SIT 789

Task 5.2: Minor research project

1. Introduction

Artificial Intelligence has been changing the way of software development across different verticals. Better deep learning models and algorithms are coming up owing to better hardware capabilities and increase in organically generated data. In [1] we can also see this impact on computer vision, where impact of deep learning in the domain of computer vision has been discussed at length. Object detection is a specific subproblem within the domain of computer vision where the objective is to find the exact location as bounding box coordinates on a given image frame. Over last few decades, several algorithms have been proposed for performing object detection. Earlier, classical machine learning methods based on hand crafted features like Haar Cascade as proposed by Viola-Jones in [2] and Histogram of Oriented Gradients (HOG) [3] were used across tasks related to object detection. The impact of deep learning can be seen in object detection scenarios as well, recent deep learning architectures like Faster RCNN [4], SSD [5] and YOLO [6] constitute some of the state-of-the-art object detection deep learning networks. This report focusses on summarising the working of YOLO9000 [7] and finally demonstrates the working using Road Sign Detection dataset [8].

2. The road to YOLO9000

At the time when YOLO [6] was introduced, detection systems used classifiers which used techniques like sliding window or region proposal to classify various regions of image at different scales. YOLO proposed a novel approach of reframing object detection problem as a regression problem, the algorithm uses a unified model to predict object coordinates and class probabilities using raw image pixels. The algorithm outputs multiple bounding boxes and probabilities representing associated class labels and then uses non-maximum suppression to choose dominating object bounding location and label (Shown in figure 1). An added advantage of this approach is that because the network looks at the complete image frame during the training stage, it also learns the contextual information associated with the object of interest through object's neighbourhood.

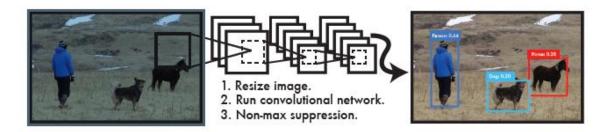


Fig 1: Image showing the working of YOLO [6].

While YOLO had its novelties, it suffered from multiple shortcomings, a significant error when compared to region proposal methods was the low recall of YOLO. YOLO9000 [7] or also known as YOLOv2 was introduced to address these shortcomings and take the YOLO architecture to at par or surpass the state-of-the-art approaches.

3. Why YOLO works?

This section discusses the additions and novel concepts introduced by YOLO9000, which make it the state-of-the-art object detection framework of the time.

YOLO9000 introduced **Batch Normalisation**, this helps the model to improve convergence and tackle regularisation issues. [7] reports 2% increase in mAP (mean Average Precision) after adding Batch Normalisation on all the convolution layers of the original YOLO architecture. Inspired from the use of priors in Faster R-CNN, YOLO9000 introduces the concept of **Anchor Boxes** to the YOLO architecture. To perform this modification, fully connected layer of the original YOLO architecture is removed, and the network learns to predicts offsets with respect to hard coded anchor boxes, this simplifies the learning process. Another key modification while introducing anchor boxes was the reducing the image resolution from 448 x 448 to 416 x416, this forces the network to output odd number of bounding box coordinates for the feature map and the network has only one centre cell. This also means that the output feature map is now of the dimension 13 x 13 as YOLO9000 has convolution layers which down sample the input image by a factor of 32.

With these modifications, another change to the YOLO architecture was needed, the original architecture predicted class probabilities based on actual locations of the object in the image, instead of this, the architecture now predicts class probabilities and *objectness score* for every anchor box. The concept of objectness score is preserved in the modified architecture as well, where objectness score denotes the IOU of the proposed bounding box and the ground truth bounding box and given there is an object, class probabilities denote the conditional probability that of the class labels associated with the object. These changes contribute to a significant increase in recall, taking the initial recall figure of 81% to 88%. While there is an increase in recall, the accuracy of the architecture takes a slight hit going down to 69.2 mAP from 69.5 mAP.

While the introduction of anchor boxes increased recall, it had some shortcomings, the first major shortcoming was the hand picked or hard coded anchors used, this makes it difficult for the network to predict better detections for different objects. To tackle this issue, authors use KMeans to select the anchor boxes (with K value of 5). This strategy results in much higher IOU as opposed to using hard coded anchor boxes.

Because the anchor boxes are predicted as offsets, they might be shifted to an inaccurate location in the image. This unconstrained nature of the anchor boxes prohibits the network to become stable, this is tackled by introducing logistic activation. This is like the approach used in YOLOv1 and the predicted bounding box coordinates are relative to the grid cell location. This squashes the input between 0 and 1 and makes the learning process easier as the offsets are localised the given grid cells and introduces additional stability on the network. Another key experiment was the introduction of passthrough layer, this allows the features from previous layers to be used deeper in the network. This brings higher resolution features and stacks them with lower resolution features, this provides the detector access to an elaborated feature map induced with fine grained features to perform detection.

Another powerful addition to the training process of the improved YOLO9000 architecture is the introduction of **multi-scale training**, during the training process the network chooses an image resolution randomly after every 10 batches. This is possible because the network only consists of convolution and pooling layer, this makes the network elastic enough to be resized during the training process. This also makes the network more robust to handle various input sizes, this makes YOLO9000 ideal for real time applications where such high frame rate is preferred. The range for these resizes

values varies from 320 x 320 to 608 x 608 (multiples of 32, this makes the down sampling convenient). The result of this multi scale training is that the network achieves very **high mAP of 78.6** for high resolution of **544** x **544** at an **FPS of 40** whereas it performs reasonably well at low resolutions of **288** x **288** where it achieves a **decent mAP of 69.0** with very high **91** FPS. This provides the end user a flexibility to use the network depending on the use case (high latency vs high accuracy).

4. Possible improvements on YOLO9000

The previous section describes how and why the YOLO9000 detector came to be known as one of the state-of-the-art detectors. While the modifications to YOLOv1 architecture made several improvements to design and performance, there is still a considerable room for future improvements to the architecture of YOLO9000. This section explores the possible improvements which can make this architecture even more efficient. Section 4.1 highlight some of the work that has already been done to improve YOLO9000 and section 4.2 highlights some proposals which can lay foundations to increase the performance even more.

4.1. The YOLO family

Over the years several implementations have contributed to adding features and improvements to the YOLO9000 architecture. Some of these are from the original authors (Yolov3) while others (YOLOv4, v5, v6, v7) are from different contributors. This is just a brief overview of the other architectures in this family.

YOLOv3 [9]: YOLOv3 aims to improve the accuracy of YOLOv2 and increases the complexity of the features extracted by the convolution layer. To achieve this, the convolution layers are increased from 19 to 53. The framework for training and testing YOLO is developed in C++ is called darknet, for YOLOv3 this framework is called as Darknet-53 and for YOLOv2 Darknet-19, the suffixed number denotes the number of convolution layers in each YOLO architecture. Because YOLOv3 is deeper, it can extract higher order features and thus there is an increase in the accuracy, this is coupled with shortcut connections which enable fine grained features.

YOLOv4 [10]: YOLOv4 builds on top of YOLOv3 and introduces universal features which improve a CNN networks performance, YOLOv4 uses **Weighted-Residual-Connections**, **Self-adversarial-training**, **Mish-activation**, **Cross mini-Batch Normalization**, **Cross-Stage-Partial-connections** to improve the performance. This also uses data augmentation techniques like CutMix, MixUp, Blurring, Mossaic to improve the robustness of the model.

YOLOv5 [11]: YOLOv5 is not a published work rather a PyTorch implementation of existing concepts with minor changes. This work is more focussed on improving integration of the YOLO architecture and is compatible with popular cloud platforms like AWS, GCP and containers like Docker. The focus of this work is to provide wide support for usage of YOLO architecture apart from Darknet framework.

Note: Due to the easy integration, PyTorch compatibility and most resemblance with YOLO9000, this repository is used to demonstrate the working of YOLO on Road Sign Detection Dataset in this report.

YOLOv6 [12]: Building on top of YOLOv4, YOLOv6 improves and modifies the architecture to improve both accuracy and speed using novel quantization method which is responsible for faster FLOPs.

YOLOv7 [13]: YOLOv7 introduces trainable bag of freebies methods, re-parameterization of original model, *compound scaling* and *extend* methods and reducing parameters to increase inference speed and accuracy.

4.2 Other improvements

While the above works suggest that there is ongoing research to increase the efficiency of YOLO architectures, it is important to evaluate these architectures with the AI bias viewpoint so that we can move forward towards a *fair* object detector (YOLO architectures are significantly used in pedestrian detection scenarios, hence it is important to evaluate them on terms of *AI bias*). This will help uncover any prevalent biases and introduce training methods which can help mitigate these.

Another important area of improvement for these architectures is focus on inference using lightweight hardware. As we move towards democratization of AI more and more mobile applications and other lightweight devices (FPGA based devices) will rely on AI models. YOLO has lightweight variants such as tiny-YOLO, but even these modifications are too heavy to run in real time on low power devices, YOLO can be stripped down to a lighter network architecture like [14].

5. Experiment on Road Sign Detection Dataset

This section demonstrates how YOLO can be used to set up a training pipeline and inference pipeline using a custom dataset.

5.1 Dataset Details: The dataset [8] contains 877 samples which are divided as shown in table 1.

The dataset has these class labels:

- traffic light
- stop
- speed limit
- crosswalk

Train	701
Validation	88
Test	88

Table 1: Dataset split

5.2 Training: To train the YOLO model we use the train.py script from the official YOLOv5 repository and save the trained weights to the specified directory. It is important to note that because this is just a demonstration of the training process, we have trained the model till 100 epochs, whereas in real world scenarios the training process can go up in order of thousands of epochs.

This also includes changes to the training hyperparameter config file, where the number of classes parameter must be changed to 4 to reflect updated number of classes.



Fig 2: Training command for YOLO

- **5.3 Testing:** There are several ways to test the trained model, the attached notebook shows using the test script to test on a given test set as well as using the API to test which can be used in real world applications and integrated into inference pipelines.
- **5.4 Results:** Although the network is trained on a small dataset and only for 100 epochs, we can see that the network achieves high mAP of 95.2%, 99.3% Precision and 90.1% Recall. It is important to note that the training uses pretrained weights of YOLOv5 which contributes to such high evaluation

metrics. This also presents the case of how easily YOLO can be used for real world dataset and thus is fit for real world applications with minimal finetuning.

