

Lecture Notes

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Chapter 1

Lecture 2

SHIVEN SINHA

1.0.1 Abstract Reduction System

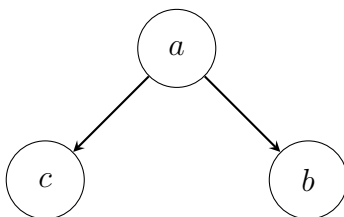
An abstract reduction system is a binary relation \rightarrow over a set of elements A .

1.0.2 Other Relations defined on \vec{A}

Identity	$\vec{A}^0 = \{(a, a) : a \in A\}$
Reflexive Closure	$\vec{A}^\geq = \vec{A} \cup \vec{A}^0$
Inverse	$\vec{A}^{-1} = \{(b, a) : a \xrightarrow{A} b\}$
Transitive Closure	$\vec{A}^+ = \bigcup_{i > 0} \vec{A}^i$
Reflexive Transitive Closure	$\vec{A}^* = \vec{A}^+ \cup \vec{A}^0$
Symmetric closure	$\vec{A}^{\leftrightarrow} = \vec{A} \cup \vec{A}^{-1}$

Note: Pay attention to the order of terms in the name of the relations. For example, the transitive symmetric closure isn't necessarily the same as

the symmetric transitive closure. Consider the following relation graph to demonstrate this.



$$(A^{\leftrightarrow})^* = \{(a, a), (a, b), (a, c), (b, a), (b, b), (b, c), (c, a), (c, b), (c, c)\}$$

$$(A^*)^{\leftrightarrow} = \{(a, b), (a, c), (b, a), (c, a)\}$$

1.0.3 Terminology

Describing the elements and their relations

- x is reducible if $\exists x'$ such that $x \xrightarrow{A} x'$.
- $\theta : F \rightarrow E$ is called an **invariant** if $\forall x \in A, \theta(x) = \theta(F(x))$. For example, for the run $x_0 \xrightarrow{F} x_1 \xrightarrow{F} x_2 \xrightarrow{F} \dots$, it must hold that $\theta(x_0) = \theta(x_1) = \theta(x_2) = \dots$.
- x is in **normal form** if it is not reducible.
- x **simplifies to** x' in A iff $x \xrightarrow{A^*} x'$.
- x' is a normal form of x in A if:
 - x' is in normal form
 - x simplifies to x'
- x has a normal form in A if $\exists x' \in A$ such that x' is a normal form of x .
- x' is an **immediate successor** of x if $x \xrightarrow{A} x'$.
- x' is a **proper successor** of x if $x \xrightarrow{A^+} x'$.
- x' is a **successor** of x if $x \xrightarrow{A^*} x'$.
- Two elements a and b in A are **joinable** if $\exists c \in A$ such that $a \xrightarrow{A^*} c$ and $b \xrightarrow{A^*} c$. This is denoted as $a \downarrow b$.
- a and b are **connected** in A if $a \xrightarrow{(A \leftrightarrow)^*} b$.

Describing the system as a whole

- \vec{A} is terminating if there is no infinite run: $a_0 \rightarrow a_1 \rightarrow \dots$.

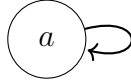


Figure 1.1: A non-terminating relation graph

- \vec{A} is normalising if every element has a normal form.

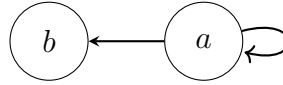


Figure 1.2: A normalising, non-terminating relation graph

- \vec{A} is confluent if $\forall a, b, c \in A$ such that $a \xrightarrow{A^*} b, a \xrightarrow{A^*} c$, it must hold that $b \downarrow c$.

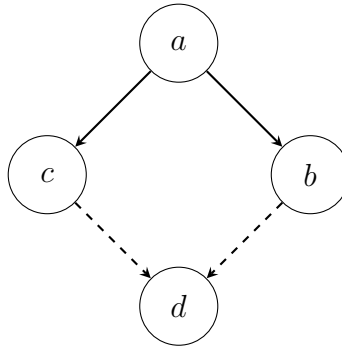


Figure 1.3: A visual representation of confluence

Chapter 2

Lecture 3

DHEERAJA RAJREDDYGARI

2.0.1 Properties of abstract reduction systems

In this lecture, we explore some properties of abstract reduction systems and look at the relationships between them.

