

```
In [181]: !pip install -q keras
import keras
```

```
In [182]: import matplotlib.pyplot as plt
%matplotlib inline
import numpy as np
import keras.utils

def generate_a_drawing(figsize, U, V, noise=0.0):
    fig = plt.figure(figsize=(figsize,figsize))
    ax = plt.subplot(111)
    plt.axis('Off')
    ax.set_xlim(0,figsize)
    ax.set_ylim(0,figsize)
    ax.fill(U, V, "k")
    fig.canvas.draw()
    imdata = np.frombuffer(fig.canvas.tostring_rgb(), dtype=np.uint8)[
    imdata = imdata + noise * np.random.random(imdata.size)
    plt.close(fig)
    return imdata

def generate_a_rectangle(noise=0.0, free_location=False):
    figsize = 1.0
    U = np.zeros(4)
    V = np.zeros(4)
    if free_location:
        corners = np.random.random(4)
        top = max(corners[0], corners[1])
        bottom = min(corners[0], corners[1])
        left = min(corners[2], corners[3])
        right = max(corners[2], corners[3])
    else:
        side = (0.3 + 0.7 * np.random.random()) * figsize
        top = figsize/2 + side/2
        bottom = figsize/2 - side/2
        left = bottom
        right = top
    U[0] = U[1] = top
    U[2] = U[3] = bottom
    V[0] = V[3] = left
    V[1] = V[2] = right
    return generate_a_drawing(figsize, U, V, noise)

def generate_a_disk(noise=0.0, free_location=False):
    figsize = 1.0
    if free_location:
        center = np.random.random(2)
    else:
        center = (figsize/2, figsize/2)
    radius = (0.3 + 0.7 * np.random.random()) * figsize/2
    return generate_a_drawing(figsize, center, radius, noise)
```

```

N = 50
U = np.zeros(N)
V = np.zeros(N)
i = 0
for t in np.linspace(0, 2*np.pi, N):
    U[i] = center[0] + np.cos(t) * radius
    V[i] = center[1] + np.sin(t) * radius
    i = i + 1
return generate_a_drawing(figsize, U, V, noise)

def generate_a_triangle(noise=0.0, free_location=False):
    figsize = 1.0
    if free_location:
        U = np.random.random(3)
        V = np.random.random(3)
    else:
        size = (0.3 + 0.7 * np.random.random())*figsize/2
        middle = figsize/2
        U = (middle, middle+size, middle-size)
        V = (middle+size, middle-size, middle-size)
    imdata = generate_a_drawing(figsize, U, V, noise)
    return [imdata, [U[0], V[0], U[1], V[1], U[2], V[2]]]

im = generate_a_rectangle(10, True)
plt.imshow(im.reshape(72,72), cmap='gray')

im = generate_a_disk(10)
plt.imshow(im.reshape(72,72), cmap='gray')

[im, v] = generate_a_triangle(20, False)
plt.imshow(im.reshape(72,72), cmap='gray')

def generate_dataset_classification(nb_samples, noise=0.0, free_location=False):
    # Getting im_size:
    im_size = generate_a_rectangle().shape[0]
    X = np.zeros([nb_samples, im_size])
    Y = np.zeros(nb_samples)
    print('Creating data:')
    for i in range(nb_samples):
        if i % 10 == 0:
            print(i)
        category = np.random.randint(3)
        if category == 0:
            X[i] = generate_a_rectangle(noise, free_location)
        elif category == 1:
            X[i] = generate_a_disk(noise, free_location)
        else:
            [X[i], V] = generate_a_triangle(noise, free_location)
            Y[i] = category
    X = (X + noise) / (255 + 2 * noise)
    return [X, Y]

def generate_test_set_classification(X, Y):

```

```

def generate_test_set_classification():
    np.random.seed(42)
    [X_test, Y_test] = generate_dataset_classification(300, 20, True)
    Y_test = np_utils.to_categorical(Y_test, 3)
    return [X_test, Y_test]

def generate_dataset_regression(nb_samples, noise=0.0):
    # Getting im_size:
    im_size = generate_a_triangle()[0].shape[0]
    X = np.zeros([nb_samples, im_size])
    Y = np.zeros([nb_samples, 6])
    print('Creating data:')
    for i in range(nb_samples):
        if i % 10 == 0:
            print(i)
            [X[i], Y[i]] = generate_a_triangle(noise, True)
    X = (X + noise) / (255 + 2 * noise)
    return [X, Y]

import matplotlib.patches as patches

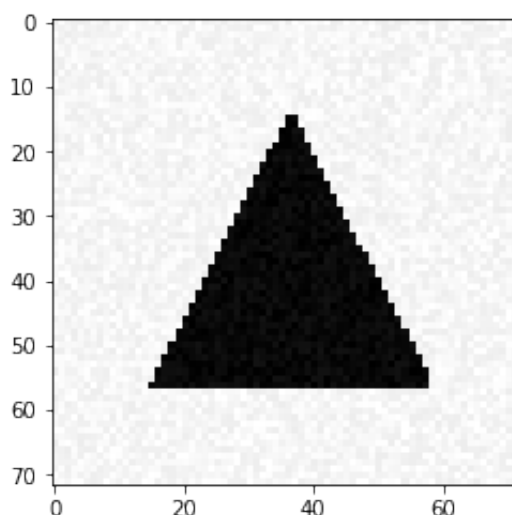
def visualize_prediction(x, y):
    fig, ax = plt.subplots(figsize=(5, 5))
    I = x.reshape((72,72))
    ax.imshow(I, extent=[-0.15,1.15,-0.15,1.15], cmap='gray')
    ax.set_xlim([0,1])
    ax.set_ylim([0,1])

    xy = y.reshape(3,2)
    tri = patches.Polygon(xy, closed=True, fill = False, edgecolor = 'r')
    ax.add_patch(tri)

    plt.show()

def generate_test_set_regression():
    np.random.seed(42)
    [X_test, Y_test] = generate_dataset_regression(300, 20)
    Y_test = np_utils.to_categorical(Y_test, 3)
    return [X_test, Y_test]