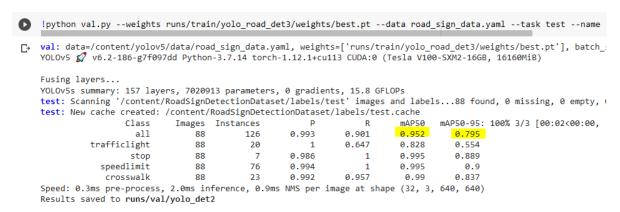


Fig 3: Result showing the overall mAP, Precision and Recall as well as class wise evaluation metrics.

Note: For entire training and testing process please refer to the attached notebook in Appendix – 1.

6. Conclusion

This report summarises the YOLO architecture and highlights the evolution of algorithm over different versions. This report also indicates future areas of improvement in YOLO9000 and other YOLO architectures. Finally, this report showcases the algorithm in practice using a real-world dataset, a similar model can be used in self driving car use-case to identify Road Signs.

7. References

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- [2] P. Viola and M. Jones, "Rapid object detection using a boosted cascade of simple features," in *Proceedings of the 2001 IEEE Computer Society Conference on Computer Vision and Pattern Recognition. CVPR 2001*, 2005, vol. 1, p. I–I.
- [3] N. Dalal and B. Triggs, "Histograms of oriented gradients for human detection," in 2005 IEEE Computer Society Conference on Computer Vision and Pattern Recognition (CVPR'05), 2005, vol. 1, pp. 886–893 vol. 1.
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- [8] Larxel, "Road sign detection." 24-May-2020.
- [9] J. Redmon and A. Farhadi, "YOLOv3: An Incremental Improvement," arXiv [cs.CV], 2018.
- [10] A. Bochkovskiy, C.-Y. Wang, and H.-Y. M. Liao, "YOLOv4: Optimal speed and accuracy of object detection," arXiv [cs.CV], 2020.
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- [12] C. Li *et al.*, "YOLOv6: A single-stage object detection framework for industrial applications," *arXiv* [cs.CV], 2022.

- [13] C.-Y. Wang, A. Bochkovskiy, and H.-Y. M. Liao, "YOLOv7: Trainable bag-of-freebies sets new state-of-the-art for real-time object detectors," *arXiv* [cs.CV], 2022.
- [14] J. Pedoeem and R. Huang, "YOLO-LITE: A real-time object detection algorithm optimized for non-GPU computers," arXiv [cs.CV], 2018.

APPENDIX - I

The following cells require the dataset to be in its respective location.

assignment_5_2

October 7, 2022

```
[1]: gpu_info = !nvidia-smi
    gpu_info = '\n'.join(gpu_info)
    if gpu_info.find('failed') >= 0:
     print('Not connected to a GPU')
    else:
     print(gpu_info)
   Thu Oct 6 12:17:28 2022
   | NVIDIA-SMI 460.32.03 | Driver Version: 460.32.03 | CUDA Version: 11.2
   |-----
                  Persistence-M | Bus-Id Disp.A | Volatile Uncorr. ECC |
   | Fan Temp Perf Pwr:Usage/Cap| Memory-Usage | GPU-Util Compute M. |
                                                           MIG M.
   |------
      O Tesla V100-SXM2... Off | 00000000:00:04.0 Off |
   | N/A 33C PO 23W / 300W | OMiB / 16160MiB |
                                                   0%
                                                          Default |
   | Processes:
   l GPU
          GI CI
                     PID Type Process name
                                                         GPU Memory |
                                                         Usage
    No running processes found
   +----+
[2]: | git clone https://github.com/ultralytics/yolov5 # clone
    !pip install -r yolov5/requirements.txt # install
   fatal: destination path 'yolov5' already exists and is not an empty directory.
   Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab-
   wheels/public/simple/
   Requirement already satisfied: matplotlib>=3.2.2 in
   /usr/local/lib/python3.7/dist-packages (from -r yolov5/requirements.txt (line
   5)) (3.2.2)
   Requirement already satisfied: numpy>=1.18.5 in /usr/local/lib/python3.7/dist-
```

packages (from -r yolov5/requirements.txt (line 6)) (1.21.6)

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Requirement already satisfied: opency-python>=4.1.1 in
/usr/local/lib/python3.7/dist-packages (from -r yolov5/requirements.txt (line
7)) (4.6.0.66)
Requirement already satisfied: Pillow>=7.1.2 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 8)) (7.1.2)
Requirement already satisfied: PyYAML>=5.3.1 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 9)) (6.0)
Requirement already satisfied: requests>=2.23.0 in
/usr/local/lib/python3.7/dist-packages (from -r yolov5/requirements.txt (line
10)) (2.23.0)
Requirement already satisfied: scipy>=1.4.1 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 11)) (1.7.3)
Requirement already satisfied: torch>=1.7.0 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 12)) (1.12.1+cu113)
Requirement already satisfied: torchvision>=0.8.1 in
/usr/local/lib/python3.7/dist-packages (from -r yolov5/requirements.txt (line
13)) (0.13.1+cu113)
Requirement already satisfied: tqdm>=4.64.0 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 14)) (4.64.1)
Requirement already satisfied: tensorboard>=2.4.1 in
/usr/local/lib/python3.7/dist-packages (from -r yolov5/requirements.txt (line
18)) (2.8.0)
Requirement already satisfied: pandas>=1.1.4 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 23)) (1.3.5)
Requirement already satisfied: seaborn>=0.11.0 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 24)) (0.11.2)
Requirement already satisfied: ipython in /usr/local/lib/python3.7/dist-packages
(from -r yolov5/requirements.txt (line 41)) (7.9.0)
Requirement already satisfied: psutil in /usr/local/lib/python3.7/dist-packages
(from -r yolov5/requirements.txt (line 42)) (5.4.8)
Requirement already satisfied: thop>=0.1.1 in /usr/local/lib/python3.7/dist-
packages (from -r yolov5/requirements.txt (line 43)) (0.1.1.post2209072238)
Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.7/dist-
packages (from matplotlib>=3.2.2->-r yolov5/requirements.txt (line 5)) (0.11.0)
Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!=2.1.6,>=2.0.1 in
/usr/local/lib/python3.7/dist-packages (from matplotlib>=3.2.2->-r
yolov5/requirements.txt (line 5)) (3.0.9)
Requirement already satisfied: python-dateutil>=2.1 in
/usr/local/lib/python3.7/dist-packages (from matplotlib>=3.2.2->-r
yolov5/requirements.txt (line 5)) (2.8.2)
Requirement already satisfied: kiwisolver>=1.0.1 in
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yolov5/requirements.txt (line 5)) (1.4.4)
Requirement already satisfied: urllib3!=1.25.0,!=1.25.1,<1.26,>=1.21.1 in
/usr/local/lib/python3.7/dist-packages (from requests>=2.23.0->-r
yolov5/requirements.txt (line 10)) (1.24.3)
Requirement already satisfied: idna<3,>=2.5 in /usr/local/lib/python3.7/dist-
packages (from requests>=2.23.0->-r yolov5/requirements.txt (line 10)) (2.10)
```