Definition 2.0.1. An abstract reduction system (A, \rightarrow_A) is said to be **Church-Rosser** if

$$\forall x, y \in A, \quad x \xleftrightarrow[A]{*} y \implies x \downarrow_A y$$

Consider abstract reduction systems A and B as shown in the figure below. System A is not Church-Rosser, since $a \xleftrightarrow[A]{*} b$ but a and b are not joinable. System B is a simple example of a Church-Rosser system.

Definition 2.0.2. An abstract reduction system (A, \rightarrow_A) is said to be **Confluent** if

$$\forall a, b, c \in A, \quad a \xrightarrow[A]{*} b \text{ and } a \xrightarrow[A]{*} c \implies b \downarrow_A c$$

Definition 2.0.3. An abstract reduction system (A, \rightarrow_A) is said to be **Semi-confluent** if

$$\forall a, b, c \in A, \quad a \rightarrow_A b \text{ and } a \xrightarrow[A]{*} c \implies b \downarrow_A c$$

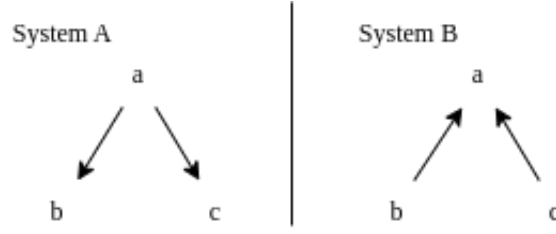


Figure 2.1: Examples of abstract reduction systems

Theorem 2.0.4. For an abstract reduction system, **Church-Rosser, Confluence and Semi-confluence are equivalent.**

Proof: We will prove this theorem in the following three stages. Clearly, the three of them combined result in the theorem stated above.

1. Church-Rosser \implies Confluence
2. Confluence \implies Semi-confluence
3. Semi-confluence \implies Church-Rosser

First, we will prove that **if a system is Church-Rosser, it is confluent.**

Let (A, \rightarrow_A) be an abstract reduction system that is Church-Rosser.

Let $a, b, c \in A : a \xrightarrow{*}_A b$ and $a \xrightarrow{*}_A c$

By definition, $b \xleftrightarrow{*}_A c$

Since A is Church-Rosser, $b \xleftrightarrow{*}_A c \implies b \downarrow_A c$

i.e. $a \xrightarrow{*}_A b$ and $a \xrightarrow{*}_A c \implies b \downarrow_A c$, proving that A is confluent

Next, we will prove that **if a system is Confluent, it is also semi-confluent.** Let (A, \rightarrow_A) be a confluent abstract reduction system.

Let $a, b, c \in A : a \rightarrow_A b$ and $a \xrightarrow{*}_A c$

Since $A \subseteq A^*$, $a \rightarrow_A b \implies a \xrightarrow{*}_A b$

Since A is confluent, $a \xrightarrow{*}_A b$ and $a \xrightarrow{*}_A c \implies b \downarrow_A c$

i.e. $a \rightarrow_A b$ and $a \xrightarrow{*}_A c \implies b \downarrow_A c$, proving that A is semi-confluent

Finally, we will prove that **if a system is semi-confluent, it is also**

Church-Rosser. Let (A, \xrightarrow{A}) be a semi-confluent abstract reduction system.

Let $a, b \in A : a \xleftrightarrow[A]{*} b$

Let p be the shortest path connecting a and b in $A^{\leftrightarrow*}$. We will use induction on $|p|$ to prove that a and b are joinable.

Base case: For $p = 0$, we have $a = b$ which makes them trivially joinable.

Induction step: Let it be true that if the shortest path connecting a and b in $A^{\leftrightarrow*}$ is $|p|$, then a and b are joinable in A . We will prove that this is also true for $|p| + 1$.