```



Simple Classification

```
In [143]: # Generate the training dataset, and transfer y_train into a category
from keras import utils as np_utils
[X_train, Y_train] = generate_dataset_classification(300, 20)
Y_train = np_utils.to_categorical(Y_train)
```

Creating data:

0
10
20
30
40
50
60
70
80
90
100
110
120
130
140
150
160
170
180
190
200
210
220
230
240
250
260
270
280
290

In []:

```
In [144]: from keras.models import Sequential
from keras.layers import Dense, Activation, Flatten, BatchNormalization
from keras.layers.convolutional import Convolution2D, MaxPooling2D
from keras.layers import Input, UpSampling2D, merge, Conv2D, Cropping2D, concatenate
from keras.models import Model
from keras import layers
```

```
In [146]: model = Sequential()
          model.add(Dense(100, input_shape=(1, 1, 1)))
```

```

n_cols = x_train[0].shape

#one single layer, and use softmax
model.add(Dense(units=3,activation='softmax',input_shape=n_cols))

# use the Adam optimizor
model.compile(loss='categorical_crossentropy',optimizer = 'adam',metrics=['accuracy'])

# fit the model
model.fit(X_train, Y_train, epochs=32, batch_size=40)

```

Epoch 1/32

300/300 [=====] - 1s 2ms/step - loss: 2.1975 - acc: 0.3433

Epoch 2/32

300/300 [=====] - 0s 103us/step - loss: 0.8739 - acc: 0.6000

Epoch 3/32

300/300 [=====] - 0s 89us/step - loss: 0.5674 - acc: 0.7933

Epoch 4/32

300/300 [=====] - 0s 79us/step - loss: 0.4464 - acc: 0.8333

Epoch 5/32

300/300 [=====] - 0s 93us/step - loss: 0.3506 - acc: 0.9433

Epoch 6/32

300/300 [=====] - 0s 91us/step - loss: 0.3118 - acc: 0.8800

Epoch 7/32

300/300 [=====] - 0s 83us/step - loss: 0.2613 - acc: 0.9633

Epoch 8/32

300/300 [=====] - 0s 92us/step - loss: 0.2149 - acc: 0.9733

Epoch 9/32

300/300 [=====] - 0s 93us/step - loss: 0.2068 - acc: 0.9733

Epoch 10/32

300/300 [=====] - 0s 87us/step - loss: 0.1742 - acc: 1.0000

Epoch 11/32

300/300 [=====] - 0s 99us/step - loss: 0.1596 - acc: 0.9833

Epoch 12/32

300/300 [=====] - 0s 88us/step - loss: 0.1523 - acc: 0.9800

Epoch 13/32

300/300 [=====] - 0s 103us/step - loss: 0.1306 - acc: 0.9967

Epoch 14/32

300/300 [=====] - 0s 98us/step - loss: 0.1257 - acc: 0.9833

Epoch 15/32

```
300/300 [=====] - 0s 93us/step - loss: 0.12
14 - acc: 1.0000
Epoch 16/32
