

AIAA SOSTC 2010

**21st century operational procedure
automation with Python and *autofly*
LESSONS LEARNED FROM
MIGRATING LEGACY
SYSTEMS AND DEVELOPING
NEW ONES**

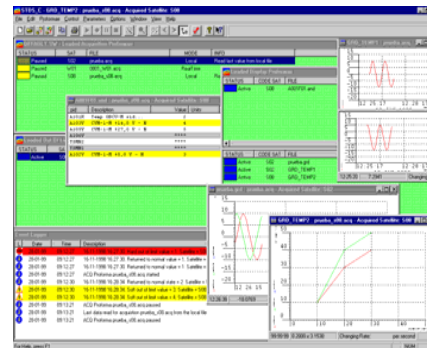
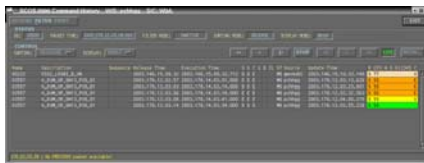
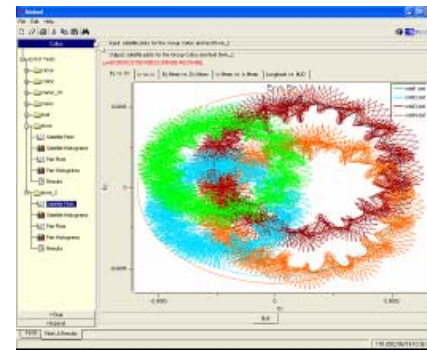
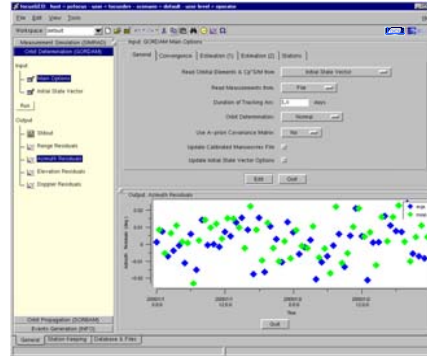
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Gonzalo Garcia
Thomas Morel*



INTRODUCTION

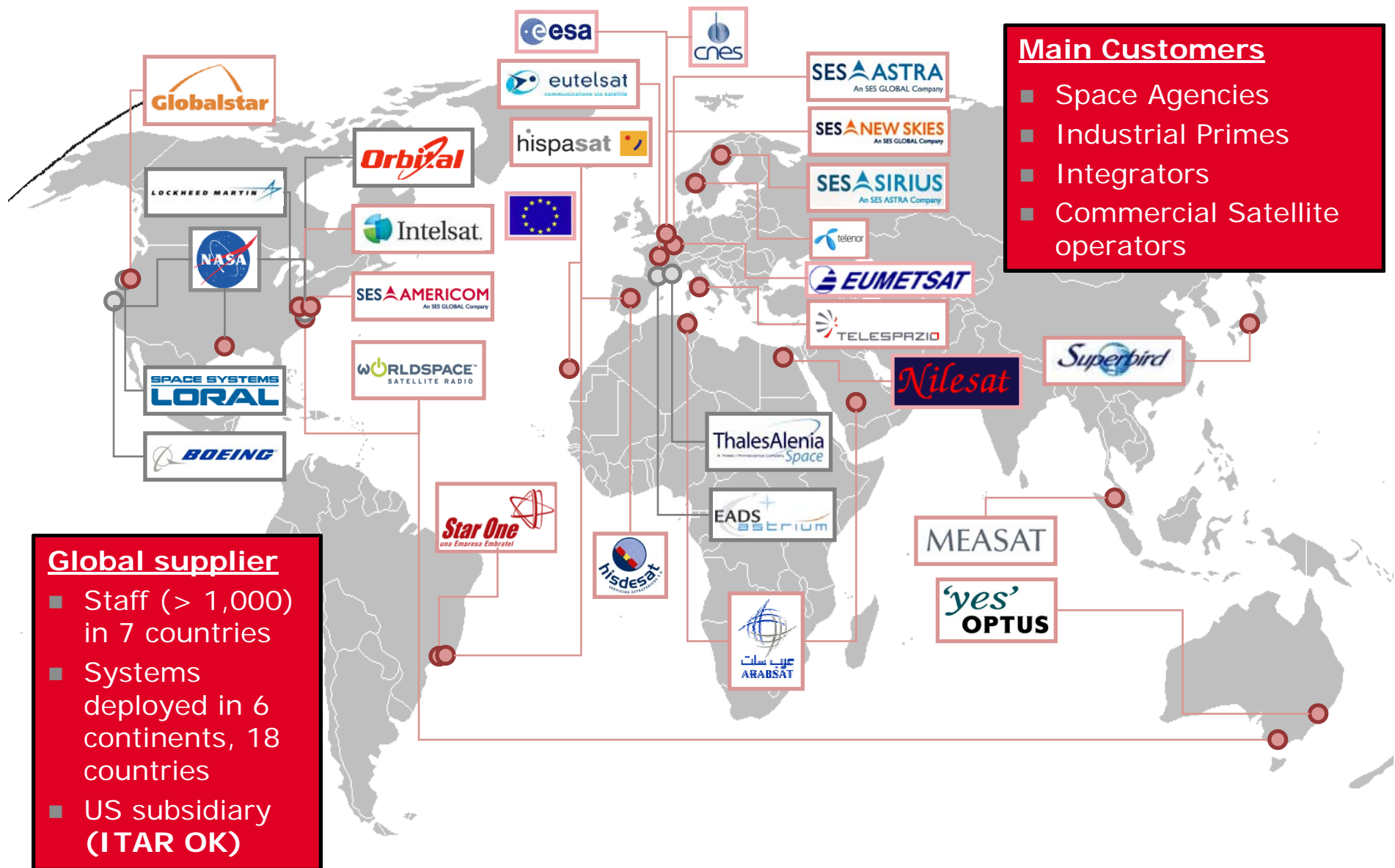


GMV IN SPACE: INTRODUCTION



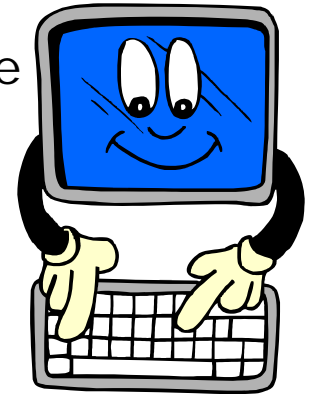
- **Mission Analysis** studies and mission analysis tools (station keeping, collocation, launch window analysis, ...)
- **Operational systems** for satellite control (inc. on-station and LEOP):
 - **Real-Time TM/TC M&C**
 - **Flight Dynamics**
 - **Mission Planning and Scheduling**
- **Special operational needs** (e.g. collision prediction/analysis, rendezvous, interstellar)
- **Satellite capacity management:**
 - Satellite capacity management
 - Payload Reconfiguration
- **Operations support**

