

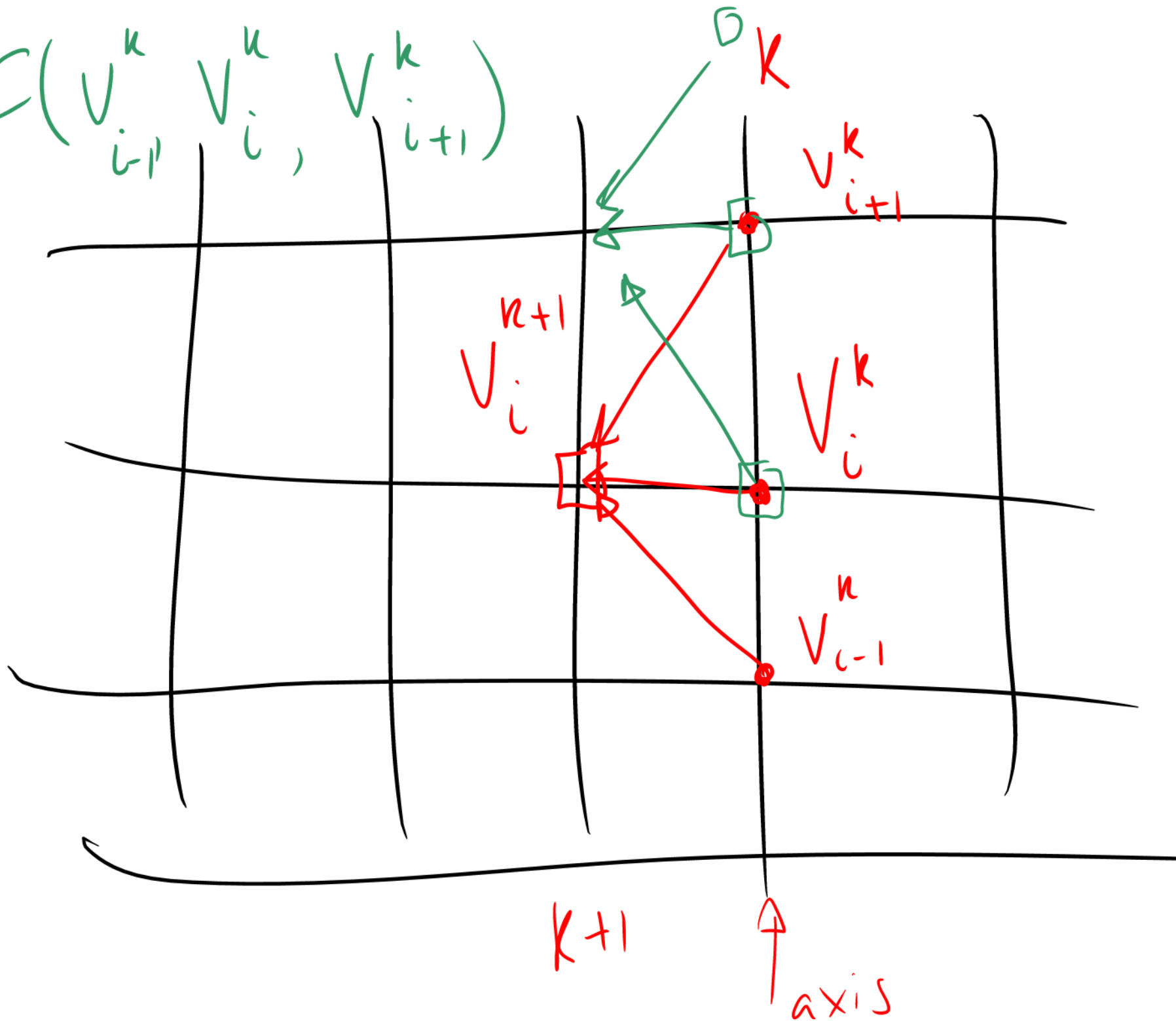
Explicit vs.