300/300 [=====] - 0s 83us/step - loss: 0.11
46 - acc: 0.9933
Epoch 17/32
300/300 [=====] - 0s 91us/step - loss: 0.09
87 - acc: 1.0000
Epoch 18/32
300/300 [=====] - 0s 96us/step - loss: 0.09
68 - acc: 0.9900

Epoch 19/32
300/300 [=====] - 0s 93us/step - loss: 0.11
78 - acc: 0.9800
Epoch 20/32
300/300 [=====] - 0s 84us/step - loss: 0.09
48 - acc: 0.9833
Epoch 21/32
300/300 [=====] - 0s 95us/step - loss: 0.08
22 - acc: 0.9967
Epoch 22/32
300/300 [=====] - 0s 95us/step - loss: 0.07
88 - acc: 0.9933
Epoch 23/32
300/300 [=====] - 0s 95us/step - loss: 0.06
78 - acc: 0.9967
Epoch 24/32
300/300 [=====] - 0s 96us/step - loss: 0.06
64 - acc: 1.0000
Epoch 25/32
300/300 [=====] - 0s 86us/step - loss: 0.06
31 - acc: 1.0000
Epoch 26/32
300/300 [=====] - 0s 89us/step - loss: 0.06
08 - acc: 1.0000
Epoch 27/32
300/300 [=====] - 0s 93us/step - loss: 0.06
54 - acc: 0.9967
Epoch 28/32
300/300 [=====] - 0s 95us/step - loss: 0.05
23 - acc: 1.0000
Epoch 29/32
300/300 [=====] - 0s 85us/step - loss: 0.05
15 - acc: 1.0000
Epoch 30/32
300/300 [=====] - 0s 88us/step - loss: 0.05
02 - acc: 1.0000
Epoch 31/32
300/300 [=====] - 0s 102us/step - loss: 0.0
435 - acc: 1.0000
Epoch 32/32
300/300 [=====] - 0s 96us/step - loss: 0.04
```

```
Out[146]: <keras.callbacks.History at 0x1855458a90>
```

```
In [147]: X_test = generate_a_disk()  
X_test = X_test.reshape(1, X_test.shape[0])  
model.predict(X_test)
```

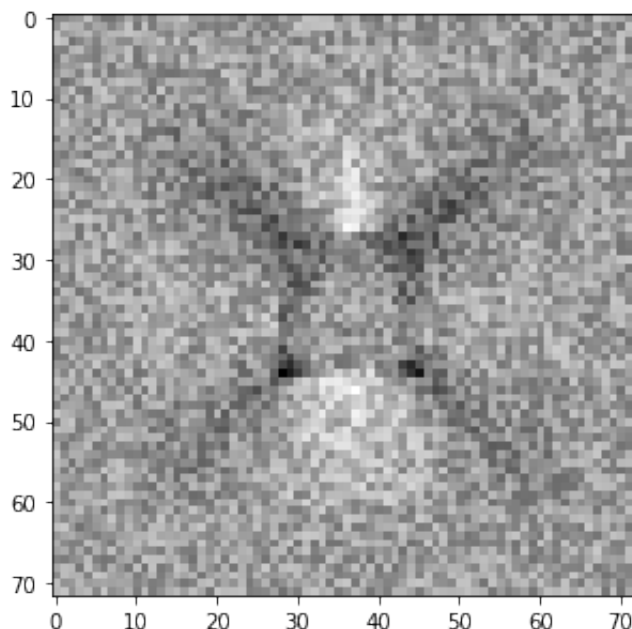
```
Out[147]: array([[ 0.,  1.,  0.]], dtype=float32)
```

Visualization of the Solution

```
In [148]: # get tjhe maxtrix of the classifie, and visualize the 3 columns  
weights = model.get_weights()  
print(type(weights))  
print(weights[0])  
fig, ax = plt.subplots(figsize=(5, 5))  
I = weights[0][:,0].reshape((72,72))  
ax.imshow(I,cmap='gray')
```

```
<class 'list'>  
[[-0.0157772  0.02108267 -0.03320824]  
 [-0.01422067 -0.01513903  0.01840402]  
 [-0.00332865 -0.0212197   0.01201476]  
 ...,  
 [ 0.02798267  0.02474933 -0.02355425]  
 [-0.03096665  0.00520328 -0.01810184]  
 [ 0.01070937 -0.00682686 -0.00869321]]
```

```
Out[148]: <matplotlib.image.AxesImage at 0x1830910ba8>
```

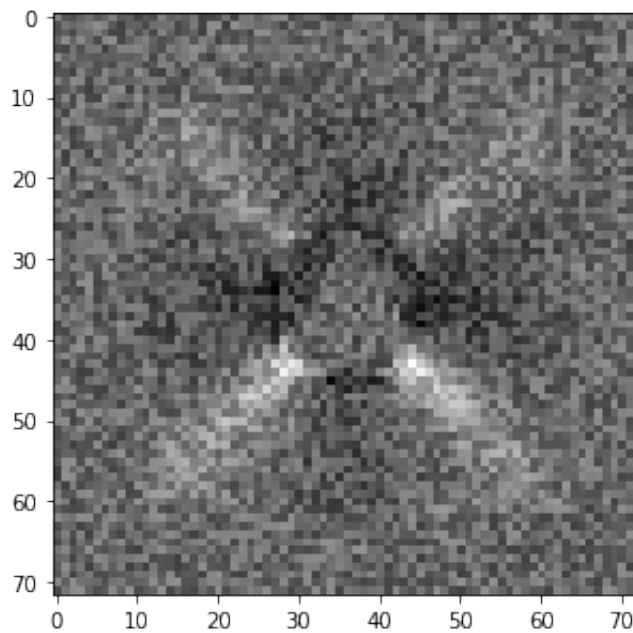


```
In [149]: for weight in weights:  
          print (weight.shape)
```

```
(5184, 3)  
(3,)
```