GMV IN THE WORLD: MAIN SPACE CUSTOMERS



INTRODUCTION (1/2)

- Presentation shares the results of GMV's experience regarding:
 - **Development of a new automation layer** for Satellite Command and Control (SCC) integrated with the *hifly* suite
 - Python as automated procedures language
 - Layer was expected to support
 - Automation of **operational** satellite control procedures
 - Automation of **non-regression SCC testing** during development, integration and maintenance.
 - All previous points also applied to **ground equipment**



Broad view of automation, applied well beyond actual operational procedures

- Experience migrating legacy and new procedures in this new infrastructure using **Python** as the scripting language



INTRODUCTION (2/2)

- Experience shared is based on several recent programs:
 - **COMPLETED:** Migration of the complete ground system of **Star One's Brasilsat B series fleet**:
 - 4 Boeing BSS-376W satellites
 - State-of-the-art ground system with cost-effective software and hardware components
 - **IN PROGRESS:** Development of an extension for a new satellite (**Star One C3**, built by Orbital Sciences Corporation), with new procedures originally in STOL.
 - **IN PROGRESS:** Development of new procedures for **Hispasat H1E**, built by Space Systems Loral. Starting with paper procs.

SCC AUTOMATION LANGUAGES



EXISTING LANGUAGES FOR SCC AUTOMATION

■ SCC automation approaches:

– **procedural scripts**

- Space-specific languages
- General purpose languages

our focus

- rule-based expert systems
- finite state models

■ Multiple **space-specific languages** currently used:

– **STOL**: Satellite Test and Operations Language

- Originally developed by NASA, multiple flavors
- Widely used by many GOTS and COTS

– **PLUTO**: some ESA missions (SCOS-2000)

– Multiple **proprietary languages** used by different companies: SOL (GMV), CCL (Harris), OCIL / CECIL (Raytheon), PIL (Astrium), SCL (ICS), etc



■ **General purpose languages** used in some missions: Perl, Tcl

CUSTOM vs GENERAL PURPOSE LANGUAGES

	SPACE-SPECIFIC (eg. STOL)	GENERAL PURPOSE (eg. Python)
PROS	<ul style="list-style-type: none"> ❑ (Sometimes) more user friendly for non-programmers ❑ Adapted to satellite operations ❑ High reliability 	<ul style="list-style-type: none"> ❑ Open source ❑ Very powerful ❑ Portable ❑ Language can be easily restricted / extended ❑ Wide availability of tools and programmers
CONS	<ul style="list-style-type: none"> ❑ Proprietary language and/or tools ❑ Portability issues ❑ Limited, enhancements are expensive 	<ul style="list-style-type: none"> ❑ Potentially less readable if coding is not done carefully ❑ Too powerful?

HOW ABOUT PYTHON?

- Python is a **portable, open, high-level, object-oriented, dynamic language**
- Conceived in the 80s, **used massively since the 90s**
- Recognized widely for its **readability, maintainability** and **modifiability**, key aspects for complex procedures that may be modified multiple times throughout a mission.
- **Performance** is much better than most other dynamic languages.
 - Compiled to bytecode
- **Widely supported by the software community**, which guarantees the availability of good programmers, Integrated Development Environments (IDEs) and extensions.

```
def add5(x):  
    return x+5  
  
def dotwrite(ast):  
    nodename = getNodeName()  
    label=symbol.sym_name.get(int(ast[0]),ast[0])  
    print '%s [label="%s"' % (nodename, label),  
    if isinstance(ast[1], str):  
        if ast[1].strip():  
            print ' = %s"' % ast[1]  
        else:  
            print ''  
    else:  
        print '];'  
        children = []  
        for n, child in enumerate(ast[1:]):  
            children.append(dotwrite(child))  
    print '%s -> {' % nodename,  
    for name in children:  
        print '%s' % name,
```

Multiple successful applications in space business
E.g. Shuttle Mission Design



ADVANTAGES OF THE USE OF PYTHON (1)



■ Portable

- Windows (XP, CE, Pocket PC), Linux, UNIX, Macintosh
- Many others: AIX, AROS, AS/400, iPOD, OS/2, Palm OS, Playstation, Psion, VxWorks, Nokia cell phones, .NET, Java Virtual Machine, ...



■ Open

- Free, even for commercial use.
- Interpreter can be embedded in products (no license fee)
- Open source, no GPL-like traps

■ Dynamic



- Dynamically typed and interpreted, ideal for fast scripting



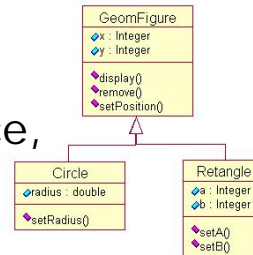
■ Powerful

- Complex built-in data structures (e.g. flexible arrays, lists, dictionaries)
- Great variety of program control instructions
- **Productivity 5 – 10 times higher than Java**
- Supports exception handling
- Automatic memory management and garbage collection
- Language is extensible

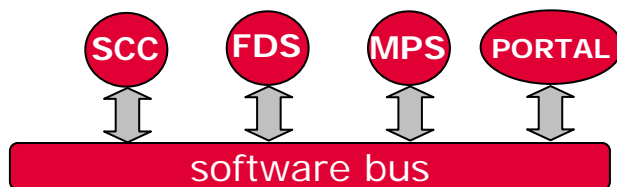
ADVANTAGES OF THE USE OF PYTHON (2)

- **Object orientation**, with all the associated benefits (reuse, abstraction, scalability, ...)