```
Requirement already satisfied: certifi>=2017.4.17 in
/usr/local/lib/python3.7/dist-packages (from requests>=2.23.0->-r
yolov5/requirements.txt (line 10)) (2022.6.15)
Requirement already satisfied: chardet<4,>=3.0.2 in
/usr/local/lib/python3.7/dist-packages (from requests>=2.23.0->-r
yolov5/requirements.txt (line 10)) (3.0.4)
Requirement already satisfied: typing-extensions in
/usr/local/lib/python3.7/dist-packages (from torch>=1.7.0->-r
yolov5/requirements.txt (line 12)) (4.1.1)
Requirement already satisfied: tensorboard-data-server<0.7.0,>=0.6.0 in
/usr/local/lib/python3.7/dist-packages (from tensorboard>=2.4.1->-r
yolov5/requirements.txt (line 18)) (0.6.1)
Requirement already satisfied: wheel>=0.26 in /usr/local/lib/python3.7/dist-
packages (from tensorboard>=2.4.1->-r yolov5/requirements.txt (line 18))
(0.37.1)
Requirement already satisfied: absl-py>=0.4 in /usr/local/lib/python3.7/dist-
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Requirement already satisfied: protobuf>=3.6.0 in /usr/local/lib/python3.7/dist-
packages (from tensorboard>=2.4.1->-r yolov5/requirements.txt (line 18))
(3.17.3)
Requirement already satisfied: google-auth<3,>=1.6.3 in
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yolov5/requirements.txt (line 18)) (1.35.0)
Requirement already satisfied: setuptools>=41.0.0 in
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yolov5/requirements.txt (line 18)) (57.4.0)
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Requirement already satisfied: google-auth-oauthlib<0.5,>=0.4.1 in
/usr/local/lib/python3.7/dist-packages (from tensorboard>=2.4.1->-r
yolov5/requirements.txt (line 18)) (0.4.6)
Requirement already satisfied: tensorboard-plugin-wit>=1.6.0 in
/usr/local/lib/python3.7/dist-packages (from tensorboard>=2.4.1->-r
yolov5/requirements.txt (line 18)) (1.8.1)
Requirement already satisfied: markdown>=2.6.8 in /usr/local/lib/python3.7/dist-
packages (from tensorboard>=2.4.1->-r yolov5/requirements.txt (line 18)) (3.4.1)
Requirement already satisfied: pytz>=2017.3 in /usr/local/lib/python3.7/dist-
packages (from pandas>=1.1.4->-r yolov5/requirements.txt (line 23)) (2022.2.1)
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yolov5/requirements.txt (line 18)) (4.9)
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Requirement already satisfied: pyasn1-modules>=0.2.1 in
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auth<3,>=1.6.3->tensorboard>=2.4.1->-r yolov5/requirements.txt (line 18))
(0.2.8)
Requirement already satisfied: cachetools<5.0,>=2.0.0 in
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auth<3,>=1.6.3->tensorboard>=2.4.1->-r yolov5/requirements.txt (line 18))
(4.2.4)
Requirement already satisfied: requests-oauthlib>=0.7.0 in
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(4.12.0)
Requirement already satisfied: zipp>=0.5 in /usr/local/lib/python3.7/dist-
packages (from importlib-metadata>=4.4->markdown>=2.6.8->tensorboard>=2.4.1->-r
yolov5/requirements.txt (line 18)) (3.8.1)
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/usr/local/lib/python3.7/dist-packages (from pyasn1-modules>=0.2.1->google-
auth<3,>=1.6.3->tensorboard>=2.4.1->-r yolov5/requirements.txt (line 18))
(0.4.8)
Requirement already satisfied: oauthlib>=3.0.0 in /usr/local/lib/python3.7/dist-
packages (from requests-oauthlib>=0.7.0->google-auth-
oauthlib<0.5,>=0.4.1->tensorboard>=2.4.1->-r yolov5/requirements.txt (line 18))
(3.2.0)
Requirement already satisfied: pexpect in /usr/local/lib/python3.7/dist-packages
(from ipython->-r yolov5/requirements.txt (line 41)) (4.8.0)
Requirement already satisfied: pygments in /usr/local/lib/python3.7/dist-
packages (from ipython->-r yolov5/requirements.txt (line 41)) (2.6.1)
Requirement already satisfied: decorator in /usr/local/lib/python3.7/dist-
packages (from ipython->-r yolov5/requirements.txt (line 41)) (4.4.2)
Requirement already satisfied: backcall in /usr/local/lib/python3.7/dist-
packages (from ipython->-r yolov5/requirements.txt (line 41)) (0.2.0)
Requirement already satisfied: traitlets>=4.2 in /usr/local/lib/python3.7/dist-
packages (from ipython->-r yolov5/requirements.txt (line 41)) (5.1.1)
Requirement already satisfied: prompt-toolkit<2.1.0,>=2.0.0 in
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(line 41)) (2.0.10)
Requirement already satisfied: pickleshare in /usr/local/lib/python3.7/dist-
packages (from ipython->-r yolov5/requirements.txt (line 41)) (0.7.5)
Requirement already satisfied: jedi>=0.10 in /usr/local/lib/python3.7/dist-
packages (from ipython->-r yolov5/requirements.txt (line 41)) (0.18.1)
Requirement already satisfied: parso<0.9.0,>=0.8.0 in
/usr/local/lib/python3.7/dist-packages (from jedi>=0.10->ipython->-r
yolov5/requirements.txt (line 41)) (0.8.3)
Requirement already satisfied: wcwidth in /usr/local/lib/python3.7/dist-packages
```

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41)) (0.2.5)
     Requirement already satisfied: ptyprocess>=0.5 in /usr/local/lib/python3.7/dist-
     packages (from pexpect->ipython->-r yolov5/requirements.txt (line 41)) (0.7.0)
[34]: import torch
      from IPython.display import Image # for displaying images
      import os
      import random
      import shutil
      from sklearn.model_selection import train_test_split
      import xml.etree.ElementTree as ET
      from xml.dom import minidom
      from tqdm import tqdm
      from PIL import Image, ImageDraw
      import numpy as np
      import matplotlib.pyplot as plt
      import glob
      import cv2
 [4]: from google.colab import drive
      drive.mount('/content/gdrive')
      !cp -f '/content/gdrive/MyDrive/sit789_assignment_5_2_data/
       →RoadSignDetectionDataset.zip' '/content/'
      !rm -rf RoadSignDetectionDataset
      !mkdir RoadSignDetectionDataset
      !unzip /content/RoadSignDetectionDataset.zip -d /content/
       →RoadSignDetectionDataset/
     Drive already mounted at /content/gdrive; to attempt to forcibly remount, call
     drive.mount("/content/gdrive", force_remount=True).
     Archive: /content/RoadSignDetectionDataset.zip
       inflating: /content/RoadSignDetectionDataset/annotations/road0.xml
       inflating: /content/RoadSignDetectionDataset/annotations/road1.xml
       inflating: /content/RoadSignDetectionDataset/annotations/road10.xml
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       inflating: /content/RoadSignDetectionDataset/annotations/road109.xml
       inflating: /content/RoadSignDetectionDataset/annotations/road11.xml
       inflating: /content/RoadSignDetectionDataset/annotations/road110.xml
       inflating: /content/RoadSignDetectionDataset/annotations/road111.xml
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(from prompt-toolkit<2.1.0,>=2.0.0->ipython->-r yolov5/requirements.txt (line

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      inflating: /content/RoadSignDetectionDataset/images/road96.png
      inflating: /content/RoadSignDetectionDataset/images/road97.png
      inflating: /content/RoadSignDetectionDataset/images/road98.png
      inflating: /content/RoadSignDetectionDataset/images/road99.png
[5]: def extract_info_from_xml(xml_file):
         root = ET.parse(xml file).getroot()
         # Initialise the info dict
         info_dict = {}
         info_dict['bboxes'] = []
         # Parse the XML Tree
         for elem in root:
             # Get the file name
             if elem.tag == "filename":
                 info_dict['filename'] = elem.text
             # Get the image size
             elif elem.tag == "size":
                 image size = []
                 for subelem in elem:
                     image_size.append(int(subelem.text))
                 info_dict['image_size'] = tuple(image_size)
             # Get details of the bounding box
             elif elem.tag == "object":
                 bbox = \{\}
                 for subelem in elem:
                     if subelem.tag == "name":
                         bbox["class"] = subelem.text
                     elif subelem.tag == "bndbox":
                         for subsubelem in subelem:
                             bbox[subsubelem.tag] = int(subsubelem.text)
                 info_dict['bboxes'].append(bbox)
         return info_dict
```

inflating: /content/RoadSignDetectionDataset/images/road90.png

```
[6]: print(extract_info_from_xml('/content/RoadSignDetectionDataset/annotations/

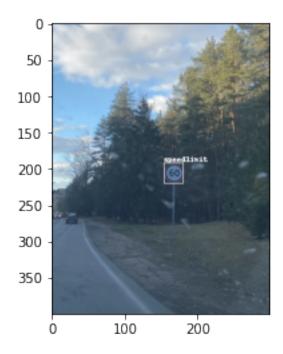
¬road4.xml'))
    {'bboxes': [{'class': 'trafficlight', 'xmin': 20, 'ymin': 109, 'xmax': 81,
    'ymax': 237}, {'class': 'trafficlight', 'xmin': 116, 'ymin': 162, 'xmax': 163,
    'ymax': 272}, {'class': 'trafficlight', 'xmin': 189, 'ymin': 189, 'xmax': 233,
    'ymax': 295}], 'filename': 'road4.png', 'image_size': (267, 400, 3)}
[7]: # Dictionary that maps class names to IDs
    class_name_to_id_mapping = {"trafficlight": 0,
                                "stop": 1,
                                "speedlimit": 2,
                                "crosswalk": 3}
    # Convert the info dict to the required yolo format and write it to disk
    def convert_to_yolov5(info_dict):
        print_buffer = []
         # For each bounding box
        for b in info_dict["bboxes"]:
            try:
                 class_id = class_name_to_id_mapping[b["class"]]
             except KeyError:
                 print("Invalid Class. Must be one from ", class_name_to_id_mapping.
      →keys())
             # Transform the bbox co-ordinates as per the format required by YOLO v5
            b_{center_x} = (b["xmin"] + b["xmax"]) / 2
            b_{eq} = (b["ymin"] + b["ymax"]) / 2
            b_{width} = (b["xmax"] - b["xmin"])
            b_height = (b["ymax"] - b["ymin"])
             # Normalise the co-ordinates by the dimensions of the image
             image_w, image_h, image_c = info_dict["image_size"]
            b center x /= image w
            b_center_y /= image_h
            b_width /= image_w
            b height
                      /= image_h
             #Write the bbox details to the file
            print_buffer.append("{} {:.3f} {:.3f} {:.3f}".format(class_id,__
      →b_center_x, b_center_y, b_width, b_height))
         # Name of the file which we have to save
         save_file_name = os.path.join("./annotations", info_dict["filename"].
      →replace("png", "txt"))
```

```
# Save the annotation to disk
          print("\n".join(print_buffer), file= open(save_file_name, "w"))
[11]: %cd /content/RoadSignDetectionDataset
     /content/RoadSignDetectionDataset
     /content/RoadSignDetectionDataset
[12]: # Get the annotations
      annotations = [os.path.join('./annotations', x) for x in os.listdir('./
      ⇒annotations') if x[-3:] == "xml"]
      annotations.sort()
      # Convert and save the annotations
      for ann in tqdm(annotations):
          info_dict = extract_info_from_xml(ann)
          convert_to_yolov5(info_dict)
      annotations = [os.path.join('./annotations', x) for x in os.listdir('./
       \rightarrowannotations') if x[-3:] == "txt"]
     100%|
               | 877/877 [00:00<00:00, 6939.27it/s]
[19]: class_id_to_name_mapping = dict(zip(class_name_to_id_mapping.values(),__

¬class_name_to_id_mapping.keys()))
      def plot_bounding_box(image, annotation_list):
         annotations = np.array(annotation_list)
         w, h = image.size
         plotted_image = ImageDraw.Draw(image)
         transformed_annotations = np.copy(annotations)
         transformed_annotations[:,[1,3]] = annotations[:,[1,3]] * w
         transformed_annotations[:,[2,4]] = annotations[:,[2,4]] * h
         transformed_annotations[:,1] = transformed_annotations[:,1] -_
       ⇔(transformed_annotations[:,3] / 2)
          transformed_annotations[:,2] = transformed_annotations[:,2] -_
       transformed_annotations[:,3] = transformed_annotations[:,1] +__
       ⇔transformed_annotations[:,3]
          transformed_annotations[:,4] = transformed_annotations[:,2] +__
       ⇔transformed annotations[:,4]
         for ann in transformed_annotations:
             obj_cls, x0, y0, x1, y1 = ann
             plotted_image.rectangle(((x0,y0), (x1,y1)))
```

```
plotted_image.text((x0, y0 - 10),__
 ⇔class_id_to_name_mapping[(int(obj_cls))])
   plt.imshow(np.array(image))
   plt.show()
# Get any random annotation file
annotation_file = random.choice(annotations)
with open(annotation_file, "r") as file:
   annotation_list = file.read().split("\n")[:-1]
   annotation_list = [x.split(" ") for x in annotation_list]
   annotation_list = [[float(y) for y in x ] for x in annotation_list]
#Get the corresponding image file
image_file = annotation_file.replace("annotations", "images").replace("txt", __

¬"png")
assert os.path.exists(image_file)
#Load the image
image = Image.open(image_file)
#Plot the Bounding Box
plot_bounding_box(image, annotation_list)
```



```
[20]: # Read images and annotations
      images = [os.path.join('images', x) for x in os.listdir('images')]
      annotations = [os.path.join('annotations', x) for x in os.
       ⇔listdir('annotations') if x[-3:] == "txt"]
      images.sort()
      annotations.sort()
      # Split the dataset into train-valid-test splits
      train_images, val_images, train_annotations, val_annotations =__
       strain_test_split(images, annotations, test_size = 0.2, random_state = 1)
      val_images, test_images, val_annotations, test_annotations =_
       otrain test split(val images, val annotations, test size = 0.5, random state)
       \Rightarrow= 1)
[21]: | mkdir images/train images/val images/test annotations/train annotations/val
       ⇒annotations/test
[22]: #Utility function to move images
      def move_files_to_folder(list_of_files, destination_folder):
          for f in list_of_files:
              try:
                  shutil.move(f, destination_folder)
              except:
                  print(f)
                  assert False
      # Move the splits into their folders
      move_files_to_folder(train_images, 'images/train')
      move files to folder(val images, 'images/val/')
      move_files_to_folder(test_images, 'images/test/')
      move_files_to_folder(train_annotations, 'annotations/train/')
      move_files_to_folder(val_annotations, 'annotations/val/')
      move files_to_folder(test_annotations, 'annotations/test/')
[26]: !mv annotations labels
      %cd ../yolov5
     mv: cannot stat 'annotations': No such file or directory
     /content/yolov5
[27]: !pwd
     /content/yolov5
[31]: | !python train.py --img 640 --cfg yolov5s.yaml --hyp hyp.scratch-high.yaml_
       →--batch 32 --epochs 100 --data road_sign_data.yaml --weights yolov5s.ptu
       →--workers 24 --name yolo_road_det
```

