

Learning zk-snark process by tools

Subtitle: Programming zkp with circom

ZK-School: Beginner

(2/16, 2023)

정동현

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Today session is..



(c) Verifier V

- INPUTS: verification key vk , input $\vec{x} \in \mathbb{F}_r^n$, and proof π
- OUTPUTS: decision bit

1. Compute $vk_{\vec{x}} := vk_{IC,0} + \sum_{i=1}^n x_i vk_{IC,i} \in \mathbb{G}_1$.

2. Check validity of knowledge commitments for A, B, C :

$$e(\pi_A, vk_A) = e(\pi'_A, \mathcal{P}_2), e(vk_B, \pi_B) = e(\pi'_B, \mathcal{P}_2), \\ e(\pi_C, vk_C) = e(\pi'_C, \mathcal{P}_2).$$

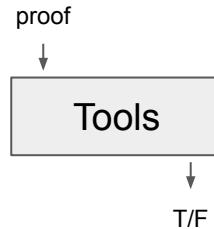
3. Check same coefficients were used:

$$e(\pi_K, vk_{\gamma}) = e(vk_{\vec{x}} + \pi_A + \pi_C, vk_{\beta\gamma}^2) \cdot e(vk_{\beta\gamma}^1, \pi_B) .$$

4. Check QAP divisibility:

$$e(vk_{\vec{x}} + \pi_A, \pi_B) = e(\pi_H, vk_Z) \cdot e(\pi_C, \mathcal{P}_2) .$$

5. Accept if and only if all the above checks succeeded.



But, we have to face the math to
go further..

Session Goals

- Circom과 snarkjs로 ZK-snark의 전체적인 프로세스 소개
 - Circuit 작성(Circom)
 - 증명생성 및 검증(snarkjs)

So,

- 톨링이 되어있는 시스템을 통해 (zk-snark)proof systems을 몰라도 큰그림을 살펴볼 수 있도록
- 추후 이론을 공부할때 이정표가 되도록(결국은 수학 필요)

Outline

1. What is zk-snark?
2. Circom
 - a. R1CS <https://www.youtube.com/watch?v=puxRj0NeqIo>
 - b. building circuit
3. snarkjs

What is zk-snark?

ZK-SNARK : Zero Knowledge Succinct Non-interactive ARgument of Knowledge

S(succinct):

증명되는 개념이 복잡해도 **proof**가 작아서 검증이 빠르게

N(non-interactive):

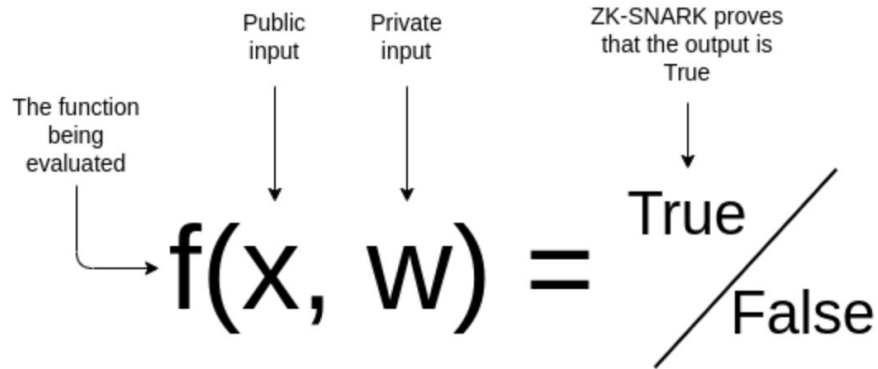
prover(증명자)와 **verifier**(검증자) 사이에 **interaction**이 필요X

ARK(Argument of Knowledge):

“지식증명”, (**prover**가 실제로 뭔가 알고 있다는 것을 증명하고자 함)

What is zk-snark?

Computational Problem: $F(x,w)$ ex). Hash(x,w), x^3+5x+3 , anything..



What is zk-snark?

Computational Problem -> R1CS 형식으로

기본적으로 유한체안에서 $(+,*)$ 연산으로만 이루어져 있는 Arithmetic circuit으로 바꿈
(R1CS는 Arithmetic circuit 표현 방법 중에 하나.)