- Supports classes, inheritance, templates



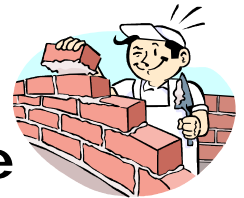
- Easy integration with
 - existing Service Oriented Architecture (**SOA**) implementations
 - **Web Services** (WSDL)
 - **GMSEC** API (Python supported)



- **Built-in development capabilities**, given as language modules



- Automatic documentation generation
- Unit testing, regression testing
- Debugger, profilers, interpreter, compiler

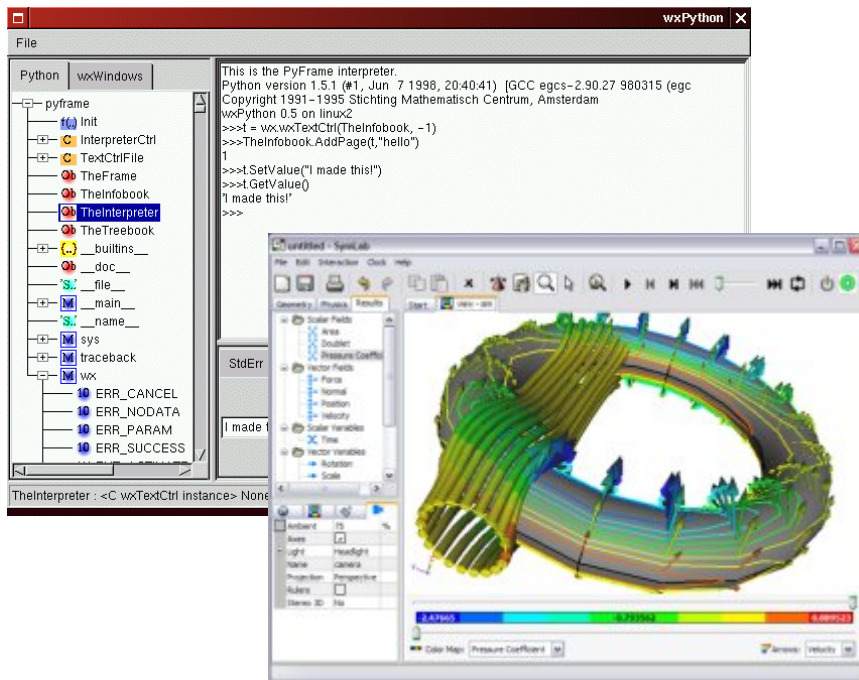


- Availability of **multiple modules** for

- **XML** processing: Multiple applications: XTCE DB parsing, SOAP messaging, etc
- **Communications**: Sockets, Internet access, RPC, email
- Time **performance measurement**
- **Many others**: database access, math, data compression, multi-threading, cryptography, operating system access, etc

ADVANTAGES OF THE USE OF PYTHON (3)

- Availability of bindings for multiple **GUI-development toolkits** (Qt4, GTK2, Tk, wxWidgets, etc)



- Wide variety of **plug-ins for Eclipse** (a popular open development platform) can be used to work with Python.
- Availability of multiple, powerful, **free tools** for
 - Development
 - Source code inspection and metrics generation
 - Debugging, testing
 - Configuration management
- Wide support by **commercial tool vendors**

RISKS OF THE USE OF PYTHON



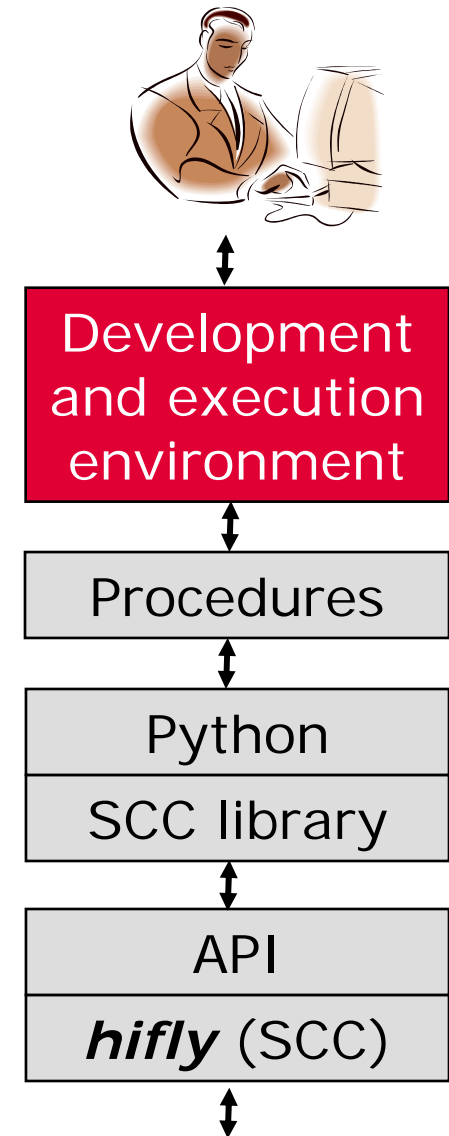
- Language may be ***too powerful*** and complex for non-programmers.
 - This can be handled by restricting the use of certain instructions from the development environment
- **Readability** may be worse than space-specific languages if coding is not done carefully
 - Strict coding standards are needed
 - Coding can be abstracted for non-programmers using a visual environment

- **Evolution of language** is controlled by others
 - This is part of the deal of using a general-purpose language
 - Compensated by all the advantages
 - A mission can just freeze the Python version & development environment and use updates on a case-by-case basis
- **Dependency** on third-party software (the interpreter)
 - But it is open source