data=road_sign_data.yaml, hyp=hyp.scratch-high.yaml, epochs=100, batch_size=32, imgsz=640, rect=False, resume=False, nosave=False, noval=False, noautoanchor=False, noplots=False, evolve=None, bucket=, cache=None, image weights=False, device=, multi scale=False, single cls=False, optimizer=SGD, sync_bn=False, workers=24, project=runs/train, name=yolo road det, exist ok=False, quad=False, cos lr=False, label_smoothing=0.0, patience=100, freeze=[0], save_period=-1, seed=0, local_rank=-1, entity=None, upload_dataset=False, bbox_interval=-1, artifact alias=latest github: up to date with https://github.com/ultralytics/yolov5 YOLOv5 v6.2-186-g7f097dd Python-3.7.14 torch-1.12.1+cu113 CUDA:0 (Tesla V100-SXM2-16GB, 16160MiB) hyperparameters: lr0=0.01, lrf=0.1, momentum=0.937, weight_decay=0.0005, warmup_epochs=3.0, warmup_momentum=0.8, warmup_bias_lr=0.1, box=0.05, cls=0.3, cls_pw=1.0, obj=0.7, obj_pw=1.0, iou_t=0.2, anchor_t=4.0, fl_gamma=0.0, hsv_h=0.015, hsv_s=0.7, hsv_v=0.4, degrees=0.0, translate=0.1, scale=0.9, shear=0.0, perspective=0.0, flipud=0.0, fliplr=0.5, mosaic=1.0, mixup=0.1, copy paste=0.1 Weights & Biases: run 'pip install wandb' to automatically track and visualize YOLOv5 runs in Weights & Biases ClearML: run 'pip install clearml' to automatically track, visualize and remotely train YOLOv5 in ClearML Comet: run 'pip install comet_ml' to automatically track and visualize YOLOv5 runs in Comet TensorBoard: Start with 'tensorboard --logdir runs/train', view at http://localhost:6006/ Downloading https://ultralytics.com/assets/Arial.ttf to /root/.config/Ultralytics/Arial.ttf...

Overriding model.yaml nc=80 with nc=4

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100% 755k/755k [00:00<00:00, 51.0MB/s]

Downloading

yolov5s.pt...

train: weights=yolov5s.pt, cfg=yolov5s.yaml,

	from	n	params	module	
arguments					
0	-1	1	3520	models.common.Conv	[3,
32, 6, 2, 2]					
1	-1	1	18560	models.common.Conv	[32,
64, 3, 2]					
2	-1	1	18816	models.common.C3	[64,
64, 1]					
3	-1	1	73984	models.common.Conv	[64,
128, 3, 2]					

https://github.com/ultralytics/yolov5/releases/download/v6.2/yolov5s.pt to

```
4
                   -1 2
                            115712 models.common.C3
[128, 128, 2]
                            295424 models.common.Conv
                   -1 1
 5
[128, 256, 3, 2]
                   -1 3
                            625152 models.common.C3
[256, 256, 3]
                   -1 1
                           1180672 models.common.Conv
 7
[256, 512, 3, 2]
                           1182720 models.common.C3
                   -1 1
[512, 512, 1]
                            656896 models.common.SPPF
 9
                   -1 1
[512, 512, 5]
                            131584 models.common.Conv
10
                   -1 1
[512, 256, 1, 1]
11
                   -1 1
                                    torch.nn.modules.upsampling.Upsample
[None, 2, 'nearest']
12
              [-1, 6]
                      1
                                 0 models.common.Concat
                                                                             [1]
13
                   -1
                       1
                            361984 models.common.C3
[512, 256, 1, False]
                   -1 1
                             33024 models.common.Conv
[256, 128, 1, 1]
15
                   -1 1
                                 0 torch.nn.modules.upsampling.Upsample
[None, 2, 'nearest']
16
              [-1, 4]
                                 0 models.common.Concat
                                                                             [1]
17
                   -1 1
                             90880 models.common.C3
[256, 128, 1, False]
                            147712 models.common.Conv
[128, 128, 3, 2]
                                 0 models.common.Concat
                                                                             [1]
19
             [-1, 14]
20
                            296448
                                    models.common.C3
[256, 256, 1, False]
21
                   -1 1
                            590336 models.common.Conv
[256, 256, 3, 2]
22
             [-1, 10]
                                 0 models.common.Concat
                                                                             [1]
                      1
23
                           1182720 models.common.C3
                   -1
[512, 512, 1, False]
         [17, 20, 23] 1
                             24273 models.yolo.Detect
                                                                             [4,
[[10, 13, 16, 30, 33, 23], [30, 61, 62, 45, 59, 119], [116, 90, 156, 198, 373,
326]], [128, 256, 512]]
YOLOv5s summary: 214 layers, 7030417 parameters, 7030417 gradients, 16.0 GFLOPs
Transferred 342/349 items from yolov5s.pt
AMP: checks passed
optimizer: SGD(lr=0.01) with parameter groups 57 weight(decay=0.0),
60 weight(decay=0.0005), 60 bias
albumentations: Blur(p=0.01, blur_limit=(3, 7)), MedianBlur(p=0.01,
blur_limit=(3, 7)), ToGray(p=0.01), CLAHE(p=0.01, clip_limit=(1, 4.0),
tile_grid_size=(8, 8))
```

train: Scanning '/content/RoadSignDetectionDataset/labels/train'

images and labels...701 found, 0 missing, 0 empty, 0 corrupt: 100% 701/701

[00:00<00:00, 5610.25it/s]

train: New cache created:

/content/RoadSignDetectionDataset/labels/train.cache

val: Scanning '/content/RoadSignDetectionDataset/labels/val' images

and labels...88 found, 0 missing, 0 empty, 0 corrupt: 100% 88/88 [00:00<00:00,

909.22it/s]

val: New cache created:

/content/RoadSignDetectionDataset/labels/val.cache

AutoAnchor: 5.59 anchors/target, 1.000 Best Possible Recall (BPR).

Current anchors are a good fit to dataset

Plotting labels to runs/train/yolo_road_det3/labels.jpg...

Image sizes 640 train, 640 val

Using 8 dataloader workers

Logging results to runs/train/yolo_road_det3

Starting training for 100 epochs...

Epoch	$\mathtt{GPU}_\mathtt{mem}$	box_loss	obj_loss	cls_loss	Instances	Size
0/99	6.46G	0.1083	0.02287	0.02311	87	640:
100% 22/22 [00	:08<00:00,	2.70it/s	:]			
	Class	Images	Instances	P	R	mAP50
mAP50-95: 100%	2/2 [00:0	2<00:00,	1.48s/it]			
	all	88		0.696	0.205	0.17
0.0441						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
1/99	8.08G	0.06918	0.02491	0.01784	100	640:
100% 22/22 [00	:04<00:00,	4.46it/s	:]			
	Class	Images	Instances	P	R	mAP50
mAP50-95: 100%	2/2 [00:0	1<00:00,	1.50it/s]			
	all	88	132	0.727	0.182	0.184
0.067						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
2/99	8.08G	0.05932	0.02193	0.01667	112	640:
100% 22/22 [00	:04<00:00,	4.75it/s	:]			
	Class	Images	Instances	P	R	mAP50
mAP50-95: 100%	2/2 [00:0	1<00:00,	1.46it/s]			
	all	88	132	0.623	0.195	0.125
0.0459						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
3/99	8.08G	0.05778	0.01939	0.01546	95	640:
100% 22/22 [00	:05<00:00,	3.87it/s	:]			
			Instances	P	R	mAP50
mAP50-95: 100%		•				
		•	_			

	all	88	132	0.738	0.239	0.197
0.106						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
4/99 100% 22/22 [00				0.01424	72	640:
mAP50-95: 100%		_	Instances 1.95it/s]	Р	R	mAP50
	all	88		0.371	0.429	0.441
0.211						
Epoch			obj_loss		Instances	Size
5/99			0.01466	0.01197	105	640:
100% 22/22 [00				D	D	ADEO
mAP50-95: 100%		•	Instances	Р	R	mAP50
mar 00 55. 100%	all	88		0.466	0.647	0.598
0.275						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
6/99				0.0103	93	640:
100% 22/22 [00			3]			
		•	Instances	P	R	mAP50
mAP50-95: 100%				0.000	0.600	0.707
0.358	all	88	132	0.832	0.629	0.787
0.556						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
7/99			-	0.008366	93	640:
100% 22/22 [00	:05<00:00,	3.89it/s	3]			
		•	Instances	P	R	mAP50
mAP50-95: 100%						
0.405	all	88	132	0.741	0.789	0.826
0.405						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
8/99	8.08G		0.01024		93	640:
100% 22/22 [00	:05<00:00,	4.03it/s	3]			
	Class	Images		P	R	mAP50
mAP50-95: 100%						
	all	88	132	0.863	0.802	0.882
0.446						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
9/99	8.08G	0.03994	U –	0.006396	107	640:
100% 22/22 [00	:05<00:00,	4.12it/s	3]			
	Class	Images		Р	R	mAP50
mAP50-95: 100%	2/2 [00:0	1<00:00,	1.57it/s]			

