

Output Perturbation for Differentially Private Convex Optimization

With Improved Population Loss and Runtime Bounds, and Applications to Adversarial Training

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Background

- Differential Privacy (DP) provides a rigorous guarantee that one's data cannot be leaked. Formally, a randomized algorithm $\mathcal{A} : \mathcal{X}^n \rightarrow \mathbb{R}^d$ is said to be (ϵ, δ) -DP if $\mathbb{P}(\mathcal{A}(X) \in S) \leq \mathbb{P}(\mathcal{A}(X') \in S)e^\epsilon + \delta$ for all $S \subset \text{Range}(\mathcal{A})$ and all adjacent data sets $X, X' \in \mathcal{X}^n$ that differ by one observation.
 - $\delta = 0$ provides strongest privacy guarantee
- Output perturbation: $\mathcal{A}(X) = w^*(X) + z$, where $w^*(X) \in \arg \min_{w \in \mathbb{R}^d} F(w, X)$
 - Applied as conceptual method for smooth classification in ERM (Chaudhuri et al., 2011)
 - Implemented with gradient descent for smooth ERM (Zhang et al., 2017)

Related Work and Gaps

1. Most work in DP learning has focused on average loss: Empirical Risk Minimization (ERM) (e.g. Bassily et al. 2014) or Stochastic Convex Optimization (SCO)
- It is important to have DP algorithms for **general loss** functions that are *not of ERM/SCO form*
 - Applications: fairness, robustness, sensitivity to outliers, bias/variance tradeoff
 - Example: $F(w, X) = \frac{1}{\tau} \log \left(\frac{1}{n} \sum_{i=1}^n e^{\tau f(w, x_i)} \right)$ (TERM) (Li et al. 2020)
2. Another gap: tight population loss and runtime bounds for **$(\epsilon, 0)$ -DP SCO**
 - Bassily et al. (2019) and Feldman et al. (2020) give tight loss bounds and fast runtimes for (ϵ, δ) -DP SCO for $\delta > 0$
3. Need for practical algorithms for **DP Adversarial Training**

Main Contributions

1. We provide a simple algorithm for **general DP convex optimization**
 - Excess risk and runtime bounds for general convex Lipschitz loss (and under smoothness and/or strong convexity)
2. We prove the tightest known excess population loss and runtime bounds for **$(\epsilon, 0)$ -DP SCO**
3. We develop a practical algorithm for **DP Adversarial Training** with excess adversarial risk and runtime guarantees
4. We attain our results through **output perturbation**
 - We detail how output perturbation can be seen as a powerful practical method for transforming any non-private solver into a DP one

Results: DP SCO ($\delta = 0$)

2. Solving $\min_{w \in \mathbb{R}^d} F(w, X) = \mathbb{E}_{x \sim \mathcal{D}} [f(w, x)]$

Function Class	Excess Population Loss	Runtime	Assumptions
L -Lipschitz, μ -strongly convex	$O\left(\frac{L^2}{\mu} \left(\frac{d}{\epsilon n} + \frac{1}{n}\right)\right)$	$O\left(nd \max\left\{n, \frac{\epsilon}{d}\right\}\right)$	$\frac{d}{\epsilon n} \lesssim 1$
L -Lipschitz, μ -strongly convex, β -smooth	$O\left(\frac{L^2}{\mu} \left(\min\left\{\kappa \left(\frac{d}{\epsilon n}\right)^2, \frac{d}{\epsilon n}\right\} + \frac{1}{n}\right)\right)$	$\tilde{O}(dn + \sqrt{nd\kappa})$	$\frac{d}{\epsilon n} \lesssim 1$
L -Lipschitz, convex	$O\left(LR \left(\sqrt{\frac{d}{\epsilon n}} + \frac{1}{\sqrt{n}}\right)\right)$	$O\left(n^2 d \max\left\{1, \left(\frac{\epsilon}{d}\right)^2\right\}\right)$	$\frac{d}{\epsilon n} \lesssim 1$
L -Lipschitz, convex, β -smooth	$O\left(\min\left\{\beta^{1/3} L^{2/3} R^{4/3} \left(\frac{d}{\epsilon n}\right)^{2/3} + \frac{1}{\sqrt{n}}, LR \left(\sqrt{\frac{d}{\epsilon n}} + \frac{1}{\sqrt{n}}\right)\right\}\right)$	$\tilde{O}\left(nd + \max\left\{n^{5/6} d^{2/3} \epsilon^{1/3} \left(\frac{\beta R}{L}\right)^{1/3}, n^{3/4} \beta^{1/4} \epsilon^{1/4} \sqrt{\frac{\beta R}{L}}\right\}\right)$	$\left(\frac{d}{\epsilon n}\right)^2 \lesssim \frac{L}{\beta R}$