$$y = f(x)$$

Implicit

$$f(x, y) = 0$$

$$V_i^{k+1} = F(V_{i-1}^k, V_i^k, V_{i+1}^k)$$

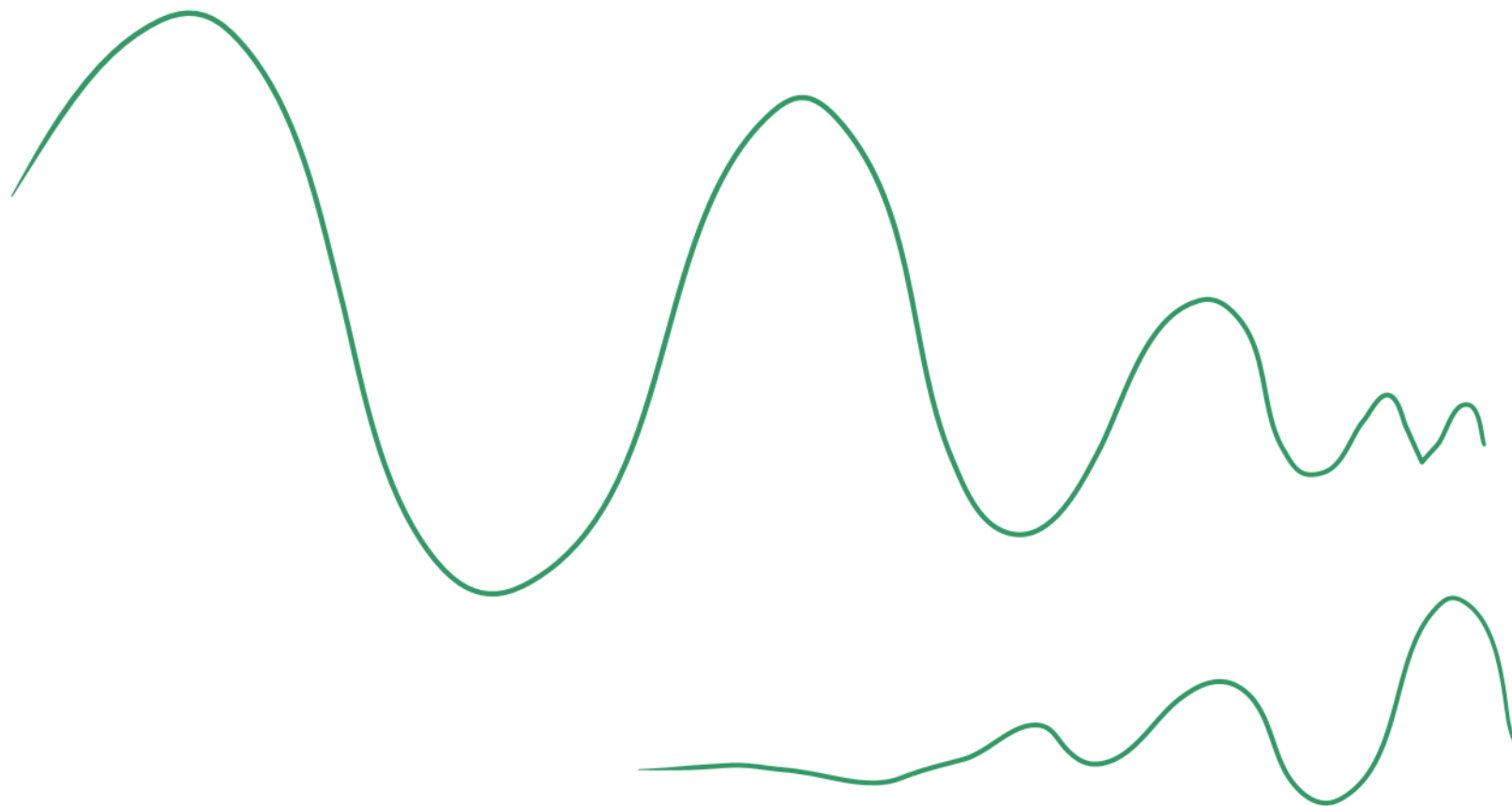


Fourier stability

$$\delta t \leq$$

$$\frac{1}{\sigma^2 I^2}$$

stability  
Condition



$$O(\delta t, \delta s^2)$$