	all	88	132	0.811	0.833	0.846
0.473						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
10/99 100% 22/22 [00			0.00921 s]	0.005511	82	640:
		_	Instances	Р	R	mAP50
mAP50-95: 100%	2/2 [00:0 all	0<00:00, 88	2.30it/s] 132	0.912	0.882	0.925
0.503	ull.	00	102	0.012	0.002	0.020
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
11/99			0.009302	0.005117	106	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		•		-		
	all	88	132	0.839	0.868	0.856
0.501						
Epoch			obj_loss		Instances	Size
12/99			0.008653	0.004564	107	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		•		_		
	all	88	132	0.931	0.914	0.931
0.527						
Epoch			obj_loss		Instances	Size
13/99			0.008664	0.004032	81	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		•		1	10	mai oo
	all	88	132	0.826	0.917	0.909
0.541						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
14/99	8.08G	0.03359		0.003831	81	640:
100% 22/22 [00	:05<00:00, Class	3.88it/s Images		Р	R	mAP50
mAP50-95: 100%		•		Г	11	IIIAF 30
	all	88	132	0.922	0.888	0.94
0.585						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
15/99	8.08G	0.03281		0.003723	88	640:
100% 22/22 [00	:05<00:00, Class			ח	מ	m \ D ⊑ ∩
mAP50-95: 100%		Images 1<00:00,		Р	R	mAP50

	all	88	132	0.965	0.88	0.941
0.579						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
16/99		0.0319		0.003496	92	640:
100% 22/22 [00		3.98it/s Images		Р	R	mAP50
mAP50-95: 100%		•		Г	r.	MAPSO
	all	88	132	0.974	0.905	0.967
0.594						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
17/99			0.007651	0.003462	72	640:
100% 22/22 [00				D	R	ADEO
mAP50-95: 100%		Images 0<00:00.		Р	r.	mAP50
	all	88	132	0.938	0.941	0.962
0.644						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
18/99			0.008038	0.003225	129	640:
100% 22/22 [00				D	D	ADEO
mAP50-95: 100%		_	Instances 2.14it/sl	Р	R	mAP50
00 001 2007	all	88	132	0.942	0.937	0.963
0.602						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
19/99		0.03093		0.00322	78	640:
100% 22/22 [00				D	ת	ADEO
mAP50-95: 100%		0	Instances 1.82it/sl	Р	R	mAP50
	all	88	132	0.964	0.953	0.975
0.637						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
20/99	8.08G	0.02957	0.007462	0.002836	95	640:
100% 22/22 [00	· ·			D	70	ADEO
mAP50-95: 100%	Class	_	Instances 2 04it/sl	Р	R	mAP50
mm 00 00. 100%	all	88	132	0.956	0.938	0.962
0.639						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
21/99	8.08G	0.02988		0.00294	72	640:
100% 22/22 [00	0:06<00:00, Class	3.65it/s Images		Р	R	mAP50
mAP50-95: 100%		_		г	II.	mar 50

	all	88	132	0.918	0.924	0.953
0.614						
Epoch 22/99 100% 22/22 [00	8.08G	0.0289		cls_loss 0.002786	Instances 100	Size 640:
mAP50-95: 100%	Class	Images	Instances	P	R	mAP50
0.606	all	88	132	0.975	0.924	0.948
0.000						
Epoch 23/99 100% 22/22 [00	8.08G	0.02918	obj_loss 0.007114		Instances 90	Size 640:
mAP50-95: 100%	Class	Images	Instances	Р	R	mAP50
mai 00 95. 100%	all	88	132	0.981	0.921	0.953
0.597						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
24/99 100% 22/22 [00	8.08G	0.02908	0.007546		93	640:
mAP50-95: 100%	Class	Images	Instances	Р	R	mAP50
miii 00 00. 100/8	all	88	132	0.95	0.949	0.978
0.695						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
25/99			•	0.002307	91	640:
100% 22/22 [00				D	D	ADEO
mAP50-95: 100%		Images 1<00:00,		Р	R	mAP50
	all	88	132	0.951	0.944	0.965
0.672						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
26/99	8.08G	0.02712	0.007153	0.002457	95	640:
100% 22/22 [00	0:05<00:00, Class			Р	R	A DE O
mAP50-95: 100%		Images 1<00:00,		P	ĸ	mAP50
0.686	all	88	132	0.942	0.928	0.966
0.000						
Epoch			u –	cls_loss		Size
27/99 100% 22/22 [00	8.08G 0:05<00:00.	0.02743 3.86it/s		0.00251	98	640:
mAP50-95: 100%	Class	Images	Instances	Р	R	mAP50
	, _, _ [00.0	,	,			

	all	88	132	0.981	0.943	0.961
0.717						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
28/99			0.00686	0.002348	107	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		_		1	10	IIIAI 50
	all	88	132	0.963	0.95	0.974
0.723						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
29/99			0.007231	0.002493	75	640:
100% 22/22 [00		3.97it/s Images		Р	R	mAP50
mAP50-95: 100%		_		1	10	IIIAI 50
	all	88	132	0.958	0.981	0.989
0.705						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
30/99				0.00217	75	640:
100% 22/22 [00				D	ת	ADEO
mAP50-95: 100%		_	Instances 1.56it/sl	Р	R	mAP50
	all	88	132	0.954	0.971	0.98
0.694						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
31/99		0.02723		0.002381	113	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		_		Г	r.	MAPSO
	all	88	132	0.966	0.944	0.977
0.713						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
32/99	8.08G	0.02561	0.007232	0.00223	85	640:
100% 22/22 [00				D	.	ADEO
mAP50-95: 100%	Class 2/2 [00:0	_	Instances 1 77it/sl	Р	R	mAP50
mm 00 00. 100/6	all	88	132	0.957	0.965	0.98
0.716						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
33/99	8.08G	0.02568		0.002239	93	640:
100% 22/22 [00	:05<00:00, Class	4.34it/s Images		Р	R	mAP50
mAP50-95: 100%				r	11	mai 50

	all	88	132	0.971	0.897	0.966
0.672						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
34/99	8.08G	0.02528		0.002148	84	640:
100% 22/22 [00		3.851t/s Images		Р	R	mAP50
mAP50-95: 100%		•		-		
	all	88	132	0.95	0.926	0.97
0.725						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
35/99			0.006875	0.001967	78	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		_		1	10	IIIAI 00
	all	88	132	0.928	0.965	0.976
0.718						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
36/99			0.00686	0.002048	129	640:
100% 22/22 [00			s] Instances	Р	R	mAP50
mAP50-95: 100%		_		Г	It.	IIIAF 50
	all	88	132	0.977	0.92	0.981
0.704						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
37/99		0.02389		0.002111	81	640:
100% 22/22 [00			s] Instances	Р	R	mAP50
mAP50-95: 100%		•		Г	It.	IIIAF 50
	all	88	132	0.968	0.943	0.962
0.731						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
38/99	8.08G	0.02478		0.001945	92	640:
100% 22/22 [00	:05<00:00, Class		s] Instances	Р	R	mAP50
mAP50-95: 100%		•		Г	r.	MAPSO
	all	88	132	0.965	0.924	0.974
0.744						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
39/99	8.08G	0.0245	0.006911	0.001883	103	640:
100% 22/22 [00	:05<00:00, Class	4.05it/s Images		Р	R	mAP50
mAP50-95: 100%				۲	r,	ШАРЭО

	all	88	132	0.986	0.924	0.978
0.73						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
40/99			0.006571	0.001915	87	640:
100% 22/22 [00				D	D	ADEO
mAP50-95: 100%		Images 0<00:00.		Р	R	mAP50
	all	88	132	0.968	0.948	0.977
0.757						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
41/99			0.006809	0.001882	120	640:
100% 22/22 [00		3.76it/s Images		ח	R	∞ A DE O
mAP50-95: 100%		_		Р	n.	mAP50
	all	88	132	0.983	0.941	0.98
0.728						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
42/99			0.00653	0.001925	78	640:
100% 22/22 [00				.		1750
mAP50-95: 100%		_	Instances 2 02it/sl	Р	R	mAP50
MAI 00 00. 100%	all	88	132	0.922	0.979	0.974
0.712						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
43/99		0.0228	0.006247	0.001741	80	640:
100% 22/22 [00				D	D	ADEO
mAP50-95: 100%		_	Instances 2.35it/sl	Р	R	mAP50
	all	88	132	0.948	0.962	0.981
0.719						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
44/99	8.08G	0.02229		0.001663	79	640:
100% 22/22 [00	· ·			_	_	1550
mAP50-95: 100%	Class	_	Instances	Р	R	mAP50
mar 50 95. 100%	all	88	132	0.889	0.974	0.972
0.738						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
45/99	8.08G	0.02211	0.006153	0.00182	90	640:
100% 22/22 [00				-	5	4550
mAP50-95: 100%	Class 2/2 [00:0	Images 0<00:00,		Р	R	mAP50