Example

$f(x) = (x_1 + x_2) * x_3 + 5$ hiding input: x_1, x_2, x_3

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$y_1 = x_1 + x_2$

$y_2 = y_1 * x_3$

$out = y_2 + 5$

⊞

hiding input: x_1, x_2, x_3

intermediate value: y_1, y_2

public output: out

Example

$f(x) = (x_1 + x_2) * x_3 + 5$ hiding input: x_1, x_2, x_3

$y_1 = x_1 + x_2$

$y_2 = y_1 * x_3$

$out = y_2 + 5$

$[?, out, x_1, x_2, x_3, y_1, y_2]$

Example

$$y1 = x1 + x2$$

$$y2 = y1 * x3$$

$$\text{out} = y2 + 5$$

$$s = [?, \text{out}, x1]$$

$$(a . s) * (b . s)$$

Dot product

$$\begin{aligned}\langle r, s \rangle &= \begin{bmatrix} 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \\ &= 2 \cdot 1 + 0 \cdot (-1) + 1 \cdot 2 \\ &= 4\end{aligned}$$

Example

$$y1 = x1 + x2 \rightarrow \langle a1 . s \rangle * \langle b1 . s \rangle - \langle c1 . s \rangle = 0$$

$$y2 = y1 * x3 \rightarrow \langle a2 . s \rangle * \langle b2 . s \rangle - \langle c2 . s \rangle = 0$$

1 이 나와야됨

$$out = y2 + 5 \rightarrow \langle a3 . s \rangle * \langle b3 . s \rangle - \langle c3 . s \rangle = 0$$

$$s = [?, out, x1, x2, x3, y1, y2]$$

$$(a . s) * (b . s) - (c . s) = 0$$

Example

$$y1 = x1 + x2 \rightarrow \langle a1 . s \rangle * \langle b1 . s \rangle - \langle c1 . s \rangle = 0$$

$$y1 = x1 + x2 \rightarrow 1^* (x1 + x2) - y1 = 0$$

$$[1, 0, 0, 0, 0, 0, 0] . s = 1$$

$$y2 = y1 * x3 \rightarrow \langle a2 . s \rangle * \langle b2 . s \rangle - \langle c2 . s \rangle = 0$$

$$\text{out} = y2 + 5 \rightarrow \langle a3 . s \rangle * \langle b3 . s \rangle - \langle c3 . s \rangle = 0$$

$$s = [?, \text{out}, x1, x2, x3, y1, y2]$$

Example

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$$s = [1, \text{out}, x1, x2, x3, y1, y2]$$

Example

$$y1 = x1 + x2 \quad \rightarrow \quad \langle a1 . s \rangle * \langle b1 . s \rangle - \langle c1 . s \rangle = 0$$

$$y1 = x1 + x2 \quad \rightarrow \quad 1*(x1 + x2) - y1 = 0$$


$$a1 = [1, 0, 0, 0, 0, 0, 0]$$

$$[0, 0, 1, 1, 0, 0, 0] . s = x1 + x2$$

$$y2 = y1 * x3 \quad \rightarrow \quad \langle a2 . s \rangle * \langle b2 . s \rangle - \langle c2 . s \rangle = 0$$

$$out = y2 + 5 \quad \rightarrow \quad \langle a3 . s \rangle * \langle b3 . s \rangle - \langle c3 . s \rangle = 0$$

$$s = [1, out, x1, x2, x3, y1, y2]$$

Example

$$y_1 = x_1 + x_2 \quad \rightarrow \quad \langle a_1 . s \rangle * \langle b_1 . s \rangle - \langle c_1 . s \rangle = 0$$

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$$b_1 = [0, 0, 1, 1, 0, 0, 0]$$

$$[0, 0, 0, 0, 0, 1, 0] . s = y_1$$

$$y_2 = y_1 * x_3 \quad \rightarrow \quad \langle a_2 . s \rangle * \langle b_2 . s \rangle - \langle c_2 . s \rangle = 0$$

$$\text{out} = y_2 + 5 \quad \rightarrow \quad \langle a_3 . s \rangle * \langle b_3 . s \rangle - \langle c_3 . s \rangle = 0$$

$$s = [1, \text{out}, x_1, x_2, x_3, y_1, y_2]$$

Example

$$y_1 = x_1 + x_2 \quad \rightarrow \quad \langle a_1 . s \rangle * \langle b_1 . s \rangle - \langle c_1 . s \rangle = 0$$

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$$a_1 = [1, 0, 0, 0, 0, 0, 0]$$

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$$s = [1, \text{out}, x_1, x_2, x_3, y_1, y_2]$$

