

Very quick introduction to Partial Differential Equations

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pabrod.github.io/intro-to-pdes-en.html

Disclaimer

These slides are a support for the crash course *Very quick introduction to partial differential equations*, given at Wageningen University in June 2018. As a direct consequence, the slides will perform poorly if used as a self-study material.

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Outline

What's the difference between ODEs and PDEs?

Introduction

Vector calculus in a nutshell

Graphical interpretation

Summary

Classical PDEs

Matlab tools

Exercises

What's the difference between ODEs and PDEs?

How are those two equations different?

$$\frac{du}{dx} = -u$$

$$\frac{\partial u}{\partial x} = -u$$

Exercises

Find a function $u(x, y)$ so

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Solution:

$$u(x, y) = \frac{x^2}{2} + \sin y$$

Key ideas

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 - ▶ That's why ODE problems need initial conditions to be well posed
- ▶ Partial derivatives are weapons of math destruction!
 - ▶ Problem posing with PDEs is hard
 - ▶ PDEs are way more powerful

Derivatives in higher dimensions

The *nabla* operator for 2-dimensions is defined as:

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When applied twice, it generates the laplacian:

$$\vec{\nabla} \cdot \vec{\nabla} u = \nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

Graphical interpretation of the gradient

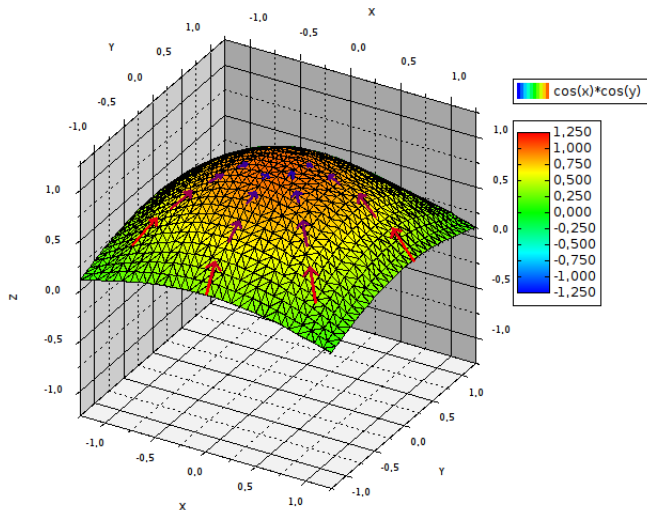


Figure 1: Gradient points to the direction of maximum slope

Graphical interpretation of the divergence

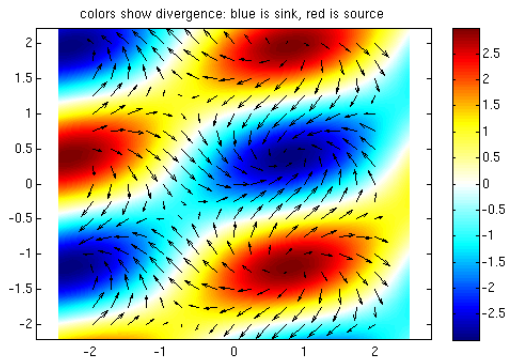


Figure 2: Divergence is maximum in sources and minimum in sinks

Summary of $\vec{\nabla}$

Operator	Shorthand	Explicit
Gradient	$\vec{\nabla} u$	$\left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y} \right)$
Divergence	$\vec{\nabla} \cdot \vec{F}$	$\frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y}$
Laplacian	$\nabla^2 u$	$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$

Table 1: Most common generalizations of derivatives to higher dimensions.

Some classical PDEs

All classical PDEs follow the structure:

$$d \frac{\partial^n u}{\partial t^n} - \vec{\nabla} \cdot (c \vec{\nabla} u) + au = f$$

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n	Type	Some applications
0	Elliptic	Electrostatics, optimization, fluid dynamics
1	Parabolic	Heat and chemical diffusion, quantum mechanics
2	Hyperbolic	Wave motion, electrodynamics

Table 2: Examples of the classical PDEs.

Boundary conditions

In 1-dimension, boundaries just need a beginning and an end

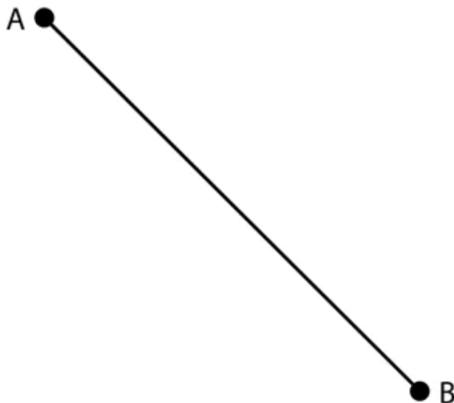


Figure 3: Our region is delimited between A and B.

Boundary conditions

In more dimensions, boundaries have a shape

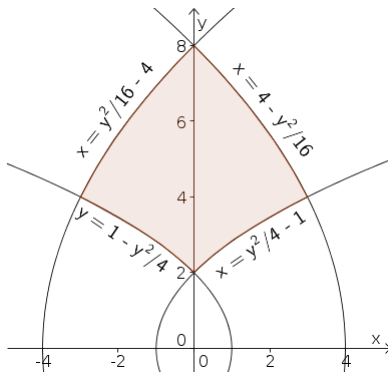


Figure 4: Our region is... well... it's complicated.

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Classical boundary conditions:

- ▶ **Dirichlet:** $u = 0$ in the border
- ▶ **Von Neumann:** directional derivative in the local perpendicular of the border is zero ($\vec{\nabla} u \cdot \vec{n} = 0$)
- ▶ **Periodic:** u is equal at equivalent sides (requires defining what *equivalent sides* means)

Matlab tools

Tool	Dimensions	Form
pdepe	$u(x,t)$	$c \frac{\partial u}{\partial t} = x^{-m} \frac{\partial}{\partial x} (x^m f) + s$
PDE Toolbox	$u(x,y,t)$	$d \frac{\partial^n u}{\partial t^n} - \vec{\nabla} \cdot (c \vec{\nabla} u) + au = f$

Table 3: PDE problems and Matlab tool.

pdepe

pdepe is used to solve equations of the following form, where c , f and s are functions of $(x, t, u, \frac{\partial u}{\partial t})$:

$$c \frac{\partial u}{\partial t} = x^{-m} \frac{\partial}{\partial x} (x^m f) + s$$

with boundary conditions:

$$p(x, t, u) + q(x, t) \cdot f = 0$$

Typically, pdepe is used as:

$$sol = pdepe(m, @pdefun, @icfun, @bcfun, x, t);$$

Where:

- ▶ m is a real number
- ▶ x and t are vectors
- ▶ $c, f, s = pdefun(x, t, u, DuDx)$
- ▶ $u_0 = icfun(x)$
- ▶ $pl, ql, pr, qr = bcfun(xl, ul, xr, ur, t)$

Cooling rod

In this example we will model step by step a cooling metallic rod.
We know that:

- ▶ The rod satisfies the heat equation
- ▶ The initial temperature of the rod is zero everywhere
- ▶ The left border is kept at zero degrees
- ▶ The temperature at the right border is forced to oscillate like $u_r(t) = \sin(t)$.

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$$u(0, t) = 0$$

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Step 3: set the initial condition $u_0(x) = 0$

Ripple tank

Waves in a water surface (for instance, a swimming pool) follow the wave equation:

$$\frac{\partial^2 u}{\partial t^2} = c^2 \nabla^2 u$$

This last exercise will be entirely done with Matlab's PDE toolbox.