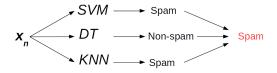
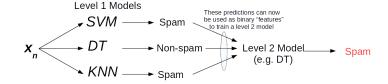
Some Simple Ensembles

Voting or Averaging of predictions of multiple pre-trained models

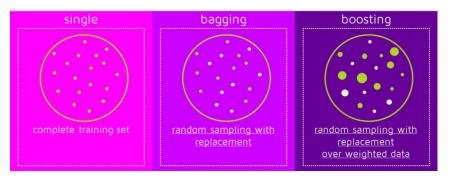


 "Stacking": Use predictions of multiple models as "features" to train a new model and use the new model to make predictions on test data



Ensembles: Another Approach

- Train same model multiple times on different data sets, and "combine" these "different" models
- Bagging and Boosting are two popular approaches for doing this
- How do we get multiple training sets (in practice, we only have one training set)?



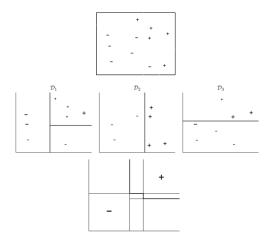
• Note: Bagging trains independent models; boosting trains them sequentially (we'll see soon)

Bagging

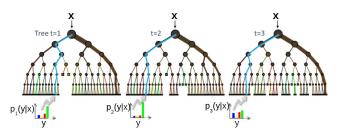
- Bagging stands for Bootstrap Aggregation
- ullet Takes original data set ${\mathcal D}$ with ${\mathcal N}$ training examples
- Creates M copies $\{\tilde{\mathcal{D}}_m\}_{m=1}^M$
 - ullet Each $ilde{\mathcal{D}}_m$ is generated from \mathcal{D} by sampling with replacement
 - Each data set $\tilde{\mathcal{D}}_m$ will have N examples
 - ullet These data sets are reasonably different from each other. Reason: Only about 63% unique examples from ${\cal D}$ appear in each ${\cal \tilde D}_m$
- Train models h_1, \ldots, h_M using $\tilde{\mathcal{D}}_1, \ldots, \tilde{\mathcal{D}}_M$, respectively
- Use an averaged model $h = \frac{1}{M} \sum_{m=1}^{M} h_m$ as the final model
- Bagging is especially useful for models with high variance and noisy data
- High variance models = models whose prediction accuracies varies a lot across different data sets

Bagging: illustration

Top: Original data, Middle: 3 models (from some model class) learned using three data sets chosen via bootstrapping, Bottom: averaged model



A Decision Tree Ensemble: Random Forests



- An bagging based ensemble of decision tree (DT) classifiers
- Also uses bagging on features (each DT will use a random set of features)
 - Example: Given a total of D features, each DT uses \sqrt{D} randomly chosen features
 - Randomly chosen features make the different trees uncorrelated
- All DTs usually have the same depth
- Prediction for a test example votes on/averages predictions from all the DTs

Boosting

- Another ensemble based approach
- The basic idea is as follows
 - Take a weak learning algorithm
 - Only requirement: Should be only slightly better than random
 - Turn it into an awesome one by making it focus on difficult cases
- Most boosting algoithms follow these steps:
 - Train a weak model on some training data
 - 2 Compute the error of the model on each training example
 - Give higher importance to examples on which the model made mistakes
 - Re-train the model using "importance weighted" training examples
 - Go back to step 2
- Note: Unlike bagging, boosting is a sequential algorithm (models learned in a sequence)

The AdaBoost Algorithm (Freund and Schapire, 1995)

- Given: Training data $(x_1, y_1), \dots, (x_N, y_N)$ with $y_n \in \{-1, +1\}$, $\forall n$
- Initialize importance weight of each example (x_n, y_n) : $D_1(n) = 1/N$, $\forall n$
- For round t = 1: T• Learn a weak $h_t(x) \to \{-1, +1\}$ using training data weighted as per D_t
 - Compute the weighted fraction of errors of h_t on this training data

$$\epsilon_t = \sum_{n=1}^{N} D_t(n) \mathbb{1}[h_t(\mathbf{x}_n) \neq y_n]$$

- Set "importance" of h_t : $\alpha_t = \frac{1}{2} \log(\frac{1-\epsilon_t}{\epsilon_t})$ (gets larger as ϵ_t gets smaller)
- Update the weight of each example

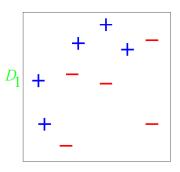
$$D_{t+1}(n)$$
 \propto $\begin{cases} D_t(n) \times \exp(-\alpha_t) & \text{if } h_t(\mathbf{x}_n) = y_n \\ D_t(n) \times \exp(\alpha_t) & \text{if } h_t(\mathbf{x}_n) \neq y_n \end{cases}$ (correct prediction: decrease weight) $D_t(n) \exp(-\alpha_t y_n h_t(\mathbf{x}_n))$

- Normalize D_{t+1} so that it sums to 1: $D_{t+1}(n) = \frac{D_{t+1}(n)}{\sum_{t=1}^{N} D_{t+1}(m)}$
- Output the "boosted" final hypothesis $H(\mathbf{x}) = \operatorname{sign}(\sum_{t=1}^{T} \alpha_t h_t(\mathbf{x}))$

AdaBoost: A Toy Example

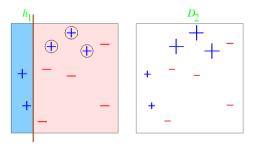
Consider binary classification with 10 training examples

Initial weight distribution D_1 is uniform (each point has equal weight =1/10)