Example

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$$a1 = [1, 0, 0, 0, 0, 0, 0]$$

$$b1 = [0, 0, 1, 1, 0, 0, 0]$$

$$c1 = [0, 0, 0, 0, 0, 1, 0]$$

$$y2 = y1 * x3 \quad \rightarrow \quad \langle a2 . s \rangle * \langle b2 . s \rangle - \langle c2 . s \rangle = 0$$

$$out = y2 + 5 \quad \rightarrow \quad \langle a3 . s \rangle * \langle b3 . s \rangle - \langle c3 . s \rangle = 0$$

$$s = [1, out, x1, x2, x3, y1, y2]$$

Example

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$a1 = [1, 0, 0, 0, 0, 0, 0]$

$b1 = [0, 0, 1, 1, 0, 0, 0]$

$c1 = [0, 0, 0, 0, 0, 1, 0]$

$$y2 = y1 * x3 \quad \rightarrow \quad \langle a2 . s \rangle * \langle b2 . s \rangle - \langle c2 . s \rangle = 0$$

$$y2 = y1 * x3 \quad \rightarrow \quad y1 * x3 - y2 = 0$$

$a2 = [0, 0, 0, 0, 0, 1, 0]$

$b2 = [0, 0, 0, 0, 1, 0, 0]$

$c2 = [0, 0, 0, 0, 0, 0, 1]$

$$out = y2 + 5 \quad \rightarrow \quad \langle a3 . s \rangle * \langle b3 . s \rangle - \langle c3 . s \rangle = 0$$

$s = [1, out, x1, x2, x3, y1, y2]$

Example

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$$y2 = y1 * x3 \quad \rightarrow \quad \langle a2 . s \rangle * \langle b2 . s \rangle - \langle c2 . s \rangle = 0$$

$a2 = [0, 0, 0, 0, 0, 1, 0]$

$b2 = [0, 0, 0, 0, 1, 0, 0]$

$c2 = [0, 0, 0, 0, 0, 0, 1]$

$$\text{out} = y2 + 5 \quad \rightarrow \quad \langle a3 . s \rangle * \langle b3 . s \rangle - \langle c3 . s \rangle = 0$$

$a3 = [1, 0, 0, 0, 0, 0, 0]$

$b3 = [5, 0, 0, 0, 0, 0, 1]$

$c3 = [0, 1, 0, 0, 0, 0, 0]$

$s = [1, \text{out}, x1, x2, x3, y1, y2]$

Example

$$y_1 = x_1 + x_2 \quad \rightarrow \quad \langle a_1 \cdot s \rangle * \langle b_1 \cdot s \rangle - \langle c_1 \cdot s \rangle = 0$$

$$a_1 = [1, 0, 0, 0, 0, 0, 0]$$

$$b_1 = [0, 0, 1, 1, 0, 0, 0]$$

$$c_1 = [0, 0, 0, 0, 0, 0, 1]$$

$$y_2 = y_1 * x_3 \quad \rightarrow \quad \langle a_2 \cdot s \rangle * \langle b_2 \cdot s \rangle - \langle c_2 \cdot s \rangle = 0$$

$$a_2 = [0, 0, 0, 0, 0, 0, 1]$$

$$b_2 = [0, 0, 0, 0, 1, 0, 0]$$

$$c_2 = [0, 0, 0, 0, 0, 0, 1]$$

$$\text{out} = y_2 + 5 \quad \rightarrow \quad \langle a_3 \cdot s \rangle * \langle b_3 \cdot s \rangle - \langle c_3 \cdot s \rangle = 0$$