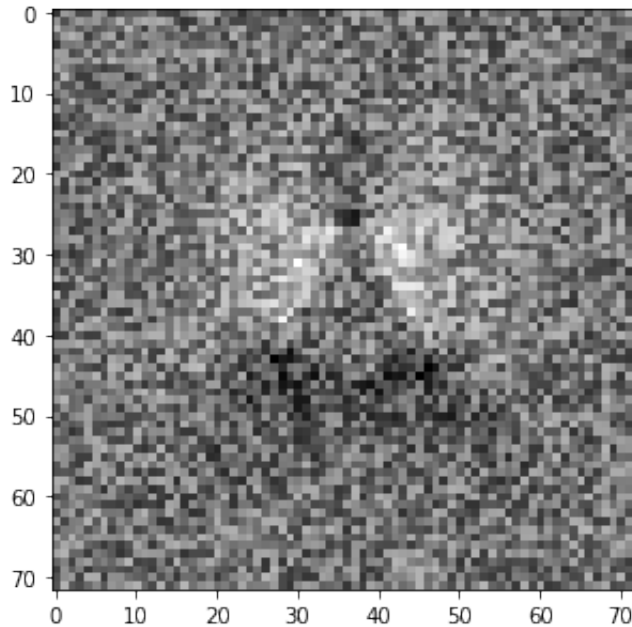
```
In [150]: weights = model.get_weights()  
fig, ax = plt.subplots(figsize=(5, 5))  
I = weights[0][:,1].reshape((72,72))  
ax.imshow(I,cmap='gray')
```

```
Out[150]: <matplotlib.image.AxesImage at 0x1830a324e0>
```




```
In [151]: weights = model.get_weights()
fig, ax = plt.subplots(figsize=(5, 5))
I = weights[0][:,2].reshape((72,72))
ax.imshow(I,cmap='gray')
```

Out[151]: <matplotlib.image.AxesImage at 0x182f53a9b0>



A More Difficult Classification Problem

```
In [152]: #generate the new training set
[X_train, Y_train] = generate_dataset_classification(2000, 20, True)

# transform x and y
Y_train = np_utils.to_categorical (Y_train,3)
X_train = X_train.reshape(X_train.shape[0],1,72,72)

330
340
350
360
370
380
390
400
410
420
430
440
450
460
470
480
490
500
510
520
```

```
In [153]: model_2 = Sequential()
# input convolution layer
model_2.add(Convolution2D(16,(5,5),activation = 'relu',input_shape=(1,
#maxpooling layer
model_2.add(MaxPooling2D(pool_size=(2, 2)))
#Flatten
model_2.add(Flatten())
#full_connected layer
model_2.add(Dense(units=30, activation = 'relu' ))
#output layer
model_2.add(Dense(units=3,activation='softmax'))
```

```
In [154]: #compile the model_2
model_2.compile(loss='categorical_crossentropy',optimizer = 'Adam',met:

# fit the model_2
model_2.fit(X_train, Y_train, epochs=32, batch_size=32)

Epoch 1/32
2000/2000 [=====] - 15s 8ms/step - loss: 1.
0920 - acc: 0.4850
Epoch 2/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
8092 - acc: 0.6235
Epoch 3/32
```

```
-----
2000/2000 [=====] - 12s 6ms/step - loss: 0.
7007 - acc: 0.7045
Epoch 4/32
2000/2000 [=====] - 15s 8ms/step - loss: 0.
6320 - acc: 0.7480

Epoch 5/32
2000/2000 [=====] - 13s 7ms/step - loss: 0.
5781 - acc: 0.7690
Epoch 6/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
5091 - acc: 0.8155: 4s -
Epoch 7/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
4601 - acc: 0.8230
Epoch 8/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
4248 - acc: 0.8520
Epoch 9/32
2000/2000 [=====] - 13s 7ms/step - loss: 0.
3573 - acc: 0.8840
Epoch 10/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
2947 - acc: 0.9105
Epoch 11/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
2737 - acc: 0.9170
Epoch 12/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
2427 - acc: 0.9175
Epoch 13/32
2000/2000 [=====] - 14s 7ms/step - loss: 0.
2019 - acc: 0.9495
Epoch 14/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
1647 - acc: 0.9600
Epoch 15/32
2000/2000 [=====] - 14s 7ms/step - loss: 0.
1578 - acc: 0.9605
Epoch 16/32
2000/2000 [=====] - 13s 7ms/step - loss: 0.
1318 - acc: 0.9685
Epoch 17/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
1084 - acc: 0.9740
Epoch 18/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
0993 - acc: 0.9775
Epoch 19/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
0796 - acc: 0.9850
Epoch 20/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
0892 - acc: 0.9795
```

```

Epoch 21/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
0627 - acc: 0.9910
Epoch 22/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.

0527 - acc: 0.9940
Epoch 23/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
0495 - acc: 0.9935
Epoch 24/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
0413 - acc: 0.9965
Epoch 25/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
0415 - acc: 0.9950
Epoch 26/32
2000/2000 [=====] - 12s 6ms/step - loss: 0.
0332 - acc: 0.9965
Epoch 27/32
2000/2000 [=====] - 13s 7ms/step - loss: 0.
0293 - acc: 0.9965
Epoch 28/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
0296 - acc: 0.9970
Epoch 29/32
2000/2000 [=====] - 13s 7ms/step - loss: 0.
0298 - acc: 0.9975
Epoch 30/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
0228 - acc: 0.9985
Epoch 31/32
2000/2000 [=====] - 13s 6ms/step - loss: 0.
0191 - acc: 0.9985
Epoch 32/32
2000/2000 [=====] - 13s 7ms/step - loss: 0.
0194 - acc: 0.9990

