independent of the error
- 6. Normality Errors are normally distributed $\epsilon_i \sim N\left(0,\sigma_\epsilon^2\right)$

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Definitions

population The observations of interest. May be theoretical sample The data you have.

parameter A function of the population distribution statistic A function of the sample sampling distribution The distribution of a statistic calculated from the distribution of samples of a given size drawn from a population.

See Sampling_Distributions.Rmd

Sampling Distribution of Simple Regression Coefficients

The sampling distributions of A, B given $Y_i = \alpha + \beta X_i + \epsilon_i$

expected values (linearity)

$$E(A) = \alpha$$
$$E(B) = \beta$$

variances (linearity, constant variance, independence)

$$V(A) = \frac{\sigma_{\epsilon}^{2}}{n} \cdot \frac{\sum x_{i}^{2}}{\sum (x_{i} - \bar{x})^{2}}$$

$$V(B) = \frac{\sigma_{\epsilon}^{2}}{\sum (x_{i} - \bar{x})^{2}} = \frac{\sigma_{\epsilon}^{2}}{n V(x)}$$

normal distribution (normal errors)

$$A \sim N(E(A), V(A))$$

 $B \sim N(E(B), V(B))$

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Coefficient sampling distributions in multiple regression

The sampling distributions of B_k given $Y_i = \alpha + \sum \beta_i X_{i,i} + \epsilon_i$

- Expected value: $E(B_K) = \beta_k$
- · Variance:

$$V(B_j) = \frac{1}{(1 - R_j^2)} \frac{\sigma_\epsilon^2}{\sum (x_{i,j} - \bar{x}_j)^2}$$
$$= \frac{\sigma_\epsilon^2}{\sum_i (x_{i,j} - \hat{x}_{i,j})^2}$$

Where R_j^2 is R^2 from regression of X_j on other X, and \hat{x}_{ij} are fitted values from that regression.

- Normally distributed if errors are normally distributed or as $n \to \infty$.
- b is multivariate normally distributed

$$b \sim N\left(\beta, \sigma_{\epsilon}^2(X'X)^{-1}\right)$$

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Let's define some things

```
statistic Function of a sample, e.g. Sample mean \bar{x} = \frac{1}{n} \sum x_i parameter Function of the population distribution, e.g. Expected value \mu of the normal distribution.
```

population parameter (estimand)

How to determine if an estimator is good?

- Is $\hat{\beta} = (X'X)^{-1}X'y$ a good estimator for β ?
- Would another estimator be better?
- First, need criteria to by which to judge estimators

What makes an estimator good?

- Bias
- Variance
- Efficiency (mean squared error)
- Consistency

Bias and Variance

Bias

On average how far off is the estimator?

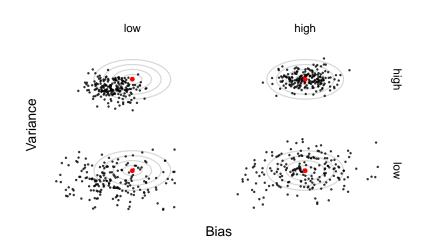
$$\mathsf{bias}(\hat{\beta}) = \mathsf{E}(\hat{\beta}) - \beta$$

Variance

Does the estimator give similar results in different samples?

$$V(\hat{\beta}) = E((\beta - E(\hat{\beta}))^2)$$

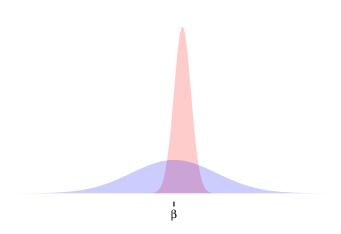
Bias and Variance Visualized



What makes an estimator good?