Let $a, b' \in A$ such that the shortest path connecting them in $A^{\leftrightarrow*}$ is of length $|p| + 1$. Then, $\exists b \in A$: the shortest path connecting a and b in $A^{\leftrightarrow*}$ is $|p|$ and $b \xleftrightarrow[A]{*} b'$. Since our induction hypothesis holds true for $|p|$, a and b are joinable (they both reduce to some $c \in A$).

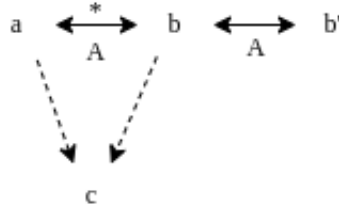


Figure 2.2: Abstract reduction system representing the induction step

We now have 2 cases.

Case 1: $b \xleftrightarrow[A]{*} b'$

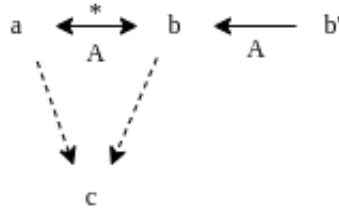


Figure 2.3: Abstract reduction system in case 1

$b' \xrightarrow{A} b \xrightarrow{A} c$. Therefore, $a \downarrow_A b'$.

Case 2: $b \xrightarrow[A]{*} b'$

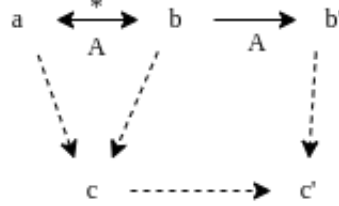


Figure 2.4: Abstract reduction system in case 2

Here we have $b \xrightarrow[A]{*} b'$ and $b \xrightarrow[A]{*} c$. Since A is semi-confluent, b' and c must be joinable. That is, $\exists c' \in A : b' \xrightarrow[A]{*} c'$ and $c \xrightarrow[A]{*} c'$. Since $a \xrightarrow[A]{*} c \xrightarrow[A]{*} c'$, we have $a \xrightarrow[A]{*} c'$. Hence, $a \downarrow_A b'$

In either case, we have shown that $a \downarrow_A b'$, which completes our induction. We have proven that $a \xrightarrow[A]{*} b \implies a \downarrow_A b$, which means A is also Church-Rosser.

This completes our proof that Church-Rosser, Confluence and Semi-confluence are equivalent properties of an abstract reduction system. While it may seem redundant to have multiple terms to refer to the same thing, they each give us a different perspective of looking at the same property which can prove to be helpful.

2.0.2 Address space

Data structures provide a way to organize and address data. For a data structure, a valid set of addresses form its address space. This is **not** a formal definition of address spaces and is only meant to give a broad idea. We will look at an example below to illustrate one way of addressing a binary tree. Let us consider the following addressing of a binary tree: each edge is labelled 1 or 2 depending on whether it leads to the left or right descendant of a node; the address of each node is obtained by appending the label of the edge leading into it to the address of its parent, with the root being ϵ . Look at the figure below to better understand this.

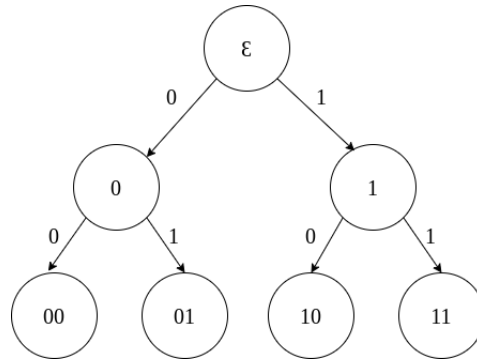


Figure 2.5: Addressing a binary tree

The address space for this binary tree would be the set $S = \{\epsilon, 0, 00, 01, 1, 10, 11\}$. The set $S_1 = \{\epsilon, 0, 00, 01, 1\}$ would also be a valid address space for some binary tree but the set $S_2 = \{0, 00, 1\}$ would not, since it does not contain ϵ , the address of the root.