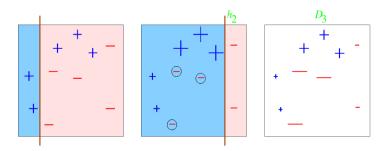
Let's assume each of our weak classifers is a very simple axis-parallel linear classifier

After Round 1



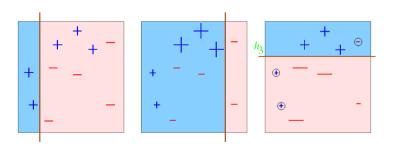
- Error rate of h_1 : $\epsilon_1 = 0.3$; weight of h_1 : $\alpha_1 = \frac{1}{2} \ln((1 \epsilon_1)/\epsilon_1) = 0.42$
- ullet Each misclassified point upweighted (weight multiplied by $\exp(lpha_1)$)
- ullet Each correctly classified point downweighted (weight multiplied by $\exp(-\alpha_1)$)

After Round 2



- Error rate of h_2 : $\epsilon_2 = 0.21$; weight of h_2 : $\alpha_2 = \frac{1}{2} \ln((1 \epsilon_2)/\epsilon_2) = 0.65$
- ullet Each misclassified point upweighted (weight multiplied by $\exp(lpha_2)$)
- ullet Each correctly classified point downweighted (weight multiplied by $\exp(-\alpha_2)$)

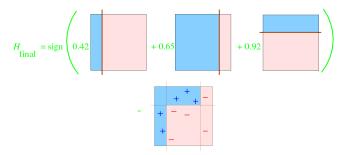
After Round 3



- Error rate of h_3 : $\epsilon_3 = 0.14$; weight of h_3 : $\alpha_3 = \frac{1}{2} \ln((1 \epsilon_3)/\epsilon_3) = 0.92$
- Suppose we decide to stop after round 3
- Our ensemble now consists of 3 classifiers: h_1, h_2, h_3

The Final Classifier

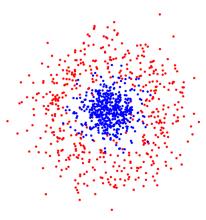
- Final classifier is a weighted linear combination of all the classifiers
- Classifier h_i gets a weight α_i



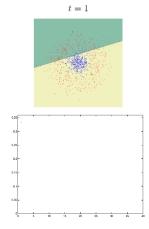
Multiple weak, linear classifiers combined to give a strong, nonlinear classifier

Another Example

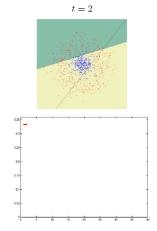
- Given: A nonlinearly separable dataset
- We want to use Perceptron (linear classifier) on this data



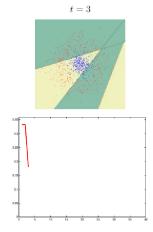
- After round 1, our ensemble has 1 linear classifier (Perceptron)
- \bullet Bottom figure: X axis is number of rounds, Y axis is training error



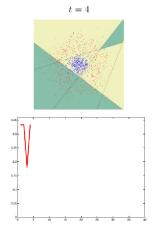
- After round 2, our ensemble has 2 linear classifiers (Perceptrons)
- \bullet Bottom figure: X axis is number of rounds, Y axis is training error



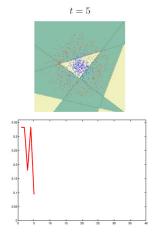
- After round 3, our ensemble has 3 linear classifiers (Perceptrons)
- \bullet Bottom figure: X axis is number of rounds, Y axis is training error



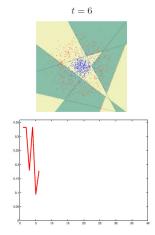
- After round 4, our ensemble has 4 linear classifiers (Perceptrons)
- \bullet Bottom figure: X axis is number of rounds, Y axis is training error



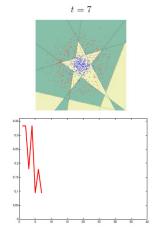
- After round 5, our ensemble has 5 linear classifiers (Perceptrons)
- \bullet Bottom figure: X axis is number of rounds, Y axis is training error



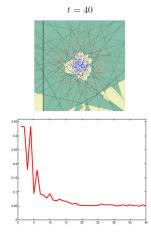
- After round 6, our ensemble has 6 linear classifiers (Perceptrons)
- \bullet Bottom figure: X axis is number of rounds, Y axis is training error



- After round 7, our ensemble has 7 linear classifiers (Perceptrons)
- Bottom figure: X axis is number of rounds, Y axis is training error



- After round 40, our ensemble has 40 linear classifiers (Perceptrons)
- Bottom figure: X axis is number of rounds, Y axis is training error



AdaBoost: The Loss Function

• AdaBoost can be shown to be optimizing the following loss function

$$\mathcal{L} = \sum_{n=1}^{N} \exp\{-y_n H(\boldsymbol{x}_n)\}\$$

where $H(\mathbf{x}) = \text{sign}(\sum_{t=1}^{T} \alpha_t h_t(\mathbf{x}))$, given weak base classifiers h_1, \dots, h_T

Summary

- Ensemble methods are highly effective at boosting performance of simple learners
- Often achieve state-of-the-art results on many problems
 - AdaBoost was used in one of the first real-time face-detectors (Viola and Jones, 2001)



- Netflix Challenge was won by an ensemble method (based on matrix factorization)
- Many Kaggle competition have been won by Gradient Boosting methods such as XGBoost
- Even outperform deep learning models on many problems
- Help reduces bias or/and variance of machine learning models
 - High bias: very simple models have high bias. Boosting can reduce it
 - High variance: very complex models have high variance. Bagging can reduce it