### **EXPERIMENT – 01**

**AIM:** TO STUDY AND EXECUTE COMMANDS IN UNIX.

### FILE RELATED COMMANDS:

1. PWD COMMAND: Prints the current working directory path.

2. CD COMMAND: Changes the current working directory.

```
__(praveen⊛ kali)-[~]

$ cd Desktop
```

3. LS COMMAND: Lists files and directories in the current directory.

```
(praveen® kali)-[~/Desktop]
$ ls -l
total 16
drwxr-xr-x 2 praveen praveen 4096 Sep 29 10:06 CET
-rwxr-xr-x 1 praveen praveen 558 Oct 4 2023 project_01_information_gathering_tool.py
-rwxr-xr-x 1 praveen praveen 1202 Oct 4 2023 project_02_network_and_port_scanner.py
-rwxr-xr-x 1 praveen praveen 328 Oct 6 2023 project_02_port_scanner.py
```

**4. RM COMMAND**: Removes files from the current directory.

```
__(praveen⊕ kali)-[~]

$ rm short.py
```

**5.** MV COMMAND: Moves or renames files or directories.

```
(praveen® kali)-[~]
$ mv cbit Desktop

(praveen® kali)-[~]
$ cd Desktop

(praveen® kali)-[~/Desktop]
$ ls -l
total 20
drwxr-xr-x 2 praveen praveen 4096 Sep 29 10:06 CET
drwxr-xr-x 2 praveen praveen 4096 Sep 29 10:11 cbit
-rwxr-xr-x 1 praveen praveen 558 Oct 4 2023 project_01_information_gathering_tool.py
-rwxr-xr-x 1 praveen praveen 1202 Oct 4 2023 project_02_network_and_port_scanner.py
-rwxr-xr-x 1 praveen praveen 328 Oct 6 2023 project_02_port_scanner.py
```

**6. CAT COMMAND**: Concatenates and displays the contents of files.

7. CMP COMMAND: Compares two files byte by byte.

```
___(praveen⊕ kali)-[~/Desktop]

$ cmp hello.txt

cmp OS.txt

hello.txt - differ: byte 1, line 1
```

**8. CP COMMAND:** Copies files or directories.

```
____(praveen⊛ kali)-[~/Desktop]

$ cp Os.txt OS1.txt
```

**9. ECHO COMMAND**: Displays a string of text on the terminal.

```
___(praveen⊕ kali)-[~/Desktop]

$\square$ echo "Hello"

Hello
```

**10. MKDIR COMMAND**: Creates a new directory.

```
___(praveen⊕ kali)-[~/Desktop]

$ mkdir sys.py
```

11. PASTE COMMAND: Merges lines of multiple files.

12. RMDIR COMMAND: Removes empty directories.

```
___(praveen⊛ kali)-[~/Desktop]

$\text{rmdir sys.py}
```

**13. HEAD COMMAND**: Displays the first part of a file.

```
(praveen® kali)-[~/Desktop]

$ head states.txt

Andhra Pradesh

Arunachal Pradesh

Assam

Bihar

Chhattisgarh

Goa

Gujarat

Haryana

Himachal Pradesh

Jammu and Kashmir
```

**14. TAIL COMMAND**: Displays the last part of a file.

```
(praveen® kali)-[~/Desktop]
$ tail states.txt
Odisha
Punjab
Rajasthan
Sikkim
Tamil Nadu
Telangana
Tripura
Uttar Pradesh
Uttarakhand
West Bengal
```

**15. DATE COMMAND**: Displays or sets the system date and time.

```
___(praveen® kali)-[~/Desktop]

$ date

Sun Sep 29 11:06:25 IST 2024
```

**16. GREP COMMAND**: Searches for patterns in files.

```
(praveen⊕ kali)-[~/Desktop]

$ grep "operating" OS1.txt

An operating system brings powerful benefits to computer software and software development. Without an operating system, every application functionality of the underlying computer, such as disk storage, network interfaces and so on. Considering the vast array of underlying he impractical.

As long as each application accesses the same resources and services in the same way, that system software -- the operating system -- can do to develop and debug an application, while ensuring that users can control, configure and manage the system hardware through a common state.
```

17. TOUCH COMMAND: Changes file timestamps or creates an empty file.

```
___(praveen⊛ kali)-[~/Desktop]
$ touch OS1.txt
```

18. CHMOD COMMAND: Changes file permissions.

```
___(praveen⊛ kali)-[~/Desktop]
$ chmod 755 OS1.txt
```

19. MAN COMMAND: Displays the manual pages for commands.

```
-(praveen⊛kali)-[~/Desktop]
    .$ man ls
LS(1)
      ls - list directory contents
  NOPSIS
ls [<u>OPTION</u>]...[<u>FILE</u>]...
 SCRIPTION

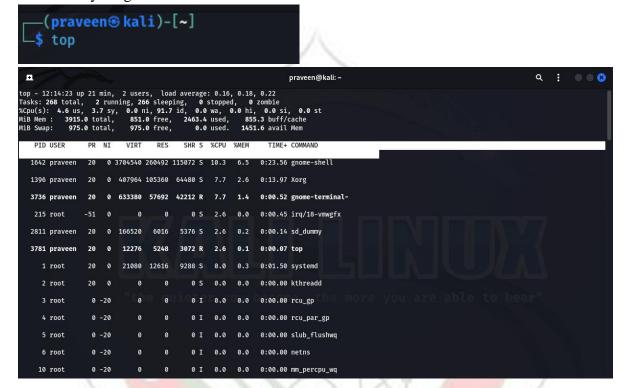
List information about the FILEs (the current directory by default). Sort entries alphabetically if none of -cftuvSUX nor --sort is specified.
      Mandatory arguments to long options are mandatory for short options too.
      -a, --all
do not ignore entries starting with .
      -A, --almost-all do not list implied . and ..
       --author
with -l, print the author of each file
           --escape
print C-style escapes for nongraphic characters
       --block-size=<u>SIZE</u>
with -l, scale sizes by SIZE when printing them; e.g., '--block-size=M'; see SIZE format below
             with -lt: sort by, and show, ctime (time of last modification of file status information); with -l: show ctime and sort by name; otherwise: sort by ctime, newest first
             list entries by columns
       --color[=<u>WHEN]</u>
color the output WHEN; more info below
           --directory
list directories themselves, not their contents
           --dired
generate output designed for Emacs' dired mode
            list all entries in directory order
       -F, --classify[=<u>WHEN]</u>
page ls(1) line 1 (press h for help or q to quit)
                                                           ಯಾರ ಆಜ್ಞನ್ಗಳ ಭಾವ
```

20. CLEAR COMMAND: Clears the terminal screen.

```
บบ:บบ:บบ [kworker/2:3H-ttm]
            53/1
                          0 13:43 ?
                    2 0 13:43 ?
2 0 13:44 ?
1299 3 13:44 ?
                                             00:00:00 [kworker/2:4H-ttm]
root
            5372
                                            00:00:00 [kworker/1:2-ata_sff
root
            5373
                                             00:00:01 /usr/bin/eog /home/p
            5378
praveen
                                             00:00:00 [kworker/u6:3-events
            5405
                          0 13:44 ?
root
                                             00:00:00 ps -ef
praveen
            5416
                     4144 0 13:44 pts/0
  —(praveen⊛ kali)-[~]
 _$ clear
```

### **PROCESS RELATED COMMANDS:**

 TOP COMMAND: Displays a real-time view of active processes, including CPU and memory usage.