```

Out[154]: <keras.callbacks.History at 0x1850cb9ba8>

model.evaluate(X_test, Y_test)

```
In [160]: [X_test, Y_test] = generate_test_set_classification()
X_test = X_test.reshape(X_test.shape[0],1,72,72)
model_2.evaluate(X_test, Y_test)
```

Creating data:

0
10
20
30
40
50
60
70
80
90
100
110
120
130
140
150
160
170
180
190
200
210
220
230
240
250
260
270
280
290
300/300 [=====] - 1s 4ms/step

```
Out[160]: [0.26112047990163167, 0.92333333412806196]
```

In []:

5 A Regression Problem

```
In [161]: # generate training set, and reshape the data
[X_train, Y_train] = generate_dataset_regression(300, 20)
X_train = X_train.reshape(-1,1,72,72)
```

Creating data:

0
10
20
30
40
50
60
70
80
90
100
110
120
130
140
150
160
170
180
190
200
210
220
230
240
250
260
270
280
290

```
In [165]: Y_train[0]
```

```
Out[165]: array([ 0.71986584,  0.92000602,  0.31926686,  0.97619732,  0.565220
72,
                0.02423682])
```

```
In [169]: x = Y_train[0]

Y_train_norm=[]
for index in range(len(Y_train)):
    x = Y_train[index]
    xx = sorted([[x[2*i], x[2*i],x[2*i+1]] for i in range(3)])
    Y_train_norm.append([y for x in xx for y in x[1:]] )

Y_train_norm = np.array(Y_train_norm)
```

```
In [170]: model_3 = Sequential()

# input convolution layer
BatchNormalization(axis=1)
model_3.add(Convolution2D(16,(3,3),activation = 'relu',input_shape=(1,
model_3.add(MaxPooling2D(pool_size=(2, 2)))

BatchNormalization(axis=1)
model_3.add(Convolution2D(32,(3,3),activation = 'relu',padding = 'same
model_3.add(MaxPooling2D(pool_size = (2,2)))

BatchNormalization(axis=1)
model_3.add(Convolution2D(64,(3,3),activation = 'relu',padding = 'same
model_3.add(MaxPooling2D(pool_size = (2,2)))

BatchNormalization(axis=1)
model_3.add(Convolution2D(128,(3,3),activation = 'relu',padding = 'same
model_3.add(MaxPooling2D(pool_size = (2,2)))

#Flatten
model_3.add(Flatten())
BatchNormalization(axis=1)
model_3.add(Dense(units=200,activation = 'tanh'))
model_3.add(Dense(units=200,activation = 'tanh'))
model_3.add(Dense(units=6,activation='tanh'))
```

```
In [171]: #compile the model_3
model_3.compile(loss='mean_squared_error',optimizer = 'SGD',metrics =

# fit the model_3
model_3.fit(X_train, Y_train_norm, epochs=20, batch_size=50)

Epoch 1/20
300/300 [=====] - 3s 11ms/step - loss: 0.27
46 - acc: 0.4033
Epoch 2/20
300/300 [=====] - 2s 7ms/step - loss: 0.070
2 - acc: 0.4833
```

```
Epoch 3/20
300/300 [=====] - 2s 8ms/step - loss: 0.060
8 - acc: 0.4833
Epoch 4/20
300/300 [=====] - 2s 8ms/step - loss: 0.060
0 - acc: 0.4833
Epoch 5/20
300/300 [=====] - 2s 7ms/step - loss: 0.059
5 - acc: 0.4833
Epoch 6/20
300/300 [=====] - 2s 7ms/step - loss: 0.059
5 - acc: 0.4833
Epoch 7/20
300/300 [=====] - 3s 9ms/step - loss: 0.059
1 - acc: 0.4833
Epoch 8/20
300/300 [=====] - 3s 8ms/step - loss: 0.059
0 - acc: 0.4833
Epoch 9/20
300/300 [=====] - 3s 11ms/step - loss: 0.05
88 - acc: 0.4833
Epoch 10/20
300/300 [=====] - 2s 8ms/step - loss: 0.058
7 - acc: 0.4833
Epoch 11/20
300/300 [=====] - 2s 8ms/step - loss: 0.058
3 - acc: 0.4833
Epoch 12/20
300/300 [=====] - 2s 8ms/step - loss: 0.058
2 - acc: 0.4833
Epoch 13/20
300/300 [=====] - 3s 9ms/step - loss: 0.058
1 - acc: 0.4833
Epoch 14/20
300/300 [=====] - 3s 9ms/step - loss: 0.058
0 - acc: 0.4833
Epoch 15/20
300/300 [=====] - 2s 8ms/step - loss: 0.057
9 - acc: 0.4833
Epoch 16/20
300/300 [=====] - 2s 8ms/step - loss: 0.057
7 - acc: 0.4833
Epoch 17/20
300/300 [=====] - 3s 9ms/step - loss: 0.057
6 - acc: 0.4833
Epoch 18/20
300/300 [=====] - 2s 8ms/step - loss: 0.057
4 - acc: 0.4833
Epoch 19/20
300/300 [=====] - 3s 9ms/step - loss: 0.057
4 - acc: 0.4833
Epoch 20/20
300/300 [=====] - 3s 8ms/step - loss: 0.057
```


