



# Master Reinforcement Learning 2022

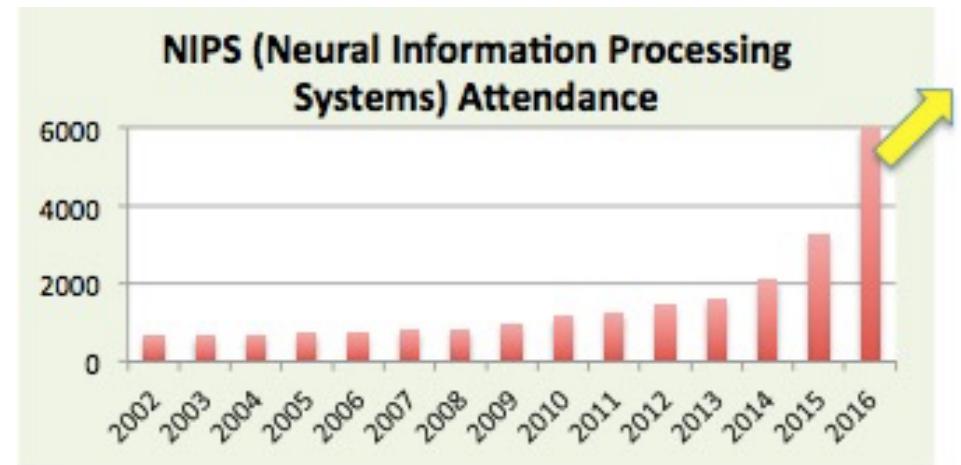
## Lecture 1: Intro

Aske Plaat



# DRL is Hot

- After Supervised Learning, Reinforcement Learning is now very much in fashion
  - Attendance AI conferences
  - Attendance RL workshops
  - Startups
- Everybody wants to understand how it works and what it can do
- Many blogs. Some quite good



# The Economist

JUNE 25TH-JULY 1ST 2016

Inside China's Ministry of Truth

Trump in trouble

Who are the Niger Delta Avengers?

