

# Acceptance Tests

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## Qualification tests

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Model: PLD PFM 2.02 / **Flight Hardware**

Test equipment / conditions: all components and sockets soldered.

Tested with OBC EM 2.02 via OBC terminal.

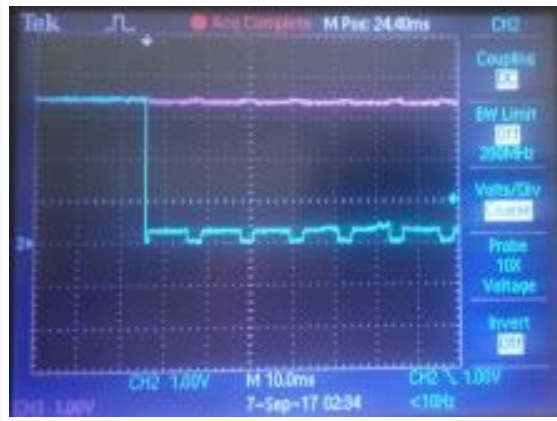
### 1. Power

	Current (raw)	Current (mA)	result
before PLD turned on	13	30	passed
after PLD turned on - idle mode	23 - 32	54 - 75	passed
current consumption - idle mode		24 - 45	passed

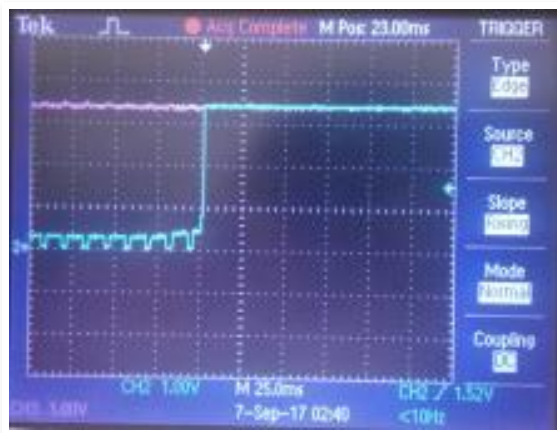
### LCL tests

OBC\_PLD\_3V3 and OBC\_BUS\_3V3 were tested against overcurrent/short-circuit. Overcurrent condition was caused by a 5 Ohm resistor.

in pink: input voltage to LCL, in blue: output voltage from LCL. Both LCLs were behaving exactly the same, so only one oscillogram is shown.



Normal operation (LCL powered up) and then short by a 5 Ohm resistor.



A moment of load (5 Ohm) disconnection.

## 2. AVR

Uploaded software: [commit 29d1b9d8dc5e0fe59c7b0065ac84c183bede075d](#)

- **WHO\_AM\_I test**

simply passed

```
OBC> obc.payload_whoami()  
Out[10]: {'Who Am I': 83}
```

- **house keeping**

field	raw value	computed voltage (V)	result
INT 3V3D	1633	3.27	passed
OBC 3V3D	1669	3.34	passed

- **payload temperatures**

Thermometer	raw	Centigrades (°C) or Resistance (Ω)	result	additional info
CAM nadir	2155	28.33°C	passed	
CAM wing	2153	27.77°C	passed	
SADS	2157	28.89°C	passed	
Sail	1238 / 3472 / 3376	433.17Ω/5564.1Ω/4688.89Ω	passed	references: 430Ω/5.6kΩ/4.7kΩ
Supply	2261	27.48°C	passed	

Xn	1238 / 3475 / 3379	433.17Ω/5595.8Ω/4712.7Ω	passed	references: 430Ω/5.6kΩ/4.7kΩ
Xp	1239 / 3475 / 3379	433.67Ω/5595.8Ω/4712.7Ω	passed	references: 430Ω/5.6kΩ/4.7kΩ
Yn	1239 / 3475 / 3379	433.67Ω/5595.8Ω/4712.7Ω	passed	references: 430Ω/5.6kΩ/4.7kΩ
Yp	1238 / 3475 / 3379	433.17Ω/5595.8Ω/4712.7Ω	passed	references: 430Ω/5.6kΩ/4.7kΩ

All channels were validated for correctness in PLD/OBC code.

- **reference sun sensor**

channel no.	test voltage 1 (V)	raw for test voltage 1	calculated value for test voltage 1	test voltage 2 (V)	raw for test voltage 2	calculated value for test voltage 2 (V)	result
V1	1.0	801	1.018	2.0	1579	2.007	passed
V2	2.0	1583	2.012	3.0	2369	3.011	passed
V3	1.0	793	1.008	2.0	1578	2.006	passed
V4	2.0	1581	2.009	3.0	2368	3.010	passed
V5	1.0	794	1.009	2.0	1579	2.007	passed

Channels naming in PLD/OBC software is correct.