Chapter 3

Lecture 4

KRITI GUPTA

3.0.1 N-Arity

$$\bar{Z}_n = [1...n]$$

An n-ary address space A is a subset of \bar{Z}_n^* that is prefix closed if $q : A$ and p is a prefix of q , then $p : A$.

Example:

$$A = \epsilon, 1, 2, 11, 21$$

Let A be an n-ary address space and let $p : A$.

$$A@p = \{q : \bar{Z}_n^* \mid pq : A\} \rightarrow \text{Address space of } A \text{ relative to } p \quad (3.1)$$

$$\text{e.g. } A@2 = \{\epsilon, 1\}$$

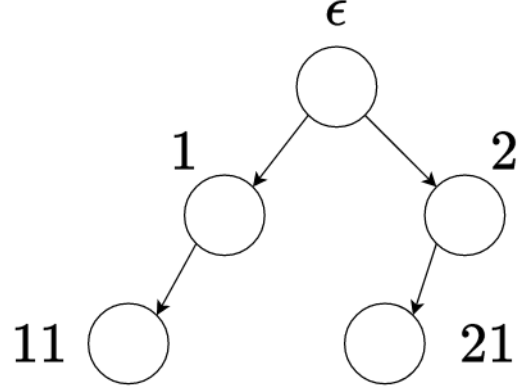


Figure 3.1:

Context at p (excluding p)

$$C_{ex}(A, p) = A \setminus pA @ p \quad (3.2)$$

$$\rightarrow \text{concatenating } p \text{ with each address (in subtree) relative to } p \quad (3.3)$$

Context at p (including p)

$$C_{in}(A, p) = C_{ex}(A, p) \cup \{p\} \quad (3.4)$$

3.0.2 Terms, Subtrees, Tree Context

Let A be an address space. A term is a map $t : A \rightarrow v$ where V is a set of values.

Example:

$$V = \mathcal{N}, A = \{\epsilon, 1, 2\} \quad (3.5)$$

$$t : \{\epsilon \rightarrow 5, 1 \rightarrow 7, 2 \rightarrow 7\} \quad (3.6)$$

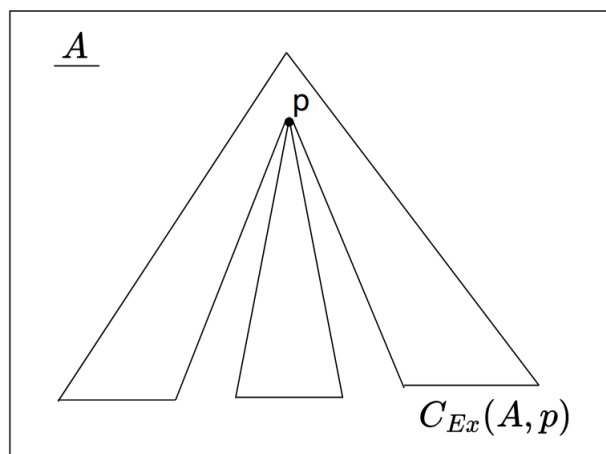


Figure 3.2:

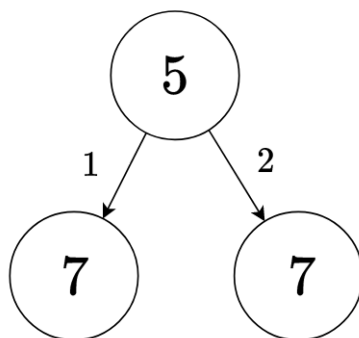


Figure 3.3:

Let $t : A \xrightarrow{v}$ be a tree and let $p : A$

$$C_{ex}(t, p) = df = t|_{C_{ex}(A, p)} \quad (3.7)$$

Let Σ_s be a set of symbols.

Let $\alpha : \Sigma_s \xrightarrow{\mathcal{N}}$ denote the arity map of Σ_s .