The flaws in executive pay

Motorcycles that fly

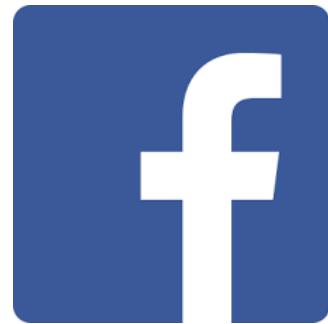
# March of the machines

A SPECIAL REPORT ON ARTIFICIAL INTELLIGENCE



Google

amazon



腾讯  
Tencent

eBay

Alibaba.com

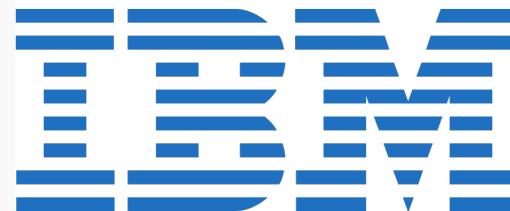


DeepMind

DE Shaw & Co



新浪微博  
weibo.com



Microsoft

Baidu 百度

NETFLIX

# Quiz: Why is DRL Hot?\*

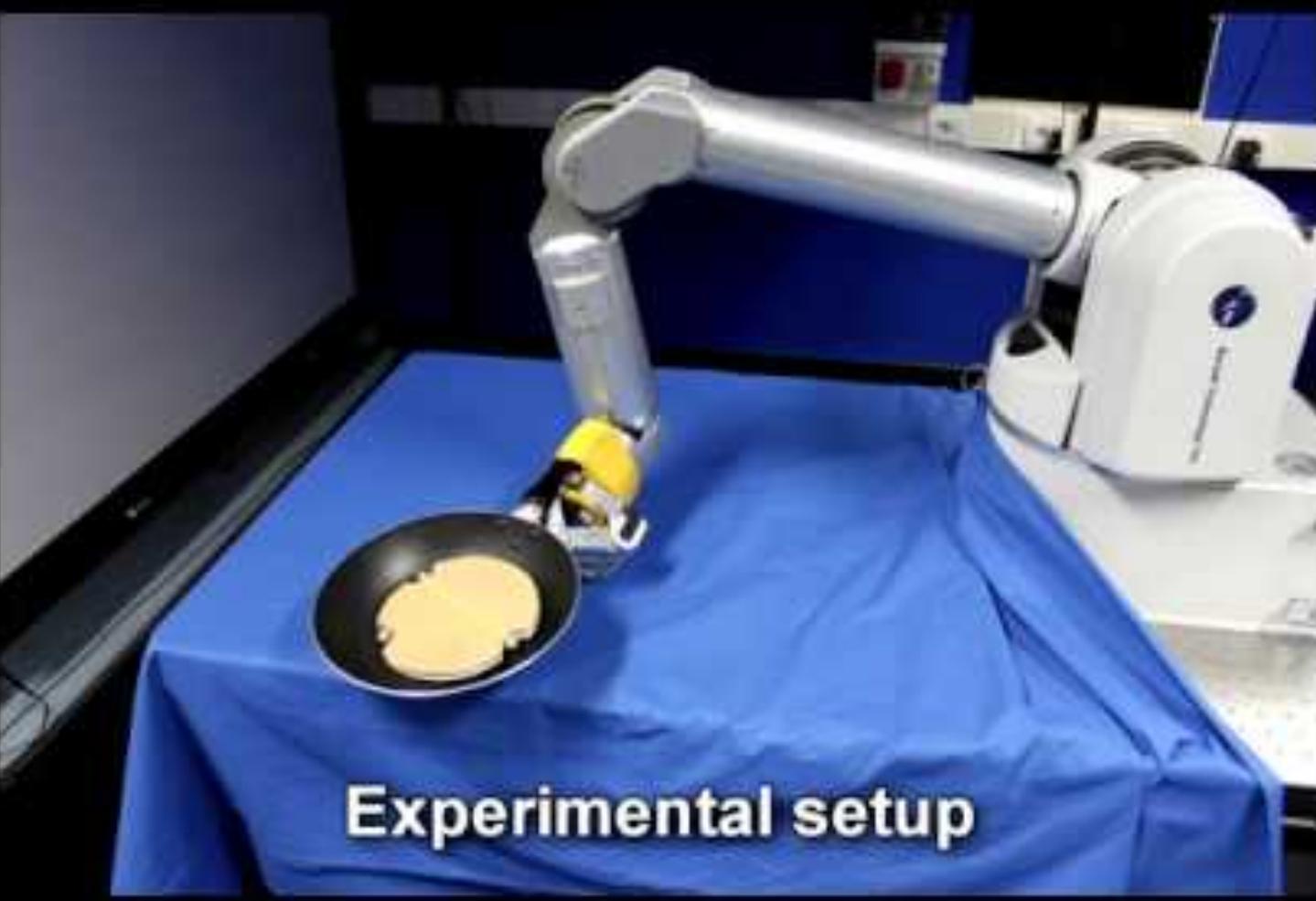


# Applications





movie



Experimental setup

movie





# **What is RL?**

# Neurological Learning



Unconditioned Response  
(Salivation)



Unconditioned Stimulus  
(Food)



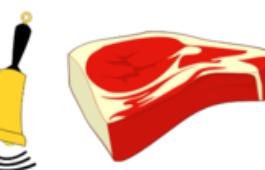
No Response



Neutral Stimulus  
(Bell Ringing)



Unconditioned Response  
(Salivation)



Neutral Stimulus  
(Bell Ringing)      Unconditioned Stimulus  
(Food)



Conditioned Response  
(Salivation)



Conditioned Stimulus  
(Bell Ringing)



# Motivation for this course

- Intelligence is fascinating
- How can computers learn as humans?



# Your Teachers



- Aske Plaat, Thomas Moerland, Matthias Müller-Brockhausen, Mike Huisman, Zhao Yang
- Members of LIACS Reinforcement Learning Group
- email: [rl@liacs.leidenuniv.nl](mailto:rl@liacs.leidenuniv.nl)
- **Brightspace**: register, course documents, assignments
- Question Hour Fridays after course

# Prerequisites



- Bachelor level Python
- Bachelor level Artificial Intelligence

# Lectures

- Theory lectures Mandatory
- Explanations & Interaction
- Fridays 09:15-11:00.
- Practice lectures (Q&A) for reflection & assignment help
- Fridays 11:15-13:00.
- See **SCHEDULE!**  
on Brightspace