3 - acc: 0.4833

Out[171]: <keras.callbacks.History at 0x182ada3d30>

In [172]: *# this is a problem with the generate_dataset_regression function, which
#Therefore ,I use the generate_dataset_regression to generate the test*

```
[X_test, Y_test] = generate_dataset_regression(100,20)
print(X_test[0])
print(Y_test[0])
X_test = X_test.reshape(-1,1,72,72)

Y_test_norm=[]
for index in range(len(Y_test)):
    x = Y_test[index]
    xx = sorted([x[2*i],x[2*i+1]] for i in range(3))
    Y_test_norm.append([y for x in xx for y in x] )

Y_test_norm = np.array(Y_test_norm)
model_3.evaluate(X_test, Y_test_norm)
```

Creating data:

```
0
10
20
30
40
50
60
70
80
90
[ 0.9968872  0.95936457  0.97097937 ...,  0.96349031  0.93627219
  0.99993519]
[ 0.90433804  0.0996677  0.58621749  0.57567444  0.0282895  0.9292
 0882]
100/100 [=====] - 1s 8ms/step
```

Out[172]: [0.061105605661869046, 0.46000000000000002]

Bonus Question

In [173]: *# change the generate_a_* functions, each function will return two gra*

```
def generate_pari_rectangle(noise=0, free_location=False):
    figsize = 1.0
    U = np.zeros(4)
    V = np.zeros(4)
    if free_location:
        corners = np.random.random(4)
```

```

        top = max(corners[0], corners[1])
        bottom = min(corners[0], corners[1])
        left = min(corners[2], corners[3])
        right = max(corners[2], corners[3])
    else:
        side = (0.3 + 0.7 * np.random.random()) * figsize
        top = figsize/2 + side/2
        bottom = figsize/2 - side/2
        left = bottom
        right = top
    U[0] = U[1] = top
    U[2] = U[3] = bottom
    V[0] = V[3] = left
    V[1] = V[2] = right
    return generate_a_drawing(figsize, U, V, noise=50), generate_a_drawing(figsize, U, V, noise=50)

def generate_pair_disk(noise=0.0, free_location=False):
    figsize = 1.0
    if free_location:
        center = np.random.random(2)
    else:
        center = (figsize/2, figsize/2)
    radius = (0.3 + 0.7 * np.random.random()) * figsize/2
    N = 50
    U = np.zeros(N)
    V = np.zeros(N)
    i = 0
    for t in np.linspace(0, 2*np.pi, N):
        U[i] = center[0] + np.cos(t) * radius
        V[i] = center[1] + np.sin(t) * radius
        i = i + 1
    return generate_a_drawing(figsize, U, V, noise=50), generate_a_drawing(figsize, U, V, noise=50)

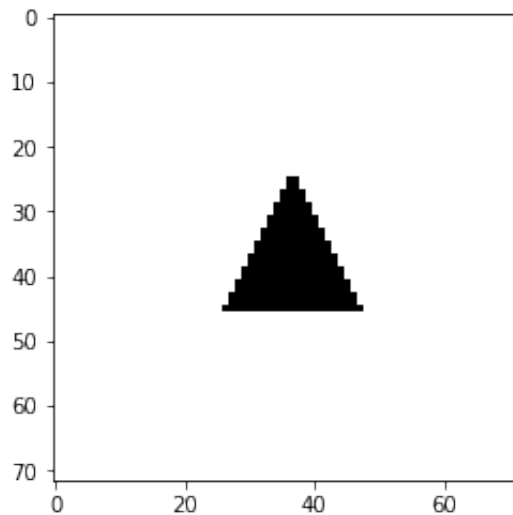
def generate_pair_triangle(noise=0.0, free_location=False):
    figsize = 1.0
    if free_location:
        U = np.random.random(3)
        V = np.random.random(3)
    else:
        size = (0.3 + 0.7 * np.random.random()) * figsize/2
        middle = figsize/2
        U = (middle, middle+size, middle-size)
        V = (middle+size, middle-size, middle-size)
    imdata = generate_a_drawing(figsize, U, V, noise=50), generate_a_drawing(figsize, U, V, noise=50)
    return imdata

