

# Mathematical Software Programming (02635)

Lecture 4 — September 27, 2018

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## Checklist — what you should know by now

- ▶ How to write a simple program in C (`int main(void) {}`)
- ▶ Basic data types (`int`, `long`, `float`, `double`, ...)
- ▶ Basic input/output (`printf`, `scanf`)
- ▶ Implicit/explicit typecasting
- ▶ How to compile and run a program from terminal / command prompt
- ▶ Control structures and loops
- ▶ Limitations of integer and floating-point arithmetic
- ▶ Automatic arrays and multidimensional arrays
- ▶ Pointers: *dereferencing* and *address of* operators

# This week

## Topics

- ▶ Program structure
- ▶ Memory allocation

## Learning objectives

- ▶ Describe and use data structures such as **arrays**, linked lists, stacks, and queues.
- ▶ Choose appropriate data types and data structures for a given problem.
- ▶ Design, implement, and document a program that solves a mathematical problem.

# Functions

```
<type> function_name(<type> <arg1>, <type> <arg2>, ...) {  
    // body  
}
```

- ▶ Function prototype, header, and body
- ▶ Single return value, multiple inputs
- ▶ Variables are *automatic* — scope is code block enclosed between { }
- ▶ **Never** return a pointer to a local variable!

## Examples

```
int main(void);  
int printf(const char* format, ...);  
void my_func1(double* param, const size_t length);  
void my_func2(double param[], const size_t length);  
double * new_vector(const size_t length);
```

## C uses *call-by-value* method to pass arguments

```
#include <stdio.h>
void swap(int a, int b);    // Function prototype
int main(void) {
    int a = 1, b = 3;
    swap(a,b);
    printf("a = %d and b = %d\n",a,b);
    return 0;
}

void swap(int a, int b) {
    int c = a;    // Store value of a in c
    a = b;        // Overwrite a with b
    b = c;        // Overwrite b with c
    return;
}
```

What is the value of a and b after calling swap(a,b)?

## Pointers as arguments

```
#include <stdio.h>
void swap2(int* a, int* b);    // Function prototype
int main(void) {
    int a = 1, b = 3;
    swap2(&a,&b);
    printf("a = %d and b = %d\n",a,b);
    return 0;
}
void swap2(int* a, int* b) {
    int c = *a;    // Store value of *a in c
    *a = *b;       // Overwrite *a with *b
    *b = c;        // Overwrite *b with c
    return;
}
```

What is the value of a and b after calling swap2(&a,&b)?

# Dynamic memory allocation

## Prototypes (stdlib.h)

```
void *malloc(size_t size);  
void *calloc(size_t nelements, size_t elementSize);  
void *realloc(void *pointer, size_t size);  
void free(void *pointer);
```

## Allocating an array of length $N$

```
double *pdata = malloc(N*sizeof(*pdata));  
  
// Check if memory allocation failed  
if (pdata == NULL) {  
    // Code to deal with memory allocation failure ...  
}
```

## Extending dynamically allocated memory

```
double *pdata = malloc(N*sizeof(*pdata));
if (pdata == NULL) {
    // Code to handle memory allocation failure ...
}

...

// Request more memory (N + 100)
N += 100;
double *ptmp = realloc(pdata, N*sizeof(*pdata));
if (ptmp == NULL) {
    // Code to handle reallocation failure ...
    //  pdata is still a valid pointer
}
else
    pdata = ptmp;
```



# Releasing memory

```
free(pdata);    // Free memory pointed to by pdata.  
pdata = NULL;   // <--- Not necessary, but good practice!
```

## Common errors

- ▶ Freeing memory twice
- ▶ Freeing unallocated memory
- ▶ Using pointer after freeing memory
- ▶ Forgetting to free memory (memory leak)

# Memory: stack vs heap

## Stack (automatic allocation)

- ▶ Layout decided at compile-time (variables cannot be resized)
- ▶ Local variables
- ▶ No allocation/deallocation overhead
- ▶ Fast access but limited by stack size

## Heap (dynamic allocation)

- ▶ Programmer must explicitly allocate/deallocate memory
- ▶ Dynamic memory allocation/deallocation is controlled by operating system
- ▶ Variables can be resized and accessed globally
- ▶ Memory may become fragmented over time
- ▶ No limit on memory size (other than hardware limitations)
- ▶ Slower access than stack

Remark: static and global variables stored in “data segment”

## Allocating a two-dimensional array (WSS, p. 94)

### Algorithm 1: naive $m \times n$ matrix allocation method

```
B = (double **)malloc(m*sizeof(double *));  
if ( B == NULL ) return NULL;  
  
for ( i = 0; i < m; i++ ){  
    B[i] = (double *)malloc(n*sizeof(double));  
    if ( B[i] == NULL ) { free(B); return NULL; }  
}
```

- ▶ How should you free the memory allocated by Algorithm 1?
- ▶ Is it possible for Algorithm 1 to leak memory?

