



# HERE Technologies GuadalaHacks Student Hackathon

May 17 & 18 2025



We make a  
unified live map  
designed for  
every moving  
vehicle





# Using location technology to solve global challenges

- HERE Technologies is a location data and technology company that created the first digital map **40 years ago**.
- Today we are the world's leading location platform company with a global footprint across **52 countries**.
- We create and maintain a new type of map - a complete, accurate and easy-to-use digital representation of the physical world.

# Prizes

1<sup>st</sup> place team: internships with HERE.

- **Potential start date:** Summer or Fall 2025 (Must be completed before end of 2025)
- **Duration:** 10-12 weeks
- **Hours:** 10-12 hours per week
- Option for remote or in-office (Leon)

2<sup>nd</sup> and 3<sup>rd</sup> place teams

- HERE Developer Blog posts

# The Problem:

## Automatically Correcting Spatial Validations

# Project Overview

The road network is continuously evolving, and we aim to maintain up-to-date maps to enhance navigation and overall user experience.

HERE develops and maintains a robust set of validations to detect issues within the data.

- Based on a comprehensive set of rules
- Currently 3000+ validations
- Intended to reflect reality situations
- Cleaned before release
- Reviewed: fixed or labeled as “legal exceptions”

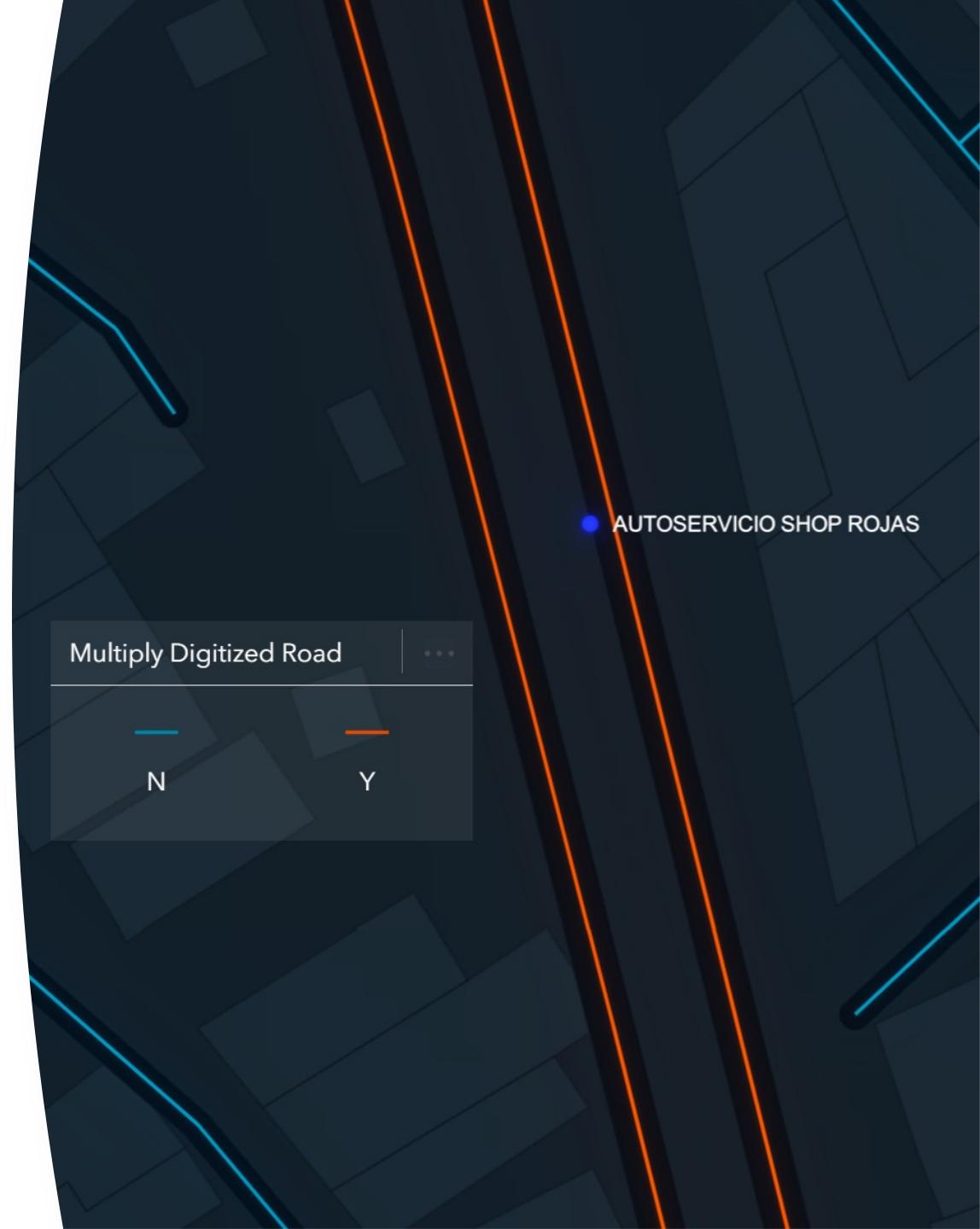
# POI295

## POI on Inside of Multi-Dig Road

**Trigger:** A Point of Interest (POI) feature is suspicious when located on the inside of Multiply Digitised roads.

### Outcome scenarios:

1. No POI in reality
2. Incorrect POI location
3. Incorrect Multiply Digitised attribution
4. Legitimate Exception from the rule



# Possible Scenarios (1/4)

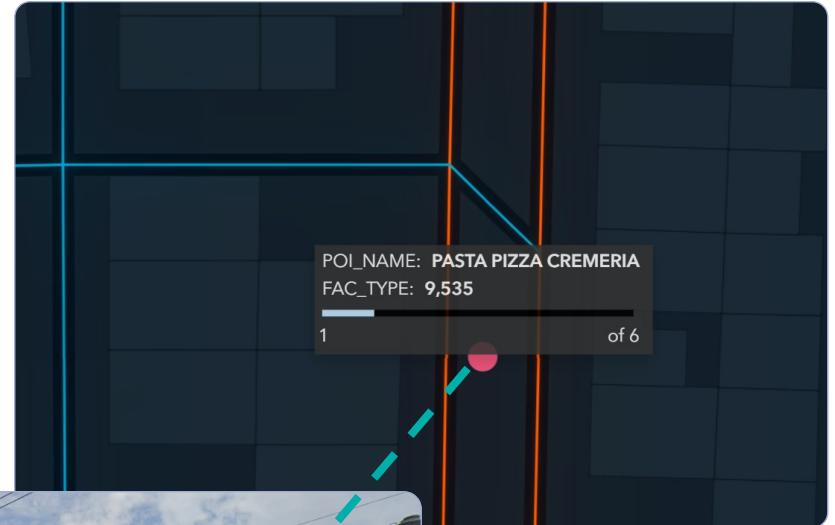
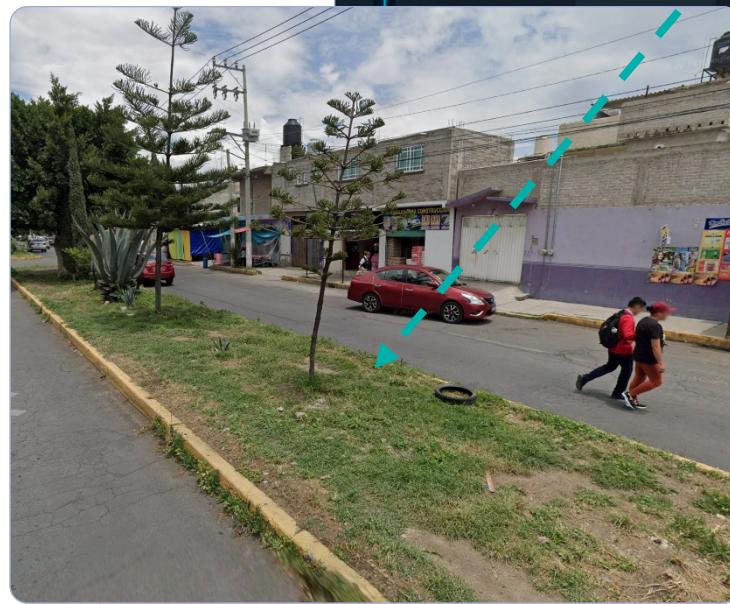
## Scenario #1: no POI in reality

### No POI in reality:

- The POI feature is most likely outdated or has been moved.