2. PS COMMAND: Shows a snapshot of the current processes in the system.

**ps:** Displays processes running in the current shell.

```
(praveen⊛ kali)-[~]

$ ps
PID TTY TIME CMD
4144 pts/0 00:00:00 zsh
4163 pts/0 00:00:00 ps
```

**ps -aux:** Shows detailed information about all processes for all users.

```
PID %CPU %MEM
1 0.1 0.3
2 0.0 0.0
                                                    VSZ RSS T
21080 12616 ?
                                                                                                                    TIME COMMAND
0:01 /sbin/init sp
0:00 [kthreadd]
USER
                                                                 RSS TTY
                                                                                            STAT START
                                                                                                     11:53
root
                                                                                            Ss
                                                                                                     11:53
                                                                                                                    0:00 [rcu_gp]
0:00 [rcu_par_gp]
0:00 [slub_flushwq
                                0.0 0.0
0.0 0.0
                                                                                                     11:53
11:53
                                                                       0 2
                                                                                            I<
root
                                0.0
0.0
                                         0.0
                                                                                            I<
I<
                                                                                                     11:53
11:53
                                                                                                                    0:00
root
                                          0.0
                                                                                                                              [netns]
                                0.0
0.0
0.0
                                                                      0 ?
0 ?
                         10
11
12
13
14
15
16
17
19
20
21
22
23
26
27
 root
                                                                                                                               [mm_percpu_wq
                                                                                                                              [rcu_tasks_kt
[rcu_tasks_ru
root
root
                                          0.0
                                                                                                     11:53
11:53
                                                                                                                    0:00
                                                                                                                    0:00
                                          0.0
                                0.0
0.0
0.0
                                                                                                                              [rcu_tasks_tr
[ksoftirqd/0]
root
                                          0.0
                                                                                                                    0:00
root
                                                                                                     11:53
                                                                                                                    0:00
                                                                                                                              [rcu_preempt]
[migration/0]
[idle_inject/
                                                                                                     11:53
                                                                                                                    0:00
                                                                                                     11:53
11:53
                                0.0
0.0
root
                                          0.0
                                                                                                                    0:00
                                                                                                                    0:00
 root
                                                                                                                   0:00 [ldle_inject/

0:00 [cpuhp/0]

0:00 [cpuhp/1]

0:00 [idle_inject/

0:00 [softired/1]

0:00 [softired/1]

0:00 [cpuhp/2]
                                                                                                     11:53
11:53
                                0.0
                                          0.0
                                0.0
                                                                      0 ?
0 ?
0 ?
                                0.0
                                0.0
                                          0.0
                                                                                                     11:53
root
                                0.0
0.0
                                          0.0
                                                                                                     11:53
root
                                                                                                                    0:00 [migration/2]
```

**ps -ef:** Lists all processes in a detailed format with additional fields.

```
-(praveen⊛kali)-[~]
 -$ ps -ef
UID
              PID
                     PPID
                           C STIME TTY
                                                  TIME CMD
                                              00:00:02 /sbin/init splash
                           0 12:40 ?
root
                1
                        0
                2
                                              00:00:00 [kthreadd]
root
                        0
                           0 12:40 ?
                3
                                              00:00:00 [rcu_gp]
root
                        2
                           0 12:40 ?
                        2
                                              00:00:00 [rcu_par_gp]
root
                           0 12:40 ?
                5
                        2
                                              00:00:00 [slub_flushwq]
                           0 12:40 ?
root
```

3. KILL COMMAND: Sends a signal to terminate or control a process. SIGKILL (-9): Forcefully terminates a process without cleanup.

```
__(praveen⊗ kali)-[~]

$ kill -9 1234
```

**SIGTERM** (-15): Gracefully terminates a process, allowing cleanup.

**4. NICE COMMAND:** Starts a process with a modified priority (niceness value), where a higher value reduces its priority.

```
(praveen⊕ kali)-[~]

$ <u>nice</u> -n 10 <u>project1.py</u>

nice: 'project1.py': No such file or directory
```

### **NETWORK RELATED COMMANDS:**

**1. PING COMMAND**: Tests network connectivity by sending ICMP echo requests and measuring response times.

```
-(praveen⊛kali)-[~]
 -$ ping facebook.com
PING facebook.com (163.70.140.35) 56(84) bytes of data.
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=1 ttl=55 time=5.14 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=2 ttl=55 time=6.13 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=3 ttl=55 time=9.49 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=4 ttl=55 time=4.58 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=5 ttl=55 time=5.72 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=6 ttl=55 time=4.70 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=7 ttl=55 time=4.66 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=8 ttl=55 time=9.09 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=9 ttl=55 time=20.7 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=10 ttl=55 time=9.53 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=11 ttl=55 time=5.39 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=12 ttl=55 time=7.05 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=13 ttl=55 time=8.11 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=14 ttl=55 time=6.01 ms
64 bytes from edge-star-mini-shv-01-hyd1.facebook.com (163.70.140.35): icmp_seq=15 ttl=55 time=6.89 ms
```

2. **IFCONFIG COMMAND**: Displays and configures network interface parameters on a system.

```
-(praveen⊛kali)-[~]
eth0: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
        inet 192.168.1.8 netmask 255.255.255.0 broadcast 192.168.1.255
        inet6 fe80::a00:27ff:fec7:b004 prefixlen 64 scopeid 0x20<link>
        ether 08:00:27:c7:b0:04 txqueuelen 1000 (Ethernet)
        RX packets 23672 bytes 21730678 (20.7 MiB)
        RX errors 0 dropped 0 overruns 0 frame 0 TX packets 13771 bytes 4784402 (4.5 MiB)
        TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
lo: flags=73<UP,LOOPBACK,RUNNING> mtu 65536
        inet 127.0.0.1 netmask 255.0.0.0
        inet6 ::1 prefixlen 128 scopeid 0x10<host>
        loop txqueuelen 1000 (Local Loopback)
        RX packets 26 bytes 1540 (1.5 KiB)
        RX errors 0 dropped 0 overruns 0 frame 0
        TX packets 26 bytes 1540 (1.5 KiB)
        TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
```

