$$S_{2} \left[D(0,T_{1}) P(T_{1}) \Delta t_{1} + D(0,T_{2}) P(T_{2}) \Delta t_{2} \right] = \underbrace{\left(1 - \mathcal{K} \right)} \left[D(0,T_{1}) \left(P(T_{0}) - P(T_{1}) \right) + D(0,T_{2}) P(T_{1}) \Delta t_{1} + S_{2} D(0,T_{2}) P(T_{2}) \Delta t_{2} \right] = \underbrace{\left(1 - \mathcal{K} \right)} \left[D(0,T_{1}) \left(P(T_{1}) - P(T_{2}) \right) + D(0,T_{2}) \times \left(P(T_{1}) - P(T_{2}) \right) + D(0,T_{2}) \times \left(P(T_{1}) - P(T_{2}) \right) + D(0,T_{1}) P(T_{1}) + D(0,T_{1}) P(T_{1}) + D(0,T_{2}) P(T_{1}) P(T_{1}) + D(0,T_{2}) P(T_{1}) P(T_{1}) + D(0,T_{2}) P(T_{1}) D(0,T_{1}) P(T_{1}) D(0,T_{2}) P(T_{2}) = \cdots$$

$$\begin{split}
& \rho(T_{2}) \left[D(0,T_{2}) \left(S_{2} \Delta t_{2} + L \right) \right] = D(0,T_{1}) \left(L - L \rho(T_{1}) - S_{2} P(T_{1}) \Delta t_{1} \right) \\
& + D(0,T_{2}) L P(T_{1}) \right. \\
& \rho(T_{2}) \left[D(0,T_{2}) \left(S_{2} \Delta t_{2} + L \right) \right] = D(0,T_{1}) \left[L - P(T_{1}) \left(L + S_{2} \Delta t_{1} \right) \right] \\
& + D(0,T_{2}) L P(T_{1}) \\
& + D(0,T_{2}) L P(T_{1}) \right. \\
& P(T_{2}) = \frac{D(0,T_{1}) \left[L - P(T_{1}) \left(L + S_{2} \Delta t_{1} \right) \right]}{D(0,T_{2}) \left(S_{2} \Delta t_{2} + L \right)} + \frac{D(0,T_{2}) L P(T_{1})}{D(0,T_{2}) \left(S_{2} \Delta t_{2} + L \right)} \\
& P(T_{2}) = \frac{D(0,T_{1}) \left[L - P(T_{1}) \left(L + S_{2} \Delta t_{1} \right) \right]}{D(0,T_{2}) \left(L + S_{2} \Delta t_{2} \right)} + \frac{P(T_{1}) L}{L + S_{2} \Delta t_{2}}
\end{split}$$

$$\frac{N=3}{P(T_N)} = \frac{\sum_{n=1}^{N-1} D(o,T_n) \left[LP(T_{n-1}) - \left(L+\Delta t_n S_N \right) P(T_n) \right]}{D(o,T_N) \left(L+\Delta t_n S_N \right)} + \frac{P(T_{N-1}) L}{\left(L+\Delta t_N S_N \right)}$$

$$P(T_3) = \frac{\sum_{n=1}^{2} D(o,T_n) \left[LP(T_{n-1}) - (L+\Delta t_n S_3) P(T_n) \right]}{D(o,T_3) \left(L+\Delta t_n S_3 \right)} + \frac{P(T_2) L}{\left(L+\Delta t_3 S_3 \right)}$$

Note: The bootstrapping formulas above are implemented in the XLS file:
Improved Bootstrapping Example. XIS

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