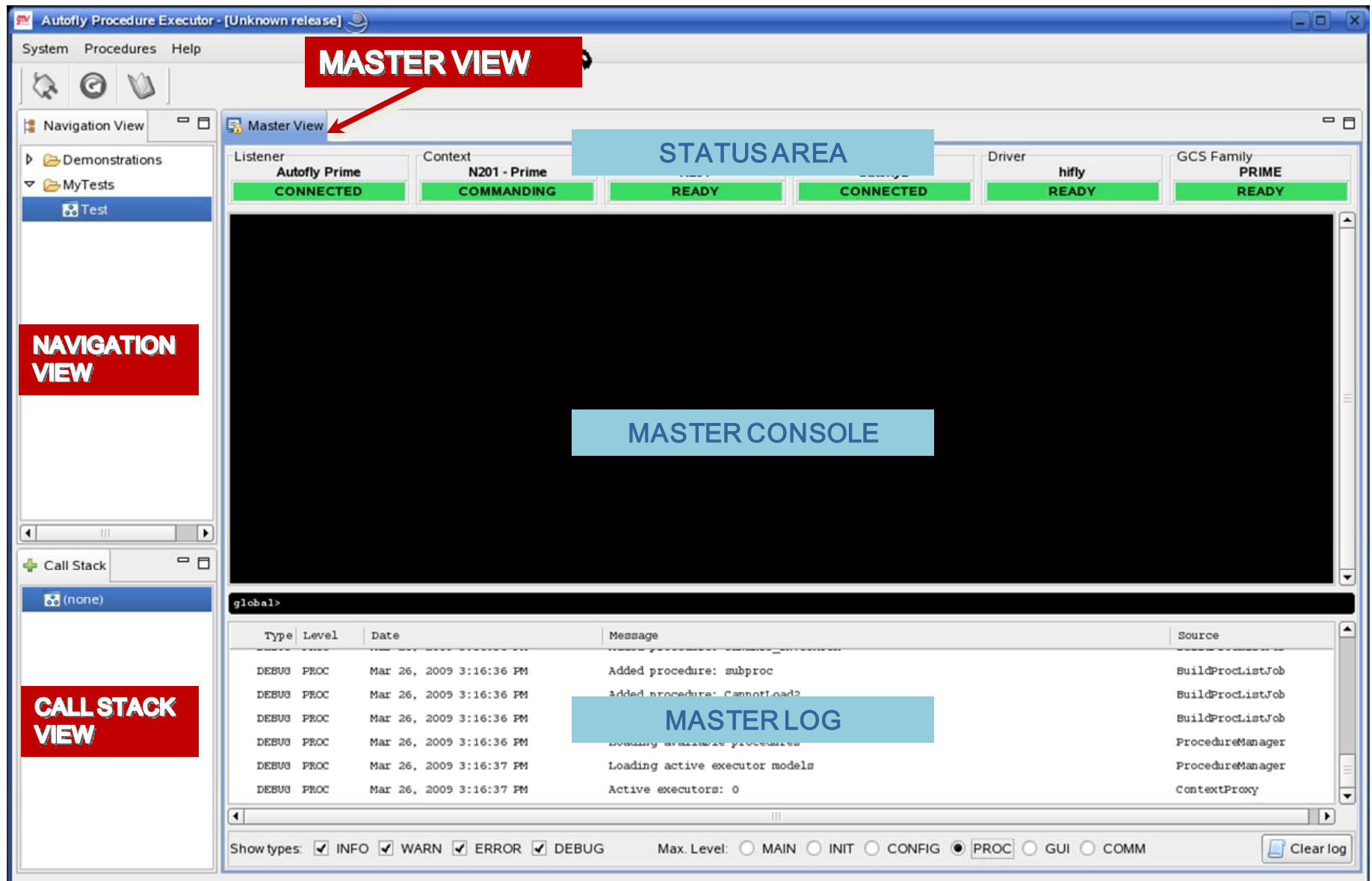
autofly Overview

autofly OVERVIEW

- ***autofly*** is a native ***hifly***[®] component allowing execution of satellite operations through automated procedures
- ***autofly*** provides the following capabilities:
 - Creation and modification of procedures from the GUI
 - Validation of procedures (statically and dynamically)
 - Scheduling (based on time or TM condition) of procedures for execution
 - Monitoring of procedure execution progress



autofly Main Window



autofly Procedure Execution

Procedure List

Status Bar

Execution Status

The screenshot displays the autofly Procedure Execution interface. The top menu bar includes 'System', 'Procedures', and 'Help'. Below the menu bar, the 'Listener' is set to 'N201', 'Context' to 'N201', 'Mode' to 'UNKNOWN', 'Domain' to 'N201', 'Family' to 'PRIME', and 'Driver' to 'hify'. The 'Navigation View' on the left lists procedures: 'CALB_AUTOFLY', 'EATTACQ_AUTOFLY', 'OSCMAN_AUTOFLY', 'S4K', and 'VECNORM_AUTOFLY'. The 'Master View' shows a 'Tabular' view of the procedure execution. A yellow status bar at the top of the Master View displays 'Skip get parameter AG1065L'. The 'Execution Status' table has columns for 'Code', 'Name', 'Value', and 'Status'. The 'Execution Controls' bar at the bottom includes buttons for 'Run', 'Step', 'Step_Over', 'Skip', 'Pause', 'Goto', 'Script', 'Reload', and 'Abort'. The 'Status Bar' at the bottom right shows 'PAUSED' and 'Autoscroll' is checked. The 'Enter command:' field is at the bottom.

#	Code	Name	Value	Status
119	GetTM("HN1006L", {ValueFormat: ENO})	HN1006L	3.0	SUCCESS
120				
121	GetTM("AE1073E", {ValueFormat: RAW})	AE1073E	7L	SUCCESS
122	GetTM("AE1073E", {ValueFormat: ENO})	AE1073E	7.0	SUCCESS
123				
124	GetTM("HN1009L", {ValueFormat: RAW})	HN1009L	1164538087L	SUCCESS
125	GetTM("HN1009L", {ValueFormat: ENO})	HN1009L	1164538087.0	SUCCESS
126				
127	# Type 3/X Status or Numeric parameters			
128				
129	GetTM("AG1051L", {ValueFormat: RAW})	AG1051L	OL	SUCCESS
130	GetTM("AG1051L", {ValueFormat: ENO})	AG1051L	0.0	SUCCESS
131				
132	GetTM("HP1051E", {ValueFormat: RAW})	HP1051E	OL	SUCCESS
133	GetTM("HP1051E", {ValueFormat: ENO})	HP1051E	'OFF'	SUCCESS
134				
135	GetTM("AT2064L", {ValueFormat: RAW})	AT2064L	OL	SUCCESS
136	GetTM("AT2064L", {ValueFormat: ENO})	AT2064L	0.0	SUCCESS
137				
138	GetTM("AT2066L", {ValueFormat: RAW})	AT2066L	OL	SUCCESS
139	GetTM("AT2066L", {ValueFormat: ENO})	AT2066L	'INIT'	SUCCESS
140				
141	GetTM("AT2062L", {ValueFormat: RAW})	AT2062L	OL	SUCCESS
142	GetTM("AT2062L", {ValueFormat: ENO})	AT2062L	'NO_ERROR'	SUCCESS

Execution Controls

autofly Procedure Execution (cont.)