```

```
In [174]: # use the generate_pair_triangle to show a pair smaple
[im,im_2] = generate_pair_triangle()

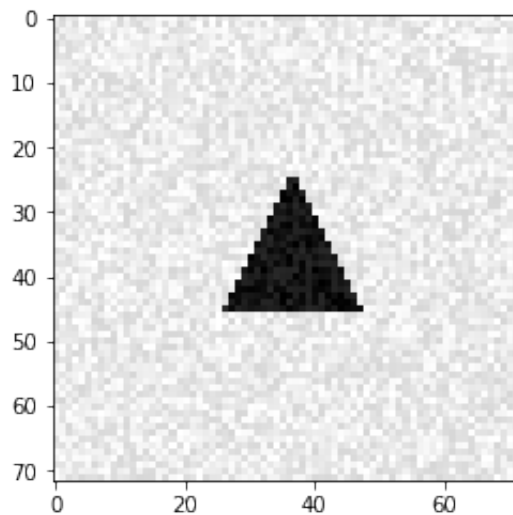
plt.imshow(im_2.reshape(72,72), cmap='gray')
```

Out[174]: <matplotlib.image.AxesImage at 0x186acb2c18>



```
In [175]: plt.imshow(im.reshape(72,72), cmap='gray')
```

Out[175]: <matplotlib.image.AxesImage at 0x1856b35eb8>



In [183]: *# redefine this function, to generate a X_train set (graph with noise*

```
def generate_dataset_denosing(nb_samples, free_location=False):
    X_train=[]
    Y_train=[]
    print('Creating data:')
    for i in range(nb_samples):
        category = np.random.randint(1,3)
        if category == 0:
            [ima_1,ima_2]=generate_pair_rectangle()
            a = ima_1
            b= ima_2
        elif category == 1:
            [ima_1,ima_2] = generate_pair_disk()
            a = ima_1
            b = ima_2

        else:
            [ima_1,ima_2] = generate_pair_triangle()
            a = ima_1
            b = ima_2
        X_train.append(a)
        Y_train.append(b)
    print ('Data Created')
    return X_train,Y_train
```

In [184]: *# generate the training data, and reshape the data*
[X_train,Y_train] = generate_dataset_denosing(300)
X_train = np.reshape(X_train,(300,72,72,1))
Y_train = np.reshape(Y_train,(300,72,72,1))

Creating data:
Data Created

In [185]: *# build a U-Net Model*

```
def get_crop_shape(target, refer):

    cw = (target.get_shape()[2] - refer.get_shape()[2]).value
    assert (cw >= 0)
    if cw % 2 != 0:
        cw1, cw2 = int(cw/2), int(cw/2) + 1
    else:
        cw1, cw2 = int(cw/2), int(cw/2)
    ch = (target.get_shape()[1] - refer.get_shape()[1]).value
    assert (ch >= 0)
    if ch % 2 != 0:
        ch1, ch2 = int(ch/2), int(ch/2) + 1
    else:
        ch1, ch2 = int(ch/2), int(ch/2)
    return (ch1, ch2), (cw1, cw2)

concat_axis = 3
inputs = Input((72, 72, 1))
```

```

inputs = Input((4, 4, 1))

conv1 = layers.Conv2D(32, (3, 3), activation='relu', padding='same')(inputs)
pool1 = layers.MaxPooling2D(pool_size=(2, 2))(conv1)
conv2 = layers.Conv2D(64, (3, 3), padding="same", activation="relu")(pool1)
pool2 = layers.MaxPooling2D(pool_size=(2, 2))(conv2)
conv3 = layers.Conv2D(32, (3, 3), activation='relu', padding='same')(pool2)
pool3 = layers.MaxPooling2D(pool_size=(2, 2))(conv3)
conv4 = layers.Conv2D(128, (3, 3), padding="same", activation="relu")(pool3)
pool4 = layers.MaxPooling2D(pool_size=(2, 2))(conv4)
conv5 = layers.Conv2D(32, (3, 3), activation='relu', padding='same')(pool4)

up_conv5 = layers.UpSampling2D(size=(2, 2))(conv5)
ch, cw = get_crop_shape(conv4, up_conv5)
crop_conv4 = layers.Cropping2D(cropping=(ch, cw))(conv4)

up6 = layers.concatenate([up_conv5, crop_conv4], axis=concat_axis)
conv6 = layers.Conv2D(256, (3, 3), padding="same", activation="sigmoid", data_format="channels_last")(up6)
up_conv6 = layers.UpSampling2D(size=(2, 2), data_format="channels_last")(conv6)
ch, cw = get_crop_shape(conv3, up_conv6)
crop_conv3 = layers.Cropping2D(cropping=(ch, cw), data_format="channels_last")(conv3)

up7 = layers.concatenate([up_conv6, crop_conv3], axis=concat_axis)
conv7 = layers.Conv2D(128, (3, 3), padding="same", activation="sigmoid", data_format="channels_last")(up7)
up_conv7 = layers.UpSampling2D(size=(2, 2), data_format="channels_last")(conv7)
ch, cw = get_crop_shape(conv2, up_conv7)
crop_conv2 = layers.Cropping2D(cropping=(ch, cw), data_format="channels_last")(conv2)

up8 = layers.concatenate([up_conv7, crop_conv2], axis=concat_axis)
conv8 = layers.Conv2D(64, (3, 3), padding="same", activation="sigmoid", data_format="channels_last")(up8)
up_conv8 = layers.UpSampling2D(size=(2, 2))(conv8)
ch, cw = get_crop_shape(conv1, up_conv8)
crop_conv1 = layers.Cropping2D(cropping=(ch, cw))(conv1)

up9 = layers.concatenate([up_conv8, crop_conv1], axis=concat_axis)
conv9 = layers.Conv2D(32, (3, 3), activation='sigmoid', padding='same')(up9)
ch, cw = get_crop_shape(inputs, conv9)
conv9 = layers.ZeroPadding2D(padding=((ch[0], ch[1]), (cw[0], cw[1])))(conv9)
conv10 = layers.Conv2D(1, (1, 1))(conv9)

#flatten = Flatten()(conv10)
model_4 = Model(input=inputs, output=conv10)
model_4.compile(loss='mean_squared_error', optimizer='rmsprop', metrics=['accuracy'])

