

# On the Unexpected Effectiveness of Reinforcement Learning for Sequential Recommendation

---

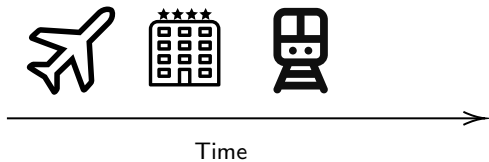
Álvaro Labarca Silva  
Denis Parra  
Rodrigo Toro



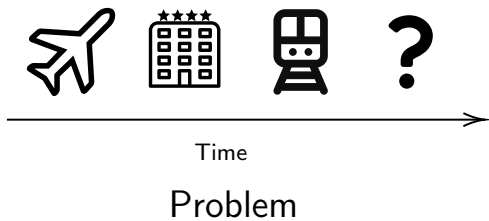
## **An Intriguing Result About Reinforcement Learning in Sequential RecSys**

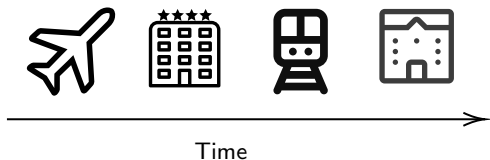
---

# The Sequential Recommendation Problem



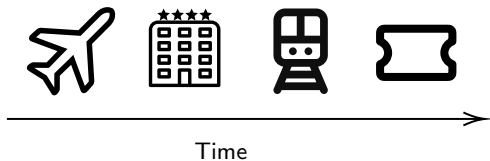
# The Sequential Recommendation Problem



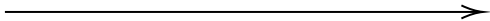


Collaborative Filtering Methods

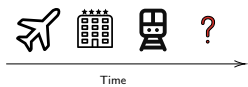
# The Sequential Recommendation Problem



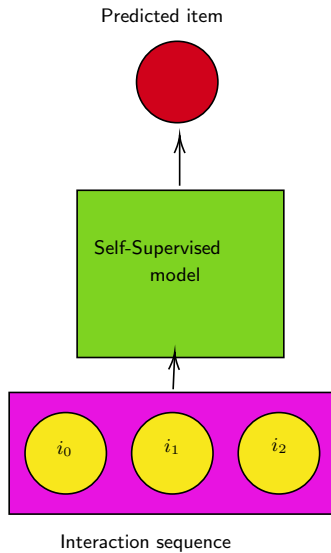
Sequential Models



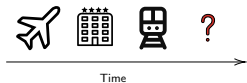
Time



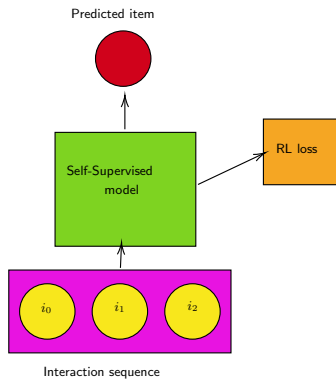
- Caser
- GRU4Rec
- NextItNet
- SASRec



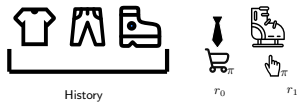




- Caser
- GRU4Rec
- NextItNet
- SASRec

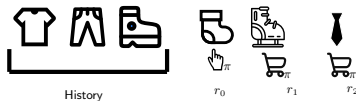


# Reinforcement Learning for Sequential Recommendation



$$R = \sum_{t=0}^{\infty} \gamma^t r_t$$

# Reinforcement Learning for Sequential Recommendation



$$R = \sum_{t=0}^{\infty} \gamma^t r_t$$

- Since RL optimizes performance in long-term, there is no reason to expect improvements on the short-term.

- Since RL optimizes performance in long-term, there is no reason to expect improvements on the short-term.

## Theorem

*For any consistent NIP metric  $\mathcal{N}$  and discount factor  $\gamma > 0$ , the relative NIP performance of an optimal policy  $\pi_*$  can be arbitrarily worse than the performance of an optimal solution  $f_*$ , according to  $L_s$ .*

## Theorem

*Let's consider any consistent NIP metric  $\mathcal{N}$  and set of interaction sequences  $\mathcal{D}$ . Let  $f_*$  be an optimal solution to the cross-entropy loss  $L_s$ . Let  $\pi$  be any optimal policy with respect to  $\mathcal{D}$ . Then,  $\mathcal{N}(\mathcal{D}, f_*) \geq \mathcal{N}(\mathcal{D}, \pi_*)$ .*

**Why do RL-based methods improve the performance under the NIP metric?**

Our hypothesis is that RL, as the process of learning an optimal policy from data, is **not directly responsible for the performance improvements**.

Our hypothesis is that RL, as the process of learning an optimal policy from data, is **not directly responsible for the performance improvements**. We believe that a clever combination of reward signals and discount factors entails useful auxiliary losses



Our hypothesis is that RL, as the process of learning an optimal policy from data, is **not directly responsible for the performance improvements**. We believe that a clever combination of reward signals and discount factors entails useful auxiliary losses that create embeddings containing information about the user or the sequence that the model can use to improve short-term recommendation.