**3. NETSTAT COMMAND**: Displays active network connections, routing tables, and interface statistics.

```
-(praveen⊛kali)-[~]
 _$ netstat -at
Active Internet connections (servers and established)
Proto Recv-Q Send-Q Local Address
                                             Foreign Address
                                                                     State
                  0 kali.bbrouter:37510
           0
                                            a23-65-124-99.dep:https ESTABLISHED
           0
                  0 kali.bbrouter:53800
                                            93.243.107.34.bc.:https ESTABLISHED
tcp
                  0 kali.bbrouter:47482
                                            bom12s21-in-f5.1e:https ESTABLISHED
tcp
           0
                  0 kali.bbrouter:60488
                                            bom12s20-in-f10.1:https ESTABLISHED
tcp
```

**4. NSLOOKUP COMMAND**: Queries DNS to retrieve domain name and IP address information.

```
(praveen® kali)-[~]

$ nslookup www.cbit.ac.in
Server: 192.168.1.1
Address: 192.168.1.1#53

Non-authoritative answer:
Name: www.cbit.ac.in
Address: 3.111.165.12
```

**5. TELNET COMMAND**: Establishes a connection to a remote server for communication or testing routes.

```
(praveen® kali)-[~]
$ telnet google.com 80
Trying 142.251.42.46...
Connected to google.com.
Escape character is '^]'.
```

**6. TRACEROUTE COMMAND**: Traces the path packets take to reach a network host, showing each hop.

```
(praveen® kali)-[~]
$ traceroute facebook.com
traceroute to facebook.com (163.70.140.35), 30 hops max, 60 byte packets
1 EARTH-1010.bbrouter (192.168.1.1) 7.475 ms 7.430 ms 7.412 ms
2 103.44.2.93 (103.44.2.93) 7.590 ms 7.698 ms 7.681 ms
3 * * *
4 * * *
5 * * *
6 ae1.pr02.hyd1.tfbnw.net (157.240.82.174) 9.853 ms 4.302 ms 4.257 ms
7 po202.asw04.hyd1.tfbnw.net (129.134.96.248) 4.232 ms 4.213 ms po202.asw01.hyd1.tfbnw.net
8 psw01.hyd1.tfbnw.net (129.134.115.158) 4.178 ms psw04.hyd1.tfbnw.net (129.134.115.155) 4
9 157.240.38.83 (157.240.38.83) 7.156 ms 173.252.67.165 (173.252.67.165) 7.103 ms 173.252.67
```

# STUDY ABOUT UNIX VI EDITORS AND ITS FEATURES

### **DESCRIPTION:**

The **vi editor** is a powerful text editor that comes pre-installed on most UNIX and Linux systems. It is used primarily for editing plain text files and is known for being lightweight and efficient. The **vi** editor operates in three different modes, which make it versatile for various text manipulation tasks:

### **MODES OF VI EDITOR:**

- 1. Command Mode: This is the default mode when vi is launched. It allows the user to navigate within the file, delete text, copy and paste, and switch to other modes.
- 2. Insert Mode: In this mode, users can input or edit text. It can be accessed from command mode by pressing i, I, a, A, etc.
- **3.** Last Line Mode (Ex Mode): This mode is used to execute more complex commands, such as saving the file, quitting the editor, searching, and performing other file operations. It is accessed by typing: in command mode.

### **KEY FEATURES OF VI EDITOR:**

- 1. Lightweight and Fast: vi is a very lightweight editor, making it efficient even on older systems.
- 2. Cross-Platform: Works on a wide range of UNIX-based systems and Linux distributions.
- **3.** No GUI Required: vi is a terminal-based editor, making it useful for servers or environments without a graphical user interface (GUI).
- **4. Syntax Highlighting**: In modern versions, such as vim (an extended version of vi), syntax highlighting is available for easier code editing.
- **5. Search and Replace**: vi offers powerful search (/searchterm) and replace (:%s/old/new/g) capabilities across files.
- **6. Multiple Buffers**: vi supports editing multiple files simultaneously by using buffers, allowing users to switch between them.

### **EXPERIMENT - 02**

<u>AIM:</u> DEMONSTARTION OF FILE RELATED SYSTEM CALLS SUCH AS CREATE, OPEN, CLOSE, READ, WRITE, LSEEK.

### **DESCRIPTION:**

- 1. Create: Creates a new file with the specified name. If the file exists, it will be truncated.
  - Syntax: int creat(const char \*pathname, mode\_t mode);
  - Parameters:
    - o pathname: The name (path) of the file to be created.
    - o mode: The file permissions (e.g., read, write, execute) for the new file.
  - **Return**: Returns a file descriptor on success or -1 on failure.
- **2. Open:** Opens an existing file and returns a file descriptor for subsequent operations.
  - **Syntax**: int open(const char \*pathname, int flags, mode\_t mode);
  - Parameters:
    - o pathname: The name (path) of the file to be opened.
    - o flags: Specifies how the file is to be opened (e.g., O\_RDONLY for read-only, O\_WRONLY for write-only).
    - o mode: File permissions (used only when creating a new file).
  - Return: Returns a file descriptor on success or -1 on failure.
- 3. Close: Closes an open file descriptor, freeing associated system resources.
  - Syntax: int close(int fd);
  - Parameters:
    - o fd: The file descriptor of the file to close.
  - **Return**: Returns 0 on success or -1 on failure.
- **4. Read:** Reads data from a file descriptor into a buffer in memory.
  - **Syntax**: ssize t read(int fd, void \*buf, size t count);
  - Parameters:
    - o fd: The file descriptor from which to read.
    - o buf: A buffer to store the data being read.
    - o count: The number of bytes to read.
  - **Return**: Returns the number of bytes read or -1 on failure.
- **5. Write:** Writes data from a buffer in memory to a file.
  - **Syntax**: ssize\_t write(int fd, const void \*buf, size\_t count);
  - Parameters:
    - o fd: The file descriptor to which to write.
    - o buf: A buffer containing the data to be written.
    - o count: The number of bytes to write.
  - **Return**: Returns the number of bytes written or -1 on failure.

- **6. Lseek:** Changes the current file offset (position) for reading or writing.
  - **Syntax**: off\_t lseek(int fd, off\_t offset, int whence);
  - Parameters:
    - o fd: The file descriptor of the file to reposition.
    - o offset: The new position relative to the location specified by whence.
    - whence: Specifies the reference point for the offset (e.g., SEEK\_SET, SEEK\_CUR, SEEK\_END).
  - **Return**: Returns the new file offset or -1 on failure.