$\delta t$  - fixed

$\delta s$  - fixed

$$\frac{1}{2} \left( k + (k+1) \right) \delta t \quad \text{Imp.}$$

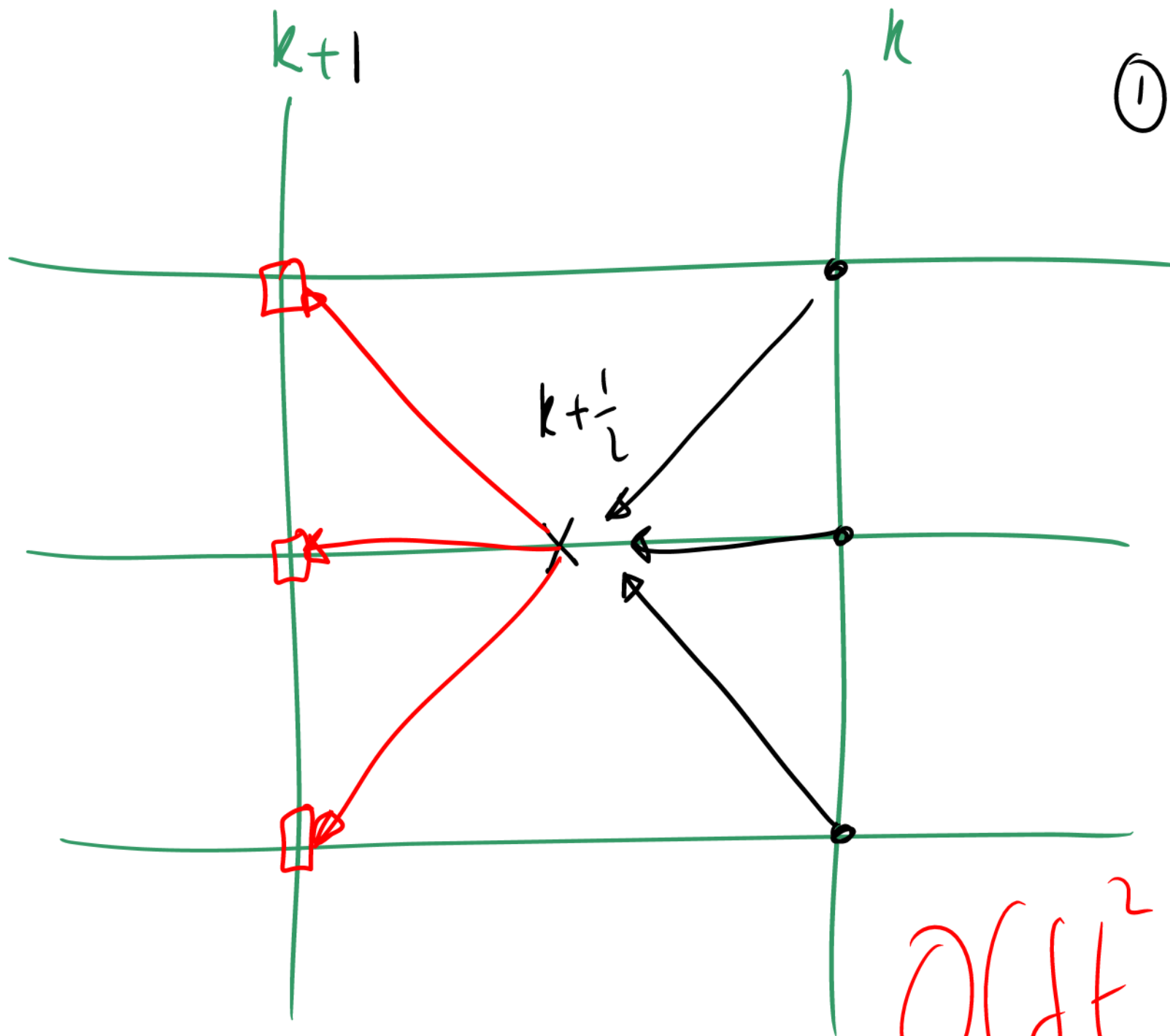
$$\delta t = 1 \times 10^{-2}$$

$$\delta J = 1 \times 10^{-3}$$



$$\left( k + \frac{1}{2} \right) \delta t$$

