ENSC 2113 Engineering Mechanics: Statics

Chapter 2:

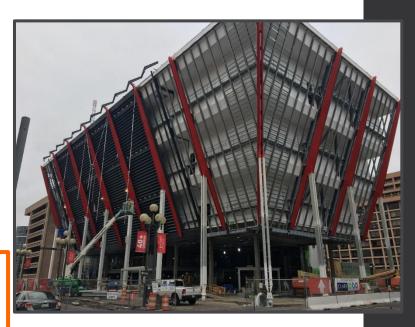
Force Vectors

(Sections 2.5-2.6)



Chapter 2 Outline:

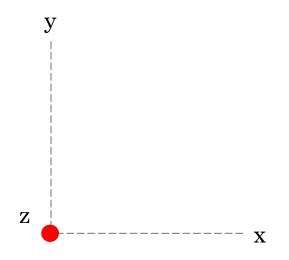
- 2.1 Scalars and Vectors
- 2.2 Vector Operations
- 2.3 Vector Addition of Forces
- 2.4 Addition of a System of Coplanar Forces
- 2.5 Cartesian Vectors
- 2.6 Addition of Cartesian Vectors
- 2.7 Position Vectors
- 2.8 Force Vector Directed Along a Line
- 2.9 Dot Product



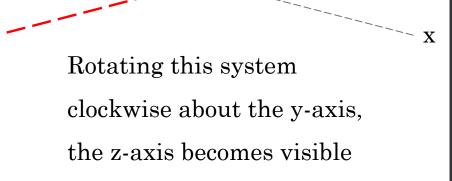
Chapter 2 Objectives:

- To show how to add forces and resolve them into components using the Parallelogram Law
- To express force and position in Cartesian vector form and explain how to determine the vector's magnitude and direction
- To introduce the dot product in order to use it to find the angle between two vectors or the projection of one vector onto another