### **PROGRAMS:**

**Program 1:** WAP to copy the content from one file to another without deleting the content of second file.

#### CODE:

```
#include <sys/types.h>
#include <sys/stat.h>
#include <fcntl.h>
#include <unistd.h>
#include <stdio.h>

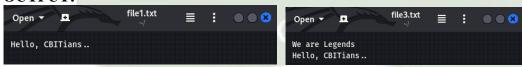
void main() {
   char b[100];

   int fd = open("file1.txt", O_RDONLY);
   int fd1 = open("file3.txt", O_WRONLY | O_APPEND);

   int n = read(fd, b, 100);

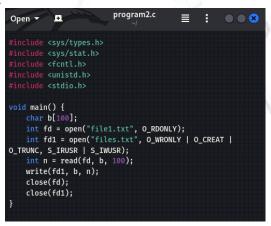
   write(fd1, b, n);
   close(fd);
   close(fd1);
}
```

#### **OUTPUT:**



**Program 2:** WAP to read from one file and write into another file.

#### **CODE:**





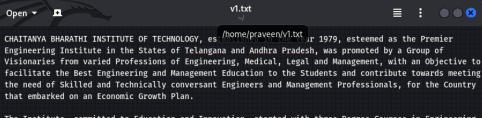
#### **OUTPUT:**



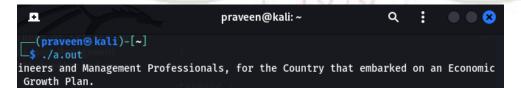
**Program 5:** WAP to print second half of the file.

### **CODE:**

#### **OUTPUT:**



The Institute, committed to Education and Innovation, started with three-Degree Courses in Engineering for 200 Students and over the 45 Years, has emerged as a Dream Destination for; Students seeking to excel in Engineering and Management Education, Teaching Community to progress with a rewarding Career and Corporates to source well-rounded Engineers.



The Institute, committed to Education and Innovation, started with three-Degree C ourses in Engineering for 200 Students and over the 45 Years, has emerged as a Dr eam Destination for; Students seeking to excel in Engineering and Management Educ ation, Teaching Community to progress with a rewarding Career and Corporates to s ource well-rounded Engineers.

**Program 6:** WAP to print characters from 10<sup>th</sup> to 20<sup>th</sup> position of a file.

### **CODE:**

### **OUTPUT:**

CHAITANYA BHARATHI INSTITUTE OF TECHNOLOGY, es home/praveen/Vl.txt r 1979, esteemed as the Premier Engineering Institute in the States of Telangana and Andhra Pradesh, was promoted by a Group of Visionaries from varied Professions of Engineering, Medical, Legal and Management, with an Objective to facilitate the Best Engineering and Management Education to the Students and contribute towards meeting the need of Skilled and Technically conversant Engineers and Management Professionals, for the Country that embarked on an Economic Growth Plan.

The Institute, committed to Education and Innovation, started with three-Degree Courses in Engineering for 200 Students and over the 45 Years, has emerged as a Dream Destination for; Students seeking to excel in Engineering and Management Education, Teaching Community to progress with a rewarding Career and Corporates to source well-rounded Engineers.

```
(praveen⊕ kali)-[~]
$ cc program6.c

(praveen⊕ kali)-[~]
$ ./a.out
BHARATHI
```



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### **EXPERIMENT – 03**

<u>AIM:</u> DEMONSTARTION OF PROCESS RELATED SYSTEM CALLS SUCH AS FORK, GETPID, GETPPID, WAIT, EXEC etc.

### **DESCRIPTION:**

Process-related system calls in Linux manage process creation, control, and synchronization:

### 1. fork()

- Header Files: #include <unistd.h>
- Syntax: pid t fork(void);
- **Explanation**: Creates a new process by duplicating the calling process. The new process (child) gets a unique process ID, sharing most of the parent's resources. It returns 0 to the child process and the child's PID to the parent. On failure, it returns -1.

### 2. getpid()

- Header Files: #include <unistd.h>
- Syntax: pid\_t getpid(void);
- Explanation: Returns the process ID (PID) of the calling process. Useful for identifying the process, especially in multi-process applications.

### 3. getppid()

- Header Files: #include <unistd.h>
- Syntax: pid t getppid(void);
- **Explanation**: Returns the parent process ID (PPID) of the calling process, useful for tracking process lineage.

### 4. exec() Family

- Header Files: #include <unistd.h>
- Syntax: int execve(const char \*pathname, char \*const argv[], char \*const envp[]);
- **Explanation**: Replaces the current process image with a new process image specified by the pathname. The argv argument holds pointers to the command's arguments, and envp holds pointers to environment variables. If successful, exec does not return; otherwise, it returns -1.

### 5. wait()

- Header Files: #include <sys/types.h>, #include <sys/wait.h>
- Syntax: pid\_t wait(int \*status);
- **Explanation**: Suspends execution of the calling process until one of its child processes terminates. It returns the PID of the terminated child and stores the child's termination status in the variable pointed to by status. Returns -1 if no child processes exist.

### 1. Program to demonstrate fork system call

```
#include <sys/types.h>
#include <unistd.h>
#include <stdio.h>
int main() {
   int a = 2;
   pid_t pid;
   pid = fork();
   printf("%d\n", pid);
   if (pid < 0) {</pre>
        printf("FORK FAILED\n");
    } else if (pid = 0) {
        printf("CHILD PROCESS \t a is: ");
        printf("%d\n", ++a);
   } else {
        printf("PARENT PROCESS \t a is: ");
        printf("%d\n", --a);
   printf("EXITING WITH X = %d\n", a);
   return 0;
}
```

### **OUTPUT:**

```
PARENT PROCESS
EXITING WITH X = 1
CHILD PROCESS
                 a is: 3
EXITING WITH X = 3
```

2. Program to demonstrate getpid(),getppid() system calls

#### Without wait()

```
స్వయం తేజస్విన్ భవ
#include <sys/types.h>
#include <unistd.h>
#include <stdio.h>
int main() {
    int a = 2;
    pid_t pid;
    pid = fork();
          printf("%d\n", pid);
        if (pid < 0) {
    printf("FORK FAILED\n");
} else if (pid = 0) {
    printf("CHILD PROCESS \t a is: %d\n", ++a);
    printf("I AM THE CHILD AND MY PROCESS ID IS %d\n", getpid());
    printf("I AM THE CHILD AND MY PARENT'S PROCESS ID IS %d\n", getpid());
} else {
    printf("PARENT PROCESS \t a is: %d\n", -a);
    printf("AM THE PARENT AND MY PROCESS ID IS %d\n", getpid());
    printf("I AM THE PARENT AND MY PROCESS ID IS %d\n", getpid());
    printf("I AM THE PARENT AND MY CHILD'S PROCESS ID IS %d\n", pid);
}</pre>
          printf("EXITING WITH X = %d\n", a);
          return 0;
```

