Definition 1

对于单变量线性函数 $f(x) = ax, f'(x) = a$，为了前后的连续性我们使用偏导符号

$$\frac{\partial f}{\partial x} = a$$

对于多变量线性函数$f(x) = a^T x = \sum_i a_i x_i$，$a, x$为(列)向量，有：

$$\frac{\partial f}{\partial x_k} = \frac{\partial \sum_i a_i x_i}{\partial x_k} = a_k \forall k = 1, \cdots, n$$

我们定义标量函数对向量的求导为下：

$$\frac{\partial f}{\partial x} = [\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \cdots, \frac{\partial f}{\partial x_n}]^T = [a_1, a_2, \cdots, a_n]^T = a$$

广义:

$$\frac{\partial f}{\partial x} = \left[ \begin{array}{ccc} \frac{\partial f}{\partial x_{11}} & \cdots & \frac{\partial f}{\partial x_{1n}} \\ \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial x_{m1}} & \cdots & \frac{\partial f}{\partial x_{mn}} \end{array} \right]$$

Theorem 1

对于多元标量函数$f(x) = a^T x$，$\frac{\partial f}{\partial x} = a.$

Proposition: 由于标量的值等于它的迹。对于$g(x) = Tr[a^T x]$, $\frac{\partial g}{\partial x} = a.$

Properties 1

Definition of Trace: $Tr[A] = \sum_i A_{ii}$，根据定义，矩阵的迹有以下的性质：

1. $Tr[A + B] = Tr[A] + Tr[B]$
2. $Tr[cA] = cTr[A]$
3. $Tr[A] = Tr[A^T]$
4. $Tr[A_1 A_2 \cdots A_n] = Tr[A_n A_1 \cdots A_{n-1}]$
5. $Tr[A^T B] = \sum_i \sum_j A_{ij} B_{ij}$

Theorem 2

对于多元标量函数$f(x) = Tr[A^T x]$，有$\frac{\partial f}{\partial x} = A \quad \forall A, x \in \mathbb{R}^{m \times n}$。

利用Properties 1(5)易证。

Tips

对于任意的标量函数$f : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}$，有$\frac{\partial f}{\partial x} = \frac{\partial Tr[x]}{\partial x}$。然后可以利用Properties 1中的性质，进行变换，化成Theorem 2的形式。

Definition 2

定义矩阵微分（differential）如下：

$$dA = \begin{bmatrix} dA_{11} & \cdots & dA_{1n} \\ \vdots & \ddots & \vdots \\ dA_{m1} & \cdots & dA_{mn} \end{bmatrix}$$

Theorem 3

根据迹的定义和Definition 2可得：

$$dTr[A] = Tr[dA]$$

Theorem 4

对于标量函数$f : \mathbb{R}^{m\times n} \to \mathbb{R}$, $df = Tr[(\frac{\partial f}{\partial x})^T dx]$. （建立了矩阵微分和矩阵求导之间的关系）

证明：$LHS = df = \sum_{ij} \frac{\partial f}{\partial x_{ij}} dx_{ij}$

依次利用Properties 1、Definition 2、Definition 1：$RHS = \sum_{ij}(\frac{\partial f}{\partial x})_{ij}(dx)_{ij} = \sum_{ij}(\frac{\partial f}{\partial x})_{ij} dx_{ij} = \sum_{ij} \frac{\partial f}{\partial x_{ij}} dx_{ij} = LHS$

Properties 2

利用Definition 2，可以得到矩阵微分的性质：

1. $d(cA) = cdA$
2. $d(A+B) = dA + dB$
3. $d(AB) = dAB + AdB$

Conclusion 1

自此，对于标量函数$f : \mathbb{R}^{m\times n} \to \mathbb{R}$，我们能够通过以下流程轻易对其求导：

1. i.e., $df = dTr[x] = Tr[dx]$
2. 利用迹的性质Properties 1对$df$进行化简，化简成$Tr[A^T dx]$形式的线性相加.
3. 利用Theorem 4，得到$\frac{\partial f}{\partial x}$.

Examples

1. $f(x) = x^T Ax, A \in \mathbb{R}^{n\times n}, x \in \mathbb{R}^n$

$$df = dTr[x^T Ax] = Tr[d(x^T Ax)] = Tr[d(x^T)Ax + x^T Adx] = Tr[d(x^T)Ax] + Tr[x^T Adx] = Tr[x^T A^T dx] + Tr[x^T A$$

Hence,

$$\frac{\partial f}{\partial x} = (x^T A^T + x^T A)^T = (A + A^T)x$$

2. $XX^{-1} = I \to d(XX^{-1}) = dI \to dXX^{-1} + XdX^{-1} \to dX^{-1} = -X^{-1}dXX^{-1}$

Definition 3

上面总结了scalar函数对x的求导。下面定义vector函数对向量x的求导：

对于vector函数$f = [f_1, f_2, \ldots, f_n]^T$，$f_i = f_i(x), x = [x_1, x_2, \ldots, x_m]^T$，我们定义:

$$\frac{\partial f}{\partial x} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_2}{\partial x_1} & \cdots & \frac{\partial f_n}{\partial x_1} \\ \frac{\partial f_1}{\partial x_2} & \frac{\partial f_2}{\partial x_2} & \cdots & \frac{\partial f_n}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_1}{\partial x_m} & \frac{\partial f_2}{\partial x_m} & \cdots & \frac{\partial f_n}{\partial x_m} \end{bmatrix}$$

Hessian Matrix and Jacobian Matrix

假设$f: \mathbb{R}^m \to \mathbb{R}^n$，$f$的Jacobian Matrix为

$$J(f) = [\frac{\partial f}{\partial x_1} \cdots \frac{\partial f}{\partial x_m}] = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_m} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \cdots & \frac{\partial f_n}{\partial x_m} \end{bmatrix}$$

假设$f: \mathbb{R}^m \to \mathbb{R}$，$f$的Hessian Matrix为

$$H(f) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_m} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_m} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_m \partial x_1} & \frac{\partial^2 f}{\partial x_m \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_m^2} \end{bmatrix} = J(\nabla f)$$

根据Definition 3，我们可以把Hessian Matrix和Jacobian Matrix重写为：

$$J(f) = (\frac{\partial f}{\partial x})^T H(f) = \frac{\partial}{\partial x}(\frac{\partial f}{\partial x})$$

Theorem 5

对于$f: \mathbb{R}^m \to \mathbb{R}^n$ $df = (\frac{\partial f}{\partial x})^T dx.$

证明$df_j = ((\frac{\partial f}{\partial x})^T dx)_j \quad \forall j.$

Conclusion 2

对于vector函数的求导，整体流程同Conclusion 1，除了不能随便用trace。

Frequently Used Formula

$$\frac{\partial Tr[A]}{\partial A} = I \frac{\partial x^T A x}{\partial x} = (A+A^T)x \frac{\partial x^T x}{\partial x} = 2x \frac{\partial A x}{x} = A^T d(X^{-1}) = -X^{-1} dX X^{-1} \frac{\partial det(A)}{\partial A} = det(A) A^{-T} \frac{\partial \log det(}{\partial A}$$