	all	88	132	0.979	0.933	0.975
0.735						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
46/99	8.08G		0.006025	0.001796	105	640:
100% 22/22 [00	:06<00:00,	3.29it/s	5]			
		Images		P	R	mAP50
mAP50-95: 100%						
0.740	all	88	132	0.981	0.944	0.977
0.743						
Epoch	CPII mem	hov loss	obj_loss	cla loss	Instances	Size
47/99			0.006173		59	640:
100% 22/22 [00				0,00000.1		0.201
			Instances	P	R	mAP50
mAP50-95: 100%	2/2 [00:0	1<00:00,	1.73it/s]			
	all	88	132	0.956	0.966	0.967
0.741						
					_	
_			obj_loss			Size
48/99		0.0216		0.001681	90	640:
100% 22/22 [00				D	D	ADEO
mAP50-95: 100%		_	Instances	Р	R	mAP50
MAP50-95. 100%	all	88	132	0.979	0.931	0.968
0.746	all	00	102	0.919	0.331	0.900
0.710						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
49/99		0.02123	-	0.001655	82	640:
100% 22/22 [00	:05<00:00,	3.88it/s	s]			
	Class	Images	Instances	P	R	mAP50
mAP50-95: 100%	2/2 [00:0	1<00:00,	1.93it/s]			
	all	88	132	0.974	0.968	0.981
0.764						
Post of	(IDII	1	.1.4 7	-1- 1	T.,	Q ÷
Epoch 50/99	GPU_mem 8.08G	0.02203	obj_loss 0.006111	cls_loss 0.001561	Instances 89	Size 640:
100% 22/22 [00				0.001561	09	640:
100% 22/22 [00	Class	Images		Р	R	mAP50
mAP50-95: 100%		•		•	10	mm 00
00 00. 100/	all	88	132	0.98	0.925	0.962
0.736						
Epoch	_	box_loss	u –		Instances	Size
51/99	8.08G	0.02125		0.001574	57	640:
100% 22/22 [00						
	Class	Images		P	R	mAP50
mAP50-95: 100%	, 2/2 [00:0	1<00:00,	1.97it/s]			

	all	88	132	0.979	0.962	0.975
0.748						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
52/99	8.08G		0.006075	0.001573	81	640:
100% 22/22 [00		4.35it/s Images		Р	R	mAP50
mAP50-95: 100%		•		1	10	IIIAI 00
	all	88	132	0.971	0.967	0.972
0.732						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
53/99			0.006079	0.001534	88	640:
100% 22/22 [00		3.22it/s Images		Р	R	mAP50
mAP50-95: 100%		•		1	10	mai oo
	all	88	132	0.928	0.973	0.975
0.76						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
54/99			0.00584	0.001547	86	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		_		Г	r.	MAPSO
	all	88	132	0.932	0.974	0.97
0.771						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
55/99		0.02098		0.001354	97	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		_		Г	r.	MAPSO
	all	88	132	0.942	0.97	0.983
0.764						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
56/99	8.08G	0.02078	0.006223	0.001337	107	640:
100% 22/22 [00	•			D	.	ADEO
mAP50-95: 100%	Class	Images 1<00.00		Р	R	mAP50
mm 00 00. 100%	all	88	132	0.936	0.971	0.984
0.75						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
57/99	8.08G	0.02053		0.00144	57	640:
100% 22/22 [00	0:06<00:00, Class	3.38it/s Images		Р	R	mAP50
mAP50-95: 100%				r	II.	шагоо

	all	88	132	0.918	0.984	0.984
0.763						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
58/99	8.08G	0.02003		0.001456	97	640:
100% 22/22 [00		3.77it/s Images		Р	R	mAP50
mAP50-95: 100%		_		1	10	IIIAI 50
	all	88	132	0.944	0.959	0.984
0.763						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
59/99			0.005878	0.001516	97	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		•		1	10	IIIAI 50
	all	88	132	0.954	0.97	0.981
0.766						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
60/99			0.005838	0.001416	83	640:
100% 22/22 [00				D	R	∞ A DE O
mAP50-95: 100%		_	Instances 1.87it/s]	Р	r.	mAP50
	all	88	132	0.984	0.914	0.975
0.765						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
61/99		0.02001		0.001352	91	640:
100% 22/22 [00			Instances	D	ת	mAP50
mAP50-95: 100%		0		Р	R	MAPSU
	all	88	132	0.951	0.97	0.984
0.77						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
62/99	8.08G	0.01964	0.005909	0.001306	78	640:
100% 22/22 [00	•			D	70	ADEO
mAP50-95: 100%	Class 2/2 [00:0	Images 0<00:00		Р	R	mAP50
mm 00 00. 100%	all	88	132	0.978	0.979	0.991
0.782						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
63/99	8.08G	0.01921	0.005922	0.001344	81	640:
100% 22/22 [00	:06<00:00, Class			ת	R	~ ADEO
mAP50-95: 100%		Images 1<00:00,		Р	ĸ	mAP50

	all	88	132	0.924	0.983	0.971
0.776						
-	-	_	obj_loss	-		Size
64/99 100% 22/22 [00	8.08G	0.018 4.07it/s		0.001249	108	640:
100% 22/22 [00		Images		Р	R	mAP50
mAP50-95: 100%		-				
0.755	all	88	132	0.965	0.934	0.976
0.700						
-			obj_loss			Size
65/99 100% 22/22 [00			0.005869	0.001095	95	640:
100% 22/22 [00		Images		Р	R	mAP50
mAP50-95: 100%						
0.775	all	88	132	0.937	0.984	0.974
0.110						
-	_	_	obj_loss	_		Size
66/99 100% 22/22 [00			0.005993	0.001225	85	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%				0.050		0 005
0.767	all	88	132	0.959	0.98	0.985
0.1.01						
-			obj_loss			Size
67/99 100% 22/22 [00		0.01945 3.60it/s		0.001283	98	640:
100,0 ==, == 200			Instances	Р	R	mAP50
mAP50-95: 100%		-		0.000	0.05	0.004
0.78	all	88	132	0.966	0.95	0.984
Epoch	-	box_loss	u =	_	Instances	Size
68/99 100% 22/22 [00	8.08G 0:05<00:00.	0.01815 3.76it/s		0.00129	87	640:
	Class	Images		Р	R	mAP50
mAP50-95: 100%				0.000	0.000	0.004
0.779	all	88	132	0.962	0.933	0.984
Epoch	_	box_loss	u –	cls_loss	Instances	Size
69/99 100% 22/22 [00	8.08G 0:05<00:00,	0.01852 3.82it/s		0.001265	102	640:
	Class	Images	Instances	Р	R	mAP50
mAP50-95: 100%	2/2 [00:0	1<00:00,	1.68it/s]			

	all	88	132	0.94	0.962	0.973
0.768						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
70/99			0.005545	0.001143	96	640:
100% 22/22 [00		3.581t/s Images		Р	R	mAP50
mAP50-95: 100%		•		•		
	all	88	132	0.977	0.947	0.973
0.79						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
71/99			0.005644	0.001157	110	640:
100% 22/22 [00			s] Instances	Р	R	mAP50
mAP50-95: 100%		_		Г	11.	IIIAF 50
	all	88	132	0.947	0.952	0.974
0.77						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
72/99	8.08G	0.01739	0.005552	0.000976	80	640:
100% 22/22 [00				D	T)	ADEO
mAP50-95: 100%		_	Instances 2.88it/sl	Р	R	mAP50
	all	88	132	0.921	0.961	0.981
0.784						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
73/99		0.0177	•	0.001083	101	640:
100% 22/22 [00				D	T)	ADEO
mAP50-95: 100%		_	Instances 2.24it/sl	Р	R	mAP50
	all	88	132	0.965	0.911	0.979
0.773						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
74/99	8.08G	0.01706		0.001092	71	640:
100% 22/22 [00	-			_	_	4850
mAP50-95: 100%	Class 2/2 [00:0	Images		Р	R	mAP50
mm 00 00. 100/0	all	88	132	0.952	0.955	0.985
0.799						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
75/99	8.08G	0.01731	-	0.001112	107	640:
100% 22/22 [00	-			-	_	
mAP50-95: 100%	Class 2/2 [00:0	Images 0<00:00,		Р	R	mAP50