$$a_3 = [1, 0, 0, 0, 0, 0, 0]$$

$$b_3 = [5, 0, 0, 0, 0, 0, 1]$$

$$c_3 = [0, 1, 0, 0, 0, 0, 0]$$

$$a_i \cdot \vec{s} + b_i \cdot \vec{s} - c_i \cdot \vec{s} = 0$$

$$s = [1, \text{out}, x_1, x_2, x_3, y_1, y_2]$$

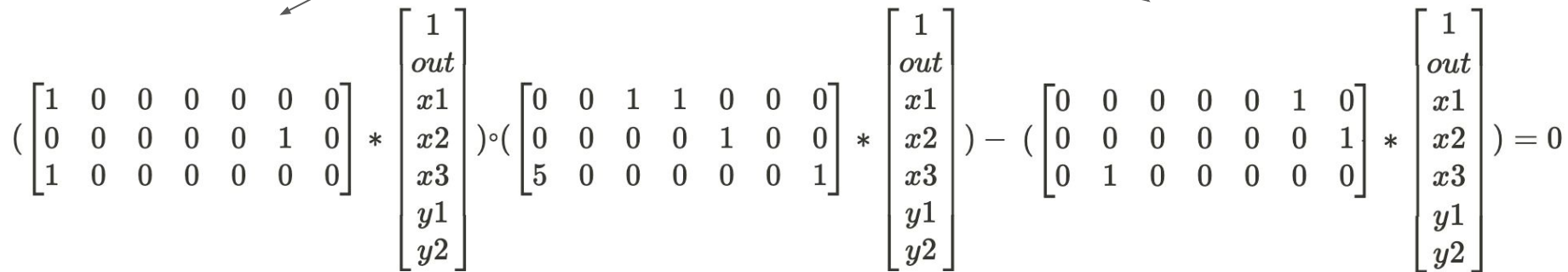
Example

$$\left(\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) \circ \left(\begin{bmatrix} 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 5 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) - \left(\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) = 0$$

R1CS(Rank-1 Constraint System) Form

Example

Constraints Matrices



The diagram illustrates the decomposition of a constraint matrix into two rank-1 matrices. At the top, the text "Constraints Matrices" has three arrows pointing downwards. The left arrow points to the first rank-1 matrix, the middle arrow points to the composition operator \circ , and the right arrow points to the second rank-1 matrix. The equation is as follows:

$$\left(\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) \circ \left(\begin{bmatrix} 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 5 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) - \left(\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) = 0$$

R1CS(Rank-1 Constraint System) Form

Example

Solution vector == witness vector



$$\left(\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) \circ \left(\begin{bmatrix} 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 5 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) - \left(\begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \right) = 0$$

R1CS(Rank-1 Constraint System) Form

Example

Solution vector == witness vector

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} * \begin{pmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{pmatrix} \circ \begin{pmatrix} 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix} * \begin{pmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{pmatrix} - \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} * \begin{pmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{pmatrix} = 0$$

with public inputs = x

private inputs = w

R1CS(Rank-1 Constraint System) Form

Example

Solution vector == witness vector

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} \circ \begin{pmatrix} 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ & & & & & & 1 \end{pmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} - \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} * \begin{bmatrix} 1 \\ out \\ x1 \\ x2 \\ x3 \\ y1 \\ y2 \end{bmatrix} = 0$$

with public inputs = x

private inputs = w

Prover가 해야할 것 : 위를 만족하는 witness vector를 알고 있음을 증명

Circom

zkrepl - Online play ground for zk circom circuits.

<https://zkrepl.dev/>

$f(x) = (x_1 + x_2) * x_3 + 5$ hiding input: x_1, x_2, x_3

$y_1 = x_1 + x_2$

$y_2 = y_1 * x_3$

$out = y_2 + 5$

Circom

Circom docs:

<https://docs.circom.io/>

Other useful tools

zkrepl - Online play ground for zk circom circuits.

<https://zkrepl.dev/>

hardhat-circom - Hardhat plugin to integrate circom and snarkjs into build process.

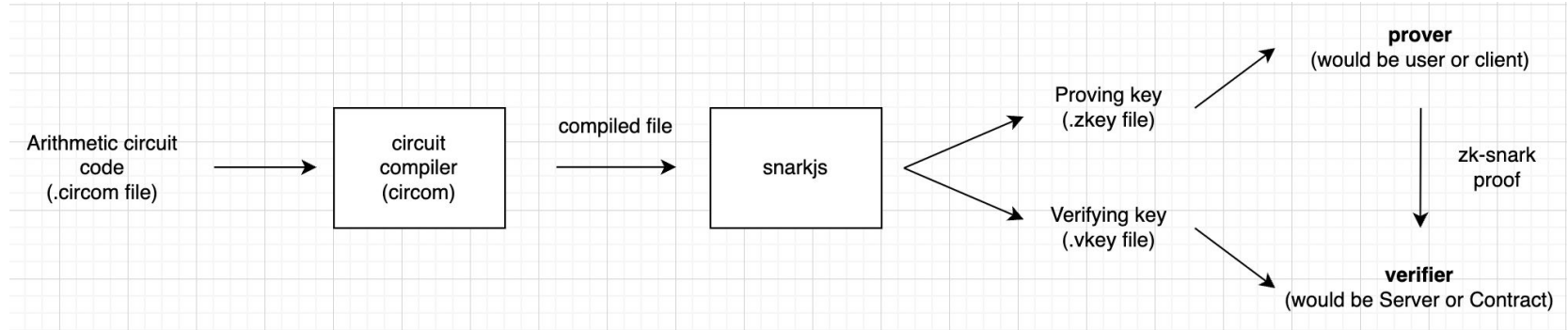
<https://github.com/projectsophon/hardhat-circom#readme>

circomlib - Repository contains a library of circuit templates.

