Ayudentia 2. Física Estadística. 2.2 Pathria 1) du del espació fase de una particula es invariante bajo una transforma pron de coordenadas contestaras (x, q, t, lx, lx, lx, lx) a coordenadas conférias. SAS-Group U.Paris 13 Solución x= y cososin p, y = rsinosinp, t= raso = r2sino o (Px, Py, Pz) B(Prilo/Pp) 1x=mx=mrsinocosp+mrcospcospo-mrsinosinpp Py=my=missinosino turcaosino o tursino capo

Py = sino sinp Pr + roso sind Po + cos of Pp 12 = cos 6 Pr - Sino Po

Px=sinocosplr+ cospare Po - sino Pp

(= mi = mr(& O - mrsingo Recordanos que en estéricas: | Pr=mir , Po=mio, Pg=missingop

$$K = \frac{1}{2}mL^{2}\dot{\theta}^{2} \qquad 0 << 1.$$

$$V = mgL(1-raso) \approx mgL\frac{\theta^{2}}{2}$$

$$H = E = \frac{\rho_{e^{2}}}{2mL^{2}} + mgL\frac{\theta^{2}}{2}$$

$$m \qquad 2mL^{2}$$

A (com) = TTab = 2TT E \frac{1}{g} - ET, T = 2TT \frac{1}{g} P

1= Pot de l'az zoné E 1= Pot de l'az l'agres de l'agre



$$P(x) dx = P(x, x+dx)$$

$$Si T = \frac{2\pi}{w_{o}} cs chievang requestion para such a performance of the control of t$$

$$R_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \end{pmatrix} \begin{pmatrix} \vec{\alpha}_{+} \end{pmatrix} = (\vec{\alpha}_{+}, \vec{\alpha}_{-} + \vec{\alpha}_{-}, \vec{\alpha}_{+}) & \vec{\sigma}_{x} = \begin{pmatrix} \vec{\alpha}_{-} \\ \vec{\alpha}_{-} \end{pmatrix} \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} = (\vec{\alpha}_{-}, \vec{\alpha}_{+}, \vec{\alpha}_{-}) & \vec{\sigma}_{x} = \begin{pmatrix} \vec{\alpha}_{-}, \vec{\alpha}_{-} \\ \vec{\alpha}_{-} \end{pmatrix} \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} = i \begin{pmatrix} \vec{\alpha}_{-}, \vec{\alpha}_{-}, \vec{\alpha}_{-} \\ \vec{\alpha}_{-} \end{pmatrix} = (\vec{\alpha}_{-}, \vec{\alpha}_{-}, \vec{\alpha}_{-}) \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) & \vec{\alpha}_{x} = \begin{pmatrix} \vec{\alpha}_{-}, \vec{\alpha}_{-} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} = i \begin{pmatrix} \vec{\alpha}_{-}, \vec{\alpha}_{-} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix} \vec{\alpha}_{+} \\ \vec{\alpha}_{-} \end{pmatrix} \\ \vec{\alpha}_{x} = (\vec{\alpha}_{+}, \vec{\alpha}_{-}) \begin{pmatrix}$$

 $|\gamma_{k,i} \times \gamma_{k,k,i}| = \begin{pmatrix} \alpha' + \alpha + & \alpha' - \alpha_+ \\ \alpha' + \alpha - & \alpha' - \alpha \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 + P_2 & P_2 - iP_3 \\ P_2 + iP_3 & 1 - P_2 \end{pmatrix}.$

3) P= < Yx 1 T 1 Yx> , F= (Tx, Ty, Tz) Pathria

17x) = a+ px,+12 +a- dx,-12

$$\hat{\rho}(l) \quad \langle |\bar{r} \rangle \rangle \\
\hat{\rho}(p|l) = \hat{\rho}(l) \quad \langle \bar{r}' | \hat{\rho}(l) | \bar{r} \rangle \\
\hat{\rho}(p|l) = \hat{\rho}(l) \quad \langle \bar{r}' | \hat{\rho}(l) | \bar{r} \rangle \\
\frac{(b)}{\langle \bar{r}' | \hat{\rho}(l) | \bar{r} \rangle} = \frac{\langle \bar{r}' | \hat{\rho}(l) | \bar{r} \rangle}{\langle \bar{r}' | \hat{\rho}(l) | \bar{r} \rangle} = \frac{1}{\sqrt{|\bar{r}'|}} \frac{\langle \bar{r}' | \bar{r}' | \hat{r} \rangle}{\langle \bar{r}' | \bar{r}' | \bar{r}' | \bar{r}' | \bar{r}' | \bar{r}' \rangle} \\
= \frac{1}{\sqrt{|\bar{r}'|}} \underbrace{\sum_{\bar{r}' | \bar{r}' | | \bar{r}' | \bar{r}' | \bar{r}' | \bar{r}' | | \bar{r}' | | \bar{r}' | | \bar{r}' | | \bar{r}' |$$

 $\leq (a)$ $\langle \hat{o} \rangle = \{ \langle \hat{o} \rangle \hat{o} \}$ $\hat{o} \}$ $\hat{o} \} = \{ \langle \hat{o} \rangle \} = \{ \langle \hat{o$

 $-\frac{1}{\sqrt{r}} = \frac{1}{\sqrt{r}} = \frac{$