The screenshot displays the autofly software interface during a procedure execution. The top status bar shows: Listener: N201, Context: N201, Mode: UNKNOWN, Domain: N201, Family: PRIME, Driver: hifi. The left sidebar contains a list of procedures: CALIB_AUTOFly, EATTACQ_AUTOFly, OSCMEAN_AUTOFly, S4K (selected), and VECNORM_AUTOFly. The main window is titled 'Master View' and shows a table of execution steps. A red box highlights a 'FAILED (0/2)' status for step 224. A red arrow points from a 'Flow Control' label to the bottom of the interface, where a dialog box is open. The dialog box contains the message: 'Send failed: Command argument 'DN_SURV' not found, reason: unknown'. Below the message are radio buttons for 'Abort', 'Resend', 'Skip', and 'Cancel'. The 'Flow Control' label is a grey box with white text. The 'Error Status' label is a grey box with white text, pointing to the 'FAILED (0/2)' status in the table.

#	Code	Name	Value	Status
214	["ANGSATVISURV", "-134.0E-2"]			
215	["ANGSATVISURV", "10.0"]			
216	["DA_ROLL_MIN", "-0.2E2"]			
217	["DA_ROLL_MAX", "1.0"]			
218	["DA_PITCH_MIN", "20.0E-3"]			
219	["DA_PITCH_MAX", "10.0E-1"]			
220	["DA_YAW_MIN", "10.001"]			
221	["DA_YAW_MAX", "-9.878"]			
222	["DN_SURV", "1.0"]			
223	["N_SURV", "1.0"]			
224	["CHECKSUM", "19366"]			FAILED (0/2)
225				
226	#Critical command			
227	Send (command="O12ONAT", arg=[["STR_ID", "STR_1"], ["STAT_FILTER", "ACTIV"]])			
228				
229	#High priority command			
230	Send (command="1141HOU")			
231				

Send failed: Command argument 'DN_SURV' not found, reason: unknown

(Type: A, R, X, Q) >

☐ Abort

☐ Resend

☐ Skip

☐ Cancel

autofly Procedure Execution (cont.)

- 2 views: **Tabular** (displays procedure view highlighting the line being executed) and **Text** view (displays procedure output).
- **Execution controls:**
 - Run / Pause / Step / Step over (avoids going into sub-procedures)
 - Skip: skips the next statement
 - Goto: go to a given line number in the procedure
 - Script: executes basic statements
 - **Send**("T001"): send command T001
 - **GetTM**("A001"): get TM A001
 - **Display**(*str(a)*): display value of variable "a"
 - **a = 1**: sets value of variable a to 1
 - **StartProc**("Operational/Test")
 - Reload: reload the procedure execution
 - Abort: abort the procedure execution
 - Entry to pass inputs to the running procedure

autofly Procedure Execution (cont.)

The screenshot shows the autofly Procedure Execution interface. At the top, there is a status bar with a red message: "Cannot start, no code available". Below this, there is a table with columns: #, Code, Name, Value, and Status. The table is currently empty. To the right of the table, there is a label "N20".

Annotations with red boxes and arrows point to various components:

- TEXT PAGE SELECTOR**: Points to the "Text" button in the top toolbar.
- CODE PAGE SELECTOR**: Points to the "Code" button in the top toolbar.
- ZOOM CONTROLS**: Points to the zoom in (+) and zoom out (-) buttons in the top toolbar.
- MESSAGE DISPLAY**: Points to the "Message" button in the top toolbar.
- SPACECRAFT INDICATOR**: Points to the "N20" label on the right side of the table.
- CODE PAGE**: A red box covering the code area, with an arrow pointing to the code text.
- EXECUTION CONTROL**: Points to the execution control buttons (Run, Step, Step_Over, Skip, Pause, Goto, Script, Reload, Abort) at the bottom.
- PROCEDURE STATUS**: Points to the "LOADED" status indicator at the bottom.
- USER INPUT AREA**: Points to the "Enter command" input field at the bottom.

The code area contains the following text:

```
# Code
1 .....
2 #
3 .....
4 .....
5 .....
6 #
7 # NAME : Send
8 # DESCRIPTION : Conversion to Autofly
9 #
10 # AUTHOR : Converter to Autofly
11 # FILE : Send.py
12 # DATE : Fri Jan 23 13:55:13 CET 2009
13 #
14 # SPACECRAFT: N201
15 #
16 .....
17 # CATEGORY : Demonstrations
18 #
19 # VALIDATED : Nobody
20 # APPROVED : Nobody
21 #
22 # HISTORY:
23 #
24 .....
25 .....
26 c = 1
27
28 while True:
29     /c= c+1
30     Display(str(c))
31
32
```

autofly Procedure Execution (cont.)