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```
OUTPUT:
      PARENT PROCESS
                            a is: 1
      I AM THE PARENT AND MY PROCESS ID IS 9784
      I AM THE PARENT AND MY CHILD'S PROCESS ID IS 9785
     EXITING WITH X = 1
     CHILD PROCESS a is: 3
I AM THE CHILD AND MY PROCESS ID IS 9785
I AM THE CHILD AND MY PARENT'S PROCESS ID IS 1299
     EXITING WITH X = 3
     With Wait()
      #include <stdio.h>
      #include <unistd.h>
#include <sys/wait.h>
      int main() {
          pid_t pid = fork();
          if (pid < 0) { // Error in creating a child</pre>
              printf("Child cannot be created\n"):
          printf("Process id of child = %d\n", pid);
printf("Process id of parent = %d\n", getpid());
             int status;
pid_t child_pid = wait(&status); // Parent waits for the child
             if (child mid > 0) {
                 if (WIFEXITED(status)) {
  printf("Child process (PID: %d) exited with status %d\n", child_pid, WEXITSTATUS(status));
                    printf("Child process (PID: %d) did not terminate normally\n", child_pid);
             } else {
                 perror("wait failed");
         else { // child section
    steep(1); // Simulate some work
    printf("Process id of child = xd\n", getpid());
    printf("Process id of parent = xd\n", getpid());
          return 6;
     OUTPUT:
      Process id of child = 9850
     Process id of parent = 9849
     Process id of child = 9850
     Process id of parent = 9849
     Child process (PID: 9850) exited with status 6
3. Write a Program to demonstrate the concept of Orphan and Zombie Process
```

### **ORPHAN CODE:**

### Sleep():

```
#include <stdio.h>
#include <stdio.h>
                                                                                                                                        #include <unistd.h>
#include <unistd.h>
                                                                                                                                             pid_t pid = fork();
     pid_t pid = fork();
                                                                                                                                             if (pid < 0) { // Error in creating a child</pre>
     if (pid < 0) { // Error in creating a child
    printf("Child cannot be created\n");</pre>
                                                                                                                                                   printf("Child cannot be created\n");
     else if (pid > 0) { // Parent section
                                                                                                                                             else if (pid > 0) { // Parent section
                                                                                                                                                   sleep(1); // Sleep to ensure child doesn't become orphan
           printf("Process id of child = %d\n", pid);
printf("Process id of parent = %d\n", getpid());
                                                                                                                                                   printf("Process id of child = %d\n", pid); // pid holds child's PID
printf("Process id of parent = %d\n", getpid());
           sleep(1); // Simulate delay to show the child becoming an orphan
printf("Process id of child = %d\n", getpid());
printf("Process id of parent = %d\n", getppid()); // Shows parent's process ID
                                                                                                                                             else { // Child section
                                                                                                                                                  printf("Process id of child = %d\n", getpid());
printf("Process id of parent = %d\n", getppid());
                                                                                                                                             return 0;
```

#### **OUTPUT:**

```
process id of child = 9915
Process id of parent = 9914

(praveen⊗ kali)-[~]

$\frac{1}{2}$ Process id of child = 9915
Process id of parent = 1299
```

### **OUTPUT:**

```
Process id of child = 10012
Process id of parent = 10011
Process id of child = 10012
Process id of parent = 10011
```

### 4. Program to demonstrate exec System Call

```
#include <stdio.h>
#include <unistd.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/wait.h>
int main(int argc, char *argv[]) {
   int pid = fork();
   if (pid < 0) {
       printf("Fork failed\n");
       return 1;
   else if (pid = 0) {
       execl("/bin/ls", "ls", NULL);
       perror("execl failed");
       exit(1);
   else {
       wait(NULL);
       printf("Child process complete\n");
   return 0;
```

### **OUTPUT:**

```
Desktop
           Public
                     file1.txt
                                getpid_withwait.c program4.c
Documents Templates file3.txt orphan.c
                                                  program5.c
Downloads Videos
                     files.txt program1.c
                                                  program6.c
Music
          a.out
                     fork.c
                                program2.c
                                                   sleep.c
          exec.c
                     getpid.c
Pictures
                                program3.c
                                                  v1.txt
Child process complete
```

## **EXPERIMENT - 04**

<u>AIM:</u> Implement CPU Scheduling Algorithms (a) Round Robin (b) SJF (c) FCFS.

### **DESCRIPTION:**

Round Robin (RR) scheduling allocates CPU time to each process in acircular order. Each process gets a fixed time quantum to execute beforebeing moved to the back of the queue. This method ensures fairness andresponsiveness but can lead to higher average turnaround times if the quantum is not well-tuned.

**Shortest Job First (SJF) scheduling** selects the process with the smallestexecution time for the CPU next. It can be either preemptive (Shortest Remaining Time First) or non-preemptive. SJF minimizes average waitingtime and turnaround time but may lead to process starvation if short jobs keep arriving.

**First Come First Serve (FCFS) scheduling** processes tasks in the order they arrive. The first process in the queue is executed to completion beforemoving to the next. While simple and easy to implement, FCFS can lead tothe "convoy effect," where longer processes delay the execution of shorter ones.

### **ALGORITHM:**

### 1. FCFS Scheduling

- 1. Input the processes along with their burst time (bt).
- 2. Find waiting time (wt) for all processes.
- 3. As first process that comes need not to wait so
  - a. waiting time for process 1 will be 0 i.e. wt[0] = 0.
- 4 Find waiting time for all other processes i.e. for
  - a. process  $i \rightarrow wt[i] = bt[i-1] + wt[i-1]$ .
- **5.** Find turnaround time = waiting\_time + burst\_time for all processes.
- **6.** Find average waiting time = total\_waiting\_time / no\_of\_processes.
- 7. Similarly, find average turnaround time = total\_turn\_around\_time / no\_of\_processes.

### 2. SJF Scheduling

- 1. Sort all processes according to the arrival time.
- 2. Select the process that has the minimum arrival time and minimum burst time.
- 3. After the completion of the process, create a pool of processes that arrive afterward until the completion of the previous process.
- 4. Select the process among the pool that has the minimum burst time.

- 5. Completion Time: Time at which the process completes its execution.
- 6. Turnaround Time: The time difference between completion time and arrival time.
  - Turnaround Time=Completion Time-Arrival Time
     Turnaround Time=Completion Time-Arrival Time
- 7. Waiting Time (W.T): The time difference between turnaround time and burst time.
  - Waiting Time=Turnaround Time-Burst Time

### 3. RR Scheduling

- 1. Initialize the queue.
- 2. Set the time quantum.
- 3. Enqueue all processes with their burst times.
- 4. While the queue is not empty:
  - current\_process = Dequeue()
  - o If burst\_time[current\_process] <= time\_quantum:</p>
    - Execute current\_process for burst\_time[current\_process].
    - Remove current\_process from the queue.
  - o Else:
    - Execute current\_process for time\_quantum.
    - Update burst\_time[current\_process] = burst\_time[current\_process] time\_quantum
  - o Enqueue current\_process at the end of the queue.
- 5. End while.

### **PROGRAMS:**

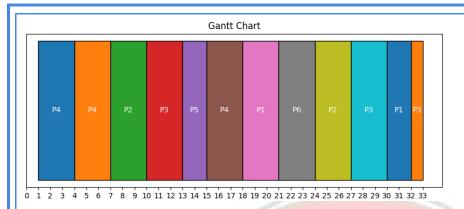
#### 1. FCFS