Example,

$$\Sigma_s = \{f, a, b\} \alpha_s : \{f \rightarrow 2, a \rightarrow 0, b \rightarrow 0\} \quad (3.8)$$

$$\implies f(a, b) \checkmark \quad a \checkmark \quad b \checkmark \quad f(a) \times \quad (3.9)$$

A term is $(A, \Sigma_s, \alpha, t : A \rightarrow \Sigma_s)$

s.t.

1. A is a prefix-closed language over \mathcal{N}_+
2. $\forall p : A$, if $t_p = S$ and $\alpha(S) = n$
then $p1, \dots, p\alpha(S) : A \quad \forall i : 1 \leq i \leq \alpha(S), pi : A, \forall i : \mathcal{N}_+ \setminus [1, \dots, \alpha(S)] pi \notin A$

Chapter 4

Lecture 5

BHARAT SAHLOT

4.0.1 Terms

ARS Abstract Reduction System

Terminating ARS An ARS is terminating *iff.* it has no infinite runs.

4.0.2 Well Founded Induction(WFI)

This is property of an abstract reduction system. A system having this property implies that,

$$\forall x \in A. \left(\forall y \in A. x \xrightarrow{+} y \implies P(y) \right) \implies P(x)$$

in other words, $P(x)$ is satisfied if $\forall y. x \xrightarrow{+} y \implies P(y)$ is satisfied.

Theorem 4.0.1. Let, (A, \longrightarrow) be an ARS, then A satisfies WFI iff. (A, \longrightarrow) is terminating.

Proof.

1. If \longrightarrow terminates, then A satisfies WFI.

Proof by contraposition. Assume that WFI does not hold. That implies that $\neg P(a_0)$ for some $a_0 \in A$. Since we assumed that WFI does not hold, $\exists a_1$, such that, $a_0 \xrightarrow{+} a_1$ and $\neg P(a_1)$. Using the same argument, $\exists a_2$, such that, $a_1 \xrightarrow{+} a_2$ and $\neg P(a_2)$. Hence there is an infinite chain $a_0 \xrightarrow{+} a_1 \xrightarrow{+} a_2 \xrightarrow{+} \dots$, i.e. \longrightarrow does not terminate.

2. If A satisfies WFI, then \longrightarrow terminates.

Proof by WFI. Let,

$$P(x) := \text{there is no infinite chain starting from } x.$$

Clearly, if there is no infinite chain starting from any successor of x , then there is no infinite chain starting from x . Hence, WFI holds and we can conclude that $P(x)$ holds for all x , i.e., \longrightarrow terminates. \square

4.0.3 Confluence

Order of evaluation does not matter.

Joinable x and y are joinable, denoted by \downarrow iff. they have the same normal form.

Local Confluence An element $x \in A$ is said to be locally confluent if $\forall y, z \in A, z \xleftarrow{+} x \xrightarrow{+} y \exists w : y \xrightarrow{*} w \xleftarrow{*} z$, in other words, $y \downarrow z$.

\rightarrow If a system is terminating and has local confluence for all vertices, then the system has **confluence**.

4.0.4 Interactive Evaluation

TODO

Chapter 5

Lecture 9

PRANAV SUBRAMANIAM

5.1 Overview of Programming Languages

5.1.1 Mathematical Foundation

1. Before lambda-calculus ("Pre-history" of computing)
 - (a) Set Theory
 - (a) First-Order Logic
 - (a) Combinatory Logic
2. Predecessor to Programming Languages
Provided mathematical framework for programming languages and computing
 - (a) Category Theory
 - (b) λ Calculus \equiv Turing Machines (1930s)
 - i. λ Calculus
 - A. Framework for programming language design
 - B. Basis for functional programming

ii. Turing Machines

A. Computability, complexity, determinism

B. Related work- Von Neumann architecture, Kurt Gödel's incompleteness theorem

5.1.2 History

S No.	Functional Languages	Imperative Languages	OOP	PROLOG (Logic Programming)	Concurrent Distributed Programming Languages
1	Lisp (1959)	FORTTRAN (1957)	Simula-Simulation-oriented, (Dahl and Nygaard - 1996)	Prolog (Colmerauer, 1971)	CSP (Communicating Sequential Processes), (Hoare, 1978)
2	Landin-SECD Machine (1964)	ALGOL (1968)	CLOS (1988)		II Calculus, (Milner, 1990s)
3	Scheme (1977)	Pascal (1970)	C++ (1985)		
4	ML (1973) (feature-types)	C (1972)	Java (1985)		
5	Haskell (1987) (feature-types) Purely function language		C# (2000)		
6	Racket				