#	Code	Name	Value	Status
18	#			
19	#			
20	# APPROVED : Somebody			
21	#			
22	# HISTORY:			
23	#			
24	#####			
25				
26				
27	i= 0			
28	j= 0			
29				
30	Step("loop", "loop")			
31				
32				
33	i= i+1			
34				
35	if (i == 100000):			
36	i= 0			

SOURCE CODE COLUMN

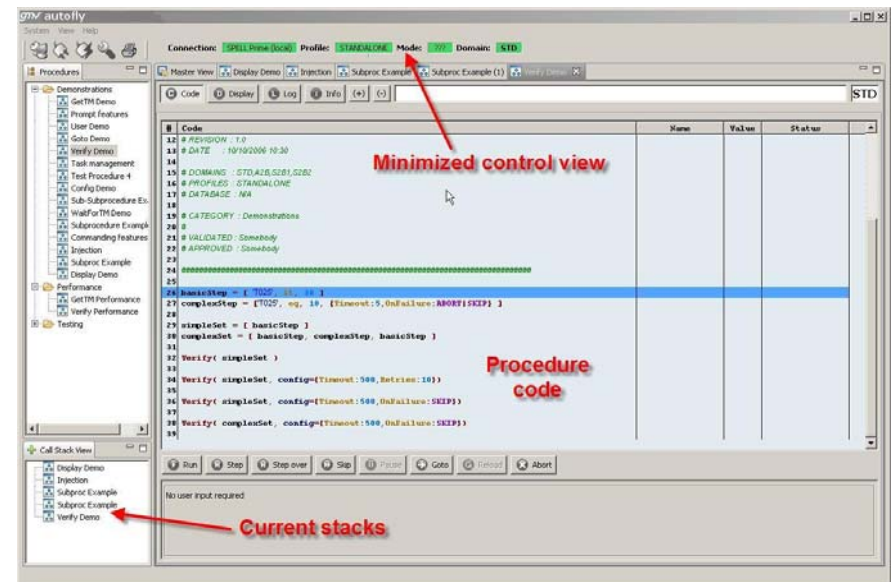
STATUS COLUMNS

CURRENTLY EXECUTED LINE

PROCEDURES MIGRATION

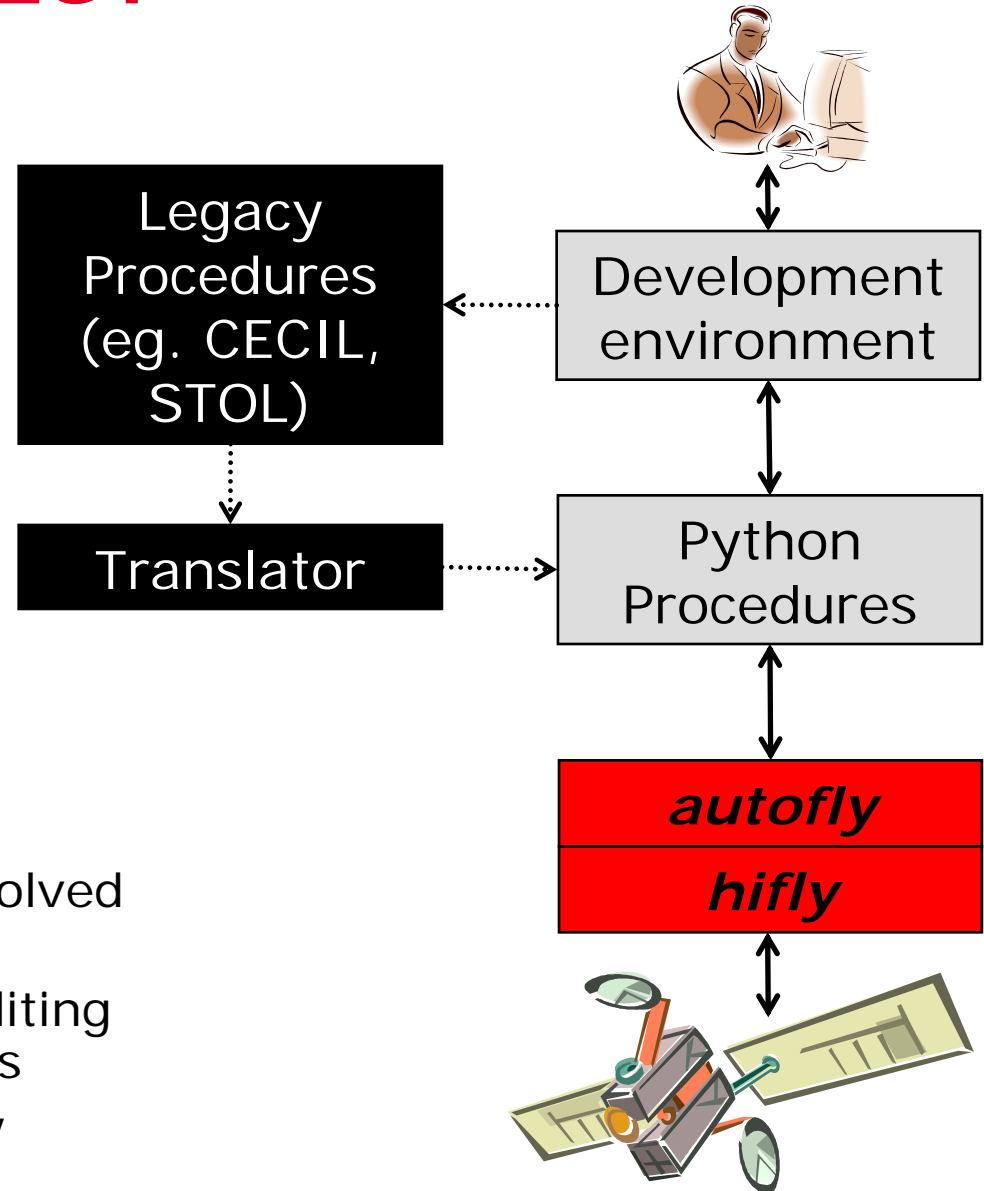
OVERVIEW

- **autofly** allows the operator to develop, test, modify, schedule and execute Python procedures, with:
 - Procedure execution
 - Parallel execution supported
 - Procedure control
 - Supports Step-by-step execution
 - Procedure monitoring
- **autofly** supports:
 - TM access and injection
 - TC injection and status monitoring
 - Event and out-of-limits access
 - Event injection
 - Modification of out-of-limit definitions
 - Open predefined TM displays
 - Display operator messages and prompt for input
 - Procedure nesting