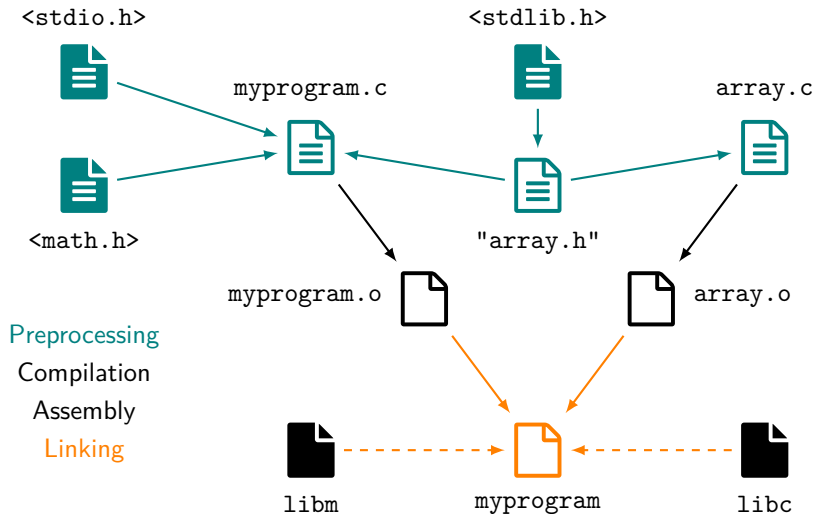
## Allocating a two-dimensional array (WSS, p. 94)

### Algorithm 2: fast $m \times n$ matrix allocation method

```
B = (double **)malloc(m*sizeof(double *));  
if ( B == NULL ) return NULL;  
  
B[0] = (double *)malloc(m*n*sizeof(double));  
if ( B[0] == NULL ) { free(B); return NULL; }  
  
/* Set the remaining pointers */  
for ( i = 1; i < m; i++ )  
    B[i] = B[0] + i*n;
```

- ▶ How should you free the memory allocated by Algorithm 2?
- ▶ Is it possible for Algorithm 2 to leak memory?

## Multiple-file projects



# Building multiple-file projects

## Manual compilation/assembly and linking

```
$ gcc -c -Wall -std=c99 array.c  
$ gcc -c -Wall -std=c99 myprogram.c  
$ gcc myprogram.o array.o -lm -o myprogram
```

## Building with make

- Create a makefile with source and library dependencies

```
$ make myprogram  
gcc -Wall -std=c99 -c -o myprogram.o myprogram.c  
gcc -Wall -std=c99 -c -o array.o array.c  
gcc myprogram.o array.o -lm -o myprogram
```

# Makefiles revisited

```
variable = value  
target : dependencies  
    command
```

- ▶ Make has many implicit rules (make -p -f/dev/null), e.g.,

```
COMPILE.c = $(CC) $(CFLAGS) $(CPPFLAGS) $(TARGET_ARCH) -c  
$(COMPILE.c) -o $@ $<  
LINK.c = $(CC) $(CFLAGS) $(CPPFLAGS) $(LDFLAGS) $(TARGET_ARCH)  
$(LINK.c) $^ $(LOADLIBES) $(LDLIBS) -o $@
```

- ▶ implicit dependencies: target depends on target.o, target.o depends on target.c
- ▶ explicit dependencies
  - ▶ object files may depend on header file(s)
  - ▶ executable target may depend on multiple object files

## Makefile for project with two source files

```
CC=gcc
CPPFLAGS=
CFLAGS=-Wall -std=c99
LDFLAGS=
LDLIBS=-lm

myprogram: myprogram.o array.o
myprogram.o: array.h
array.o: array.h

.PHONY: clean          # "clean" does not create file with target name
clean:                 # Removes myprogram and all object files
    -$(RM) myprogram *.o
```

Automatically generate dependencies with GCC/Clang

```
$ gcc -MM *.c
```



## Generic makefile for multiple-file projects

```
CC=gcc
CPPFLAGS=
CFLAGS=-Wall -std=c99
LDFLAGS=
LDLIBS=-lm
objects=$(patsubst %.c,%.o,$(wildcard *.c))

myprogram: $(objects)

.PHONY: clean run
clean:
    -$(RM) myprogram $(objects)

# target for Atom extension "gcc-make-run"
run: myprogram
    ./myprogram $(ARGS)
```

## Quiz time!

1. Go to [socrative.com](https://socrative.com) on your laptop or mobile device
2. Enter “room number” **02635**
3. Answer ten quick question (the quiz is anonymous)