```
matplotlib.pyplot as plt
print("FIRST COME FIRST SERVE SCHEDULING")
n = int(input("Enter number of processes: "))
processes = {}
processes = dict(sorted(processes.items(), key=lambda item: item[1][0]))
WT = []
for i in range(len(processes)):
    if i == 0:
         ET.append(processes[list(processes.keys())[i]][0] + processes[list(processes.keys())[i]][1])
         ET.append(ET[i - 1] + processes[list(processes.keys())[i]][1])
TAT = [ET[i] - processes[list(processes.keys())[i]][0] for i in range(len(processes))]
WT = [TAT[i] - processes[list(processes.keys())[i]][1] for i in range(len(processes))]
     - []
for i in range(len(processes)):
    if i == 0:
         RT.append(0)
         RT.append(ET[i - 1] - processes[list(processes.keys())[i]][0])
avg_WT = sum(WT) / n
avg_TAT = sum(TAT) / n
total_time = ET[-1]
throughput = n / total_time
print("Process | Arrival | Burst | Exit | Turn Around | Wait | Response")
 process_key = list(processes.keys())[i]
print(f" (process_key) | (process_key)
                                         {processes[process_key][0]} | {processes[process_key][1]} | {ET[i]} | {TAT[i]}
                                                                                                                                                   | {WT[i]} | {RT[i]}")
```

```
print("Average Waiting Time:", avg_WT)
print("Average Turnaround Time:", avg_TAT)
print("Throughput:", throughput, "processes/unit time")
     plt.figure(figsize=(10, 3))
     plt.figure(rigsize=(io, 3,,
current_time = 0
for i in range(n):
    plt.barh(y=0, width=processes[list(processes.keys())[i]][1], left=current_time, edgecolor='black')
    plt.text(x=current_time + processes[list(processes.keys())[i]][1] / 2,
                    y=0,
s=list(processes.keys())[i],
                    ha='center',
va='center'.
         va center,
color='white')
current_time += processes[list(processes.keys())[i]][1]
    plt.yticks([])
plt.xticks(range(current_time + 1))
plt.xlabel("Time")
     plt.title("Gantt Chart")
    OUTPUT:
      FIRST COME FIRST SERVE SCHEDULING
      Enter number of processes: 5
      Enter arrival time of process P1: 0
      Enter burst time of process P1: 4
      Enter arrival time of process P2: 1
      Enter burst time of process P2: 3
      Enter arrival time of process P3: 2
      Enter burst time of process P3: 1
      Enter arrival time of process P4: 3
      Enter burst time of process P4: 2
      Enter arrival time of process P5: 4
      Enter burst time of process P5: 5
      Process | Arrival | Burst | Exit | Turn Around | Wait | Response
                             | 4 | 4 | 4 | 4 | 3 | 7 | 6 | 1 | 8 | 6 | 2 | 10 | 7
                      0
         P1
                                                               101
                                                                               0
         P2
                       1
                                                                 131
                                                                 | 5 |
         P3
                       2
                                                                   | 5
         P4
                       3
                                                                          - 1
                                 | 5 | 15 |
         P5
                                                        11
                                                                     | 6
      Average Waiting Time: 3.8
      Average Turnaround Time: 6.8
      Throughput: 0.333333333333333 processes/unit time
                                                           Gantt Chart
                                                                          PΔ
                                                                                  10
                                                                                         'n
                                                                                                12
                                                                                                        13
                                                                                                                14
2. SJF
                                                             KANKA TAMON E KK
    import matplotlib.pyplot as plt
    def sjf scheduling():
         print("SHORTEST JOB FIRST SCHEDULING")
n = int(input("Enter number of processes: "))
         processes = []
          for i in range(n):
              process_id = i + 1
arrival_time = int(input(f"Enter arrival time of process P{process_id}: "))
burst_time = int(input(f"Enter burst time of process P{process_id}: "))
               processes.append([process_id, arrival_time, burst_time])
         processes.sort(key=lambda x: x[1])
waiting_time = [0] * n
turnaround_time = [0] * n
completion_time = [0] * n
response_time = [0] * n
          total_waiting_time = 0
         total_turnaround_time = 0
total_response_time = 0
current_time = 0
         completed_processes = 0
completed = [False] * n
gantt_chart = []
gantt_times = []
```

```
le completed processes < n:
available_processes = [p for p in processes if p[1] <= current_time and not completed[p[0] - 1]]</pre>
          if available processes:
               available_processes:
available_processes.sort(key=lambda x: x[2])
process = available_processes[0]
process_id = process[0]
arrival_time = process[1]
burst_time = process[2]
               if response_time[process_id - 1] == 0:
    response_time[process_id - 1] = current_time - arrival_time
start_time = current_time
               start time = current_time
completion_time[process_id - 1] = start_time + burst_time
waiting_time[process_id - 1] = start_time - arrival_time
turnaround_time[process_id - 1] = waiting_time[process_id - 1] + burst_time
current_time += burst_time
completed_process_es += 1
completed[process_id - 1] = True
gantt_chart.append(f"P(process_id)")
                gantt_times.append((start_time, current_time))
               gantt_chart.append("IDLE")
               gantt_times.append((current_time, current_time + 1))
current_time += 1
    avg_waiting_time = sum(waiting_time) / n
avg_turnaround_time = sum(turnaround_time) / n
avg_response_time = sum(response_time) / n
total_time = completion_time[-1]
throughput = n / total_time if total_time > 0 else_0
     print("\nProcess | Arrival Time | Burst Time | Waiting Time | Turnaround Time")
for i in range(n):
    print(f" P(processes[i][0]) | {processes[i][1]} | {processes[i][2]} | {waiting_time[i]} | {turnaround_time[i]}")
     print(f"\nAverage Waiting Time: {avg_waiting_time:.2f}")
print(f"Average Turnaround Time: (avg_turnaround time:.2ff)")
print(f"Average Response Time: {avg_response_time:.2f}")
print(f"Arroughput: {throughput:.2f} processes/unit time")
     print("\nGantt Chart:")
     plt.figure(figsize=(10, 3))
     plt.yticks([])
     plt.xticks(range(int(current_time) + 1))
plt.xlabel("Time")
plt.title("Gantt Chart")
     plt.show()
sjf scheduling()
OUTPUT:
SHORTEST JOB FIRST SCHEDULING
Enter number of processes: 5
Enter arrival time of process P1: 1
Enter burst time of process P1: 7
Enter arrival time of process P2: 2
Enter burst time of process P2: 5
Enter arrival time of process P3: 3
Enter burst time of process P3: 1
Enter arrival time of process P4: 4
Enter burst time of process P4: 2
Enter arrival time of process P5: 5
Enter burst time of process P5: 8
Process | Arrival Time | Burst Time | Waiting Time | Turnaround Time
  P1 | 1 | 7 | 0 | 7
  P2 | 2 | 5 | 9 | 14
  P3 | 3 | 1 | 5 | 6
  P4 | 4 | 2 | 5 | 7
  P5 | 5 | 8 | 11 | 19
Average Waiting Time: 6.00
Average Turnaround Time: 10.60
Average Response Time: 6.00
                                                                                                                                    1 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24
Throughput: 0.21 processes/unit time
```

```
3. RR
      import matplotlib.pyplot as plt
      from collections import dequ
     def round_robin(processes, burst_time, arrival_time, quantum):
    n = len(processes)
           process queue = deque()
           process_start_time = [-1] * n
           while True:
                 for i in range(n):
    if arrival_time[i] <= t and remaining burst_time[i] > 0 and i not in process_queue:
                            process_queue.append(i)
                 if process queue:
                      i = process_queue.popleft()
if process_start_time[i] == -1:
    process_start_time[i] = t
start_time = t
burst = min(quantum, remaining_burst_time[i])
t += burst
                       remaining_burst_time[i] -= burst
                      if remaining_burst_time[i] == 0:
    waiting_time[i] = t - burst_time[i] - arrival_time[i]
    turnaround_time[i] = t - arrival_time[i]
                       else:
                       process_queue.append(i)
gantt_chart.append((processes[i], start_time, t))
                       next\_arrival = min([arrival\_time[i] \ for \ i \ in \ range(n) \ if \ arrival\_time[i] \ > t], \ default= \\ None)
                      if next_arrival is
                             t = next_arrival
                            break
          avg_waiting_time = sum(waiting_time) / n
avg_turnaround_time = sum(turnaround_time) / n
avg_response_time = sum(response_time) / n
total_time = max(t, max([arrival_time[i] + burst_time[i] for i in range(n)]))
throughput = n / total_time if total_time > 0 else 0
           plt.figure(figsize=(10, 3))
           for process, start, end in gantt_chart:
    plt.barh(y=0, width=end - start, left=start, edgecolor='black')
    plt.text(x=start + (end - start) / 2, y=0, s=f"P{process}", ha='center', va='center', color='white')
           plt.yticks([])
          plt.xticks(range(int(t) + 1))
plt.xlabel("Time")
plt.title("Gantt Chart")
          plt.show()
           print("\nProcess\tArrival Time\tBurst Time\tWaiting Time\tTurnaround Time\tResponse Time")
           for i in range(n):
    print(f"P{processes[i]}\t{arrival time[i]}\t\t{burst time[i]}\t\t{waiting time[i]}\t\t{turnaround time[i]}\t\t{response time[i]}")
          print(f"\nAverage Waiting Time: {avg_waiting_time:.2f}")
print(f"Average Turnaround Time: {avg_turnaround time:.2f}")
print(f"Average Response Time: {avg_response_time:.2f}")
print(f"Throughput: (throughput..2f) processes/unit time")
     n = int(input("Enter the number of processes: "))
processes = []
burst_time = []
arrival_time = []
     for i in range(n):
          process id = i + 1
           processes.append(process id)
bt = int(input(f"Enter the burst time for process P{process_id}: "))
burst_time.append(bt)
                 int(input(f"Enter the arrival time for process P{process id}: "))
           arrival time.append(at)
     quantum = int(input("Enter the time quantum: "))
round_robin(processes, burst_time, arrival_time, quantum)
    OUTPUT:
    Enter the number of processes: 6
    Enter the burst time for process Pl: 5
Enter the arrival time for process Pl: 5
     Enter the burst time for process P2: 6
    Enter the arrival time for process P2: 4 Enter the burst time for process P3: 7
     Enter the arrival time for process P3: 3
    Enter the burst time for process P4: 9
    Enter the arrival time for process P4: 1
     Enter the burst time for process P5: 2
    Enter the arrival time for process P5: 2
    Enter the burst time for process P6: 3
     Enter the arrival time for process P6: 6
    Enter the time quantum: 3
```



Proces Time	ss Arrival Time	Burst Time	Waiting Time	Turnaround Time	Response
TIME					
P1	5	5	22	27	22
P2	4	6	17	23	17
P3	3	7	23	30	23
P4	1	9	8	17	8
P5	2	2	11	13	11
P6	6	3	15	18	15

Average Waiting Time: 16.00 Average Turnaround Time: 21.33 Average Response Time: 16.00 Throughput: 0.18 processes/unit time

### **OUTPUT ANALYSIS:**

### 1. First Come First Serve (FCFS)

Time Complexity: O(n)

Processes are executed in the order they arrive.

**Space Complexity: O(n)** 

Requires space to store process information, such as arrival time, burst time, completion time, waiting time, and turnaround time (TAT).

### 2. Shortest Job First (SJF)

Time Complexity: O(n log n)

Sorting processes by burst time takes O(n log n).

**Space Complexity: O(n)** 

Space is needed to store process details and the sorted list.

### 3. Round Robin (RR)

Time Complexity: O(n \* q)

Each process may be processed multiple times (up to n times), and each time quantum qqq may require O(n) operations. Thus, the complexity is O(n \* q), where qqq is the time quantum.

### **Space Complexity: O(n)**

Uses a queue to manage processes, requiring space proportional to the number of processes.

### **EXPERIMENT - 05**

<u>AIM:</u> DEMONSTARTION OF IPC MECHANISMS SUCH AS PIPE and SHARED MEMORY.

### **DESCRITION:**

Inter-Process Communication (IPC) mechanisms, like **pipes** and **sharedmemory**, enable data exchange between processes.

- **Pipes** provide a unidirectional communication channel, allowing one process to write and another to read data sequentially.
- **Shared memory** enables multiple processes to access common memory space, facilitating fast data exchange by minimizing copying.

### Pipe()