# 2022: New!

- This year's course is about **Deep Reinforcement Learning**
- **Deep Reinforcement Learning** =  
**Deep Learning + Reinforcement Learning**
- *Old assignments no longer valid (they never are)*
- *New Book (still free) <https://deep-reinforcement-learning.net>*
- *Old books are still useful but only as additional book*
- *Programming! Every three weeks an assignment*

# Book

- **Book:** <https://deep-reinforcement-learning.net>
- **Mandatory material**
- Follow Book, Slides are extra
- **Preprint: Comments are Greatly Appreciated**
- [Optional Book Learning to Play, RL + Games]
- [Optional Book Sutton & Barto, the Bible of RL]

# Different Aspects

- Deep Learning [B]
- Model-free
  - Value-based [2,3]
  - Policy-based [4]
- Model-based
  - Learned Transition model [5]
  - Perfect; Two-Agent [6]
- Multi-agent [7]
- Hierarchical Reinforcement Learning (Sub-goals) [8]
- Meta Learning [9]

# Teaching Philosophy

- Read Chapter
  - Attend Lecture
  - Try **Assignment**
  - Practicals Ask Help



# Field of RL

- Teach latest scientific achievements
- Learning by doing: Assignments are where you learn the most
- Work hard learn much.  
LOTS OF PROGRAMMING!
- Results in research papers are based on much tuning, which they do not tell with so many words.
- Computational Demands. Long Training
- Rough ride in friendly atmosphere



# Assignments



- 3 Assignments, each 25%
- 1 Theory exam 25%  
(Quizzes: see Book. Sample Exam see Blackboard)
- Final grade is the average of the 5 individual elements:  
4 assignments and 1 theory exam. No pass thresholds for individual items. You pass when the average >5.5  
9-9-9-9-1 is fine:  $37/5=7.4$
- There is no retake for the assignments, but there is a late-hand-in policy:  
one point off for each day late.
- All assignments are valid for only one year. If you do this course a second time you have to do everything over.

# Assignment Groups

- First assignment: individual
- Second & Third assignment: Groups of 3  
Put all names on each report
- If from Math, Astro, Physics,  
choose a CS in your group (programming!)
- Register on Brightspace
- Submit assignments to 1 course (not also to Neural Networks or to Game AI)
- Working code + short report
- Well written, well documented,  
clear report, reproducible, insights



# Grading Criteria

- See Brightspace
- Clear Explanation of experiments
- Good measurements, graphs
- Try explanations of findings
- Fair grading: all who seriously try should be able to pass

The screenshot shows a web browser window for wired.com. The main headline reads "Artificial Intelligence Confronts a 'Reproducibility' Crisis". Below the headline is a subtext: "Machine-learning systems are black boxes even to the researchers that build them. That makes it hard for others to assess the results." At the bottom of the page, there is a banner with the text "3 FREE ARTICLES LEFT THIS MONTH" and a "Subscribe" button.



*Joelle Pineau*

# Exam

- Theory exam and re-take
- 25%
- **Multiple Choice**
- Closed book, No SmartWatches, SmartPhones, Laptops  
(only human intelligence and mechanical time piece allowed)
- Inspired by “Questions” in Exercise Sections in Book
- Sample Exam is available on website and Brightspace



# No Fraud

- Fraud is absolutely forbidden
- All copying of other's work should be properly referenced in customary scientific fashion, e.g., [Sutton, 2018]
- All cases of fraud will be directed to the exam committee. You may be expelled from the course or from your master program. Crying will not help you
- No using part of the code of last year, another group, etc.
- No looking at your neighbours exam
- No electronic equipment during exam
- Cheating is fraud



# No Fraud



- A consequence of fraud is likely failing this course
- If you follow a track in which this course is mandatory, you waste a full year by cheating
- Your work should be your own, or that of your group
- Take precautions against others copying your work



# Recommended



- Deep Learning and Neural Networks, Wojtek Kowalczyk
- Modern Game AI, Mike Preuss
- Elective Seminar Advanced Deep RL Sep-Dec 2022  
Limited enrolment



# Resources

FREE

- Book:

**Deep Reinforcement Learning:** [Plaat 2022, Preprint] <https://deep-reinforcement-learning.net>



- Additional material

- Reinforcement Learning: An Introduction [Sutton & Barto 2018] <http://incompleteideas.net/book/RLbook2018.pdf>



- Deep Learning [Goodfellow et al. 2016] <http://www.deeplearningbook.org>



- RL course David Silver UCL <http://www.cs.ucl.ac.uk/staff/d.silver/web/Teaching.html>



- RL course Emma Brunskill Stanford <http://web.stanford.edu/class/cs234/index.html>



- Deep RL Sergey Levine Berkeley <http://rail.eecs.berkeley.edu/deeprlcourse/>



- ML course Nando de Freitas <https://www.cs.ox.ac.uk/people/nando.defreitas/machinelearning/>

# Assignments due

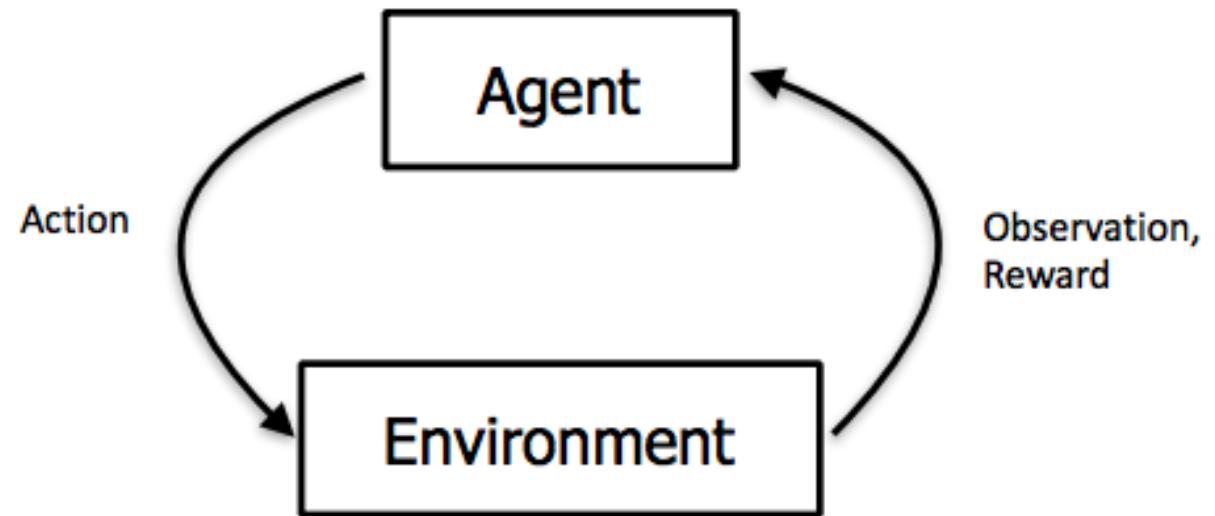
- 6 Mar Assignment 1 (2: Tabular) Individual
- 3 Apr Assignment 2 (3: DQN) Group of 3
- 8 May Assignment 3 (4: Policy) Group of 3
- 9 June Exam Individual
- 14 July Retake exam Individual

# Questions?



# Overview of Course

- 1: Machine Learning
- 2: MDP + Tabular Value Based
- 3: Deep Value Based
- 4: Policy Based
- 5: Model Based
- 6: Two-Agent (AlphaZero)
- 7: Multi-Agent (Poker, StarCraft)
- 8: Hierarchical
- 9: Meta Learning
- [B: Deep Supervised Learning]