## Top Down Approach




















---

# Interaction prediction

Purchase: 5

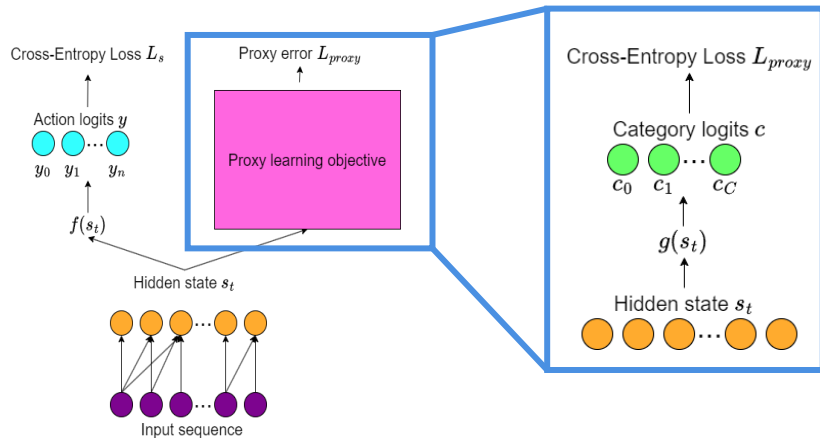
Click: 1

Discount Factor ( $\gamma$ ): 0.5

$i_0$	$i_1$	$i_2$	$i_3$	$i_4$	$i_5$	$i_6$	$i_7$	$i_8$	$i_9$	$i_{10}$	$i_{11}$	$i_{12}$	$i_{13}$	$i_{14}$	$i_{15}$	$i_{16}$	$i_{17}$	$i_{18}$
																		
6.9	3.8	5.5	9.0	8.0	6.0	2.0	2.0	2.0	2.0	2.1	2.1	2.2	2.6	3.2	4.4	6.8	3.5	5.0

$$\begin{aligned}q_{\pi}(s_t, a_t) &= r_{t+1} + \frac{1}{2}r_{t+2} + \frac{1}{4}r_{t+3} + \sum_{k=3}^{\infty} \frac{1}{2^k} r_{t+k+1} \\ &\leq r_{t+1} + \frac{1}{2}r_{t+2} + \frac{1}{4}r_{t+3} + 1.25\end{aligned}$$

# CAT Model



$$L_{proxy} = - \sum_i^C y_i \log(f(c)_i)$$

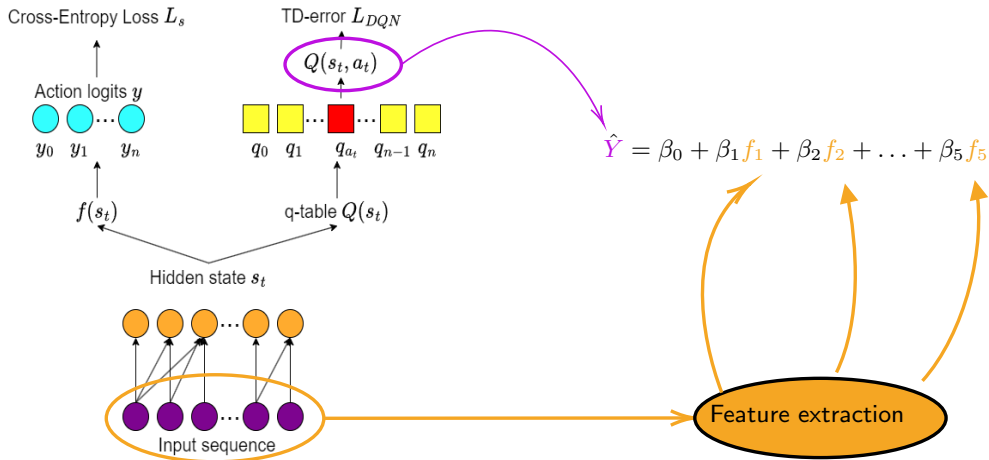
$$f(c)_i = \frac{e^{c_i}}{\sum_j^C e^{c_j}}$$

Model	HR@5	NDCG@5	HR@20	NDCG@20
GRU	0.1601	0.1248	0.2306	0.1456
GRU-SQN	<b>*0.1921</b>	<b>0.1519</b>	<b>*0.2698</b>	<b>0.1743</b>
GRU-CAT	0.1644	0.1282	*0.2384	0.1495