①  $\varepsilon_{xp}$



$$O(\delta t^2, \delta s^2)$$

# Numerical Analysis

Burden, Faires

$\theta$  - Method  $0 \leq \theta \leq 1$

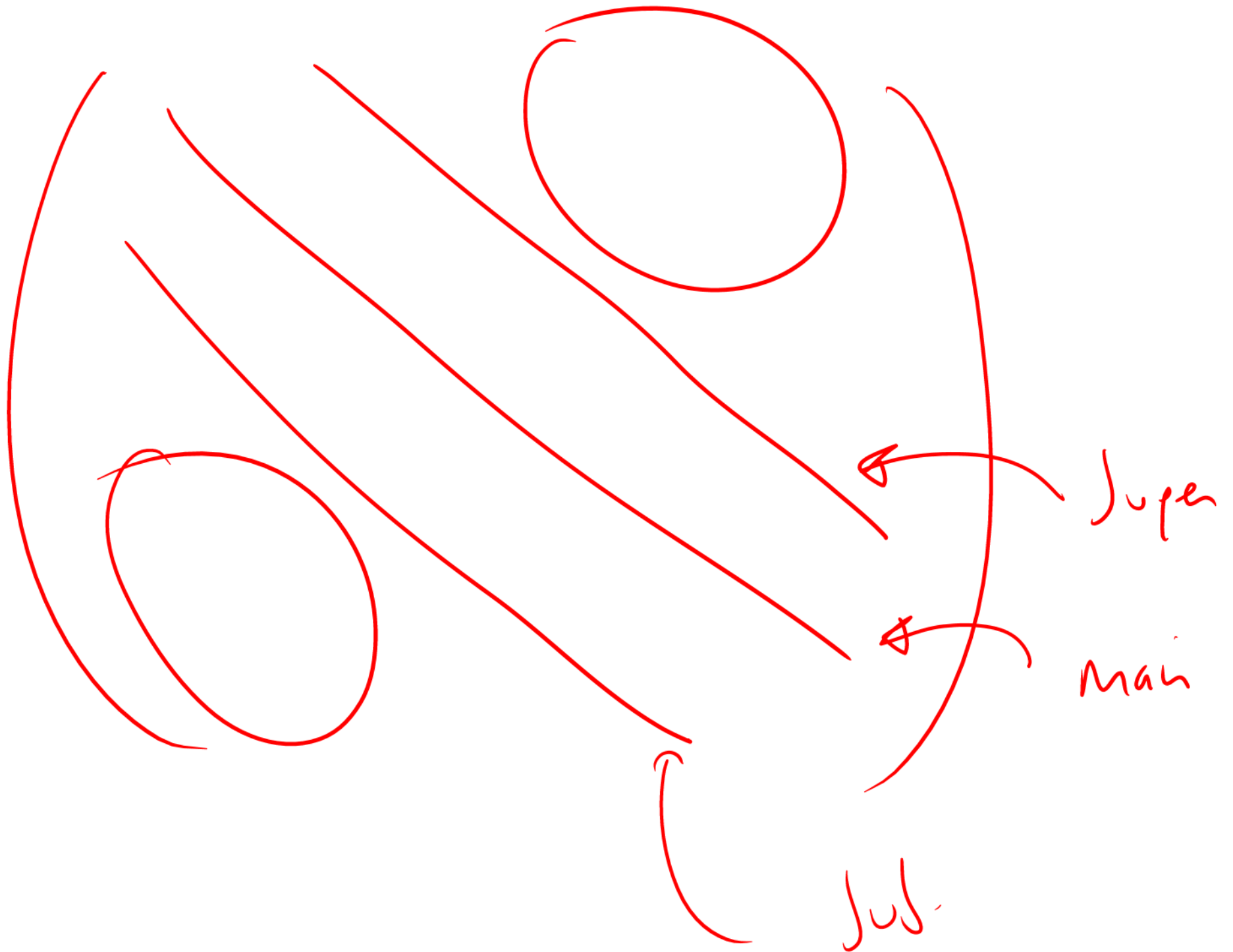
$$\theta \times \text{Imp} + (1 - \theta) \times \text{Exp}$$