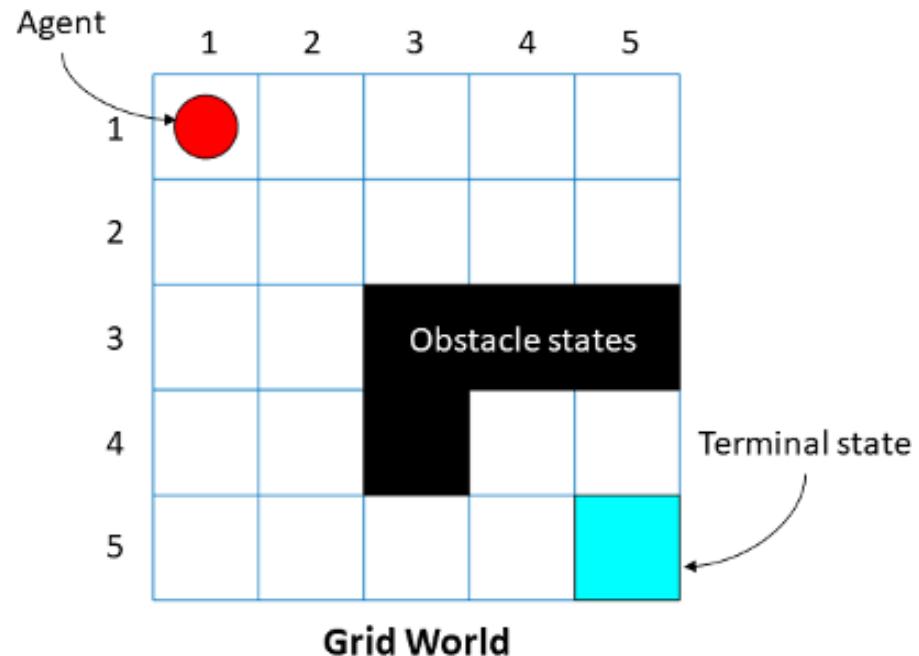


# 1. Machine Learning

- Reverse Engineering a function from data
- 1. Supervised: labeled dataset
- 2. Reinforcement: environment that return a number
- 3. Unsupervised: no labels, inherent clustering

# 2. MDP + Tabular

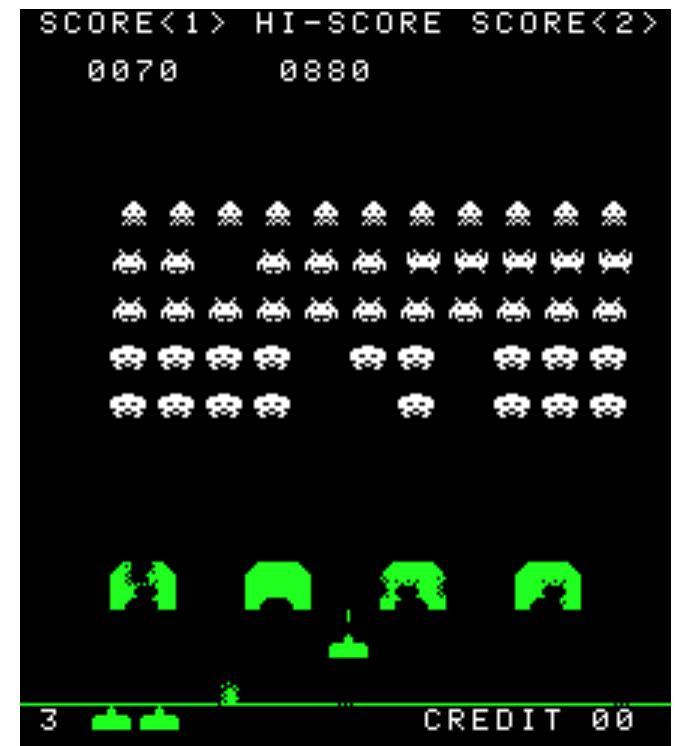
- State
- Action
- Transition
- Reward
- Discount



- Learn the **Policy** Function: what action to take in what state
- “Tabular” means array
- Exact algorithms for small problems that fit fully in memory, **Q-learning**

