Basic

- There are 4 main parts in a layer program:
 - constants
 - data
 - networks
 - scripts

Constants

- There are three different constants to define (default values):
 - threads: number of threads for parallelization (4)
 - batch size: size of the batch for the network (100)
 - log: log file where some messages are saved (netparser.log)

```
const{
  threads=4
  batch=10
  log="mnist.log"
}
```

Data

• Data can be read in ascii or binary. Data format is the following:

```
samples dim output

sample1_1 ... sample1_dim out1_1 .. out1_c

...

samplen_1 ... samplen_dim outn_1 .. outn_c
```

- samples is the number of samples (int)
- dim is the dimensionality of the samples (int)
- out is the number of output targets, classes in a classification problem (int)
- each row is a sample (float values)

Note: when samples are color images the channels appear separated, firts R, then G and then B and *dim* must be \$3\times rows\times cols\$

· An example of data definition:

```
data {
   D1 [filename="../training", binary]
   D2 [filename="../test", binary]
   Dval [filename="../valid", ascii]
}
```

- D1, D2 and Dval are the name of the data variables
- Full path to file can be used

Networks

- Networks are the main part of a Layer program
- · Networks are composed by three main parts:
 - Data
 - Layers
 - Connections
- The networks are defined like this:

```
network N1 {
    ...
}
```

• where N1 is the name of the network

Networks - Data

- The Networks have to defined at least a training data set
- Test and validation data sets are optional:

```
network N1 {
   //data
   data tr D1 //mandatory
   data ts D2 //optional
   data va Dval //optional
   ...
}
```

 When test or validation data are provided the error function of the net will be also evaluated for that data sets

Networks - Layers

- There are different layers that can be created:
 - FI: Input Fully Connected layer
 - CI: Input Covolutional layer
 - F: Fully Connected layer
 - FO: Ouput layer
 - C: Convolutional layer
 - MP: MaxPooling layer
 - · CA: Cat layer

Networks - Layers - FI

• FI has not parameters just serve as a connection with the data

```
//NETWORK
network N1 {
   //data
   data tr D1

// Fully Connected Input
   FI in
   ...
}
```

- in is the name of the layer
- The number of units is the dimensionality representation of the data

Networks - Layers - CI

- Convolutional input has three mandatory parameters that indicate how the raw data has to be mapped into an input Map
- The parameters are:
 - o nz: number of channels
 - o nr: image rows
 - nc: image cols

```
//NETWORK
network N1 {
   //data
   data tr D1

// Convolutional Input for MNIST
CI in [nz=1, nr=28, nc=28]
...
}
```

• in is the name of the layer

Networks - Layers -CI

Convolutional input has optional parameters:

```
cr: crop rowscc: crop cols
```

- Images will be randomly cropped on training phase
- Images will be center-cropped in test phase

```
//NETWORK
network N1 {
  //data
  data tr D1

// Convolutional Input for MNIST
  // Images will be randomly cropped to 24x24
  CI in [nz=1, nr=28, nc=28, cr=24, cc=24]
  ...
}
```

Networks - Layers - F

• A fully connected layer

```
//NETWORK
network N1 {
   //data
   ...

// Fully connected
F f1 [numnodes=1024]
   ...
}
```

- f1 is the name of the layer
- numnodes is a mandatory parameter

Networks - Layers - FO

- FO has a mandatory parameter {classification,regression} that define the cost error: cross-entropy or mse respectivelly
- For regression, optionally, we can define an autoencoder

```
network N1 {
    ...
    // Targets are the output in data (one-hot)
    FO out1 [classification] // Cross-entropy

    // Targets are the output in data (real values)
    FO out2 [regression] // mse over output

    // Targets are the same input in data
    FO out3 [regression,autoencoder] // mse over input
    ...
}
```

Networks - Layers - C

- Convolutional layers have three mandatory parameters:
 - nk: number of kernels
 - · kr: height of kernel
 - · kc: width of kernel

```
network N1 {
    ...
    // Convolutional Layer
    C c1 [nk=32, kr=3, kc=3]
    ...
}
```

- c1 is the name of the layer
- Convolutional layers have the following optional parameters:
 - rpad: indicates if padding is done in the rows (0)
 - cpad: indicates if padding is done in the cols (0)
 - stride: stride value (1)

```
network N1 {
...
// Convolutional Layer with padding
// To keep the same size of Input Maps
// use rpad=cpad=1
C c1 [nk=32, kr=3, kc=3,rpad=1,cpad=1]

// Stride=2 and only padding in cols
C c2 [nk=32, kr=3, kc=3,cpad=1,stride=2]
...
}
```

Networks - Layers - MP

- MaxPool layers have two mandatory parameters:
 - o sizer: height of the pooling region
 - sizec: width of the pooling region

```
network N1 {
    ...
    // Maxpool layer sizer=sizec=2
    MP p1[sizer=2,sizec=2]
    ...
}
```

Networks - Layers - CA

Cat layers does not require any parameter

```
network N1 {
    ...
    // CAT Layer
    CA cat
    ...
}
```

Networks - Connections

• To connect two layers use the symbols "->"

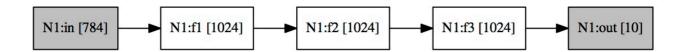
```
network N1 {
    ...
    c1->c2
}
```

Networks - Examples

Example 1 - MLP MNIST

```
// A typical MLP for MNIST
// 784->1024->1024->10
//CONSTANTS
const{
 threads=8
 batch=10
  log="mnist.log"
}
// DATA FILES
data {
  D1 [filename="../training", binary]
  D2 [filename="../test", binary]
}
//NETWORK
network N1 {
  //data
  data tr D1 //mandatory
  data ts D2 //optional
  // Fully Connected Input
  FI in
  // Fully connected
    f1 [numnodes=1024]
  F f2 [numnodes=1024]
  F f3 [numnodes=1024]
  // Fully Connected Output
  FO out [classification]
  // Links
  in->f1
  f1->f2
  f2->f3
  f3->out
}
```

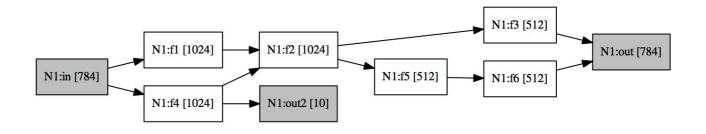
- layers generates a dot file with the name of each network
- Use "dot -T pdf N1.dot > N1.pdf" to generate a PDF with the network:



• but yes, more complicated networks can be defined

Example 2 - Hybrid MLP MNIST

```
//NETWORK
network N1 {
  //data
 data tr D1
  data ts D2
  // Fully Connected Input
 FI in
  // Fully connected
 F f1 [numnodes=1024]
  F f2 [numnodes=1024]
  F f3 [numnodes=512]
  // Fully connected
 F f4 [numnodes=1024]
 F f5 [numnodes=512]
 F f6 [numnodes=512]
  // Output
  FO out [regression, autoencoder]
  FO out2 [classification]
  // Connections
  in->f1
  f1->f2
  f2->f3
  f3->out
  in->f4
  f4->f2
  f4->out2
  f2->f5
  f5->f6
  f6->out
}
```

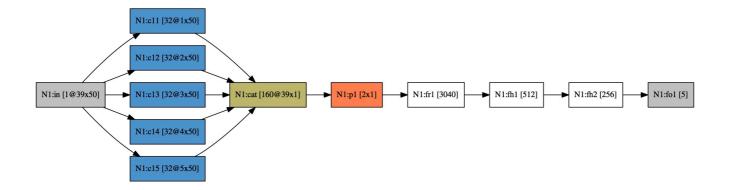


Example 3 - Convolutional CIFAR

```
network N1 {
 data tr D1
 data ts D2
 CI in [nz=3, nr=32, nc=32]
 C c0 [nk=16, kr=3, kc=3]
 MP p0[sizer=2,sizec=2]
 C c1 [nk=32, kr=3, kc=3]
 MP p1 [sizer=2,sizec=2]
 C c2 [nk=64, kr=3, kc=3]
 MP p2 [sizer=2,sizec=2]
  // FC reshape
     f0 []
  // FC hidden
     f1 [numnodes=128]
 // FC output
 FO f2 [classification]
  // Conecctions
  in->c0
 c0->p0
 p0->c1
 c1->p1
 p1->c2
 c2->p2
  //reshape
 p2->f0
  f0->f1
  f1->f2
}
```

Example 4 - CAT layers

```
network N1 {
 data tr D1
 data ts D2
 CI in [nz=1, nr=39, nc=50]
 C c11 [nk=32, kr=1, kc=50,rpad=1]
 C c12 [nk=32, kr=2, kc=50,rpad=1]
 C c13 [nk=32, kr=3, kc=50,rpad=1]
 C c14 [nk=32, kr=4, kc=50,rpad=1]
 C c15 [nk=32, kr=5, kc=50,rpad=1]
 MP p1 [sizer=2,sizec=1]
 CA cat
  // FC reshape
 F fr1 []
 // FC hidden
 F fh1 [numnodes=512]
 F fh2 [numnodes=256]
 // FC output
 FO fol [regression]
 // Connections
  in->c11
  in->c12
  in->c13
  in->c14
  in->c15
 c11->cat
 c12->cat
 c13->cat
 c14->cat
 c15->cat
 cat->p1
 p1->fr1
  fr1->fh1
  fh1->fh2
  fh2->fo1
}
```



Scripts

- Script is a block of actions. There are two different types of actions:
 - functions
 - parameters modifications

Scripts Functions

- There are several functions that can be applied to the defined objects:
 - For Data:
 - zscore(): To normalize Data
 - yuv(): to convert RGB Maps to YUV maps
 - center(): To center Data (mean=0)
 - div(x): To div all the data
 - For Networks:
 - train(epochs): to train networks
 - save(fname): to save the network parameters to file
 - load(fname): to load the network parameters from file

Note that **save** and **load** do not take into accont the network structure, only the parameters of the layers (learning rate, dropout,...) and weights (and bias). So in order to load a network the network structure must match the network structure used when it was saved.

- testout("fname"): writes the output of all the test data in the file. Forward over all data set.
- · For Layers:
 - printkernels("fname"): save the weights of a paricular layer in the file.

For convolutional networks printkernels loop over each filter, then over each map (depth) and

then over each pixel (rows and cols). For fully connected layers printkernels loop over each unit and then over each connection to next layer units.

In any case, saving a network with the **save** command provides the weights (and bias) of **all** the layers.

More functions will be soon implemented

```
script {
 D1.yuv()
  D2.yuv()
  D1.center()
  D2.center(D1)
  D1.div(255.0)
  D2.div(255.0)
 D1.zscore()
 D2.zscore(D1) //normalize D2 with D1 statistics
 N1.train(100)
  N1.save("N1.saved")
 N1.load("N1.saved")
 N1.f1.printkernels("N1f1.txt")
 N1.train(100)
 N1.testout("test output.txt")
}
```

Scripts Parameters

- There are several parameters that can be modified:
 - o mu: learning rate
 - o mmu: momentum rate
 - I2: I2 regularization (weight decay)
 - I1: I1 regularization
 - maxn: maxnorm regularization
 - o noiser: noise ratio after activation function

```
noisesd: standard deviation of noise ($N(0.0,\sigma)$)
noiseb: ratio of binary noise (only for input layer)
drop: dropout (0<drop<1)</li>
bn: batch normalization ({0,1})
act: activation (0 Linear, 1 Relu, 2 Sigmoid, 3 ELU)
flip: to flip input images ({1,0})
shift: to shift randomly input images * balance: for balancing data classes
```

• Parameters can be modified for one particular layer or data:

```
script{
...
N1.c2.drop=0.5
N1.in.flip=1
N1.in.shift=2
N1.in.noiseb=0.2
D1.balance=1
...
}
```

Or, parameters can be modified for all the layers of the same network:

```
script{
...
N1.mu=0.001
N1.12=0.0005
// noise in all the layers of the network:
N1.noiser=0.5
N1.noisesd=0.3
...
}
```

• Some examples of scripts:

```
script {
  D1.yuv()
  D2.yuv()
  D1.zscore()
  D2.zscore(D1)
 N1.in.flip=1
 N1.in.noiser=0.5
 N1.in.noisesd=1.0
  N1.f1.drop=0.5
 N1.12=0.0005
 N1.bn=1
  // Learning rate annealing every 15 epochs
  N1.mu=0.01
 N1.train(15)
 N1.mu=0.005
 N1.train(15)
 N1.mu=0.0025
  N1.train(15)
}
```

```
script {
   D1.zscore()
   D2.zscore(D1)

   N1.noiser=0.0
   N1.noisesd=1.0
   N1.in.noiser=0.5
   N1.mu=0.001
   N1.maxn=3.0

   N1.train(100)
}
```

The whole picture

```
// A typical MLP
// 784->1024->1024->10
// Check N1.dot and get a pdf of the net with:
// dot -T pdf N1.dot > N1.pdf
//CONSTANTS
const{
 threads=8
 batch=10
  log="mnist.log"
}
// DATA FILES
data {
  D1 [filename="../training", binary]
  D2 [filename="../test", binary]
}
//NETWORK
network N1 {
  //data
  data tr D1 //mandatory
  data ts D2 //optional
  // Fully Connected Input
  FI in
  // Fully connected
  F f1 [numnodes=1024]
  F f2 [numnodes=1024]
  F f3 [numnodes=1024]
  // Fully Connected Output
 FO out [regression]
  // Links
  in->f1
  f1->f2
  f2->f3
  f3->out
}
```

```
//RUN SCRIPT
script {

D1.zscore()
D2.zscore(D1)

//N1.noisesd=1.0
//N1.noiser=0.5
N1.mu=0.01
//N1.maxn=3.0

N1.train(10)

}
```

```
const {
threads=4
batch=100
}
data {
 D1 [filename="training", binary]
 D2 [filename="test", binary]
}
network N1 {
  data tr D1
  data ts D2
  // Covolutional Input
 CI in [nz=3, nr=32, nc=32]
 C c0 [nk=16, kr=3, kc=3]
 MP p0[sizer=2,sizec=2]
 C c1 [nk=32, kr=3, kc=3]
 MP p1 [sizer=2,sizec=2]
  C c2 [nk=64, kr=3, kc=3]
 MP p2 [sizer=2,sizec=2]
  // FC reshape
  F f0 []
  // FC hidden
    f1 [numnodes=128]
```

```
// FC output
 FO f2 [classification]
  // Connections
  in->c0
  c0->p0
  p0->c1
  c1->p1
  p1->c2
  c2->p2
  //reshape
  p2->f0
  f0->f1
  f1->f2
}
// RUN
script {
 D1.zscore()
 D2.zscore(D1)
 N1.mu=0.1
  N1.in.noiser=0.5
  N1.in.noisesd=1.0
  //N1.bn=1
 N1.train(1000)
}
```

ADVANCED ISSUES

Networks sharing layers

TODO

Training several networks

TODO

. . .