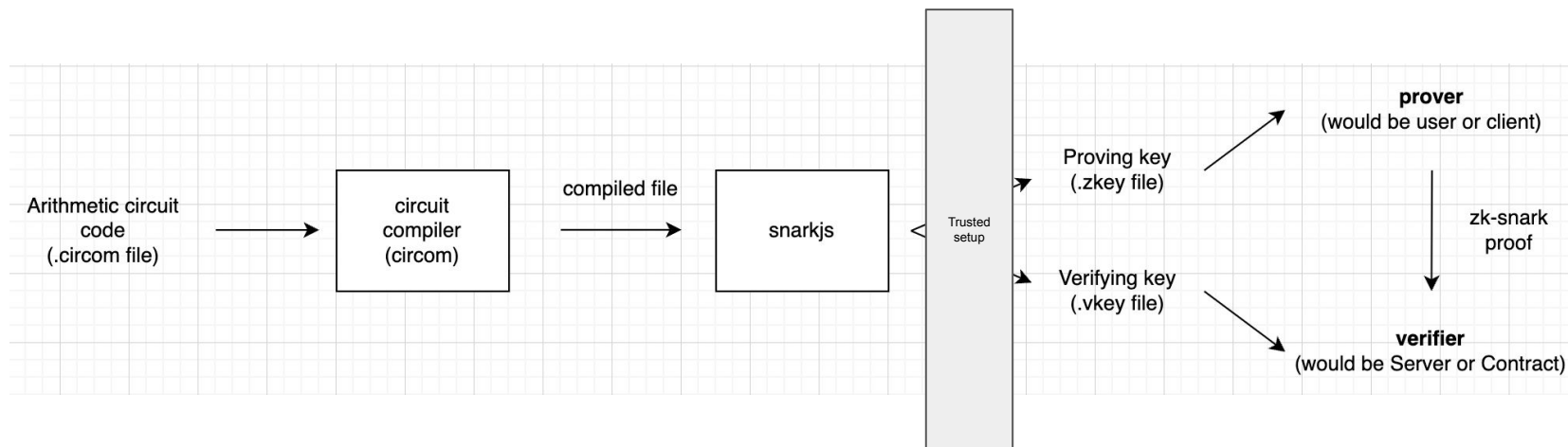
<https://github.com/iden3/circomlib>

Circuit clear!
Next step is..