Epoch		all	88	132	0.95	0.976	0.988
T6/99	0.792						
Class Images Instances P R mAP50	Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
mAP50-95: 100% 2/2 [00:00<00:00, 2.01it/s] all 88 132 0.956 0.944 0.987 0.802 Epoch GPU_mem box_loss obj_loss cls_loss Instances 77/99 8.080 0.01741 0.005503 0.001028 88 640: 100% 22/22 [00:04<00:00, 4.50it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:00<00:00, 2.95it/s] all 88 132 0.95 0.982 0.989 0.783 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 78/99 8.080 0.01702 0.005364 0.001006 81 640: 100% 22/22 [00:06<00:00, 3.28it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:00<00:00, 2.21it/s] all 88 132 0.971 0.985 0.993 0.786 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 79/99 8.080 0.01664 0.005333 0.0009713 96 640: 100% 22/22 [00:06<00:00, 3.61it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.77it/s] all 88 132 0.981 0.965 0.989 0.809 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 80/99 8.080 0.0164 0.005115 0.0009644 96 640: 100% 22/22 [00:04<00:00, 4.84it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.77it/s] all 88 132 0.981 0.965 0.989 0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 80/99 8.080 0.0164 0.005115 0.0009684 96 640: 100% 22/22 [00:04<00:00, 4.84it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.53it/s] all 88 132 0.966 0.967 0.988 0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.080 0.01661 0.005311 0.0009634 90 640: Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.080 0.01661 0.005311 0.0009634 90 640: Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.080 0.01661 0.005311 0.0009634 90 640:					0.001084	88	640:
0.802 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 77/99 8.08G 0.01741 0.005503 0.001028 88 640: 100% 22/22 [00:04<00:00, 4.50it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:00<00:00, 2.95it/s] all 88 132 0.95 0.982 0.989 0.783	ADEO OF: 100%		_		Р	R	mAP50
Epoch GPU_mem box_loss obj_loss cls_loss Instances	map50-95: 100/				0.956	0.944	0.987
T7/99	0.802						
Class Images Instances P R mAP50	_			-			
mAP50-95: 100% 2/2 [00:00<00:00, 2.95it/s] nAP50 0.783 all 88 132 0.95 0.982 0.989 0.783 Epoch GPU_mem box_loss obj_loss cls_loss Instances 78/99 8.08G 0.01702 0.005364 0.001006 81 640: Size 78/99 8.08G 0.01702 0.005364 0.001006 81 640: 100% 22/22 [00:06<00:00, 3.28it/s] Class Images Instances P R R mAP50					0.001028	88	640:
mAP50-95: 100% 2/2 [00:00<00:00, 2.95it/s] all 88 132 0.95 0.982 0.989 0.783 Epoch GPU_mem box_loss obj_loss cls_loss Instances 78/99 8.08G 0.01702 0.005364 0.001006 81 640: 100% 22/22 [00:06<00:00, 3.28it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:00<00:00, 2.21it/s] all 88 132 0.971 0.985 0.993	100% 22/22 [00				Р	R	mAP50
Epoch GPU_mem box_loss obj_loss Cls_loss Instances Size 78/99 8.08G 0.01702 0.005364 0.001006 81 640: 100% 22/22 [00:06<00:00, 3.28it/s] Class Images Instances P R mAP50 all 88 132 0.971 0.985 0.993 0.786 Epoch GPU_mem box_loss obj_loss Cls_loss Instances Size 79/99 8.08G 0.01664 0.005333 0.0009713 96 640: 100% 22/22 [00:06<00:00, 3.61it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.77it/s] all 88 132 0.981 0.965 0.989 0.809 Epoch GPU_mem box_loss obj_loss Cls_loss Instances Size MAP50-95: 100% 2/2 [00:01<00:00, 1.77it/s] all 88 132 0.981 0.965 0.989 0.809 Epoch GPU_mem box_loss obj_loss Cls_loss Instances Size 80/99 8.08G 0.0164 0.005115 0.0009684 96 640: 100% 22/22 [00:04<00:00, 4.84it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.53it/s] all 88 132 0.966 0.967 0.988 0.796 Epoch GPU_mem box_loss obj_loss Cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	mAP50-95: 100%		•				
Epoch GPU_mem box_loss obj_loss cls_loss Instances 78/99 8.08G 0.01702 0.005364 0.001006 81 640: 100% 22/22 [00:06<00:00, 3.28it/s]	. 500	all	88	132	0.95	0.982	0.989
78/99 8.08G 0.01702 0.005364 0.001006 81 640: 100% 22/22 [00:06<00:00, 3.28it/s]	0.783						
100% 22/22 [00:06<00:00, 3.28it/s]	Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:00<00:00, 2.21it/s]					0.001006	81	640:
mAP50-95: 100% 2/2 [00:00<00:00, 2.21it/s] all 88 132 0.971 0.985 0.993 0.786 all 88 132 0.971 0.985 0.993 Epoch GPU_mem box_loss obj_loss cls_loss Tinstances 79/99 8.08G 0.01664 0.005333 0.0009713 96 640: 640: 100% 22/22 [00:06<00:00, 3.6fit/s]	100% 22/22 [00				D	D	ADEO
0.786 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 79/99 8.08G 0.01664 0.005333 0.0009713 96 640: 100% 22/22 [00:06<00:00, 3.61it/s]	mAP50-95: 100%		•		Р	ĸ	map50
Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 79/99 8.08G 0.01664 0.005333 0.0009713 96 640: 100% 22/22 [00:06<00:00, 3.61it/s]	mii 00 00. 100)				0.971	0.985	0.993
79/99 8.08G 0.01664 0.005333 0.0009713 96 640: 100% 22/22 [00:06<00:00, 3.61it/s]	0.786						
79/99 8.08G 0.01664 0.005333 0.0009713 96 640: 100% 22/22 [00:06<00:00, 3.61it/s]	Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.77it/s] all 88 132 0.981 0.965 0.989 0.809 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 80/99 8.08G 0.0164 0.005115 0.0009684 96 640: 100% 22/22 [00:04<00:00, 4.84it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.53it/s] all 88 132 0.966 0.967 0.988 0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50					0.0009713	96	640:
mAP50-95: 100% 2/2 [00:01<00:00, 1.77it/s]	100% 22/22 [00	-			_	_	
0.809 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 80/99 8.08G 0.0164 0.005115 0.0009684 96 640: 100% 22/22 [00:04<00:00, 4.84it/s]	mAD50-05. 100%		•		Р	R	mAP50
Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 80/99 8.08G 0.0164 0.005115 0.0009684 96 640: 100% 22/22 [00:04<00:00, 4.84it/s]	mar 50 - 95. 100/				0.981	0.965	0.989
80/99 8.08G 0.0164 0.005115 0.0009684 96 640: 100% 22/22 [00:04<00:00, 4.84it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.53it/s] all 88 132 0.966 0.967 0.988 0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	0.809						
80/99 8.08G 0.0164 0.005115 0.0009684 96 640: 100% 22/22 [00:04<00:00, 4.84it/s] Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.53it/s] all 88 132 0.966 0.967 0.988 0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	Epoch	GPU mem	box loss	obj loss	cls loss	Instances	Size
Class Images Instances P R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.53it/s] all 88 132 0.966 0.967 0.988 0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	80/99			-			640:
mAP50-95: 100% 2/2 [00:01<00:00, 1.53it/s] all 88 132 0.966 0.967 0.988 0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	100% 22/22 [00	-					
0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	ADEO OE - 100%		•		Р	R	mAP50
0.796 Epoch GPU_mem box_loss obj_loss cls_loss Instances Size 81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	MAP50-95: 100/				0.966	0.967	0.988
81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	0.796						
81/99 8.08G 0.01661 0.005311 0.0009634 90 640: 100% 22/22 [00:05<00:00, 3.78it/s] Class Images Instances P R mAP50	Epoch	GPU mem	box loss	obi loss	cls loss	Instances	Size
Class Images Instances P R mAP50	-			-			
$oldsymbol{arphi}$	100% 22/22 [00						
	mAP50-95: 100%		•		Р	R	mAP50

	all	88	132	0.972	0.96	0.988
0.798						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
82/99			0.00552	0.0009595	106	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		_		-		
	all	88	132	0.959	0.98	0.988
0.802						
Epoch	GPU_mem	box_loss	obj_loss	cls_loss	Instances	Size
83/99			0.005174	0.0009515	85	640:
100% 22/22 [00			s] Instances	Р	R	mAP50
mAP50-95: 100%		•		Г	n.	MAPSO
	all	88	132	0.939	0.97	0.983
0.792						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
84/99			0.005249	0.0009134	60	640:
100% 22/22 [00				D	70	ADEO
mAP50-95: 100%		_	Instances 2.51it/sl	Р	R	mAP50
	all	88	132	0.943	0.961	0.977
0.796						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
85/99			0.005192	0.0009041	98	640:
100% 22/22 [00				_	_	4850
mAP50-95: 100%		•	Instances 2 18it/sl	Р	R	mAP50
mii 00 00. 100%	all	88	132	0.974	0.928	0.976
0.794						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
86/99		0.01652	-	0.0008908	69	640:
100% 22/22 [00				_	_	
mAP50-95: 100%	Class	_	Instances	Р	R	mAP50
MAI 30 93. 100%	all	88	132	0.902	0.992	0.984
0.787						
Epoch	GPU_mem	hov logg	obj_loss	cls_loss	Instances	Size
87/99	8.08G	0.0157	•	0.0009021	54	640:
100% 22/22 [00	:06<00:00,	3.53it/s	3]			
mAP50-95: 100%	Class		Instances	Р	R	mAP50
marou-90: 100%	, Z/Z LUU:U	0.00.00,	Z.101f/2]			

	all	88	132	0.941	0.986	0.985
0.785						
_			obj_loss			Size
88/99 100% 22/22 [00			0.005297	0.0008223	84	640:
	Class	Images	Instances	P	R	mAP50
mAP50-95: 100%	% 2/2 [00:0 all	0<00:00,	2.22it/s] 132	0.971	0.955	0.985
0.795	all	00	132	0.971	0.900	0.965
	apu		1 . 7		. .	a .
Epoch 89/99			obj_loss 0.005096	cls_loss 0.0008322	Instances 100	Size 640:
100% 22/22 [00				0.00000		0.201
mAP50-95: 100%		•	Instances	Р	R	mAP50
MAP50-95: 100%	all	88	132	0.939	0.972	0.984
0.797						
Epoch	GPU mem	box loss	obj_loss	cls loss	Instances	Size
90/99	8.08G	0.01604	0.005375	0.0008942	75	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%		_		1	10	IIIAI 50
	all	88	132	0.972	0.969	0.989
0.794						
_			obj_loss		Instances	Size
91/99 100% 22/22 [00			0.00493	0.0009987	79	640:
100% 22/22 [00			Instances	Р	R	mAP50
mAP50-95: 100%						
0.799	all	88	132	0.976	0.968	0.989
0.100						
_			obj_loss			Size
92/99 100% 22/22 [00	8.08G 0:05<00:00.	0.015 3.93it/s		0.0007106	84	640:
	Class	Images	Instances	Р	R	mAP50
mAP50-95: 100%				0 077	0.050	0.000
0.793	all	88	132	0.977	0.958	0.988
_					_	
Epoch 93/99	GPU_mem 8.08G	box_loss 0.01462	U –	cls_loss 0.0008006	Instances 89	Size 640:
100% 22/22 [00				3.000000	00	010.
ADEO 05 400M	Class	Images		Р	R	mAP50
mAP50-95: 100%	, 2/2 LOO:0	u <uu:00,< td=""><td>∠.U51t/s]</td><td></td><td></td><td></td></uu:00,<>	∠.U51t/s]			

	all	88	132	0.943	0.974	0.981
0.805						
Epoch 94/99 100% 22/22 [00	8.08G	0.01492		cls_loss 0.0008217	Instances 100	Size 640:
	Class	Images	Instances	P	R	mAP50
mAP50-95: 100%	all	88	1.841t/s]	0.99	0.924	0.972
0.797						
Epoch 95/99 100% 22/22 [00	8.08G	0.01456	obj_loss 0.005134		Instances 89	Size 640:
mAP50-95: 100%	Class	Images	Instances	Р	R	mAP50
0.808	all	88	132	0.989	0.925	0.972
96/99	8.08G	0.01425	obj_loss 0.004754			Size 640:
100% 22/22 [00 mAP50-95: 100%	Class	Images	Instances	P	R	mAP50
	all	88	132	0.992	0.928	0.971
0.802						
Epoch 97/99 100% 22/22 [00	8.08G	0.01453	obj_loss 0.004586	cls_loss 0.0007498	Instances 82	Size 640:
mAP50-95: 100%	Class	Images	Instances	Р	R	mAP50
	all	88	132	0.985	0.937	0.974
0.819						
Epoch 98/99	8.08G	0.01493	0.005011	cls_loss 0.0006505	Instances 85	Size 640:
100% 22/22 [00	0:05<00:00, Class	3.81it/s Images		Р	R	mAP50
mAP50-95: 100%	2/2 [00:0	1<00:00,	1.76it/s]	0.06	0.07	
0.82	all	88	132	0.96	0.97	0.985
Epoch	_	box_loss	u –	cls_loss		Size
99/99 100% 22/22 [00			3]	0.0009268	90	640:
mAP50-95: 100%	Class 5 2/2 [00:0	Images 0<00:00,		Р	R	mAP50

all 88 132 0.993 0.922 0.983 0.812

100 epochs completed in 0.215 hours.