5.2 Closures: Functions as values

Higher-order functions can take functions as arguments and can return functions.

```
> (define add
    (lambda (x y)
      (+ x y)))
```

Add function can be rewritten as-

```
> (define add
    (lambda (x) ;; lambda (x) takes x, returns a function lambda (y)
      (lambda (y)
        (+ x y))))
> (add 3)
#(procedure>
> ((add 3) 4)
7
```

Examples of higher-order functions include computing derivatives- ($\frac{d}{dx}$ takes f , returns f') and function composition ($h = f \circ g$)

Higher-order functions require the domain for expressible values to contain functions-

$$EXPVAL = NUM \quad | \quad BOOL \quad | \quad FUNCTION$$

5.2.1 Functional Language

Recall the objective to build a program to compute expressions of numbers. We add the Functional Language to the language previously consisting of Arithmetic, IF+DIV, Global and Lexical Scope components.

Abstract Syntax

$$\begin{array}{ll}
\bar{n} & \text{NUM} \\
\bar{b} & \text{BOOL} \\
e ::= & \text{ifte} \quad e \ e \ e \\
& \lambda \quad \bar{x} \ \dots \ e \\
& @ \quad e \ e \ \dots
\end{array}$$

Abstract syntax form- (number, boolean, if-then-else, procedure, application)
 Notice Arithmetic operators and LET are replaced by λ and $@$.

Concrete Syntax

$$\begin{aligned}
(\text{let } ([x \ e] \ \dots) \ \text{body}) = & ((\lambda \ (x \ \dots) \\
& \quad \text{body}) \\
& \quad e \ \dots)
\end{aligned}$$

5.2.2 Evaluation Semantics

Expressible values -

$$\begin{aligned}
EXPVAL &= NUM \oplus BOOL \oplus FUNCTION \\
DENVAL &= EXPVAL
\end{aligned}$$

NOTE: Evaluation semantics of a good language design requires precision to ensure bug-free logic and language. Ideally, EXPVAL should be partitioned completely and thus should be a disjoint union.

Example: integer datatypes in C allows pointer values. Better design-

$$EXPVAL = NUM \oplus BOOL \oplus POINTER$$

Rules: For grammar Γ , expression e , EXPVAL v -

$$\Gamma \vdash e \Rightarrow v$$

(\vdash : Turnstile operator, expression reads "Under Γ , e evaluates to v ")

1. $\frac{}{\Gamma \vdash \bar{n} \Rightarrow n}$ NUM
2. $\frac{}{\Gamma \vdash \bar{b} \Rightarrow b}$ BOOL
3. $\frac{\Gamma(x) = v}{\Gamma \vdash x \Rightarrow v}$ ID
4. $\frac{\Gamma \vdash e_1 \Rightarrow \#t \quad \Gamma \vdash e_2 \Rightarrow v_2}{\Gamma \vdash \text{ifte } e_1 \ e_2 \ e_3 \Rightarrow v_2}$ IFTE-TRUE
5. $\frac{\Gamma \vdash e_1 \Rightarrow \#f \quad \Gamma \vdash e_3 \Rightarrow v_3}{\Gamma \vdash \text{ifte } e_1 \ e_2 \ e_3 \Rightarrow v_3}$ IFTE-FALSE

Building an application: $\frac{}{\Gamma \vdash (\lambda (x \dots) e) \Rightarrow v}$

5.2.3 Lexical Scope vs Dynamic Scope

Racket code demonstrating lexical scope

```
> (let ([x 5])
    (let ([f (lambda (y)
                (+ x y))])
      (let ([x 0])
        (f 3))))
8
```

Lexical scope gives returns 8, dynamic scope returns 3.