## Bottom-up Approach

---

# Feature Importance



# Feature importance results

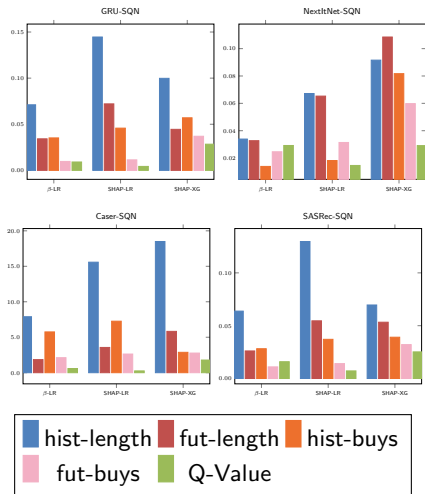
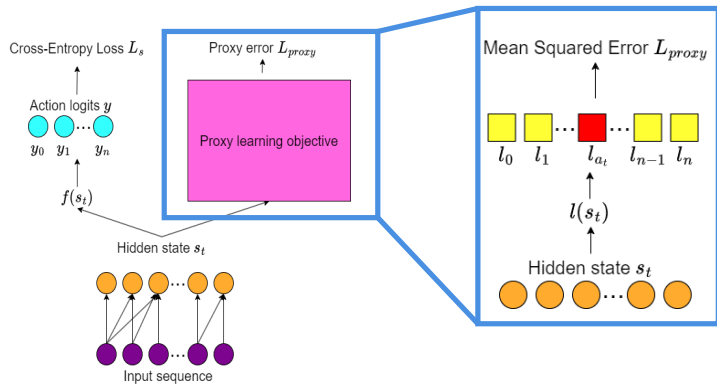


Figure 1: Feature Importance for Different Models



# HIST Model



$$L_{proxy} = \frac{1}{N} \sum_{i=1}^N (Y_i - l_{a_t})^2$$

## Results

---

GRU					NIN				
Model	HR@5	NDCG@5	HR@20	NDCG@20	Model	HR@5	NDCG@5	HR@20	NDCG@20
GRU	0.1601	0.1248	0.2306	0.1450	NIN	0.2282	0.1785	0.3215	0.2053
GRU-SQN	*0.1921	0.1519	*0.2698	0.1743	NIN-SQN	<u>*0.3307</u>	<u>*0.2577</u>	<u>*0.4418</u>	<u>*0.2901</u>
GRU-EVAL	<u>*0.1962</u>	<u>*0.1545</u>	<u>*0.2718</u>	<u>*0.1762</u>	NIN-EVAL	<b>*0.3308</b>	<b>*0.2582</b>	<b>*0.4421</b>	<b>*0.2905</b>
GRU-cat	0.1644	0.1282	*0.2384	0.1495	NIN-cat	*0.2505	0.1959	*0.3483	0.2242
GRU-hist	<b>*0.1980</b>	<b>*0.1549</b>	<b>*0.2747</b>	<b>*0.1770</b>	NIN-hist	*0.3001	*0.2348	*0.4110	*0.2667
Caser					SAS				
Model	HR@5	NDCG@5	HR@20	NDCG@20	Model	HR@5	NDCG@5	HR@20	NDCG@20
Caser	0.1682	0.1361	0.2217	0.1514	SAS	0.2458	0.1872	0.3509	0.2176
Caser-SQN	<u>*0.2020</u>	*0.1601	<u>*0.2715</u>	<u>*0.1801</u>	SAS-SQN	<b>*0.3012</b>	<b>*0.2280</b>	<b>*0.4227</b>	<b>*0.2634</b>
Caser-EVAL	0.2000	<u>0.1610</u>	*0.2638	0.1794	SAS-EVAL	<u>0.2963</u>	<u>*0.2242</u>	<u>*0.4195</u>	<u>*0.2600</u>
Caser-cat	0.1765	0.1434	0.2307	0.1591	SAS-cat	*0.2636	*0.1999	*0.3731	*0.2315
Caser-hist	<b>*0.2399</b>	<b>*0.1893</b>	<b>*0.3296</b>	<b>*0.2152</b>	SAS-hist	*0.2960	*0.2231	0.3847	*0.2573

## Conclusions and Future Work

---

- The HIST model achieved competitive results with the SQN model.

- The HIST model achieved competitive results with the SQN model.
- With the GRU and Caser self-supervised base, the HIST model outperformed SQN.

- The HIST model achieved competitive results with the SQN model.
- With the GRU and Caser self-supervised base, the HIST model outperformed SQN.
- Different reward schemes and models may learn other signals.

- The HIST model achieved competitive results with the SQN model.
- With the GRU and Caser self-supervised base, the HIST model outperformed SQN.
- Different reward schemes and models may learn other signals.
- The research serves as a necessary step to improve the understanding, explainability and performance of RL methods in recommendation.



- Explore different signals.

- Explore different signals.
- Deepen the understanding of the HIST model.

- Explore different signals.
- Deepen the understanding of the HIST model.
- Extend research to different RL models.

- Explore different signals.
- Deepen the understanding of the HIST model.
- Extend research to different RL models.
- Develop methods to evaluate the RL effect in the long term.