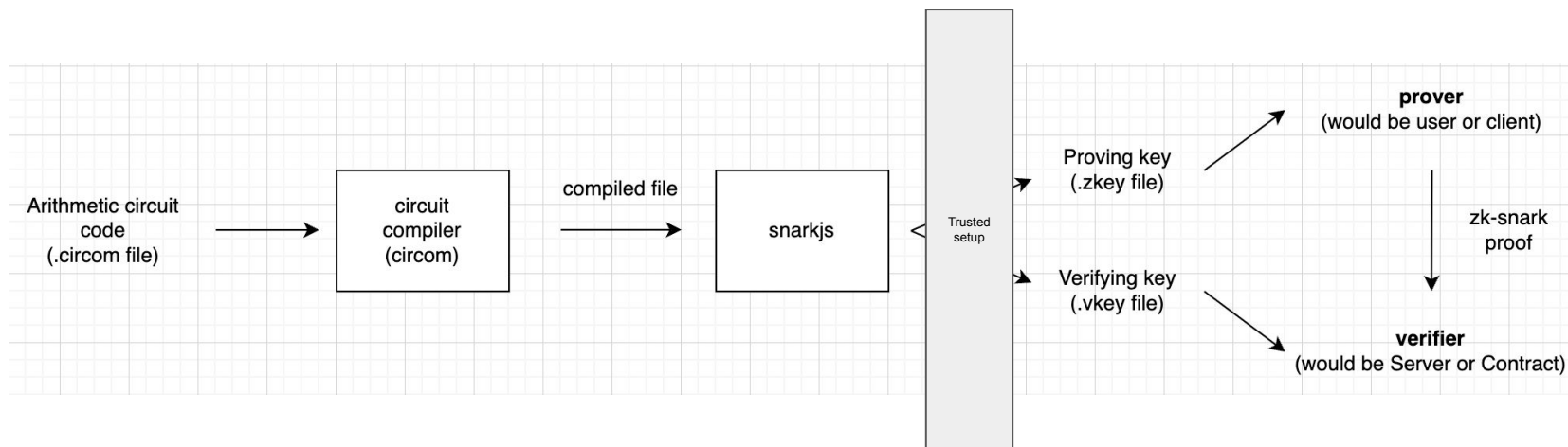
snarkjs



snarkjs



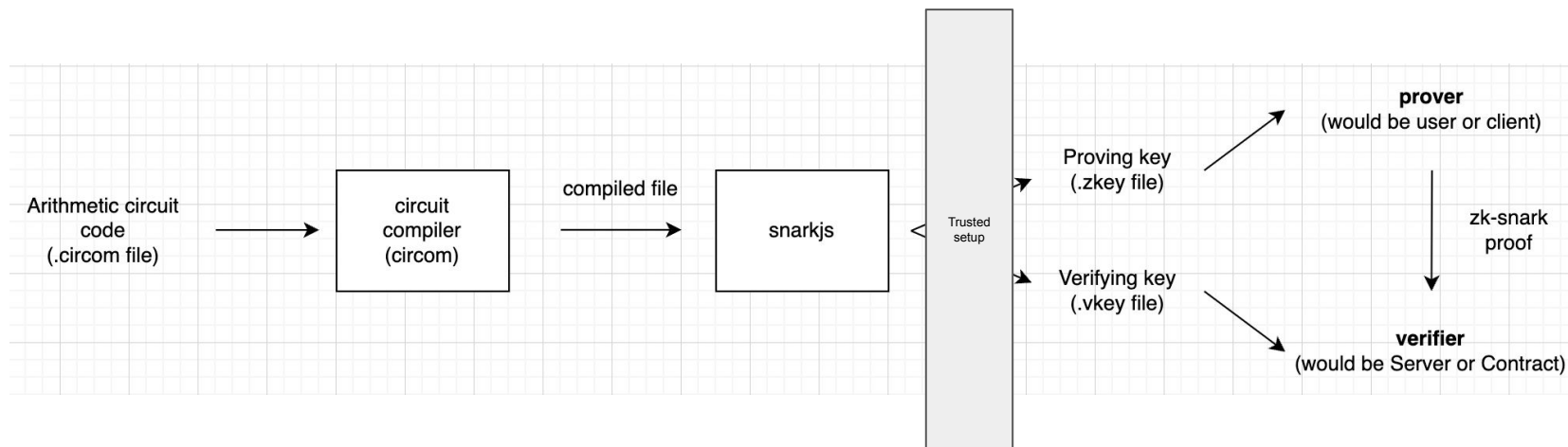
snarkjs



Groth16: circuit별로 trusted setup 필요. (CRS)

Plonk: universal하게 trusted setup 필요. (SRS)

snarkjs

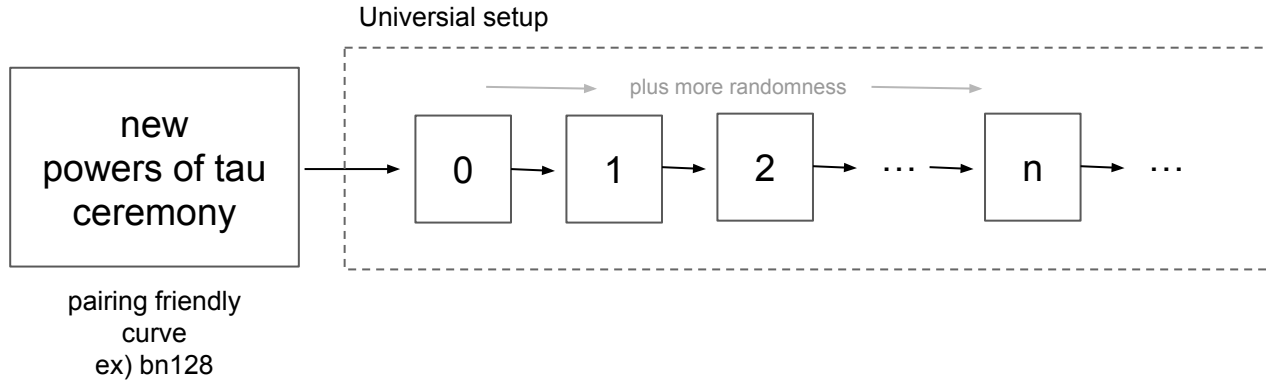


Groth16: circuit별로 trusted setup 필요. (CRS)
Plonk: universal하게 trusted setup 필요. (SRS)