$\theta = 0 \Rightarrow \text{Exp Scheme}$

$\theta = 1 \Rightarrow \text{Imp Scheme}$

$\theta = \frac{1}{2} \Rightarrow \text{C-N Scheme}$





$$\begin{pmatrix} & A & & \\ & & I & \\ & & & \\ & & & \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & \\ 0 & 1 & 0 & \\ 0 & 0 & 1 & \\ & & & A^{-1} \end{pmatrix}$$

$$M_{\underline{v}} = \underline{g}$$

$$L\left(\bigcup \underline{v}\right) = \underline{g}$$

$\underline{v}$  - unknown.

Put  $\bigcup \underline{v} = \underline{\omega} \rightarrow$

$$L \underline{\omega} = \underline{g}$$

$\downarrow$   
unknown.

Solve for  $\underline{\omega}$

then put in  $\bigcup \underline{v} = \underline{\omega} \rightarrow \underline{v}$

$$M_{\underline{V}} = \underline{g}$$

$$\underline{V} = \overline{T} \underline{V} + \underline{C}$$

# Convergence Criteria

$$\underline{v} \in \mathbb{R}^N$$

$$|\underline{v}| = \sqrt{v_1^2 + \dots + v_n^2}$$

$$\|\underline{x}\|_p = \left( \sum_{i=1}^N |x_i|^p \right)^{1/p}$$

Vector norm

$$p=2$$

Euclidean norm

$l_2$  norm

$$p=\infty$$

$l_\infty$  norm

$$\|\underline{x}\|_\infty = \max_{1 \leq i \leq N} |x_i|$$

$$\frac{\left\| V^{(k+1)} - V^{(k)} \right\|_{\infty}}{\left\| V^{(k)} \right\|_{\infty}} < \epsilon$$

$\epsilon$  - level tolerance

$$\underline{A} \underline{x} = \underline{b}$$

Strictly diagonally dominant  
 using Jacobi / Gauss-Jordan  
 used sol<sup>n</sup>

$$\begin{bmatrix} \alpha & \beta & \gamma \\ A & B & C \\ a & b & c \end{bmatrix}$$

$$\begin{aligned} |\alpha| &\geq |\beta| + |\gamma| \\ |B| &> |A| + |C| \\ |c| &> |a| + |b| \end{aligned}$$

$$A_{\underline{x}} = \underline{b}$$

If  $\underline{x}$  is exact then  $A_{\underline{x}} - \underline{b} = \underline{0}$