**Thank you! Any questions?**

## Full results - GRU click

Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
GRU	0.1205	0.0938	0.1472	0.1024	0.1633	0.1067	0.1751	0.1094
GRU-SQN	*0.1416	*0.1105	*0.1705	*0.1199	*0.1874	*0.1244	*0.1999	*0.1273
GRU-SAC	<b>*0.1475</b>	<b>*0.1148</b>	<b>*0.1774</b>	<b>*0.1245</b>	<b>0.1947</b>	<b>*0.1291</b>	<b>*0.2069</b>	<b>*0.1320</b>
GRU-QVAL	*0.1400	*0.1089	*0.1680	*0.1180	*0.1849	*0.1224	*0.1970	*0.1253
GRU-EVAL	*0.1426	*0.1109	*0.1714	*0.1203	*0.1888	*0.1249	<u>*0.2009</u>	*0.1277
GRU-cat	*0.1228	*0.0955	*0.1497	*0.1042	*0.1665	*0.1086	*0.1784	*0.1114
GRU-cat3	*0.1249	*0.0969	*0.1514	*0.1054	*0.1677	*0.1097	*0.1797	*0.1126
GRU-hist	<u>*0.1434</u>	<u>*0.1118</u>	<u>*0.1717</u>	<u>*0.1210</u>	<u>*0.1880</u>	<u>*0.1253</u>	*0.1997	<u>*0.1281</u>
GRU-fut	0.0390	0.0312	0.0474	0.0339	0.0528	0.0353	0.0569	0.0375

Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
NIN	0.1345	0.1059	0.1612	0.1145	0.1774	0.1188	0.1892	0.1216
NIN-SQN	<b>*0.1673</b>	<b>*0.1310</b>	<u>*0.1996</u>	<b>*0.1414</b>	<u>*0.2178</u>	<b>*0.1463</b>	<u>*0.2305</u>	<b>*0.1493</b>
NIN-SAC	<u>*0.1671</u>	*0.1301	<b>*0.1999</b>	*0.1407	<b>*0.2186</b>	*0.1457	<b>*0.2317</b>	*0.1488
NIN-QVAL	*0.1653	*0.1295	*0.1963	*0.1396	0.2141	*0.1443	*0.2273	*0.1474
NIN-EVAL	*0.1668	<u>*0.1306</u>	*0.1993	<u>*0.1411</u>	*0.2176	<u>*0.1459</u>	*0.2302	<u>*0.1489</u>
NIN-cat	*0.1431	*0.1121	*0.1721	*0.1215	*0.1890	*0.1259	*0.2014	*0.1289
NIN-cat3	*0.1436	*0.1129	*0.1732	*0.1225	0.1903	*0.1271	*0.2027	*0.1300
NIN-hist	*0.1638	*0.1284	*0.1951	*0.1386	*0.2130	*0.1433	*0.2256	0.1463
NIN-fut	0.0939	0.0750	0.1100	0.0802	0.1194	0.0827	0.1263	0.0830

## Full results - Caser click

Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
Caser	0.1400	0.1107	0.1640	0.1185	0.1781	0.1222	0.1877	0.1245
Caser-SQN	*0.1560	0.1218	*0.1849	*0.1312	*0.2018	*0.1357	*0.2136	*0.1385
Caser-SAC	*0.1539	0.1190	*0.1836	*0.1286	*0.2012	*0.1333	*0.2132	*0.1361
Caser-QVAL	<u>*0.1608</u>	<u>*0.1269</u>	<u>*0.1883</u>	<u>*0.1358</u>	<u>*0.2040</u>	<u>*0.1400</u>	<u>*0.2151</u>	<u>*0.1426</u>
Caser-EVAL	0.1577	0.1246	0.1849	0.1334	0.2005	0.1375	0.2116	0.1401
Caser-cat	0.1415	0.1135	0.1652	0.1212	0.1790	0.1249	0.1888	0.1344
Caser-cat3	0.1565	*0.1241	*0.1830	*0.1327	*0.1982	*0.1367	0.2090	*0.1393
Caser-hist	<b>0.1669</b>	<b>*0.1300</b>	<b>*0.1979</b>	<b>0.1401</b>	<b>*0.2160</b>	<b>*0.1449</b>	<b>*0.2283</b>	<b>*0.1478</b>
Caser-fut	0.0248	0.0189	0.0316	0.0210	0.0358	0.0222	0.0393	0.0230



Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
SAS	0.1635	0.1249	0.1982	0.1361	0.2176	0.1413	0.2313	0.1445
SAS-SQN	<u>0.1835</u>	<u>*0.1397</u>	<u>*0.2228</u>	<u>*0.1524</u>	<u>*0.2445</u>	<u>*0.1582</u>	<u>*0.2597</u>	<u>*0.1618</u>
SAS-SAC	<b>*0.1852</b>	<b>*0.1398</b>	<b>*0.2266</b>	<b>*0.1532</b>	<b>*0.2496</b>	<b>*0.1593</b>	<b>*0.2649</b>	<b>*0.1629</b>
SAS-QVAL	*0.1804	*0.1373	*0.2189	*0.1498	*0.2409	*0.1556	*0.2557	*0.1591
SAS-EVAL	0.1815	*0.1382	*0.2212	*0.1511	*0.2433	*0.1569	*0.2584	0.1605
SAS-cat	*0.1689	*0.1285	*0.2057	*0.1404	*0.2259	*0.1458	*0.2399	*0.1491
SAS-cat3	0.1669	0.1271	*0.2034	0.1390	*0.2239	0.1444	*0.2380	0.1477
SAS-hist	*0.1812	*0.1376	*0.2204	*0.1503	*0.2424	*0.1561	*0.2576	*0.1597
SAS-fut	0.0099	0.0071	0.0138	0.0083	0.0168	0.0091	0.0193	0.0097

## Full results - GRU buy

Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
GRU	0.1601	0.1248	0.1932	0.1355	0.2151	0.1413	0.2306	0.1456
GRU-SQN	*0.1921	0.1519	*0.2304	0.1643	*0.2531	0.1703	*0.2698	0.1743
GRU-SAC	<u>0.1973</u>	<u>*0.1546</u>	<u>*0.2338</u>	<u>*0.1664</u>	<u>*0.2575</u>	<u>*0.1727</u>	<u>*0.2734</u>	<u>*0.1764</u>
GRU-QVAL	*0.1884	*0.1487	*0.2233	*0.1599	*0.2448	*0.1656	*0.2601	*0.1693
GRU-EVAL	*0.1962	*0.1545	*0.2333	*0.1664	*0.2555	*0.1723	*0.2718	*0.1762
GRU-cat	0.1644	0.1282	*0.2004	*0.1400	*0.2225	0.1457	*0.2384	0.1495
GRU-cat3	*0.1696	*0.1325	*0.2044	*0.1438	*0.2272	*0.1498	*0.2435	*0.1536
GRU-hist	<b>*0.1980</b>	<b>*0.1549</b>	<b>*0.2352</b>	<b>*0.1670</b>	<b>*0.2588</b>	<b>*0.1732</b>	<b>*0.2747</b>	<b>*0.1770</b>
GRU-fut	0.0505	0.0400	0.0623	0.0438	0.0697	0.0457	0.0756	0.0471

## Full results - NIN buy

Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
NIN	0.2282	0.1785	0.2746	0.1935	0.3018	0.2007	0.3215	0.2053
NIN-SQN	<u>*0.3307</u>	*0.2577	<b>*0.3890</b>	*0.2767	<u>*0.4200</u>	*0.2849	*0.4418	*0.2901
NIN-SAC	*0.3303	<b>*0.2594</b>	*0.3880	<b>*0.2781</b>	<b>*0.4201</b>	<b>*0.2867</b>	<b>*0.4422</b>	<b>*0.2919</b>
NIN-QVAL	*0.3216	*0.2511	0.3791	*0.2675	0.4094	*0.2778	0.4310	*0.2829
NIN-EVAL	<b>*0.3308</b>	<u>*0.2582</u>	<u>*0.3885</u>	<u>*0.2770</u>	*0.4199	<u>*0.2853</u>	<u>*0.4421</u>	<u>*0.2905</u>
NIN-cat	*0.2505	0.1959	*0.2998	0.2119	*0.3280	0.2194	*0.3483	0.2242
NIN-cat3	*0.2543	*0.1973	*0.3046	*0.2136	*0.3346	*0.2215	*0.3553	*0.2264
NIN-hist	*0.3001	*0.2348	*0.3566	*0.2529	*0.3896	*0.2616	*0.4110	*0.2667
NIN-fut	0.1980	0.1581	0.2301	0.1685	0.2490	0.1735	0.2623	0.1767

## Full results - Caser buy

Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
Caser	0.1682	0.1361	0.1947	0.1446	0.2105	0.1488	0.2217	0.1514
Caser-SQN	*0.2020	*0.1601	*0.2367	*0.1713	*0.2568	*0.1766	*0.2715	*0.1801
Caser-SAC	*0.1979	*0.1559	*0.2237	*0.1684	*0.2581	*0.1741	<u>*0.2737</u>	*0.1778
Caser-QVAL	<u>*0.2050</u>	<u>*0.1644</u>	<u>*0.2391</u>	<u>*0.1755</u>	<u>*0.2594</u>	<u>*0.1808</u>	*0.2731	<u>*0.1841</u>
Caser-EVAL	0.2000	0.1610	*0.2321	0.1714	*0.2505	0.1762	*0.2638	0.1794
Caser-cat	0.1765	0.1434	0.2032	0.1521	0.2193	0.1564	0.2307	0.1591
Caser-cat3	0.1936	*0.1565	*0.2254	*0.1668	*0.2420	*0.1712	*0.2541	*0.1740
Caser-hist	<b>*0.2399</b>	<b>*0.1893</b>	<b>*0.2857</b>	<b>*0.2041</b>	<b>*0.3112</b>	<b>*0.2108</b>	<b>*0.3296</b>	<b>*0.2152</b>
Caser-fut	0.0299	0.0222	0.0378	0.0247	0.0435	0.0262	0.0481	0.0273

## Full results - SAS buy

Model	HR@5	NG@5	HR@10	NG@10	HR@15	NG@15	HR@20	NG@20
SAS	0.2458	0.1872	0.2995	0.2046	0.3283	0.2123	0.3509	0.2176
SAS-SQN	<u>*0.3012</u>	<u>*0.2280</u>	<u>*0.3657</u>	<u>*0.2490</u>	<u>*0.3989</u>	<u>*0.2577</u>	<u>*0.4227</u>	<u>*0.2634</u>
SAS-SAC	<b>*0.3143</b>	<b>*0.2379</b>	<b>*0.3810</b>	<b>*0.2596</b>	<b>*0.4153</b>	<b>*0.2687</b>	<b>*0.4382</b>	<b>*0.2741</b>
SAS-QVAL	*0.2860	*0.2163	*0.3471	*0.2361	*0.3799	*0.2448	*0.4010	*0.2498
SAS-EVAL	0.2963	*0.2242	*0.3619	*0.2454	*0.3962	*0.2545	*0.4195	*0.2600
SAS-cat	*0.2636	*0.1999	*0.3190	*0.2178	*0.3504	*0.2261	*0.3731	*0.2315
SAS-cat3	0.2572	0.1948	*0.3130	0.2129	*0.3437	0.2211	*0.3651	0.2261
SAS-hist	*0.2960	*0.2231	0.3315	*0.2428	0.3630	*0.2519	0.3847	*0.2573
SAS-fut	0.0207	0.0144	0.0285	0.0170	0.0349	0.0187	0.0400	0.0199

## Deriving Theorem 1

Let's consider a sequential recommendation problem with two items  $\mathcal{I} = \{x_1, x_2\}$  and only two possible interaction sequences that any user can take:  $\{x_1, x_2\}$  and  $\{x_2\}$ . For simplicity, let's consider that the training and testing sets are identical, meaning that overfitting for the training test will lead to optimal performances in the testing set.

This set  $\mathcal{D}$  contains one trace  $\{x_1, x_2\}$  and  $n > 1$  copies of the trace  $\{x_2\}$ .

An optimal solution  $f_*$  to the cross-entropy loss – assuming that  $f_*$  has enough capacity to encode such a solution – is the following:  $f_*(x_1|\emptyset) = \frac{1}{n+1}$ ,  $f_*(x_2|\emptyset) = \frac{n}{n+1}$ , and  $f_*(x_2|\{x_1\}) = 1$ . As a result, the NIP performance of  $f_*$  over  $\mathcal{D}$  is the following:

$$\mathcal{N}(\mathcal{D}, f_*) = \frac{1}{n+2} (n \cdot s(1) + s(2) + s(1)) = \frac{n+1}{n+2},$$

## Deriving Theorem 1

On the other hand, an optimal policy  $\pi_*$  for  $\mathcal{D}$  first recommends  $x_1$  because the expected discounted return of recommending  $x_1$  is  $q_*(\emptyset, x_1) = r(1 + \gamma)$  whereas the Q-function of recommending  $x_2$  is  $q_*(\emptyset, x_2) = r$ . Thus, as long as we define a positive reward  $r$  for interacting with an item and we use a discount of  $\gamma > 0$ , then  $\pi_*(x_1|\emptyset) = 1$ . And once the user interacts with  $x_1$ , the next recommendation will be  $x_2$ :  $\pi_*(x_2|x_1) = 1$ . Therefore, according to the NIP performance,  $\pi_*$  will fail at recommending  $x_1$  instead of  $x_2$  in  $n$  sequences in  $\mathcal{D}$ :

$$\mathcal{N}(\mathcal{D}, \pi_*) = \frac{1}{n+2} (n \cdot s(2) + s(1) + s(1)) = \frac{2}{n+2},$$

Hence, the ratio between the scores of  $f_*$  and  $\pi_*$  is the following:

$$\frac{\mathcal{N}(\mathcal{D}, f_*)}{\mathcal{N}(\mathcal{D}, \pi_*)} = n + \frac{1}{2} > n.$$

Then, as we increase the value of  $n$  the optimal policy  $\pi_*$  can perform arbitrarily worse than  $f_*$  according to any consistent NIP metric.

## Deriving Theorem 2

Let  $\mathcal{R}_\pi$  be a sequential recommender that ranks items according to a policy  $\pi$  and  $\mathcal{R}_f$  be a sequential recommender that ranks items according to  $f_*$ . Let  $C_{\mathcal{D}} : \mathcal{I}^* \rightarrow \mathbb{N}$  be a function that returns the number of times a subsequence appears in  $\mathcal{D}$ . In particular,  $C_{\mathcal{D}}(x_{1:t})$  is equal to the number of sequences in  $\mathcal{D}$  that begins with  $x_{1:t}$ . Then,

$$f_*(x_{1:t}, y) = \frac{C(x_{1:t} \circ y \mid \mathcal{D})}{C(x_{1:t} \mid \mathcal{D})} \quad \text{for all } y \in \mathcal{I}, \quad (1)$$

where  $x \circ y$  represents the concatenation of  $x$  and  $y$ .

$$\mathcal{N}(\mathcal{D}, \mathcal{R}) = \frac{1}{N} \sum_{x_s \subset \mathcal{D}} \sum_{y \in \mathcal{I}} C(x_s \circ y \mid \mathcal{D}) \cdot s(\mathcal{R}(x_s, y))$$

Let  $\mathcal{N}(\mathcal{D}, \mathcal{R}, x_s)$  be the following:

$$\mathcal{N}(\mathcal{D}, \mathcal{R}, x_s) = \sum_{y \in \mathcal{I}} C(x_s \circ y \mid \mathcal{D}) \cdot s(\mathcal{R}(x_s, y))$$



## Deriving Theorem 2

Then, we will prove that, for all subsequence  $x_s \subset \mathcal{D}$ :

$$\begin{aligned}\mathcal{N}(\mathcal{D}, \mathcal{R}_f, x_s) &= \sum_{y \in \mathcal{I}} C(x_s \circ y \mid \mathcal{D}) \cdot s(\mathcal{R}_f(x_s, y)) \\ &\geq \sum_{y \in \mathcal{I}} C(x_s \circ y \mid \mathcal{D}) \cdot s(\mathcal{R}_\pi(x_s, y)) = \mathcal{N}(\mathcal{D}, \mathcal{R}_\pi, x_s)\end{aligned}\tag{2}$$

$\mathcal{R}_f(x_s, y)$  ranks the items according to  $C(x_s \circ y \mid \mathcal{D})$ .

We will prove that Equation 2 holds by showing that no other ranking could achieve a higher  $\mathcal{N}(\mathcal{D}, \mathcal{R}_f, x_s)$  value than  $\mathcal{R}_f$ , for any  $x_s$ . Let's assume that there exists a policy  $\pi$  such that its ranking  $\mathcal{R}_\pi(x_s, \cdot)$  for the next item given the interaction sequence  $x_s$  has higher  $\mathcal{N}(\mathcal{D}, \mathcal{R}_\pi, x_s)$  value. For now, let's consider that the only difference between the rankings  $\mathcal{R}_f(x_s, \cdot)$  and  $\mathcal{R}_\pi(x_s, \cdot)$  is in the location of two items  $y_1$  and  $y_2$  that are swapped. That is,  $\mathcal{R}_f(x_s, y_1) = \mathcal{R}_\pi(x_s, y_2)$  and  $\mathcal{R}_f(x_s, y_2) = \mathcal{R}_\pi(x_s, y_1)$ . Let's say that  $f_*$  ranks  $y_1$  higher than  $y_2$ . Let  $p_1^f$  be the position of  $y_1$  according to  $f_*$  and  $p_2^f$  be the position of  $y_2$ . Conversely, let  $p_1^\pi$  be the position of  $y_1$  according to  $\pi$  and  $p_2^\pi$  be the position of  $y_2$ .

## Deriving Theorem 2

Since  $f_*$  ranks  $y_1$  higher than  $y_2$ , then  $C_1 = C(x_s \circ y_1 \mid \mathcal{D}) \geq C(x_s \circ y_2 \mid \mathcal{D}) = C_2$ . Therefore,

$$C_1 = C_2 + \epsilon ,$$

for some  $\epsilon \geq 0$ . In addition, we know that the scoring function  $s$  is non-increasing. That means that:

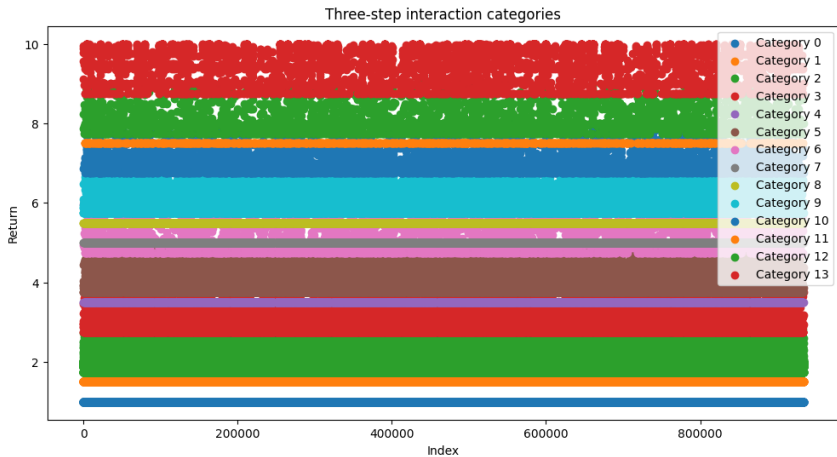
$$s(p_1^f) = s(p_2^f) + \beta ,$$

where  $\beta \geq 0$ . We now prove that the swap cannot increase the value of  $\mathcal{N}(\mathcal{D}, \mathcal{R}_f, x_s)$ .