**OUTCOME:**  
*Mark the feature for deletion*



# Possible Scenarios (2/4)

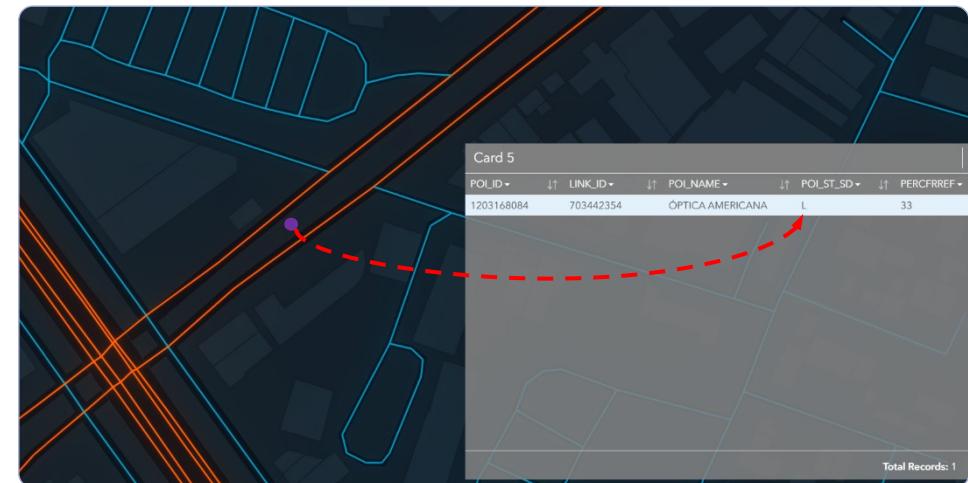
## Scenario #2: POI placed on incorrect side of the road

### Incorrect road matching:

- There is a POI in reality, but it has been associated to the wrong side of the road segment.



**OUTCOME:**  
*Update the POI record with a new associated Link*



Actual Street Side = **Right**



# Possible Scenarios (3/4)

## Scenario #3: Incorrect Multiply Digitised attribution

### Incorrect road attribution:

- The POI is in the correct place, however the road segment was erroneously attributed as 'Multiply Digitised = YES'



#### OUTCOME:

*Update the Link feature's MULTIDIGIT attribute to 'N'*

- See more about Multiply Digitised (MULTIDIGIT) coding in the *Navstreets Reference Guide* (pg. 468-470).



# Possible Scenarios (4/4)

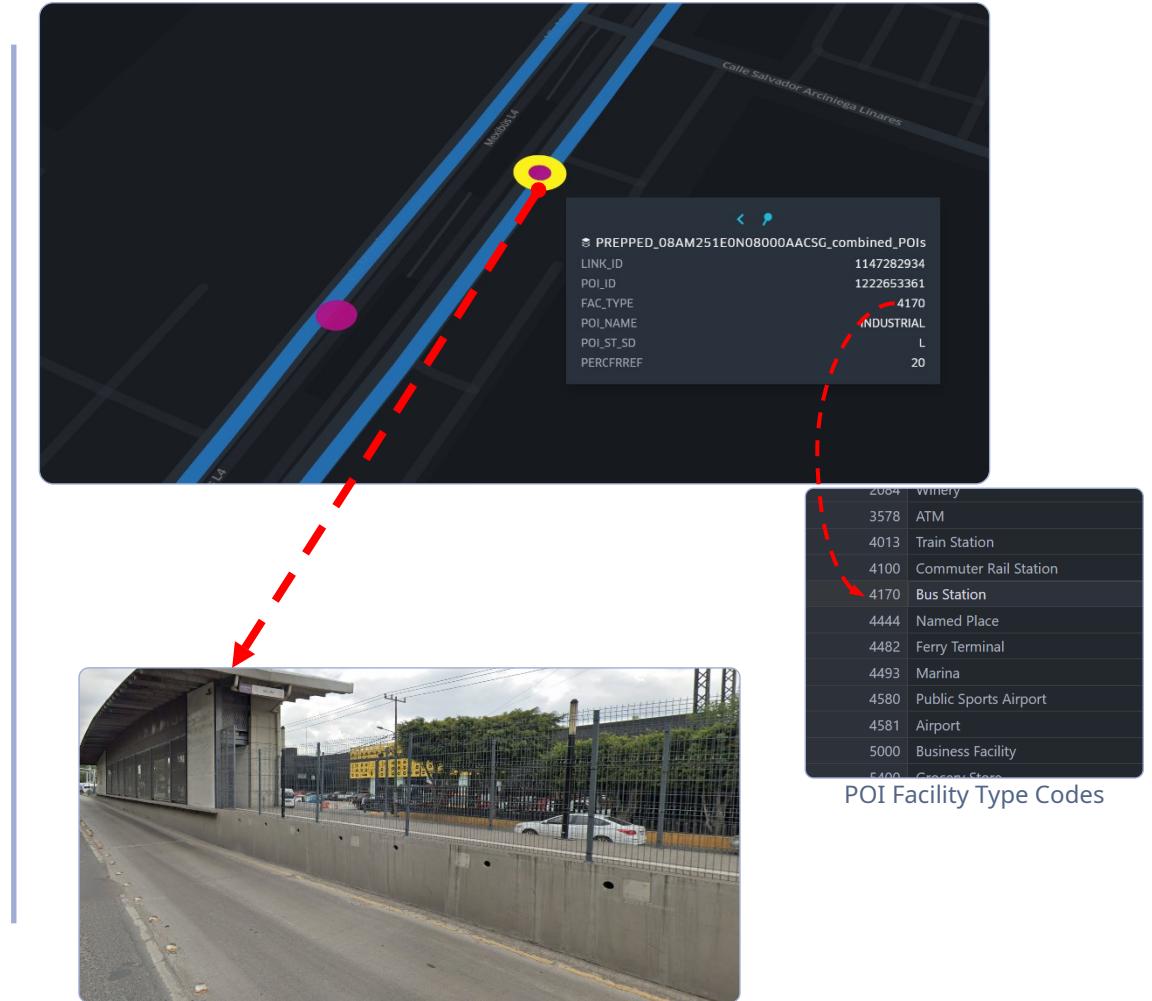
Legitimate Exception: correct location and confirmed existence

**Valid exception from the rule:**

- There is a POI in reality and its location within a multi-dig set of road links is correct



**OUTCOME:**  
*mark violation as  
'Legitimate Exception' in the  
Validations dataset*



# Dataset Characteristics

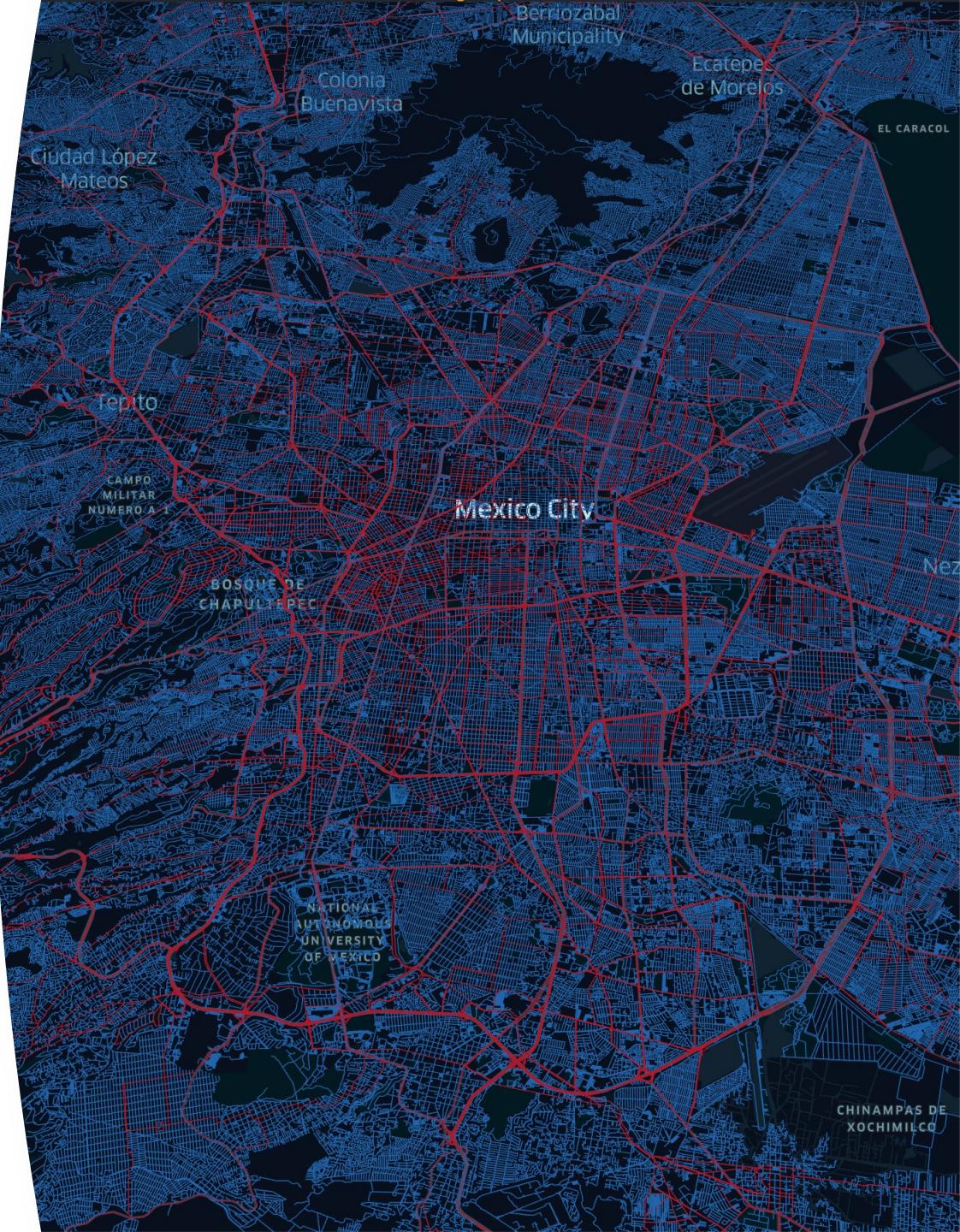
The provided data includes the Street Network and Places of Interest in parts of Mexico City and surrounding area. It also includes *hidden errors...*

## Included:

- Road Network Dataset (geometry, street type etc.)
- Points of Interest Dataset (restaurants, banks etc.)
- Satellite Imagery (*through the HERE REST APIs*)

## Allowed:

- Open-source data (as reference, not as sole data source)



# The Datasets

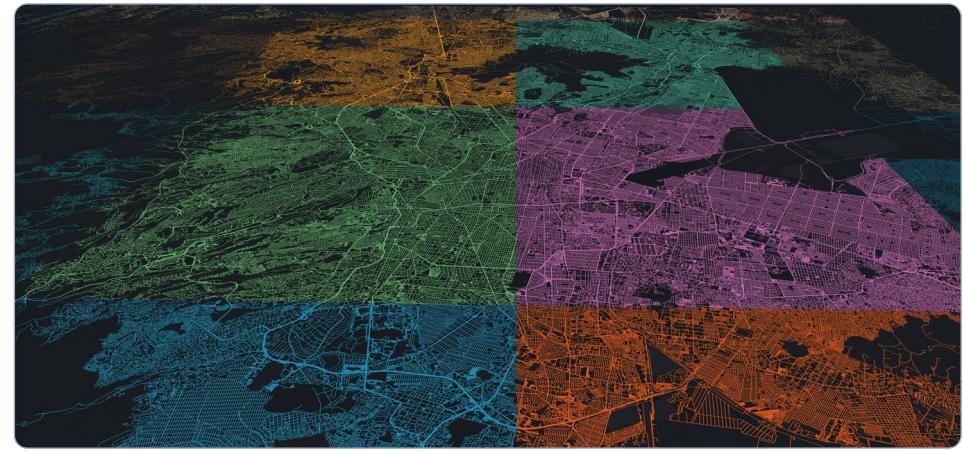
## Street Network - Nav Dataset

### Definition

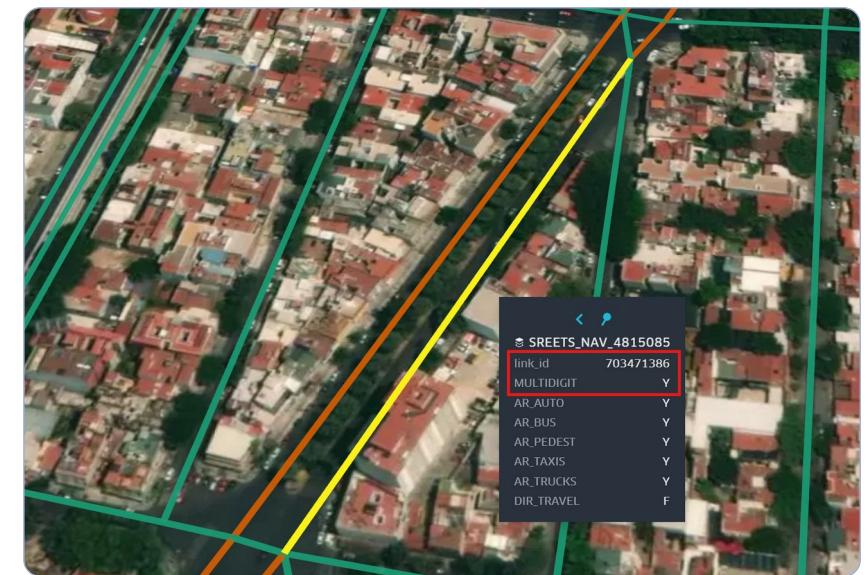
- The **Streets - Nav** dataset contains all roads plus Road Network features related to navigation such as direction of travel, dividers, lane counts etc.
- **Spatial Feature Type:** LineString

### Location

- Geojson files can be found in the 'STREETS\_NAV' folder.
- Data is split into 20 separate files for convenience.



20 'tiles' of Street Network Data



'link\_id' acts as the unique ID while other columns show relevant attribution of the feature.

# The Datasets

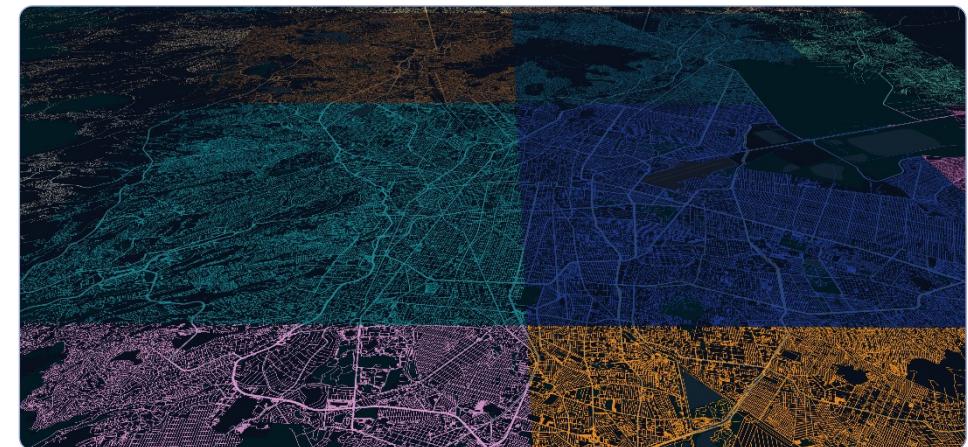
## Street Network – Naming & Addressing Dataset

### Definition

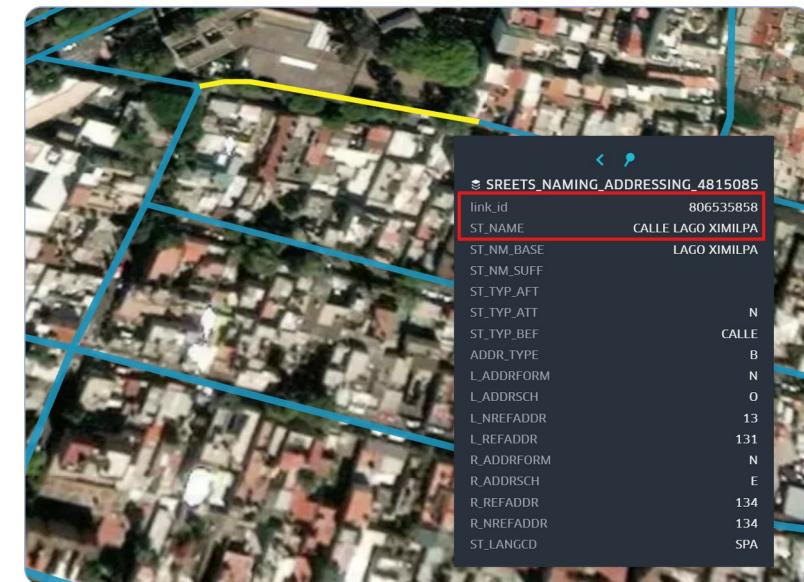
- The **Streets – Naming & Addressing** dataset contains all roads plus Road Network features related to naming and addressing.
- **Spatial Feature Type:** LineString

### Location

- Geojson files can be found in the 'STREETS\_NAMING\_ADDRESSING' folder.
- Data is split into 20 separate files for convenience.



20 'tiles' of Street Network Data



'link\_id' acts as the unique ID while other columns show relevant attribution of the feature.

# The Datasets

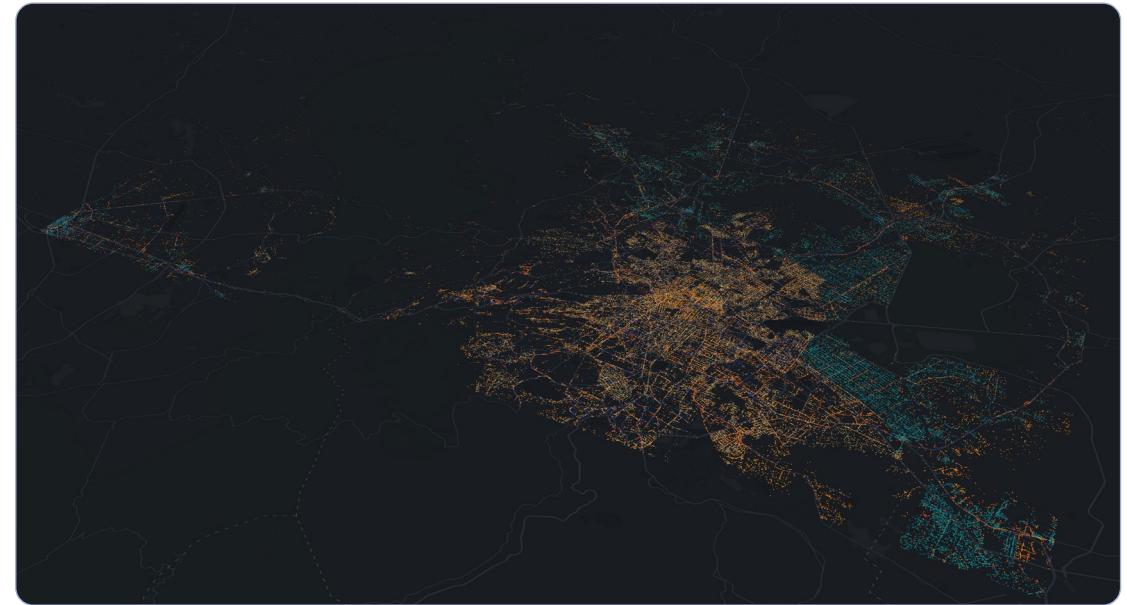
## Places of Interest (POI) Dataset

### Definition

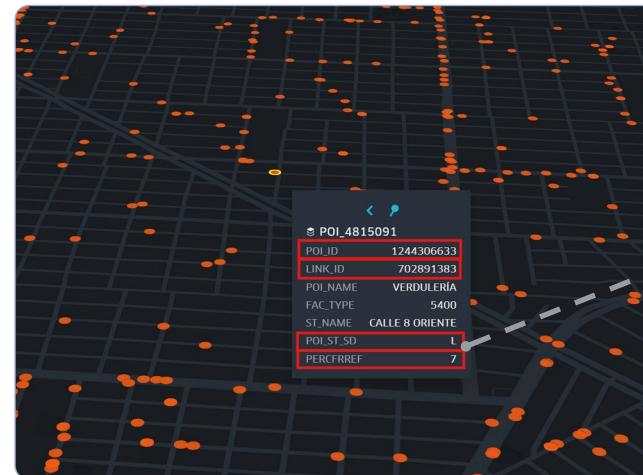
- The **POI** dataset contains all Places of Interest features along with relevant attribution.
- Its **location is derived** by joining it with the Streets dataset and calculating its placement based on indicated distances.
- **Spatial Feature Type:** Point (but its geometry needs to be derived)