Optimizer stripped from runs/train/yolo_road_det3/weights/last.pt, 14.4MB Optimizer stripped from runs/train/yolo_road_det3/weights/best.pt, 14.4MB

Validating runs/train/yolo_road_det3/weights/best.pt... Fusing layers...

YOLOv5s summary: 157 layers, 7020913 parameters, 0 gradients, 15.8 GFLOPs Class Images Instances R mAP50 mAP50-95: 100% 2/2 [00:01<00:00, 1.27it/s] 0.985 all 0.96 0.97 132 0.823 trafficlight 88 19 0.894 0.89 0.956 0.626 88 10 0.972 1 0.995 stop 0.923 0.972 1 0.995 speedlimit 81 88 0.906 crosswalk 88 22 1 0.989 0.995 0.835

Results saved to runs/train/yolo_road_det3

```
[43]: model_name = "/content/yolov5/runs/train/yolo_road_det3/weights/best.pt"
      test model = torch.hub.load("ultralytics/yolov5", 'custom', model name)
      test_model.conf = 0.25 # confidence threshold (0-1)
      test_model.iou = 0.45
      test_model.eval()
      test_path = "/content/RoadSignDetectionDataset/"
      test_files = glob.glob(test_path + "/images/test/*")
      labels = ["trafficlight", "stop", "speedlimit", "crosswalk"]
      for files in test_files:
        test_image = cv2.imread(files)
       file_basename = os.path.basename(files)
        print (file_basename)
        txt name = file basename[:file basename.rfind(".")] + ".txt"
        txt_file = open(test_path + "/labels/test/" + txt_name, "r")
        data = txt file.read()
        data_into_list = data.split("\n")
        #print(data_into_list)
        results = test_model(test_image, size=640)
        results_df = results.pandas().xyxy
        print (results_df[0].name)
```

print("\n")

Using cache found in /root/.cache/torch/hub/ultralytics_yolov5_master YOLOv5 2022-10-6 Python-3.7.14 torch-1.12.1+cu113 CUDA:0 (Tesla V100-SXM2-16GB, 16160MiB)

Fusing layers...

YOLOv5s summary: 157 layers, 7020913 parameters, 0 gradients, 15.8 GFLOPs Adding AutoShape...

 ${\tt road113.png}$

0 speedlimit

Name: name, dtype: object

road801.png

0 speedlimit

Name: name, dtype: object

road486.png

0 speedlimit
1 trafficlight

Name: name, dtype: object

road385.png

0 speedlimit

Name: name, dtype: object

road679.png

0 speedlimit

Name: name, dtype: object

road360.png

0 speedlimit

Name: name, dtype: object

road599.png

0 speedlimit

Name: name, dtype: object

road563.png

0 speedlimit
1 crosswalk

Name: name, dtype: object

road731.png

0 speedlimit
1 speedlimit

Name: name, dtype: object

 ${\tt road418.png}$

0 speedlimit

Name: name, dtype: object

road316.png

0 speedlimit
1 speedlimit
2 crosswalk

Name: name, dtype: object

road709.png

0 speedlimit 1 speedlimit

Name: name, dtype: object

road80.png

0 stop

Name: name, dtype: object

road50.png

0 trafficlight

Name: name, dtype: object

road809.png

0 speedlimit

Name: name, dtype: object

road403.png

0 speedlimit

road590.png

0 speedlimit

Name: name, dtype: object

road337.png

0 speedlimit

Name: name, dtype: object

road803.png

0 speedlimit

Name: name, dtype: object

road445.png

0 speedlimit
1 speedlimit

Name: name, dtype: object

road417.png

0 speedlimit

Name: name, dtype: object

road661.png

0 speedlimit
1 stop

Name: name, dtype: object

road600.png

0 speedlimit

1 stop

Name: name, dtype: object

road206.png

0 speedlimit

Name: name, dtype: object

road18.png

0 trafficlight

road129.png

0 crosswalk 1 trafficlight

Name: name, dtype: object

road796.png
0 speedlimit

Name: name, dtype: object

road543.png

0 speedlimit 1 crosswalk

Name: name, dtype: object

road854.png

0 speedlimit

Name: name, dtype: object

road819.png

0 stop

1 trafficlight
2 trafficlight

Name: name, dtype: object

road321.png

0 speedlimit
1 crosswalk
2 stop

Name: name, dtype: object

road433.png

0 speedlimit 1 stop

Name: name, dtype: object

 ${\tt road367.png}$

0 speedlimit

 ${\tt road67.png}$

0 stop

Name: name, dtype: object

road37.png

0 trafficlight

Name: name, dtype: object

road174.png

0 speedlimit

Name: name, dtype: object

road356.png

0 stop

Name: name, dtype: object

road199.png

0 speedlimit

Name: name, dtype: object

road494.png

0 speedlimit

Name: name, dtype: object

road408.png

0 speedlimit

Name: name, dtype: object

road315.png

0 speedlimit

crosswalk

Name: name, dtype: object

road293.png

0 speedlimit

crosswalk

Name: name, dtype: object

road804.png

0 speedlimit

Name: name, dtype: object

road318.png

0 speedlimit
1 crosswalk

Name: name, dtype: object

road764.png

0 speedlimit

Name: name, dtype: object

road91.png

0 stop 1 speedlimit

Name: name, dtype: object

road267.png

0 speedlimit

Name: name, dtype: object

road667.png

0 speedlimit

Name: name, dtype: object

road142.png

0 crosswalk

Name: name, dtype: object

road564.png

0 speedlimit
1 crosswalk

Name: name, dtype: object

road160.png

0 stop

1 crosswalk

road665.png

0 speedlimit

Name: name, dtype: object

road672.png

0 speedlimit
1 stop

Name: name, dtype: object

road498.png

0 speedlimit

Name: name, dtype: object

road183.png

0 crosswalk
1 crosswalk
2 trafficlight

Name: name, dtype: object

road3.png

0 trafficlight
1 trafficlight

Name: name, dtype: object

road558.png

0 speedlimit

Name: name, dtype: object

road643.png

0 speedlimit

Name: name, dtype: object

road695.png

0 speedlimit

1 speedlimit

2 stop

Name: name, dtype: object

road261.png

0 speedlimit

Name: name, dtype: object

road609.png

0 speedlimit 1 crosswalk

Name: name, dtype: object

road789.png

0 speedlimit

Name: name, dtype: object

road490.png

0 speedlimit

Name: name, dtype: object

road328.png

0 speedlimit

Name: name, dtype: object

road164.png

0 trafficlight

Name: name, dtype: object

road43.png

- 0 trafficlight
- 1 trafficlight
- 2 trafficlight
- 3 trafficlight
- 4 trafficlight
- 5 trafficlight
- 6 trafficlight
- 7 trafficlight
- 8 trafficlight

Name: name, dtype: object

road617.png

0 speedlimit

Name: name, dtype: object

road157.png

0 speedlimit

Name: name, dtype: object

 ${\tt road143.png}$

0 crosswalk

Name: name, dtype: object

road841.png

0 speedlimit

1 crosswalk

Name: name, dtype: object

road194.png

0 crosswalk

1 trafficlight

Name: name, dtype: object

road47.png

0 trafficlight

Name: name, dtype: object

road96.png

0 stop

Name: name, dtype: object

road550.png

0 speedlimit

Name: name, dtype: object

road748.png

0 speedlimit
1 speedlimit

Name: name, dtype: object

road784.png

0 speedlimit 1 crosswalk

road640.png

0 speedlimit
1 speedlimit

Name: name, dtype: object

road721.png

0 speedlimit

Name: name, dtype: object

road492.png

0 speedlimit

Name: name, dtype: object

road100.png

0 speedlimit

Name: name, dtype: object

road712.png

0 speedlimit
1 speedlimit

Name: name, dtype: object

road140.png

0 crosswalk

Name: name, dtype: object

road730.png

0 speedlimit

1 speedlimit

Name: name, dtype: object

 ${\tt road431.png}$

0 speedlimit

Name: name, dtype: object

road547.png

0 speedlimit

1 crosswalk

2 crosswalk

road33.png

0 trafficlight

Name: name, dtype: object

road175.png
0 speedlimit

Name: name, dtype: object

road625.png
0 speedlimit

Name: name, dtype: object

val: data=/content/yolov5/data/road_sign_data.yaml,
weights=['runs/train/yolo_road_det3/weights/best.pt'], batch_size=32, imgsz=640,
conf_thres=0.001, iou_thres=0.6, max_det=300, task=test, device=, workers=8,
single_cls=False, augment=False, verbose=False, save_txt=False,
save_hybrid=False, save_conf=False, save_json=False, project=runs/val,
name=yolo_det, exist_ok=False, half=False, dnn=False
YOLOv5 v6.2-186-g7f097dd Python-3.7.14 torch-1.12.1+cu113 CUDA:0 (Tesla
V100-SXM2-16GB, 16160MiB)

Fusing layers...

YOLOv5s summary: 157 layers, 7020913 parameters, 0 gradients, 15.8 GFLOPs

test: Scanning '/content/RoadSignDetectionDataset/labels/test'

images and labels…88 found, 0 missing, 0 empty, 0 corrupt: 100% 88/88

[00:00<00:00, 2895.35it/s] test: New cache created:

/content/RoadSignDetectionDataset/labels/test.cache

mAP50-95	Class 5: 100% 3/3 [00:02	O	tances it/sl	P	R	mAP50
	all	88	126	0.993	0.901	0.952
0.795	trafficlight	88	20	1	0.647	0.828
0.554	stop	88	7	0.986	1	0.995
0.889	speedlimit	88	76	0.994	1	0.995
0.9	•				_	
	crosswalk	88	23	0.992	0.957	0.99

```
0.837
```

Speed: 0.3ms pre-process, 2.0ms inference, 0.9ms NMS per image at shape (32, 3, 640, 640)

Results saved to runs/val/yolo_det2

[]: