

Input: $n = 4$, $edges = [[3,1,2],[3,2,3],[1,1,3],[1,2,4],[1,1,2],[2,3,4]]$

(i) priority \rightarrow type 3

(ii) DSU

remove = 1 + 2

type u v

✓ 3 1 2

✓ 3 2 3

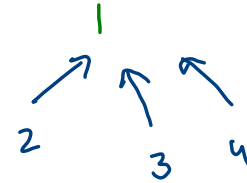
✗ 1 1 3

✓ 1 2 4

✗ 1 1 2

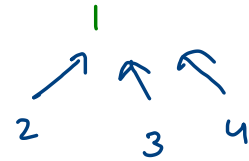
✓ 2 3 4

Alice



$ca = 4$

Bob



$cb = 4$

Floyd warshall : (i) all pairs shortest path.

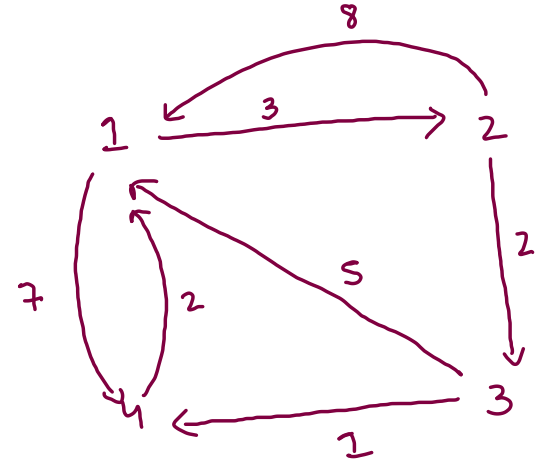
(ii) DP based.

(iii) -ve edge wt.

Ao \rightarrow

	1	2	3	4
1	0	3	∞	7
2	8	0	2	∞
3	5	∞	0	1
4	2	∞	∞	0

Adjacency matrix



$A_0 \rightarrow$

	1	2	3	4
1	0	3	∞	7
2	8	0	2	∞
3	5	∞	0	1
4	2	∞	∞	0

$\rightarrow uv$

no intermediate

A_1

	1	2	3	4
1	0	3	∞	7
2	8	0	2	15
3	5	8	0	1
4	2	5	∞	0

$\rightarrow uv$
 u_{i_1}, v

1 as intermediate

A_2

	1	2	3	4
1	0	3	5	7
2	8	0	2	15
3	5	8	0	1
4	2	5	7	0

\rightarrow

2 as intermediate

uv

$(1, 2)$

u_{i_1}, v

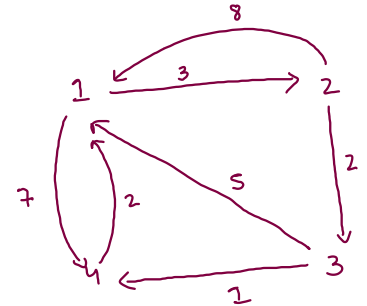
$(3, 2)$

u_{i_2}, v

$(1, 3)$

$u_{i_1 i_2}, v$

$(4, 3)$



3 intermediate

4 intermediate

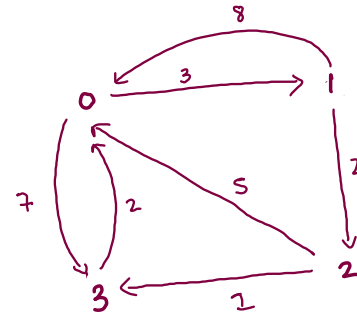
intermediate $\rightarrow k$
[src $\rightarrow u$
[dest $\rightarrow v$
]



$$\text{mat}[u][v] = \min \left(\begin{array}{l} \text{mat}[u][v], \\ \text{mat}[u][k] + \text{mat}[k][v] \end{array} \right)$$

A₀ →

	0	1	2	3
0	0	3	-1	7
1	8	0	2	-1
2	5	-1	0	1
3	2	-1	-1	0



```

//to select an intermediate
for(int k=0; k < matrix.length;k++) {
    //to select a src
    for(int u=0; u < matrix.length;u++) {
        //to select a dest
        for(int v=0; v < matrix.length;v++) {
            if(u == v || u == k || v == k || matrix[u][k] == -1 || matrix[k][v] == -1) {
                continue;
            }
            else if(matrix[u][v] == -1 || matrix[u][k] + matrix[k][v] < matrix[u][v]) {
                matrix[u][v] = matrix[u][k] + matrix[k][v];
            }
        }
    }
}

```

	0	1	2	3
0	0	3	-1	7
1	8	0	2	15
2	5	8	0	1
3	2	5	-1	0

k = 0

Alien dictionary

5

wrt wrf er ett rftt

wrt, wrf, er, ett, rftt

t < j

r < t

r < t < f

w < e < r

(i) graph

(ii) topological sort

w < e < r < t < j

wrt, wrf, er, ett, rjtt

HashMap <char, ArrayList <char>> graph;

wrt wr

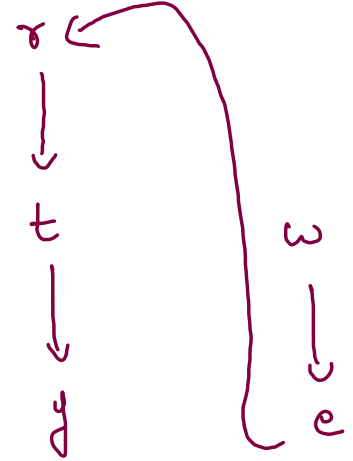
w →

r →

t →

j →

e →



wertj