

* Algorithm for Working of Vacuum Cleaner:-

- Considering 2 rooms for cleaning
- Also making sure vacuum cleaner comes to initial state after doing its work
- location and status considering two precepts
- Now,

1 → represents a dirty room

0 → represents a clean room

- Vacuum cleaner working in 2-d grid, so it can move left, Right, Up and down.

```
def is_dirty():
```

```
    return self.rooms[self.position] == 1
```

```
def clean():
```

```
    if self.is_dirty():
```

```
        self.rooms[self.position] = 0
```

```
        self.cleaned_rooms += 1
```

```
def move():
```

```
    self.position = 1 - self.position
```

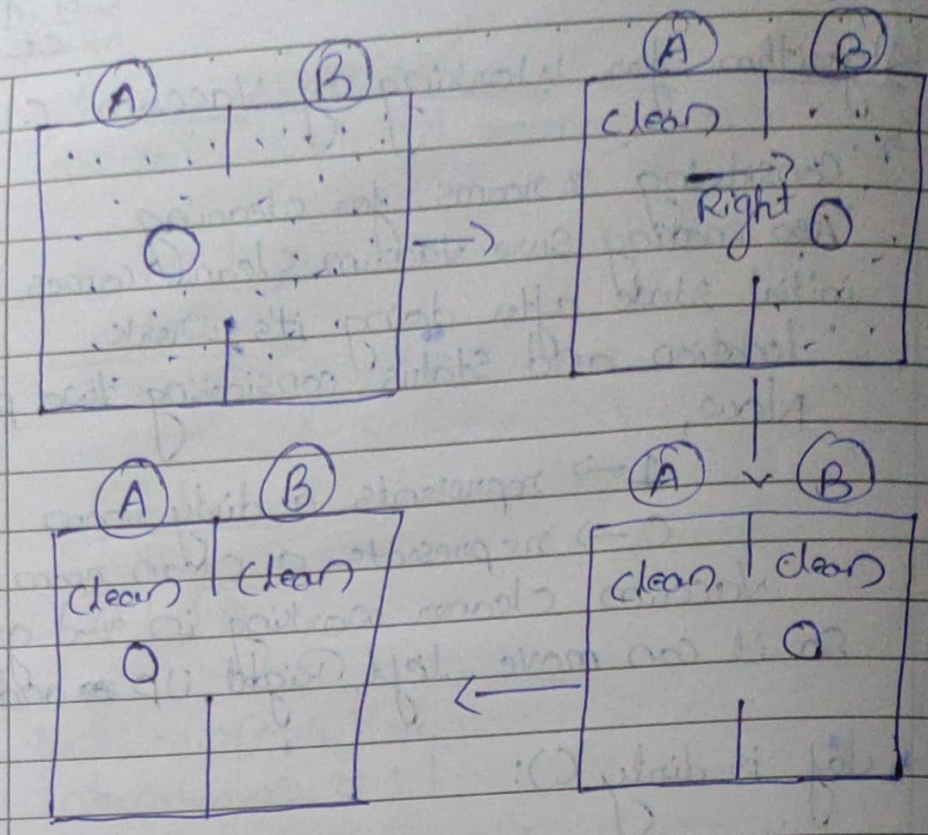
```
def run(steps):
```

```
    for step in range(steps):
```

```
        clean()
```

```
        move()
```

```
rooms = [1, 0]
```

=> Percept Sequence

check: Room A, Dirty

Action: Clean Room A & move

check: Room B, Dirty

Action: clean Room B & move

I: -> (Room 1, Dirty)

II: -> (Room 2, clean)

III: -> (Room 1, clean)

IV: -> (Room 2, clean)

V: -> (Room 1, clean)

// program Code

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```
class VacuumCleaner:
```

```
    def __init__(self, rooms, start_position):
```

```
        self.rooms = rooms
```

```
        self.position = start_position
```

```
        self.cleaned_rooms = 0
```

```
        self.percept_sequence = []
```

```
    def is_dirty(self):
```

```
        return self.rooms[self.position] == 1
```

```
    def clean(self):
```

```
        if self.is_dirty():
```

```
            print(f"Cleaning room {self.position+1}")
```

```
            self.rooms[self.position] = 0
```

```
            self.cleaned_rooms += 1
```

```
    def move(self):
```

```
        if self.position < len(self.rooms) - 1:
```

```
            self.position += 1
```

```
        else
```

```
            self.position = 0
```

```
            print(f"Moved to room {self.position+1}")
```

```
    def perceive(self):
```

```
        room_state = "Dirty" if self.is_dirty()
```



```

else "clean"
percept = (f"Room {self.position+1}", room.status)
self.percept_sequence.append(percept)
print(f"perception: {percept}")

```

```

def run(self, steps):
    for step in range(steps):
        print(f"step {step+1}:")
        self.perceive()
        self.clean()
        self.move()
        print(f"rooms status: {self.rooms}")

```

```

print(f"Total cleaned rooms: {self.cleaned_rooms}")
print(f"percept sequence: {self.percept_sequence}")

```

```
rooms = [1, 0, 1, 1]
```

```
vacuum.run(steps=8)
```

⇒ Output :-

Step 1:
Perception: ('Room 1', 'Dirty')

Step 1:
Perception: ('Room 1', 'Clean')

moved to room 2

Step 2:

Perception: ('Room 2', 'Dirty')

Cleaning room 2

Moved to room 3

Step 3:

Perception: ('Room 3', 'Dirty')

Cleaning room 3

Moved to room 4

Step 4:

Perception: ('Room 4', 'Dirty')

Cleaning room 4

Moved to room 1

Step 5:

Perception: ('Room 1', 'Clean')

Moved to room 2

Step 6:

Perception: ('Room 2', 'Clean')

Moved to Room 3

Step 7:

Perception: ('Room 3', 'Clean')

Moved to Room 4

Step 8:

Perception: ('Room 4', 'Clean')

Moved to room 1

Total cleaned rooms: 3

Recapt Sequence: ['Room', 'Clean'],
 ['Room2', 'Dirty'],
 ['Room3', 'Dirty'],
 ['Room4', 'Dirty'],
 ['Room1', 'Clean'],
 ['Room2', 'Clean'],
 ['Room3', 'Clean'],
 ['Room4', 'Clean'] //

Sub B
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