

# Search in Python

Chapter 3

# **Today's topics**

- Norvig's Python code
- What it does
- How to use it
- A worked example: water jug program
- What about Java?

### **Overview**

To use the AIMA python code for solving the two water jug problem (WJP) using search we'll need four files

- wj.py: need to write this to define the problem, states, goal, successor function, etc.
- search.py: Norvig's generic search framework, imported by wj.py
- util.py and agents.py: more generic Norvig code imported by search.py

# **Two Water Jugs Problem**





- Given two water jugs, J1 and J2, with capacities C1 and C2 and initial amounts W1 and W2, find actions to end up with W1' and W2' in the jugs
- Example problem:
  - -We have a 5 gallon and a 2 gallon jug
  - Initially both are full
  - We want to end up with exactly one gallon in J2 and don't care how much is in J1

## search.py

- Defines a Problem class for a search problem
- Provides functions to perform various kinds of search given an instance of a Problem
  - e.g.: breadth first, depth first, hill climbing, A\*, ...
- Has a Problem subclass, InstrumentedProblem, and function, compare\_searchers, for evaluation experiments
- To use for WJP: (1) decide how to represent the WJP,
   (2) define WJP as a subclass of Problem and (3) provide methods to (a) create a WJP instance, (b) compute successors and (c) test for a goal.

# **Two Water Jugs Problem**





Given J1 and J2 with capacities C1 and C2 and initial amounts W1 and W2, find actions to end up with W1' and W2' in jugs

#### **State Representation**

State = (x,y), where x & y are water in J1 & J2

- Initial state = (5,0)
- Goal state = (\*,1),where \* is any amount

#### Operator table

Actions	Cond.	Transition	Effect
Empty J1	-	$(x,y) \rightarrow (0,y)$	Empty J1
Empty J2	-	$(x,y) \rightarrow (x,0)$	Empty J2
2to1	x ≤ 3	$(x,2) \rightarrow (x+2,0)$	Pour J2 into J1
1to2	$x \ge 2$	$(x,0) \rightarrow (x-2,2)$	Pour J1 into J2
1to2part	y < 2	$(1,y) \rightarrow (0,y+1)$	Pour J1 into J2 until full

# Our WJ problem class

# Our WJ problem class

```
def successor(self, (J1, J2)): # returns list of successors to state
    successors = []
    (C1, C2) = self.capacities
    if J1 > 0: successors.append(('Dump J1', (0, J2)))
    if J2 > 0: successors.append(('Dump J2', (J1, 0)))
    if J2 < C2 and J1 > 0:
        delta = min(J1, C2 - J2)
        successors.append(('Pour J1 into J2', (J1 - delta, J2 + delta)))
    if J1 < C1 and J2 > 0:
        delta = min(J2, C1 - J1)
        successors.append(('pour J2 into J1', (J1 + delta, J2 - delta)))
    return successors
```

## Solving a WJP

```
code> python
>>> from wj import *; from search import *
                                                # Import wj.py and search.py
>>> p1 = WJ((5,2), (5,2), ('*', 1))
                                                 # Create a problem instance
>>> p1
WJ((5, 2),(5, 2),('*', 1))
>>> answer = breadth_first_graph_search(p1) # Used the breadth 1st search function
>>> answer
                                                 # Will be None if the search failed or a
<Node (0, 1)>
                                                 # a goal node in the search graph if successful
>>> answer.path_cost
                                                # The cost to get to every node in the search graph
                                                # is maintained by the search procedure
                                                # A node's path is the best way to get to it from
>>> path = answer.path()
                                                 # the start node, i.e., a solution
[<Node (0, 1)>, <Node (1, 0)>, <Node (1, 2)>, <Node (3, 0)>, <Node (3, 2)>, <Node (5, 0)>, <Node (5, 2)>]
>>> path.reverse()
>>> path
[<Node (5, 2)>, <Node (5, 0)>, <Node (3, 2)>, <Node (3, 0)>, <Node (1, 2)>, <Node (1, 0)>, <Node (0, 1)>]
```

## **Comparing Search Algorithms Results**

```
searchers = [breadth_first_tree_search, breadth_first_graph_search, depth_first_graph_search, ...]
  problems = [WJ((5,2), (5,0), (0,1)), WJ((5,2), (5,0), (2,0))]
  for p in problems:
    for s in searchers:
      print 'Solution to', p, 'found by', s. name
      path = s(p).path() # call search function with problem
      path.reverse()
                          # print solution path
      print path, '\n'
  print 'SUMMARY: successors/goal tests/states generated/solution'
  # Now call the comparison function to show data about the performance of the dearches
  compare searchers(problems=problems,
    header=['SEARCHER', 'GOAL:(0,1)', 'GOAL:(2,0)'],
    searchers=[breadth first tree search, breadth first graph search, depth first graph search,...])
# if called from the command line, call main()
if __name__ == "__main__": main()
```

## **Comparing Search Algorithms Results**

- Uninformed searches: breadth\_first\_tree\_search, breadth\_first\_graph\_search, depth\_first\_graph\_ search, iterative\_deepening\_search, depth\_limited\_ search
- All but depth\_limited\_search are sound (solutions found are correct)
- Not all are complete (always find a solution if one exists)
- Not all are optimal (find best possible solution)
- · Not all are efficient
- AIMA code has a comparison function

## **The Output**

```
code> python wj.py
Solution to WJ((5, 2), (5, 0), (0, 1)) found by breadth_first_tree_search
[<Node (5, 0)>, <Node (3, 2)>, <Node (3, 0)>, <Node (1, 2)>, ..., <Node (0, 1)>]
...
Solution to WJ((5, 2), (5, 0), (2, 0)) found by depth_limited_search
[<Node (5, 0)>, <Node (3, 2)>, <Node (0, 2)>, <Node (2, 0)>]

SUMMARY: successors/goal tests/states generated/solution
SEARCHER GOAL:(0,1) GOAL:(2,0)
breadth_first_tree_search < 25/ 26/ 37/(0, > < 7/ 8/ 11/(2, >
breadth_first_graph_search < 8/ 17/ 16/(0, > < 5/ 8/ 9/(2, >
depth_first_graph_search < 5/ 8/ 12/(0, > < 8/ 13/ 16/(2, >
iterative_deepening_search < 35/ 61/ 57/(0, > < 8/ 16/ 14/(2, >
depth_limited_search < 194/ 199/ 200/(0, > < 5/ 6/ 7/(2, >
code>
```