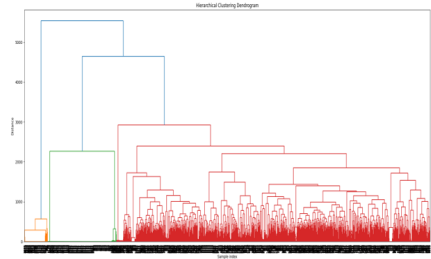
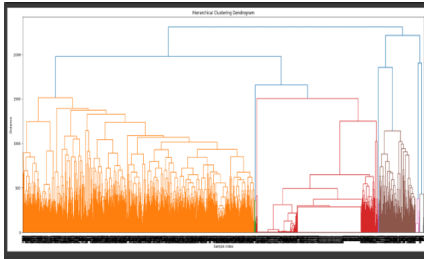
$$\begin{aligned} C_1 \cdot s(p_1^f) + C_2 \cdot s(p_2^f) &= (C_2 + \epsilon) \cdot (s(p_2^f) + \beta) + C_2 \cdot s(p_2^f) \\ &\geq C_2 \cdot s(p_2^f) + C_2 \cdot \beta + \epsilon \cdot s(p_2^f) + C_2 \cdot s(p_2^f) \\ &= C_2 \cdot s(p_2^\pi) + s(p_1^\pi) \cdot C_1 \end{aligned}$$

Thus, swapping the order of  $y_1$  and  $y_2$  cannot increase the value of  $\mathcal{N}(\mathcal{D}, \mathcal{R}_f, x_s)$ . And, for the same reason, making more than one swaps cannot increase the value of  $\mathcal{N}(\mathcal{D}, \mathcal{R}_f, x_s)$ . This means that, regardless the policy  $\pi$ ,  $\mathcal{N}(\mathcal{D}, \mathcal{R}_f, x_s) \geq \mathcal{N}(\mathcal{D}, \mathcal{R}_\pi, x_s)$ . And since this relation holds for all  $x_s \subset \mathcal{D}$ ,  $\mathcal{N}(\mathcal{D}, f_*) \geq \mathcal{N}(\mathcal{D}, \pi_*)$  – proving the theorem.

# Three-Step categorization (CAT2 model)



# Clustering approach-Hierarchical Clustering



**Table 1:** Initial list of features before filtering

Feature	Description
Interaction	Categorical feature denoting the interaction type (click, buy) at the target timestamp
Interaction_2	Categorical feature denoting the interaction type (click, buy, done) at timestamp $t + 1$
Interaction_3	Categorical feature denoting the interaction type (click, buy, done) at timestamp $t + 2$
Is_done	Binary feature denoting whether the sequence finishes at timestamp $t$
hist-length	Number of past user interactions in the sequence.
fut-length	Number of future user interactions in the sequence.
total-length	Number of interactions in the complete sequence.
Q-Value (eval)	The expected return following the sequence in the history log.
hist-buys	Number of items the user bought in past interactions.
fut-buys	Number of items the user will buy in future interactions.
Steps2Buy	Number of steps until the next buy interaction in the sequence.

**Table 2:** Feature importance values for clustering models

Feature	Kmeans-4	Kmeans-8	Hierarchical
hist-length	<b>0.418</b>	<b>0.362</b>	<b>0.448</b>
total-length	<u>0.255</u>	<u>0.255</u>	<u>0.237</u>
fut-length	0.113	0.117	0.115
Q-Value (EVAL)	0.073	0.085	0.060
fut-buys	0.092	0.057	0.037
hist-buys	0.031	0.035	0.030
Steps2Buy	0.021	0.028	0.029

**Table 3:** Model parameters used in training. **Batch:** Batch size used. **lr:** learning rate. **h\_factor:** Hidden factor or item embedding size. **filter#** Number of horizontal filters used in Caser. **f\_sizes:** The size of the horizontal filters in Caser. **Head#** : Number of heads in self-attention in SASRec. **dropout:** Dropout Rate. **CR:** Click Reward. **BR:** Buy Reward

Model	Optimizer	Epochs	Batch	lr	$\gamma$	h_factor	filter#	f_sizes	Head#	dropout	CR	BR
GRU	Adam	50	256	0.005	0.5	64	-	-	-	0	1	5
NIN	Adam	50	256	0.005	0.5	64	-	-	-	0	1	5
Caser	Adam	50	256	0.005	0.5	64	16	[2,3,4]	-	0.1	1	5
SAS	Adam	50	256	0.005	0.5	64	-		1	0.1	1	5