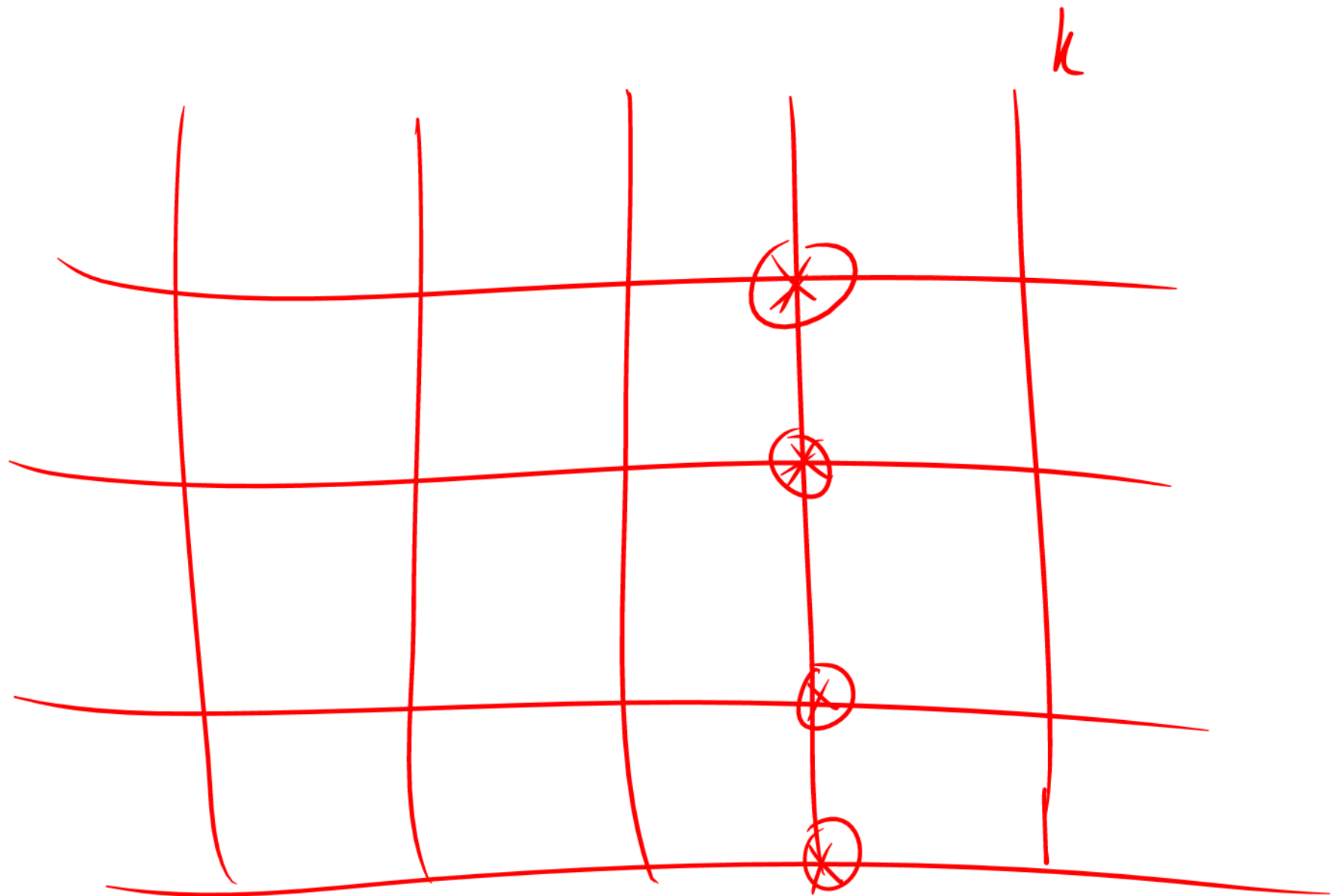
If  $\underline{x}$  not exact then  $A_{\underline{x}} - \underline{b} = \underline{r}$

$$\lim_{n \rightarrow \infty} \underline{r} \rightarrow 0$$



$$\delta t \leq \frac{1}{\delta^2 \underbrace{N^2}}$$

$$4 \delta t \leq \frac{1}{\delta^2 N}$$



$V \geq \text{Payoff}$

$$V(r, s, c, t)$$

$\swarrow$   $\searrow$   $\downarrow$   $\swarrow$   
 $h dr$   $m dJ$   $i dC$   $k dt$

$$V_{nmc}^R$$

$$\frac{\partial}{\partial r} \left( \frac{\partial V}{\partial S} \right)$$

$$V(r, S, t) = V(j \delta r, i \delta S, k \delta t)$$

$$= V_{ij}^k$$

$$\frac{\partial}{\partial r} \left[ \frac{V_{i+1,j}^k - V_{i-1,j}^k}{2 \delta S} \right] = \frac{\frac{V_{i+1,j+1} - V_{i-1,j+1}}{2 \delta S} - \frac{V_{i+1,j-1} - V_{i-1,j-1}}{2 \delta S}}{2 \delta r}$$