```

/anaconda3/lib/python3.6/site-packages/ipykernel_launcher.py:65: Use
rWarning: Update your `Model` call to the Keras 2 API: `Model(inputs

```
=Tensor("in...", outputs=Tensor("co..."))`
```

```
In [186]: model_4.fit(X_train,Y_train,epochs=20, batch_size=32)
```

```
Epoch 1/20
300/300 [=====] - 30s 102ms/step - loss: 52
151.3580 - acc: 0.0684
Epoch 2/20
300/300 [=====] - 28s 93ms/step - loss: 519
90.0401 - acc: 0.0588
Epoch 3/20
300/300 [=====] - 29s 95ms/step - loss: 519
65.5042 - acc: 0.1685
Epoch 4/20
300/300 [=====] - 27s 89ms/step - loss: 519
42.7035 - acc: 0.1878
Epoch 5/20
300/300 [=====] - 25s 83ms/step - loss: 519
20.2876 - acc: 0.1905
Epoch 6/20
300/300 [=====] - 24s 79ms/step - loss: 518
97.9852 - acc: 0.1945
Epoch 7/20
300/300 [=====] - 24s 79ms/step - loss: 518
75.8240 - acc: 0.1962
Epoch 8/20
300/300 [=====] - 24s 78ms/step - loss: 518
53.8347 - acc: 0.1966
Epoch 9/20
300/300 [=====] - 24s 80ms/step - loss: 518
23.8266 - acc: 0.1970
Epoch 10/20
300/300 [=====] - 24s 80ms/step - loss: 517
97.4738 - acc: 0.1971
Epoch 11/20
300/300 [=====] - 23s 77ms/step - loss: 517
72.5152 - acc: 0.1971
Epoch 12/20
300/300 [=====] - 24s 79ms/step - loss: 517
47.3055 - acc: 0.1971
Epoch 13/20
300/300 [=====] - 25s 83ms/step - loss: 517
22.0333 - acc: 0.1971
Epoch 14/20
300/300 [=====] - 24s 80ms/step - loss: 516
96.4715 - acc: 0.1968
Epoch 15/20
300/300 [=====] - 23s 78ms/step - loss: 516
71.3779 - acc: 0.1971
Epoch 16/20
300/300 [=====] - 24s 78ms/step - loss: 516
46.4246 - acc: 0.1971
Epoch 17/20
```

```

300/300 [=====] - 24s 80ms/step - loss: 516
21.4936 - acc: 0.1969
Epoch 18/20
300/300 [=====] - 23s 78ms/step - loss: 515
96.5389 - acc: 0.1971
Epoch 19/20
300/300 [=====] - 23s 78ms/step - loss: 515
71.7388 - acc: 0.1971
Epoch 20/20
300/300 [=====] - 24s 79ms/step - loss: 515
46.5883 - acc: 0.1971

```

Out[186]: <keras.callbacks.History at 0x1838b29f98>

```

In [187]: [X_test,Y_test] = generate_dataset_denosing(100)
X_test = np.reshape(X_test,(100,72,72,1))
Y_test = np.reshape(Y_test,(100,72,72,1))
model_4.evaluate(X_test, Y_test)

```

```

Creating data:
Data Created
100/100 [=====] - 4s 39ms/step

```

Out[187]: [52317.851718749997, 0.18424768805503844]

```

In [188]: model_4.predict(X_test[0])

```

```

-----
-----
AttributeError                                Traceback (most recent call last)
<ipython-input-188-9a4b4aa4b3cf> in <module>()
----> 1 model_4.predict(X_test[0])

AttributeError: 'Model' object has no attribute 'predict'

```

In []: