

$$U'(C_t)=C_t^{(-\phi_c)}$$

$$U'(C_{t+1})=C_{t+1}^{(-\phi_c)}$$

$$U''(C_t)=(-\phi_c)\;C_t^{(-\phi_c)-1}$$

$$U''(C_{t+1})=(-\phi_c)\;C_{t+1}^{(-\phi_c)-1}$$

$$f(k_t)=K_{t-1}^{\alpha}$$

$$f(k_{t-1})=K_{t-2}^{\alpha}$$

$$f'(k_t)=\alpha\,K_{t-1}^{\alpha-1}$$

$$f'(k_{t-1})=\alpha\,K_{t-2}^{\alpha-1}$$

$$g(\mu)=\theta_1\,\mu_t^{\theta_2}$$

$$g'(\mu)=\theta_1\,\theta_2\,\mu_t^{\theta_2-1}$$

$$h(Y)=Y_t^{1-\gamma}$$

$$h'(Y)=(1-\gamma)\;Y_t^{(-\gamma)}$$

$$d(X_t)=d_2\,X_{t-1}^2+X_{t-1}\,d_1+d_0$$

$$d(X_{t+1})=d_0+d_2\,X_t^2+d_1\,X_t$$

$$d'(X_T)=d_1+X_{t-1}\,2\,d_2$$

$$Z_\tau=\frac{\frac{\theta_2}{\theta_2-1}\;Z_t}{\tau_t}$$

$$Z_Y=\frac{Z_t\;\frac{\theta_2\;(1-\gamma)-1}{\theta_2-1}}{Y_t}$$

$$E_\tau=\frac{Y_t^{1-\gamma}\;\mu t^{\frac{(-1)}{\theta_2-1}}}{\tau_t}$$

$$E_y = (1 - \gamma) Y_t^{(-\gamma)} - Y_t^{(-\gamma)} \mu_t \left(1 + \frac{(-\gamma)}{\theta_2 - 1} - \gamma \right)$$

$$R_\tau = Y_t^{1-\gamma} (1 - \gamma) (-\alpha) K_{t-2}^{(-1)} + \alpha (1 - \gamma) + K_{t-2}^{(-1)} Y_t^{1-\gamma} \mu_t \left(1 + \frac{1}{\theta_2 - 1} \right) - \mu_t^{\theta_2} K_{t-2}^{(-1)} Y_t \frac{\theta_2 \alpha \theta_1}{\theta_2 - 1} \tau_t^{(-1)}$$

$$R_Y = \alpha K_{t-2}^{(-1)} - K_{t-2}^{(-1)} Y_t^{(-\gamma)} \tau_t \alpha (1 - \gamma)^2 + K_{t-2}^{(-1)} Y_t^{(-\gamma)} \mu_t \tau_t \alpha (1 - \gamma) \left(1 - \gamma - \frac{\gamma}{\theta_2 - 1} \right) - \mu_t^{\theta_2} K_{t-2}^{(-1)} \alpha \theta_1 \left(1 - \frac{\theta_2 \gamma}{\theta_2 - 1} \right)$$

$$R_K(\tau_t, y_t, k_{t-1}) = Y_t (-\alpha) K_{t-2}^{(-2)} + K_{t-2}^{(-2)} Y_t^{1-\gamma} \tau_t \alpha (1 - \gamma) - K_{t-2}^{(-2)} Y_t^{1-\gamma} \mu_t \tau_t \alpha (1 - \gamma) + \mu_t^{\theta_2} K_{t-2}^{(-2)} Y_t \alpha \theta_1$$

$$R_K(\tau_{t+1}, y_{t+1}, k_t) = (-\alpha) Y_{t+1} K_{t-1}^{(-2)} + K_{t-1}^{(-2)} \alpha (1 - \gamma) \tau_{t+1} Y_{t+1}^{1-\gamma} - K_{t-1}^{(-2)} Y_{t+1}^{1-\gamma} \alpha (1 - \gamma) \tau_{t+1} \mu_{t+1} + K_{t-1}^{(-2)} \alpha \theta_1 Y_{t+1} \mu_{t+1}^{\theta_2}$$

$$\log(A_t) = \rho \log(A_{t-1}) + \epsilon_t \quad (1)$$

$$R_t = \frac{\alpha K_{t-1}^{\alpha-1} Y_t}{K_{t-1}^\alpha} \left(1 - (1 - \gamma) Y_t^{(-\gamma)} \tau_t (1 - \mu_t) - \theta_1 \mu_t^{\theta_2} \right) \quad (2)$$

$$Y_t^{1-\gamma} \tau_t = \theta_1 \theta_2 \mu_t^{\theta_2-1} Y_t \quad (3)$$

$$C_t^{(-\phi_c)} = (R_{t+1} + 1 - \delta) C_{t+1}^{(-\phi_c)} \beta \quad (4)$$

$$C_t = Y_t - K_{t-1} + (1 - \delta) AUX_ENDO_LAG.2.1_{t-1} - Z_t \quad (5)$$

$$X_t = X_{t-1} \eta + (1 + \nu) E_t \quad (6)$$

$$Y_t = A_t \left(1 - (d_2 X_{t-1}^2 + X_{t-1} d_1 + d_0) \right) AUX_ENDO_LAG.2.1_{t-1}^\alpha \quad (7)$$

