

Timing: 3 hrs

Date: Nov 17, 2025 Time: 9:30 AM - 12:30 PM

Max. Marks: 40

Instructions

- Answer all questions. Each question must begin on a **new page**.
- Provide complete justifications for your answers. Partial/unjustified answers may not receive full credit.
- Mention assumptions and conditions clearly wherever necessary.

1. Consider a dataset $\{(x_n, y_n)\}_{n=1}^N$ and a nonlinear transformation $z_n = \Phi(x_n)$. The PLA is run on the transformed data $\{z_n, y_n\}$ and is observed to converge in T updates. Assume:

- $\|z_n\| \leq R$ for all n ;
- the final PLA weight vector satisfies $\|w\| = W$;
- the margin of this separator is $\gamma = \min_n y_n w^\top z_n$ (value unknown).

Now, before running PLA again, you apply a second linear mapping $u_n = \Psi(z_n)$, where Ψ has singular values in the interval $[s_{\min}, s_{\max}]$. Let T' be the number of PLA updates required after the second mapping.

- (a) Derive upper and lower bounds on T' in terms of s_{\min}, s_{\max} and T . [4]
- (b) Give a simple condition (in terms of s_{\min} and s_{\max}) under which PLA is guaranteed to make fewer updates after the mapping, i.e. $T' < T$. [4]
2. Let x is some integer in the set $X = \{1, 2, \dots, 50, 51, 52\}$, and where each hypothesis $h \in \mathcal{H}$ is an interval of the form $b \leq x \leq a$, with b and a as any integers between 1 and 52 (inclusive), so long as $b \leq a$. A hypothesis $b \leq x \leq a$ labels instance x positive if x falls into the interval defined by a and b , and labels the instance negative otherwise.
- (a) How many distinct hypotheses are there in such \mathcal{H} ? (No explanation required) [0.5]
- (b) Suppose we draw N independent examples uniformly from X with \mathcal{H} hypothesis space. Using Hoeffding's inequality: If $\epsilon = 0.05$, calculate the minimum number of samples N needed to ensure that the confidence is at least 95%. [0.5]
- (c) If instead of Hoeffding's, we use Chebyshev inequality then what will be N ? What is making N with Chebyshev inequality larger or smaller compared to Hoeffding's? [1]
3. Derive the closed-form (analytical) expression of weights update in Linear Regression model, define all variables and their sizes and state all assumptions. [4]
4. Write pseudo code of PLA and Pocket Algorithms. Can PLA converge? State the condition and prove if it does. [4+4]
5. Answer the following questions. [3]
- (a) Given $\mathbf{w} = (2, -1, 0.5)$ and input $\mathbf{x} = (1, 2, 1)$, the perceptron prediction $\text{sign}(\mathbf{w}^\top \mathbf{x})$ is:
- (b) Current weight: $\mathbf{w} = (0, 1, -2)$. Misclassified point: $\mathbf{x} = (1, -2, 3)$, $y = +1$. What is the updated weight after one PLA update?
- (c) Given $h(\mathbf{x}) = w_0 + w_1 x$ with $w_0 = 1.2$ and $w_1 = 0.8$, the predicted output for $x = 4$ is:
6. Hoeffding's inequality provides concentration bounds for sums of independent bounded random variables. Explain mathematically why the independence assumption is essential for Hoeffding's inequality, and what breaks down when the X_i 's are not independent. Also state Azuma's Inequality and condition under which it is valid. [1+4]
7. Consider a binary classifier that applies the following quadratic feature transformation to an input vector $\mathbf{x} = (x_1, x_2)$:

$$\mathbf{z} = \begin{bmatrix} z_0 \\ z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 1 \\ x_1^2 + x_2^2 \\ x_1 x_2 \end{bmatrix}.$$

The PLA learns a linear classifier in the transformed space: $f(\mathbf{z}) = w_0 + w_1 z_1 + w_2 z_2 = 0$.

- (a) Derive the decision boundary equation in the original x -space in terms of x_1 and x_2 . Simplify the expression as far as possible. [1]
- (b) For the following weight vectors (w_0, w_1, w_2) , identify the geometric shape of the resulting decision boundary in x -space (circle, ellipse, parabola, hyperbola, pair of lines, etc.): [2]
1. $w_0 = -9, w_1 = 1, w_2 = 0$
 2. $w_0 = -16, w_1 = 1, w_2 = -1$
 3. $w_0 = 0, w_1 = 0, w_2 = 1$
 4. $w_0 = 0, w_1 = 1, w_2 = 1$

8. You are given a linear regression model: $\hat{y} = wx + b$ with the following training dataset:

i	x_i	y_i
1	1	4
2	2	7
3	3	10

The loss function is: $L(w, b) = \frac{1}{2m} \sum_{i=1}^m (wx_i + b - y_i)^2$. Assume the initial parameters: $w = 0, b = 0$, and learning rate: $\eta = 0.1$. Answer the following:

- (a) Compute the initial cost $L(w, b)$ at $w = 0, b = 0$. Perform one full step of Batch Gradient Descent (using all 3 samples). Compute updated values of w and b . [1]
- (b) Perform two sequential steps of Stochastic Gradient Descent using samples in order $(1 \rightarrow 2)$. Start again from $w = 0, b = 0$. Show updated values after each step. [2]
9. For linear regression, the out-of-sample error is $E_{\text{out}}(h) = \mathbb{E}[(h(x) - y)^2]$. Show that among all hypotheses, the one that minimizes E_{out} is given by

$$h^*(x) = \mathbb{E}[y | x].$$

The function h^* can be treated as a deterministic target function, in which case we can write $y = h^*(x) + \epsilon(x)$, where $\epsilon(x)$ is an (input-dependent) noise variable. Show that $\epsilon(x)$ has expected value zero. [4]

End of Paper