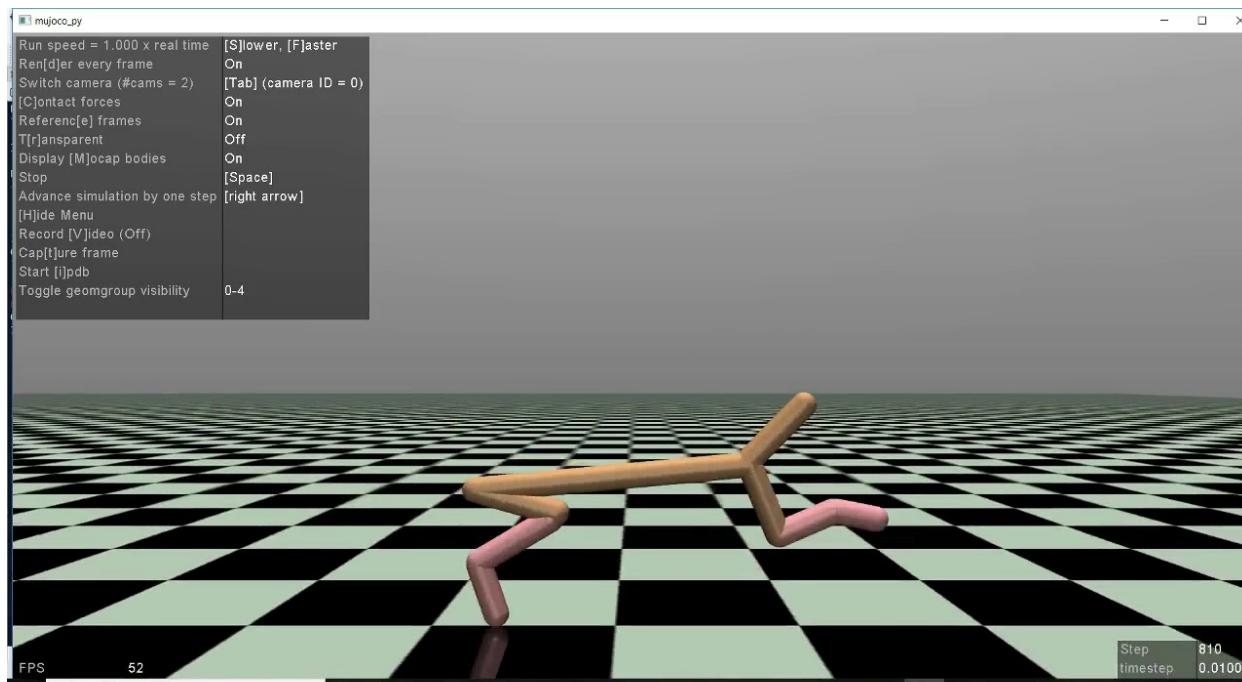
# 3. Deep Value-Based

- Large problem that are “solved” with function approximation
- Deep Learning of the policy function
- **DQN**
- 1980’s Atari video games, policy from pixel to joystick
- Space invaders as topic of serious scientific breakthrough



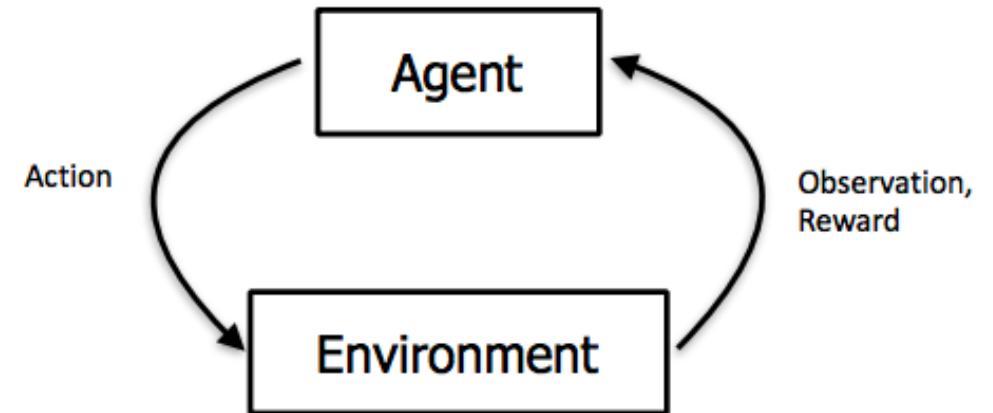
# 4. Policy-Based

- Direct Policy for Continuous Action Space
- PPO
- (Simulated) Robots that learn themselves to walk