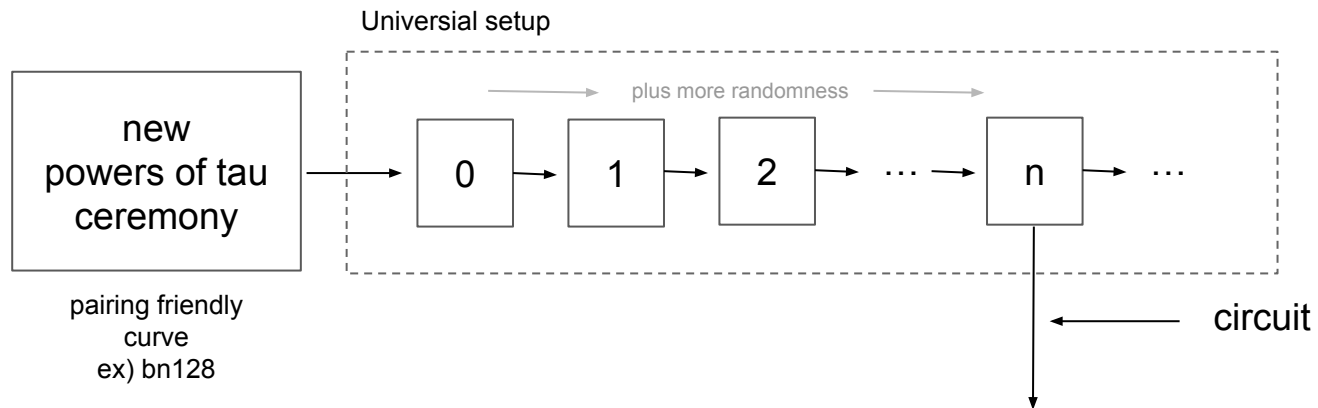
New!! “FFlonk”