Table 2: Excess population Loss, $\delta = 0$. All excess risk bounds should be read as $\min\{LR, \dots\}$ by taking the trivial algorithm (e.g. if $d > \epsilon n$).

- **Excess population loss** := $\mathbb{E}_{\mathcal{A}, x \sim \mathcal{D}} f(\mathcal{A}(X), x) - \min_{w \in \mathbb{R}^d} \mathbb{E}_{x \sim \mathcal{D}} f(w, x)$

DP Adversarial Training

3. Solving $\min_{w \in \mathbb{R}^d} \max_{v \in S^n} F(w, X + v)$: adversary perturbs feature components of data set X , while corresponding labels are fixed (not perturbed)
- Applying our framework results in the first excess adversarial risk and runtime bounds for DP adversarial training
- **Excess adversarial risk** := $\mathbb{E}_{\mathcal{A}} \max_{v \in S^n} F(\mathcal{A}(X), X + v) - \min_{w \in \mathbb{R}^d} \max_{v \in S^n} F(w, X + v)$

Results: General DP Optimization

1. Solving $\min_{w \in \mathbb{R}^d} F(w, X)$ for **general (non-ERM) loss**

Function Class	Excess Risk	Runtime	Assumptions
L -Lipschitz, μ -strongly convex	$O\left(\frac{L^2}{\mu} \frac{d}{\epsilon}\right)$	$O(n\epsilon)$	$d \lesssim \epsilon$
L -Lipschitz, μ -strongly convex, β -smooth	$O\left(\frac{L^2}{\mu} \left(\frac{d}{\epsilon}\right) \min\left\{\kappa \left(\frac{d}{\epsilon}\right), 1\right\}\right)$	$\tilde{O}(dn\sqrt{\kappa})$	$d \lesssim \epsilon$
L -Lipschitz, convex	$O\left(LR \sqrt{\frac{d}{\epsilon}}\right)$	$O\left(\frac{n\epsilon^2}{d}\right)$	$d \lesssim \epsilon$
L -Lipschitz, convex, β -smooth	$O\left(\min\left\{\beta^{1/3} L^{2/3} R^{4/3} \left(\frac{d}{\epsilon}\right)^{2/3}, LR \sqrt{\frac{d}{\epsilon}}\right\}\right)$	$\tilde{O}\left(n \max\left\{\left(\frac{\beta R}{L}\right)^{1/3} \epsilon^{1/3} d^{2/3}, \left(\frac{\beta R}{L}\right)^{1/2} \epsilon^{1/4} d^{3/4}\right\}\right)$	$\left(\frac{d}{\epsilon}\right)^2 \lesssim \frac{L}{\beta R}$
TERM	$O\left(\frac{L^2 C_\tau}{\mu} \frac{d}{\epsilon n}\right)$	$O\left(\frac{n^2 d}{C_\tau} \max\left\{\frac{d}{\epsilon}, \frac{n}{C_\tau}\right\}\right)$	f bounded on $\mathcal{W} \times \mathcal{X}$, $\frac{d}{\epsilon n} \lesssim 1$
Smooth TERM	$O\left(\frac{L^2 C_\tau}{\mu} \frac{d}{\epsilon n} \min\left\{1, \kappa_\tau \frac{d}{\epsilon n}\right\}\right)$	$\tilde{O}(nd\kappa_\tau)$	f bounded on $\mathcal{W} \times \mathcal{X}$, $\frac{d}{\epsilon n} \lesssim 1$

Table 1: General loss (non-ERM, non-SCO), $\delta = 0$. For $\delta > 0$, d gets replaced by $\sqrt{d} \log \left(\frac{1}{\delta} \right)$ in excess risk bounds.

- **Excess risk** := $\mathbb{E}_{\mathcal{A}} F(\mathcal{A}(X), X) - F(w^*(X), X)$

References

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