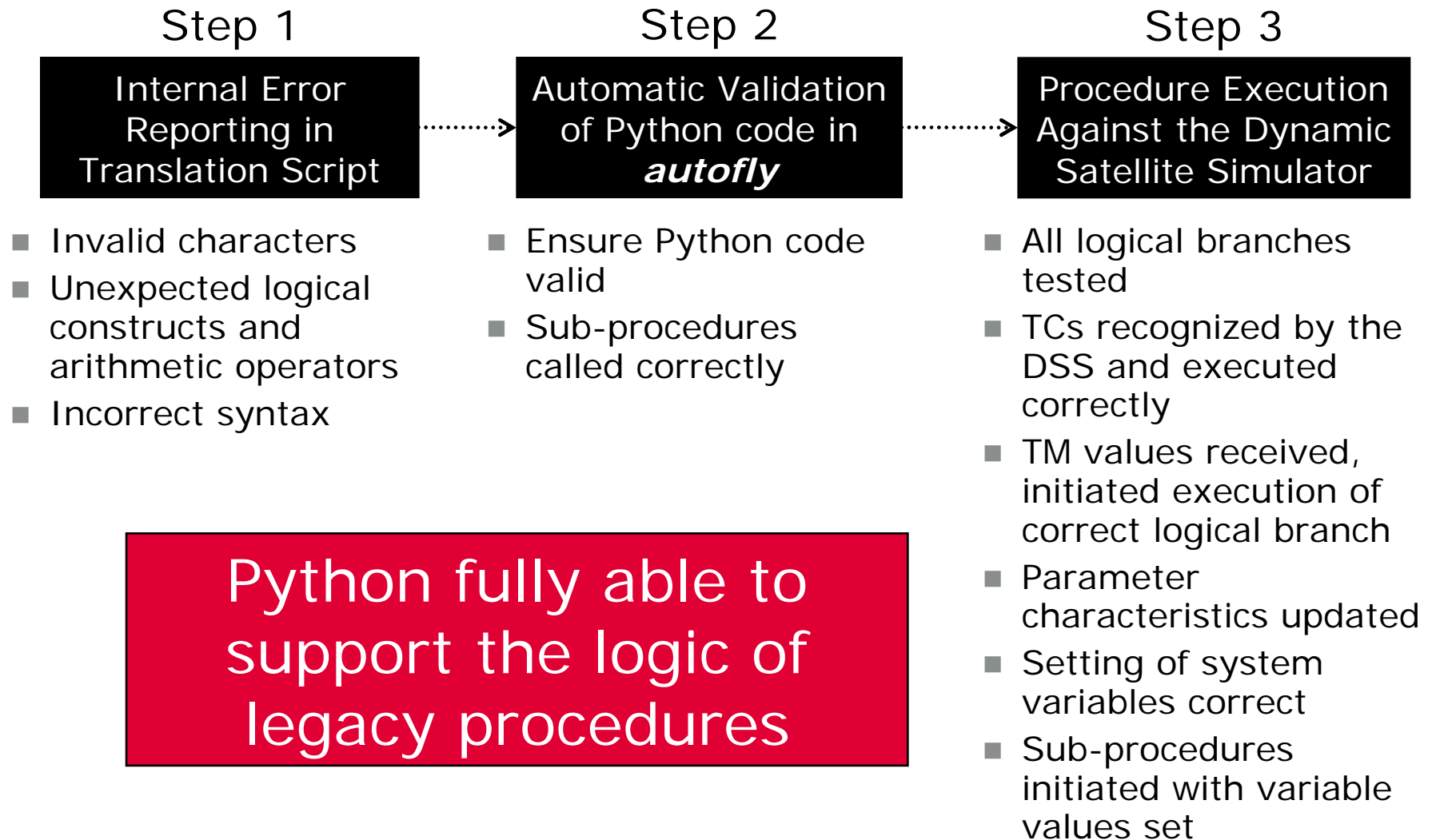


MIGRATION STRATEGY

- In the case of the Star One migration, a **translator** script was created to directly translate CECIL code to Python:
 - Avoid creating Python procedures from scratch
 - Iterative process
 - Testing the procedures
 - Updating the translator
 - Re-translating the procedures
 - Repeated conversion issues solved in translation script
 - Minimal amount of manual editing for one time conversion issues
 - Assures **traceability** is easily maintained



VALIDATION STRATEGY



LESSONS LEARNED



LESSONS LEARNED (1)

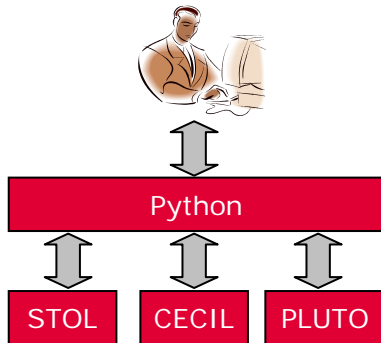


- Many **space-specific languages** currently used for the development of operational procedures were **defined decades ago** and are **not used outside of the space industry**. In many cases they are **proprietary** and require **expensive** products.



- Future **support for proprietary languages and** availability of **tools** is not guaranteed. Some operators have had serious problems replacing a system once the HW became obsolete, typical in a GEO mission (> 15 years)
- Lessons from **Ada**:
 - Language designed under contract to the US DoD during 1977 – 1983
 - Targeted at embedded and real-time systems
 - Mandatory for new software DoD projects since 1987
 - Excellent language, used successfully for thousands of projects
 - 2003, Software Engineering Institute:
“Due to a dearth of tools and compilers and lack of trained, experienced programmers [...] Ada is a programming language with a dubious or nonexistent future”

LESSONS LEARNED (2)



- Operators with a **heterogeneous fleet** usually end up having to use different languages. This increases training & operations costs and increases the complexity of the system.
- Python allows the definition of a **homogeneous front-end** for a heterogeneous fleet
- **Coding rules, customized development environment and training** needed to guarantee the high quality & maintainability of procedures
- With Python, operators can **benefit** enormously from the **software community**:
 - Using **modern, powerful, open source languages** like Python and **tools** like Eclipse/RCP widely supported
 - Approach allows the operators to have an **open, integrated environment** for operational and testing procedure development, verification, execution, configuration management and metric generation
 - It also **reduces** the **dependency** on proprietary technologies and the **risks** of software obsolescence

LESSONS LEARNED (3)



- A **close collaboration** between the operator and GMV's team was essential in the cases of **procedures migration**
 - Achieve a complete understanding of the legacy system procedures
 - Ensure a **smooth transition**
 - Presence of operator experts in **long testing campaigns** extremely important
- Performing **procedures testing** against a satellite simulator prior to installation at customer site was highly beneficial
 - Procedures can be used to **validate** TM/TC **database translation**
 - **Identify issues** leading to modifications at an early stage
 - **Reduce risk** for surprised during on-site testing

A black and white photograph of a person hanging upside down from a horizontal bar. The person is wearing a dark tank top and has their hands and feet gripping the bar. They are looking directly at the camera with a slight smile. The background is solid black.