<https://twitter.com/jbaylina/status/1624116186861404188>

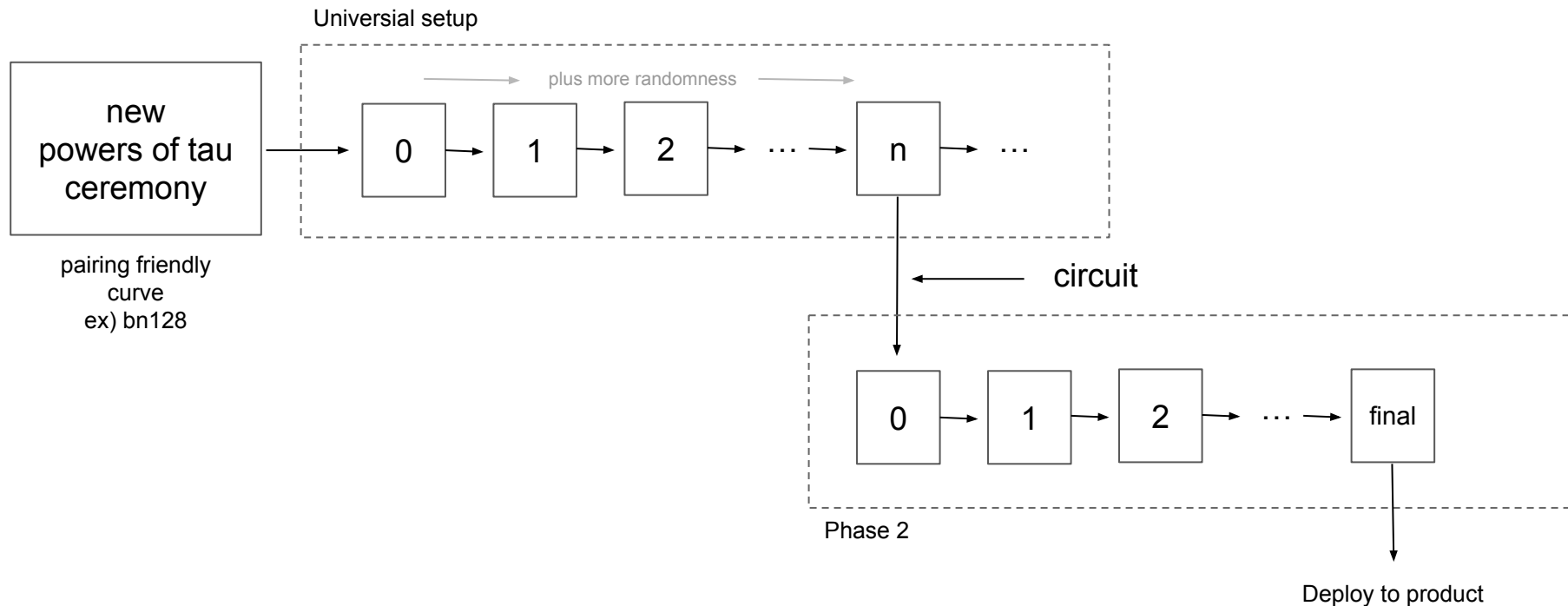
Powers of tau



Powers of tau



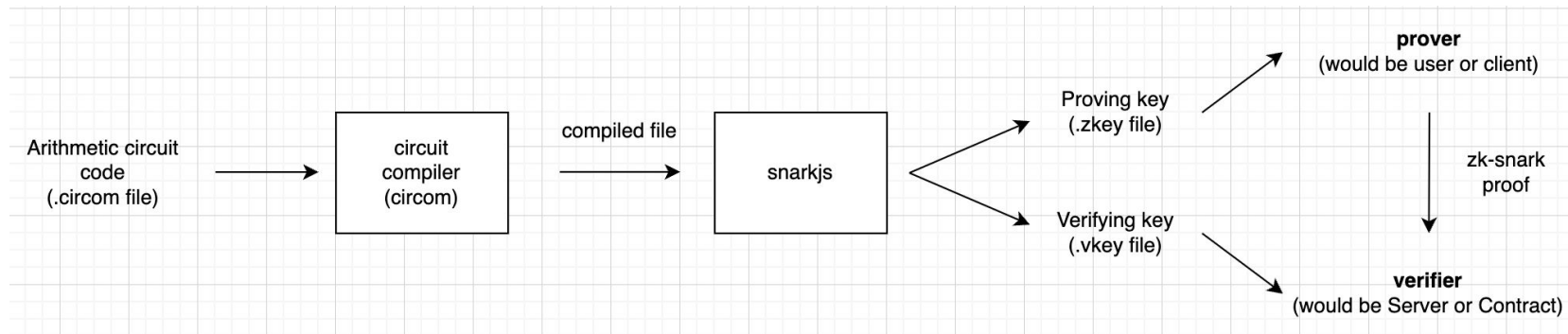
Powers of tau



snarkjs

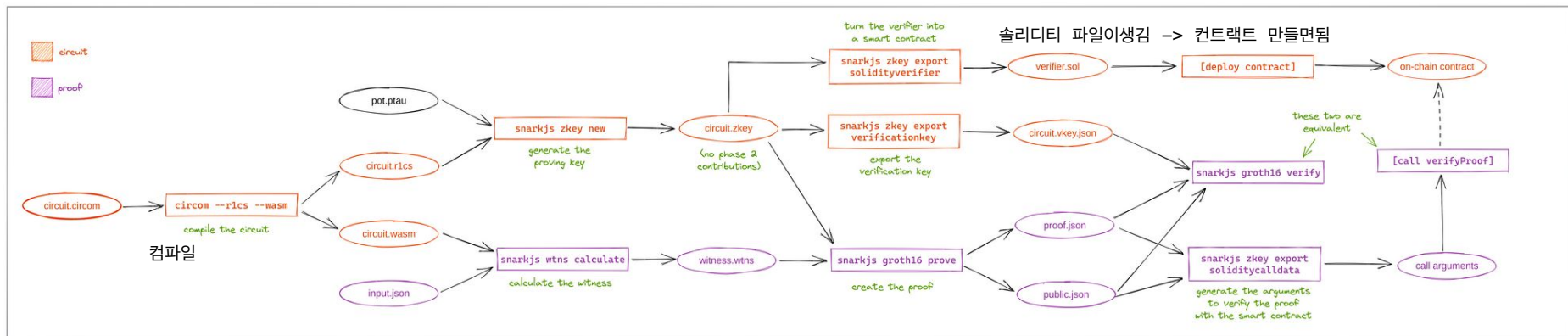
Key point!

Proving key와 witness로
proof 생성



Verifying key와 proof로
T/F 검증

snarkjs



- made by fvictorio