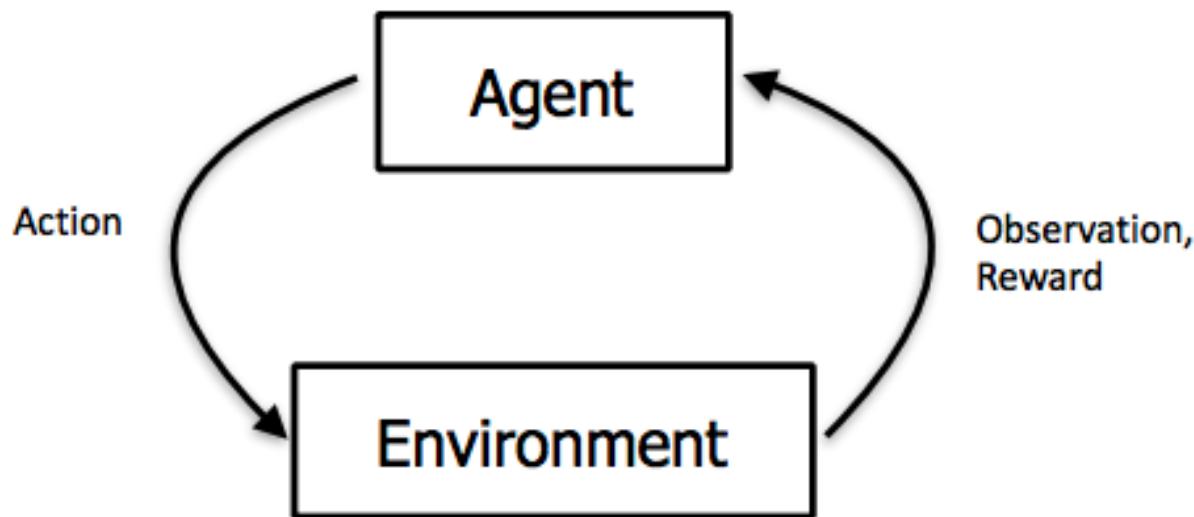
# 5. Model-Based

- $s_1 \rightarrow a_1 \rightarrow s_2 \rightarrow a_2 \rightarrow s_3 \rightarrow a_3 \rightarrow s_4 \rightarrow a_4 \rightarrow s_5$
- **Policy** function is  $s \rightarrow a$
- **Transition** function is  $a \rightarrow s$
- Model-free: Agent learn **policy** from environment
- Model-based: Agent first learns **Transition** from environment and then uses planning to learn **policy**



# 6. Two Agent Self Play

- What if agent has PERFECT transition function?  
(Because you are your own opponent)
- Then we can learn “perfect” policy by self-play
- Board games: TD-Gammon, AlphaGo



# 7. Multi Agent

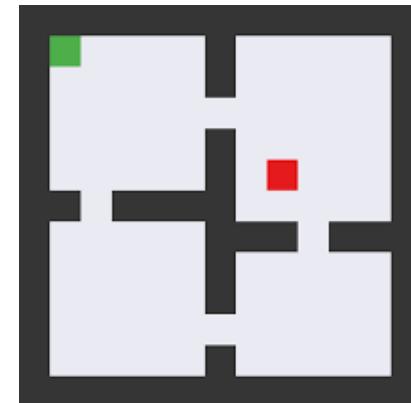
- Model many Agents
- Competition, Cooperation
- Nash, Pareto, Prisoner's Dilemma
- Non-stationarity, Partial Observability
- Population-based approaches