```
pipe(2) DESCRIPTION
 pipe(2
                                                                  System Calls Manual
                                                                                                                                                                                               pipe() creates a pipe, a unidirectional data channel that can be used for interprocess communication. The array <u>pipefd</u> is used to return two file descriptors referring to the ends of the pipe. <u>pipefd[0]</u> refers to the read end of the pipe. <u>pipefd[1]</u> refers to the write end of the pipe. Data written to the write end of the pipe. Bata written to the write end of the pipe. For further details, see pipe(7).
              pipe, pipe2 - create pipe
LIBRARY
               Standard C library (libc, -lc)
 YNOPSIS
#include <unistd.h>
                                                                                                                                                                                                If \underline{\mbox{flags}} is 0, then \mbox{pipe2}() is the same as \mbox{pipe}(). The following values can be bitwise ORed in \underline{\mbox{flags}} to obtain different behavior:
               int pipe(int pipefd[2]);
              #define _GNU_SOURCE
#include <fcntl.h>
#include <unistd.h>
                                                                                                                                                                                              O_CLOEXEC

Set the close-on-exec (FD_CLOEXEC) flag on the two new file descriptors. See the description of the same flag in open(2) for reasons why this may be useful.
                                                                                     /* See feature_test_macros(7) */
/* Definition of 0_* constants */
              int pipe2(int pipefd[2], int flags);
                                                                                                                                                                                               O_DIRECT (since Linux 3.4)

Create a pipe that performs I/O in "packet" mode. Each write(2) to the pipe is dealt with as a separate packet, and read(2)s from the pipe will read one packet at a time. Note the follow-
              /* On Alpha, IA-64, MIPS, SuperH, and SPARC/SPARC64, pipe() has the following prototype; see VERSIONS */ \,
               #include <unistd.h>
              struct fd_pair {
    long fd[2];
                                                                                                                                                                                                                    Writes of greater than PIPE_BUF bytes (see pipe(7)) will be split into multiple packets. The constant PIPE_BUF is defined in \leq 1 \text{mits.h} \geq 1.
               };
struct fd_pair pipe(void);
```

#### **Shared Memory**

```
System Calls Manual
                                                                                                                                              shmget(2)
SHMOP(2)
shmaet(2)
             shmget - allocates a System V shared memory segment
                                                                                                                                                                                   shmat, shmdt - System V shared memory operations
                                                                                                                                                                      IBRARY
              Standard C library (<u>libc</u>, <u>-lc</u>)
                                                                                                                                                                                    Standard C library (libc, -lc)
 SYNOPSIS
#include <sys/shm.h>
                                                                                                                                                                     SYNOPSIS
                                                                                                                                                                                    #include <sys/shm.h>
             int shmget(key_t key, size_t size, int shmflg);
                                                                                                                                                                                    void *shmat(int \underline{shmid}, const void *_Nullable \underline{shmaddr}, int \underline{shmflg}); int \underline{shmdt}(\underline{const void *}\underline{shmaddr});
 DESCRIPTION
             shaget() returns the identifier of the System V shared memory segment associated with the value of the argument <u>key</u>. It may be used either to obtain the identifier of a previously created shared memory segment (when <u>shmflg</u> is zero and <u>key</u> does not have the value IPC_PRIVATE), or to create a new set.
                                                                                                                                                                      DESCRIPTION
                                                                                                                                                                           shmat()
                                                                                                                                                                                   shmat() attaches the System V shared memory segment identified by <u>shmid</u> to the address space of the calling process. The attaching address is specified by <u>shmaddr</u> with one of the following criteria:
              A new shared memory segment, with size equal to the value of <u>size</u> rounded up to a multiple of PAGE_SIZE, is created if <u>key</u> has the value IPC_PRIVATE or <u>key</u> isn't IPC_PRIVATE, no shared memory segment corresponding to <u>key</u> exists, and IPC_CREAT is specified in <u>shmflg</u>.
                                                                                                                                                                                   - If \underline{\mathsf{shmad} r} is NULL, the system chooses a suitable (unused) page-aligned address to attach the segment.
```

```
shmdt()
    shmdt() detaches the shared memory segment located at the address spec-
    ified by shmaddr from the address space of the calling process. The
    to-be-detached segment must be currently attached with shmaddr equal to
    the value returned by the attaching shmat() call.

On a successful shmdt() call, the system updates the members of the
    shmid_ds structure associated with the shared memory segment as fol-
    lows:

    * shm_dtime* is set to the current time.

    * shm_lpid is set to the process-ID of the calling process.

    * shm_nattch* is decremented by one. If it becomes 0 and the segment
    is marked for deletion, the segment is deleted.
```

### 1. Program to Demonstrate Ordinary Pipe IPC Mechanism

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
int main()
    int fd[2];
    if (pipe(fd) == -1) {
        perror("Pipe creation failed");
        exit(EXIT_FAILURE);
    // Fork a child process
    pid_t pid = fork();
    if (pid == -1) {
    perror("Fork failed");
        exit(EXIT_FAILURE);
    if (pid == 0) {
        // Child process
        close(fd[0]); // Close the read end of the pipe
        char message[] = "Hello from the child process!\n";
        write(fd[1], message, sizeof(message));
        close(fd[1]); // Close the write end of the pipe in the child
    } else {
        // Parent process
        close(fd[1]); // Close the write end of the pipe
        char buffer[100];
        read(fd[0], buffer, sizeof(buffer));
        printf("Parent received: %s", buffer);
        close(fd[0]); // Close the read end of the pipe in the parent
    return 0;
```

#### **OUTPUT:**

```
cbit@cbit-VirtualBox:-$ gedit pipec.c
cbit@cbit-VirtualBox:-$ cc pipec.c
cbit@cbit-VirtualBox:-$ ./a.out
Parent received: Hello from the child process!
cbit@cbit-VirtualBox:-$
```

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### 2. Program to Demonstrate Shared Memory IPC Mechanism.

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include <sys/shm.h>
#include <sys/ipc.h>
#define SHM SIZE 1024 // Size of the shared memory
int main() {
    key_t key = ftok("shmfile", 65); // Generate unique key
    int shmid = shmget(key, SHM_SIZE, 0666 | IPC_CREAT); // Create shared memory
    if (shmid == -1) {
       perror("shmget failed");
       exit(1);
    char *shared_memory = (char*) shmat(shmid, NULL, 0); // Attach to shared memory
    if (fork() == 0) { // Child Process
        sleep(1); // Ensuring parent writes first
        printf("Child reads: %s\n", shared_memory); // Read data from shared memory
        shmdt(shared_memory); // Detach from shared memory
    } else { // Parent Process
        strcpy(shared_memory, "Hello from parent!"); // Write data to shared memory
        printf("Parent wrote to shared memory.\n");
       wait(NULL); // Wait for child to finish
        shmctl(shmid, IPC_RMID, NULL); // Destroy shared memory
    return 0;
}
```

### **OUTPUT:**

Parent Process: Creates a shared memory segment and writes data to it.

Child Process: Reads the data from the shared memory.

```
Parent wrote to shared memory.
Child reads: Hello from parent!
```