- **photodiodes**

Test carried out with photodiode simulator (VCCS) and real photodiode. Chanel naming in OBC/PLD software was validated also.

photodiode	phd test current (mA)	measured raw	computed measured current (mA)	result
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Xn	1.373 / 0.520 / 0.109	1457 / 606 / 195	1.37 / 0.52 / 0.11	passed
Xp	1.368 / 0.516 / 0.108	1453 / 602 / 194	1.37 / 0.52 / 0.11	passed
Yn	1.371 / 0.520 / 0.109	1457 / 605 / 195	1.38 / 0.52 / 0.11	passed
Yp	1.375 / 0.518 / 0.110	1461 / 604 / 195	1.38 / 0.52 / 0.11	passed

- **RadFET**

Power consumption:

	Current (raw)	Current (mA)	result
before RadFET turned on	21 - 31	49 - 73	passed
after RadFET turned on - idle mode	24 - 36	56 - 84	passed
current consumption - idle mode	3 - 5	7 - 12	passed

Operation:

`radfet_read` after power cycle when radfet is off:

```
{'Status': 225, 'Temperature': 0, 'Vth0': 0, 'Vth1': 0, 'Vth2': 0}
```

`radfet_on`:

```
{'Status': 225, 'Temperature': 0, 'Vth0': 0, 'Vth1': 0, 'Vth2': 0}
```

`radfet_read` (when radfet is on):

```
{'Status': 33, 'Temperature': 8237364, 'Vth0': 13729448, 'Vth1': 13680988, 'Vth2': 13748803}
```

radfet\_off (when radfet is on):

```
{'Status': 32, 'Temperature': 8237364, 'Vth0': 13729448, 'Vth1': 13680988, 'Vth2': 13748803}
```

### 3. Sail indicator

Tested on values indicated in telemetry. OBC correctly recognizes state of the sail indicator.

Tested values: jumper (0 Ohm), 430Ω, 4.7kΩ - all passed.

### 4. Cameras

Power consumption:

camera	before turn on raw / mA	after turn on raw / mA	consumption raw / mA	test result	comment
nadir	20 / 42.2	58 / 126.6	38 / 84.4	passed	
wing	18 / 39.8	55 / 121.9	37 / 82.1	passed	

Statistics of taken photos:

Camera	Qty of photos taken	Fails	% of fails	Result
Nadir	351	3	0.85%	passed
Wing	351	0	0%	passed

### 5. SunS

Power consumption:

- current EPS before SunS turning on: 18 raw / 0.042 A

- current EPS after: 28 raw / 0.066 A
- current consumption by the SunS: 10 raw / 0.024 A

Test passed.

Communication via I2C + INT with the SunS was successfully tested for 1000 times.

## 6. Gyroscope

`gyro init` - passed

`gyro read` - passed - 1000 samples taken.

The samples were logged into csv file and can be taken as calibration data for gyro (null offset).



**flight\_gyroscope\_calibration.csv** 19 KB

[Download](#)

## 7. RTC

- **time counting test** - OBC range test: passed | 2-second test: passed | 5-minute test:

1st run:

```
>rtc test
Start: 0-1-1 18:4:0 (946749840 sec since epoch)
Seconds range: ok
Minutes range: ok
Hours range: ok
+2s: 0-1-1 18:4:2 (946749842 sec since epoch)
Time after 2 seconds: ok
```

```
Waiting 5 minutes...
+5min: 0-1-1 18:9:3 (946750143 sec since epoch)
System reported 301000 milliseconds
    RTC reported 301000 seconds
ok
```

2nd run:

```
>rtc test
Start: 0-1-1 18:15:10 (946750510 sec since epoch)
Seconds range: ok
Minutes range: ok
Hours range: ok
+2s: 0-1-1 18:15:12 (946750512 sec since epoch)
Time after 2 seconds: ok
Waiting 5 minutes...
+5min: 0-1-1 18:20:13 (946750813 sec since epoch)
System reported 300050 milliseconds
    RTC reported 301000 seconds
ok
```

- **backup power test for at least 1 hour** - passed

before power down

```
>rtc get
0-1-3 11:16:42 (946898202 sec since epoch)
```



after 1 hour lack of power:

```
>rtc get  
0-1-3 12:20:29 (946902029 sec since epoch)
```

- **backup power test for 2 hour** - test passed
- **backup power test for 3 hour** - not carried out

## 8. FRAM

- run OBC diagnostics:

```
>fram testall f  
Fram 1 read write ok: 1  
Fram 2 read write ok: 1  
Fram 3 read write ok: 1
```

Test was repeated for 200 times. All passed.

## 9. FLASH

- run OBC diagnostics

```
>Flash 1 id valid: 1  
Flash 2 id valid: 1  
Flash 3 id valid: 1
```

Test repeated for 1000 times.

```
>erase all  
Erasing all flashes ...  
Erase result: 0
```

Tests passed.

## 10. **LED**

OK

## 11. **Access port**

#	Function	Status
1	Kill switch	OK
2	I2C BUS	OK
3	I2C PLD	OK
4	OBC UART	OK
5	MPPT X Input	OK
6	MPPT Y- Input	OK
7	MPPT Y+ Input	OK