- Unbiased methods may still miss the truth by a large amount, just direction not systematic
- Unbiased estimates can be horrible: random draw from numbers 0-24 for time of day
- Biased estimates are not necessarily terrible: a clock that's 2 minutes fast

You may prefer a biased, low variance estimator to an unbiased, high variance estimator



Mean Squared Error (MSE)

MSE is

$$MSE(\hat{\beta}) = E((\hat{\beta} - \beta)^2)$$

MSE trades off bias and variance

$$MSE(\hat{\beta}) = E((\hat{\beta} - E(\hat{\beta}))^2) + E(E(\hat{\beta}) - \beta))^2$$
$$= V(\hat{\beta}) + (bias(\hat{\beta}, \beta))^2$$

- root mean squared error (RMSE) √MSE: on average how far is an estimate from the truth
- An efficient estimator has the smallest MSE
- What is the MSE of an unbiased estimator?

$$MSE(\hat{\beta}) = V(\hat{\beta}) + \left(bias(\hat{\beta}, \beta)\right)^2 = V(\hat{\beta}) + 0 = V(\hat{\beta})$$

MSE Example

- Suppose population parameter $\beta = 1$
- Consider two estimators $\hat{\beta}_1$ and $\hat{\beta}_2$.
 - $\hat{\beta}_1 \sim N(1, 1^2)$
 - $\hat{\beta}_2 \sim N(0.5, 0.5^2)$
- What are the bias, variance, and MSE of each estimator?

Consistency

 A consistent estimator converges to the parameter value as the number of observations grows

$$E(\hat{\beta} - \beta) \to 0$$
 as $n \to \infty$

- A concern of econometricians
- May not be as much a concern in finite, small sample sizes
- We will mainly be concerned with efficiency, secondarily with bias, rarely with consistency

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LS assumptions and consequences of violations

	Assumption		Consequence of violation
1	No perfect collinearity	$\operatorname{rank}(X) = k, k < n$	Coefficients unidentified
2	X is exogenous	$E(X\epsilon) = 0$	Biased, even as $n \to \infty$
3	Disturbances have mean 0	$E(\epsilon) = 0$	Biased, even as $n \to \infty$
4	No serial correlation	$E(\epsilon_i \epsilon_j) = 0, i \neq j$	Unbiased but ineff. Wrong se.
5	Homoskedastic errors	$E(\epsilon'\epsilon') = \sigma^2 I$	Unbiased but ineff. Wrong se.
_6	Normal errors	$\epsilon \sim N(0, \sigma^2)$	se wrong unless $n \to \infty$

Assumptions stronger from top to bottom, 4 and 5 could be combined

Unbiasedness of LS

- Only need assumptions 1-3 (no collinearity, X exogenous, $E(\epsilon) = 0$
- · Start with

$$\hat{\beta} = (X'X)^{-1}X'(X\beta + \epsilon)$$
$$= \beta + (X'X)^{-1}X'\epsilon$$

· Take the expectation

$$E(\hat{\beta}) = E(\beta) + E(X'X)^{-1}X'\epsilon)$$

$$= E(\beta) + X'X)^{-1}X' E(\epsilon)$$

$$= E(\beta)$$

• Since $E(\hat{\beta}) = E(\beta)$, LS is unbiased.

Gauss-Markov

- If make assumptions 1–5: LS is the best linear unbiased estimator (BLUE)
- LS estimator is **linear** because $\hat{\beta} = My$, where $M = (X'X)^{-1}X'$
- best is best mean squared error (MSE).
- If LS is unbiased, then its mean squared error is the same as its ...?
- Could exist other non-linear unbiased estimators with smaller MSE,
 e.g. Robust regression when population has fat tailed errors
- If errors are Gaussian, LS is Minimum Variance Unbiased (MVU).
- MVU = for *all* estimators that are unbiased. $\hat{\beta}$ has smallest variance (and MSE).

References

- Some slides derived from Christopher Adolph Linear Regression in Matrix Form / Propoerties & Assumptions of Linear Regression. Used with permission.
 - http://faculty.washington.edu/cadolph/503/topic3.pw.pdf
- Material included from
 - Fox Ch 6, 9.3
 - Angrist and Pischke, Chapter 3

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