$$E_t = Y_t^{1-\gamma} (1 - \mu_t) \quad (8)$$

$$Z_t = \theta_1 \mu_t^{\theta_2} Y_t \quad (9)$$

$$\begin{aligned} C_t^{(-\phi_c)} \frac{\frac{\theta_2}{\theta_2-1} Z_t}{\tau_t} = \zeta_t \left(- \left(\frac{Y_t^{1-\gamma} \mu_t \frac{(-1)}{\theta_2-1}}{\tau_t} \right) \right) + \frac{\frac{\theta_2}{\theta_2-1} Z_t}{\tau_t} (-\phi_c) C_t^{(-\phi_c)-1} \lambda_t + \lambda_{t-1} \left((1 + R_t - \delta) (-\phi_c) C_t^{(-\phi_c)-1} \left(- \left(\frac{\frac{\theta_2}{\theta_2-1} Z_t}{\tau_t} \right) \right) + C_t^{(-\phi_c)} \left(\alpha (1 - \gamma) \right. \right. \\ \left. \left. + Y_t^{1-\gamma} (1 - \gamma) (-\alpha) AUX_ENDO_LAG.2.1_{t-1}^{(-1)} + Y_t^{1-\gamma} \mu_t \left(1 + \frac{1}{\theta_2 - 1} \right) AUX_ENDO_LAG.2.1_{t-1}^{(-1)} - \tau_t^{(-1)} \mu_t^{\theta_2} Y_t \frac{\theta_2 \alpha \theta_1}{\theta_2 - 1} AUX_ENDO_LAG.2.1_{t-1}^{(-1)} \right) \right) \end{aligned} \quad (10)$$

$$\beta \eta \zeta_{t+1} = \zeta_t + (d_1 + X_{t-1} 2 d_2) A_t \omega_t \alpha AUX_ENDO_LAG.2.1_{t-1}^{\alpha-1} \quad (11)$$

$$\begin{aligned}
& \omega_t + \zeta_t \left(- \left((1-\gamma) Y_t^{(-\gamma)} - Y_t^{(-\gamma)} \mu_t \left(1 + \frac{(-\gamma)}{\theta_2 - 1} - \gamma \right) \right) \right) + C_t^{(-\phi_c)} \left(1 - \frac{Z_t \frac{\theta_2 (1-\gamma) - 1}{\theta_2 - 1}}{Y_t} \right) + \left(1 - \frac{Z_t \frac{\theta_2 (1-\gamma) - 1}{\theta_2 - 1}}{Y_t} \right) \lambda_t \left(- \left((-\phi_c) C_t^{(-\phi_c) - 1} \right) \right) \\
& + \lambda_{t-1} \left((1 + R_t - \delta) (-\phi_c) C_t^{(-\phi_c) - 1} \left(1 - \frac{Z_t \frac{\theta_2 (1-\gamma) - 1}{\theta_2 - 1}}{Y_t} \right) + C_t^{(-\phi_c)} \left(\alpha AUX_ENDO_LAG_2.1_{t-1}^{(-1)} - Y_t^{(-\gamma)} \tau_t \alpha (1-\gamma)^2 AUX_ENDO_LAG_2.1_{t-1}^{(-1)} \right. \right. \\
& \left. \left. + Y_t^{(-\gamma)} \mu_t \tau_t \alpha (1-\gamma) \left(1 - \gamma - \frac{\gamma}{\theta_2 - 1} \right) AUX_ENDO_LAG_2.1_{t-1}^{(-1)} - \mu_t^{\theta_2} \alpha \theta_1 \left(1 - \frac{\theta_2 \gamma}{\theta_2 - 1} \right) AUX_ENDO_LAG_2.1_{t-1}^{(-1)} \right) \right) = 0
\end{aligned} \tag{12}$$

$$\begin{aligned}
C_t^{(-\phi_c)} &= \lambda_{t-1} + (1-\delta) C_{t+1}^{(-\phi_c)} \beta + \lambda_{t+1} \beta (1-\delta) \left(- \left((-\phi_c) C_{t+1}^{(-\phi_c) - 1} \right) \right) + \lambda_t \left((-\phi_c) C_t^{(-\phi_c) - 1} + (1 + R_{t+1} - \delta) (1-\delta) (-\phi_c) C_{t+1}^{(-\phi_c) - 1} \beta \right. \\
& \quad \left. + \left((-\alpha) Y_{t+1} K_{t-1}^{(-2)} + K_{t-1}^{(-2)} \alpha (1-\gamma) \tau_{t+1} Y_{t+1}^{1-\gamma} - K_{t-1}^{(-2)} Y_{t+1}^{1-\gamma} \alpha (1-\gamma) \tau_{t+1} \mu_{t+1} + K_{t-1}^{(-2)} \alpha \theta_1 Y_{t+1} \mu_{t+1}^{\theta_2} \right) C_{t+1}^{(-\phi_c)} \beta \right) \\
& \quad + (1 + R_t - \delta) \left(- \left((-\phi_c) C_t^{(-\phi_c) - 1} \right) \right) - \alpha K_{t-1}^{\alpha-1} A_{t+1} \beta \omega_{t+1} (1 - (d_0 + d_2 X_t^2 + d_1 X_t))
\end{aligned} \tag{13}$$

$$AUX_ENDO_LAG_2.1_t = K_{t-1} \tag{14}$$