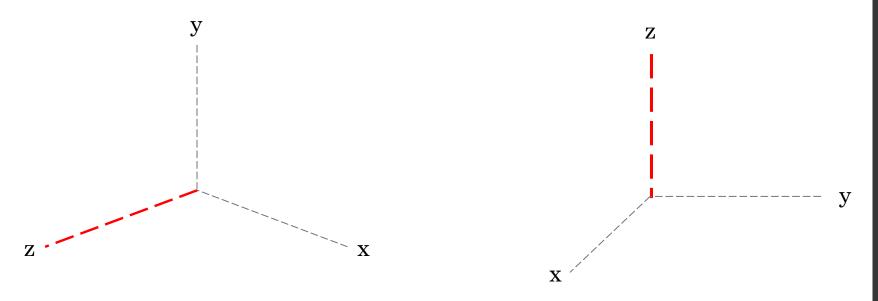
■ 3-D coordinate system



In the 2-D system, the z-axis is coming out of the page

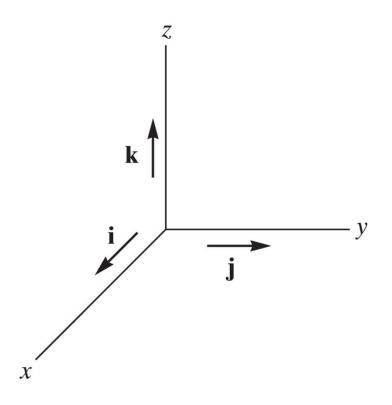


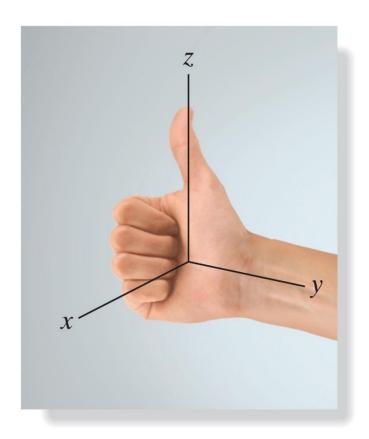
■ 3-D coordinate system



Rotate this system 90 degrees

■ 3-D coordinate system



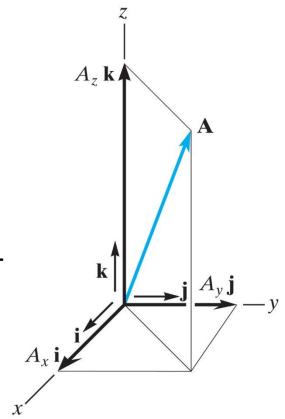


Cartesian Vector Representation

$$\vec{A} = \left\{ A_x \hat{\imath} + A_y \hat{\jmath} + A_z \hat{k} \right\}$$

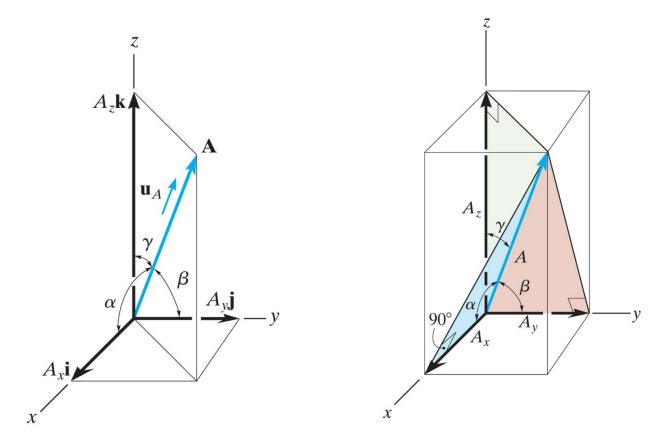
Magnitude of a Vector

$$A = \sqrt{(A_x)^2 + (A_y)^2 + (A_z)^2}$$

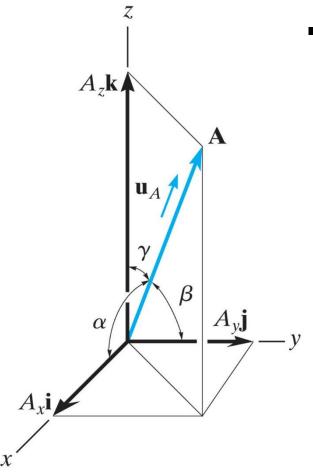


Direction Angles or Direction Cosines

 α = angle between the vector and the positive x-axis β = angle between the vector and the positive y-axis γ = angle between the vector and the positive z-axis



Direction Angles or Direction Cosines



Finding the components from the magnitude and direction angles:

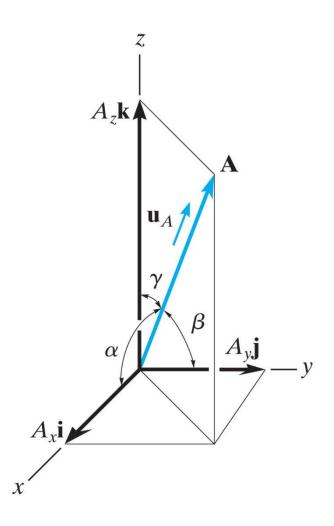
$$A_x = A \cos \alpha$$
$$A_y = A \cos \beta$$
$$A_z = A \cos \gamma$$

$$A_{v} = A \cos \beta$$

$$A_z = A \cos \gamma$$

Note: angles >90 degrees produce negative components

Solving for the direction angles



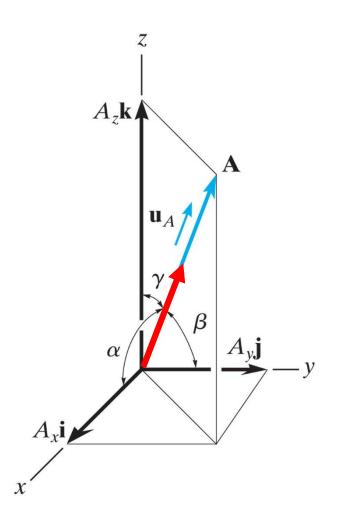
 Finding the direction angles from the magnitude and components

$$\alpha = \cos^{-1} \frac{A_{\chi}}{A}$$

$$\beta = \cos^{-1} \frac{A_y}{A}$$

$$\gamma = \cos^{-1} \frac{A_z}{A}$$

Unit vector – using direction angles

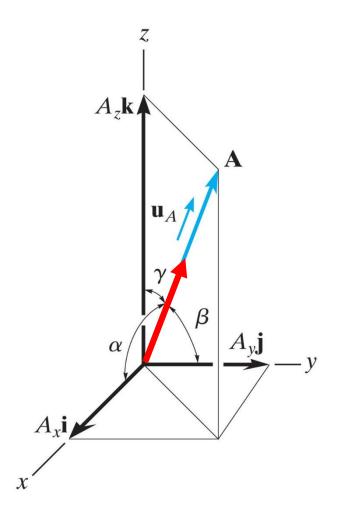


$$\vec{A} = \{ A \cos \alpha \,\hat{\imath} + A \cos \beta \,\hat{\jmath} + A \cos \gamma \,\hat{k} \}$$

The unit vector is one unit in the same direction as the vector and can be found using the direction angles:

$$\vec{u} = \{\cos\alpha\,\hat{\imath} + \cos\beta\,\hat{\jmath} + \cos\gamma\,\hat{k}\}\$$

Unit vector – using magnitude and components



The unit vector is one unit in the same direction as the vector and can be found by dividing the vector by the magnitude:

$$\vec{u} = \left\{ \frac{A_x}{A} \hat{\imath} + \frac{A_y}{A} \hat{\jmath} + \frac{A_z}{A} \hat{k} \right\}$$

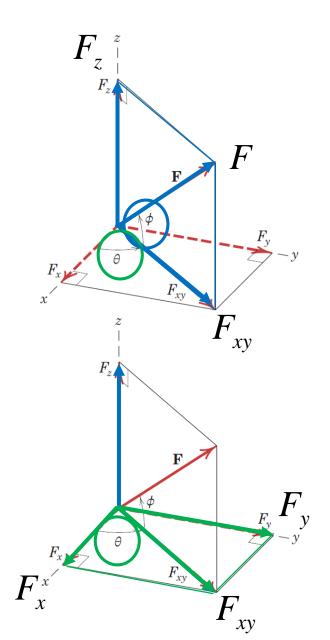
- Specification by two angles
 - Step 1: Horizontal and Vertical Components (z-xy plane)

$$F_{xy} = F \cos \phi$$
 $F_z = F \sin \phi$

Step 2: Components in x-y plane

France
$$F_{x} = F_{xy} \cos \theta = F \cos \phi \cos \theta$$

$$F_{y} = F_{xy} \sin \theta = F \cos \phi \sin \theta$$



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