Thank you!!

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gmV[®]
INNOVATING SOLUTIONS

BACKUP SLIDES
**WRITING
PROCEDURES IN
PYTHON**

autofly python constructs

- Comments: line starting by “#” character
- Indentation: python groups statements using indentation
- Variables have to be initialized before being used
- Variable names are case sensitive
- Arrays
- Arithmetic expressions
- Conditional statements
- Loops
- User-defined functions

autofly python constructs (cont.)

- Indentation examples:

- Example 1:

```
if (a == 1):  
    b= 2  
    c= 3  
    d= 4
```

- Example 2:

```
if (a == 1):  
    b= 2  
    c= 3  
  
d= 4
```

autofly python constructs (cont.)

■ Variables:

```
# initialization of variables
boolean_variable = True
integer_variable = 1
float_variable = 1.0
string_variable = 'string'
```

```
# python allows using either single quotes or double quotes
# this allows to flexibly use quotes as part of the string
string_var1= "This string contains 'word' quoted with single quotes"
string_var2= 'This string contains "word" quoted with double quotes'
```

■ Arrays:

```
array_variable = [False, 222, 222.99, 'any string']
```

```
# access first element in array to get value
first_element= array_variable[0]
```

```
# access first element in array to change its value
array_variable[0]= True
```

autofly python constructs (cont.)

■ Arithmetic expressions:

```
a = abs(-7.5)           # Absolute Value
b = asin(0.5)           # Arc sine, returns in rads
c = pow(b,3)            # c = b^3
d = ((max (a, b) + 2.0) % 10) * a  # Compound expression
```

■ Boolean expressions:

```
a = 1
b = 2
c = 3
boolean_variable = (a != b) and (not (b > c))
```

■ String expressions:

```
i= 5
Message = "Integer: " + str(i) + " , Binary: " + bin(i)
Display(Message)
```

autofly python constructs (cont.)

■ IF statement:

```
a = 1
b = 2
if (a > b):
    Display ("a is greater than b")
```

```
boolean_variable = a > b
```

```
if (boolean_variable):
    Display("a is greater than b")
elif (boolean_variable):
    Display("a is less than b")
else:
    Display("a is equal to b")
```

autofly python constructs (cont.)

■ Loops:

■ for

```
# loop 10 times (with variable "i" taking values 0 to 9)
array_variable = [0,1,2,3,4,5,6,7,8,9]
for i in array_variable: Display(str(i))
```

■ while

```
# loop 10 times (with variable "i" taking values 0 to 9)
i = 0
while (i < 10):
    Display(str(i))
    i=i+1
```

autofly python constructs (cont.)

■ Functions:

```
# Function declaration
def funcA(x, y):
    a= x+y
    b= x+1
    c= y+1

    return a, b,
```


autofly built-in functions

- GetTM: timeout, format, wait

```
variable = GetTM( 'TM NAME', Wait = False )
```

- Verify: timeout, format, delay, wait, retries, tolerance

```
Verify ( ['TM NAME', eq, 'VALUE'], Delay= 20, Timeout= 5, Retries= 4 )
```

```
verif = [ [ 'PARAM1', eq, 'VALUE1', ],  
          [ 'PARAM2', eq, 'VALUE2', {Retries:3} ],  
          [ 'PARAM3', eq, 'VALUE3', {Wait:False} ] ]
```

```
Verify ( verific, Timeout = 10 )
```

- Send

```
Send(command = 'CMDNAME', args = [ [ 'ARG1', ' ON' ],  
  [ 'ARG2', 0xA3C, {ValueType:LONG, Radix:HEX} ],  
  [ 'ARG3', 0.34] ] )
```

autofly built-in functions

- GetTCparam

execCommand = **GetTCparam**('CMDNAME', 'execCommand')

- SetGroundParameter

SetGroundParameter ('VARIABLE NAME', Value)

- GetTMparam: get limits

Get the lower hard (Red) limit defined:

LoRed= **GetTMParm**("A0001", **LoRed**)[0]

- SetTMparam: set limits

Set all limits

ret = **SetTMparam**("A0001",**LoRed**=1.0,**LoYel**=0.5,**HiRed**=3.0,
HiYel=2.0)

Set all limits (with hard and soft limits set to the same value)

ret = **SetTMparam**("A0001",**LoBoth**=1.0,**HiBoth**=3.0)

autofly built-in functions (cont.)

- Event: raise events with a specific severity

By default severity is INFO if qualifier is not specified

Event ('MESSAGE', Severity = INFORMATION)

Event ('MESSAGE', Severity = WARNING)

Event ('MESSAGE', Severity = ERROR)

- WaitFor: holds the execution. Different options: interval, time, delay, TM condition.

WaitFor (['TM NAME', eq, 'VALUE'], Delay = 20)

WaitFor(2)

- Display: displays a message in the GUI and log the message

Display ('a = ' + a + 'i = ' + str(i))

autofly built-in functions (cont.)

- Prompt: prompts the user for input
 `user_choice= Prompt ('Please make choice', OK_CANCEL)`
 `user_supplied_value= Prompt ('Enter value: ', NUM)`
 `user_supplied_date= Prompt ('Enter date: ', DATE)`
- OpenDisplay:
 `OpenDisplay ('Display_name')`
- PrintDisplay:
 `PrintDisplay ('Display_name', Format= "vector")`
 `PrintDisplay ('Display_name', Printer= "lpt1")`
- Flow control: Step, Goto, Pause, Abort.
 `Step('Step_name', 'Title')`
 ..
 ..
 `Goto('Step_name')`