# 8. Hierarchical RL

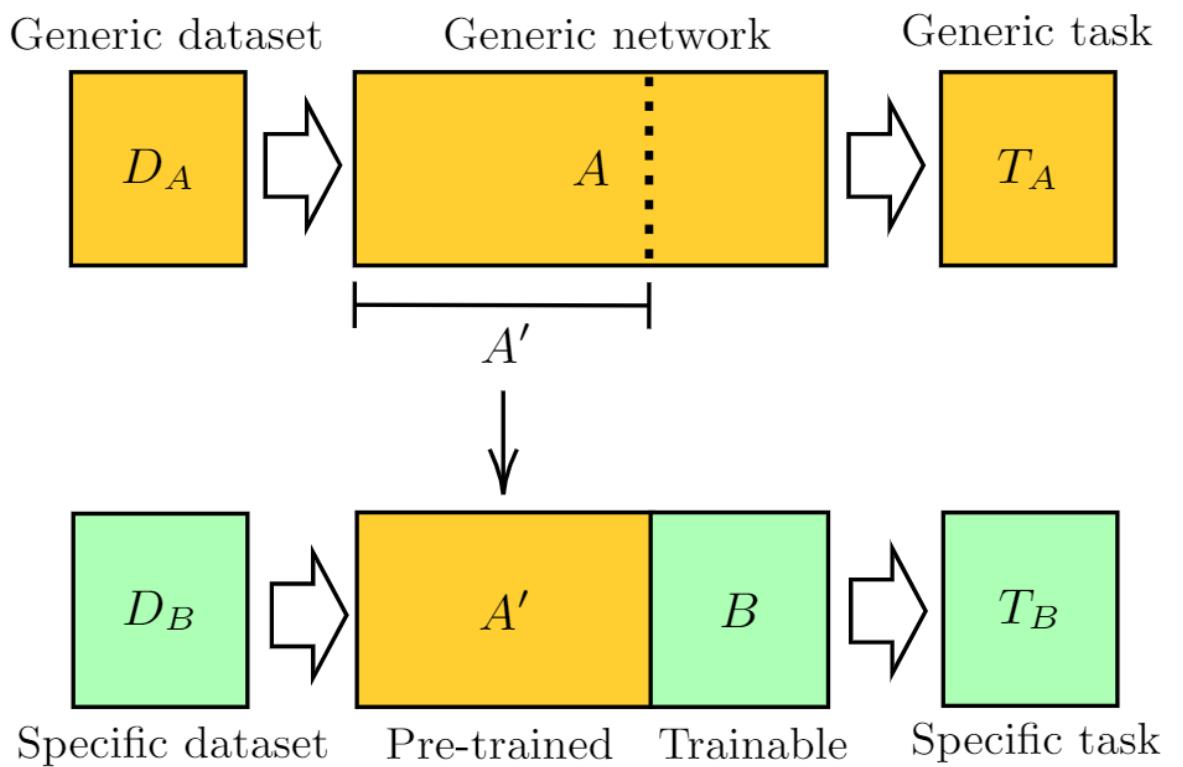


- Travel intuition
- Subgoals, subpolicies
- Goal conditioned functions
- Intrinsic motivation



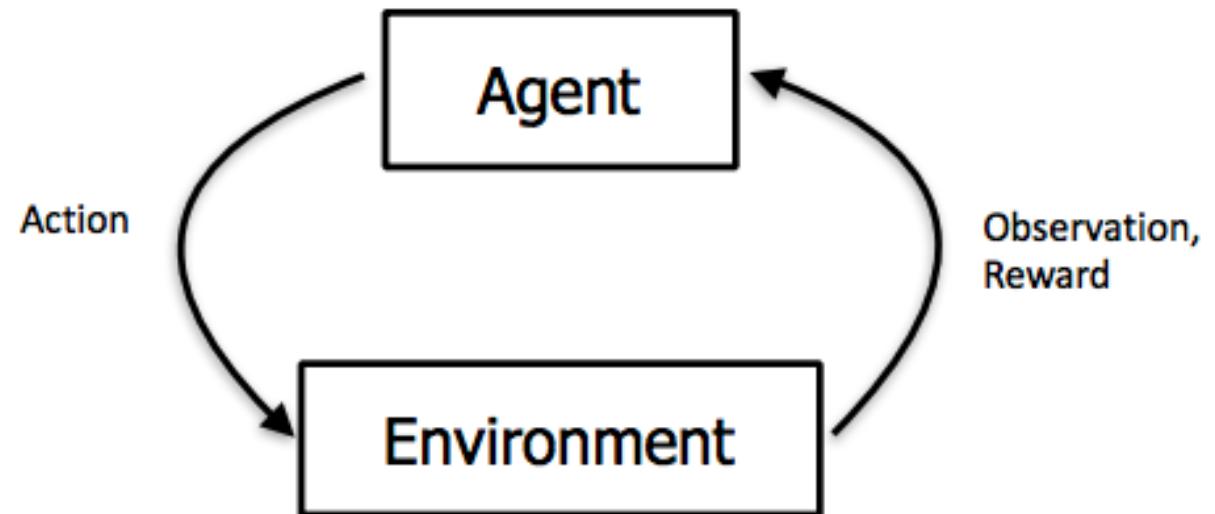
# 9. Meta Learning

- Learn faster by using knowledge from related tasks
- Lower layers contain more general knowledge
- Upper layers more task specific
- Transfer lower layers
- Learning to learn from a sequence



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