### Location

- Geojson files can be found in the 'POIs' folder.
- Data is split into 20 separate files for convenience.



~190,000 POI records in the Mexico City area



**LINK\_ID** = associates POI with a street.  
**POI\_ST\_SD** = side of street where the POI is located.

**PERCREF** = indicates the location of the POI on the link in terms of percent from the reference node.

# The Datasets

## Satellite Imagery (HERE REST API requests)

### Definition

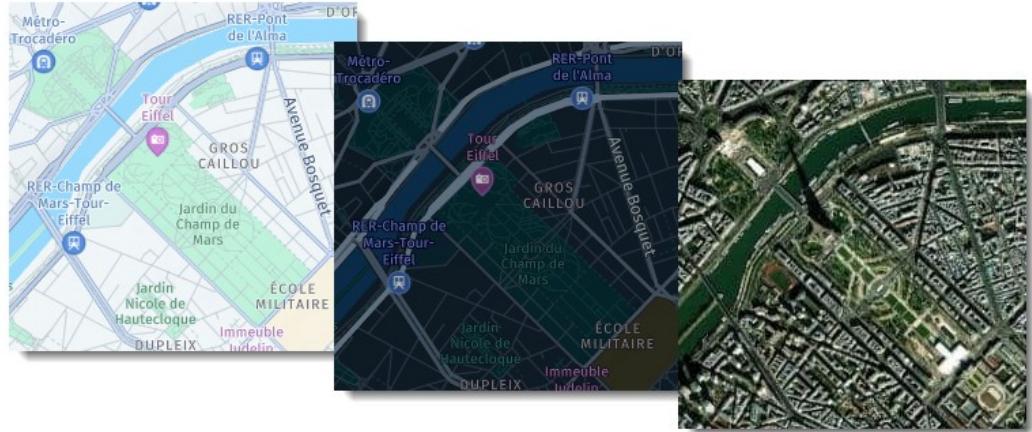
- The HERE Raster Tile API offers bitmap images with a resolution of either 256x256 or 512x512 pixels.
- Satellite imagery is one of the pre-defined response types that can be requested.

### Location

- Available through REST API requests. Requires API Key (30k request for free in the [Base Plan](#))

### How to:

- Example python code snippet to request satellite imagery is provided in the docs.



HERE Raster Tile API style examples

```
def get_satellite_tile(lat,lon,zoom,tile_format,api_key):
    x,y = lat_lon_to_tile(lat, lon, zoom)

    # Construct the URL for the map tile API
    url = f"https://maps.hereapi.com/v3/base/tiles/{zoom}/{x}/{y}/{tile_format}&style=satellite.day&size={tile_size}?apiKey={api_key}"

    # Make the request
    response = requests.get(url)

    # Check if the request was successful
    if response.status_code == 200:
        # Save the tile to a file
        with open(f'satellite_tile.{tile_format}', 'wb') as file:
            file.write(response.content)
        print('Tile saved successfully.')
    else:
        print(f'Failed to retrieve tile. Status code: {response.status_code}')

    bounds = get_tile_bounds(x,y,zoom)
    wkt_polygon = create_wkt_polygon(bounds)
    return wkt_polygon

#####
# Define the parameters for the tile request
api_key = '<YOUR API KEY>'
latitude = 48.8583
longitude = 2.3512
zoom_level = 16 # Zoom level
tile_size = 512 # Tile size in pixels
tile_format = 'png' # Tile format

# Execute request and save tile
wkt_bounds = get_satellite_tile(latitude,longitude,zoom_level,tile_format,api_key)
print(wkt_bounds)
```

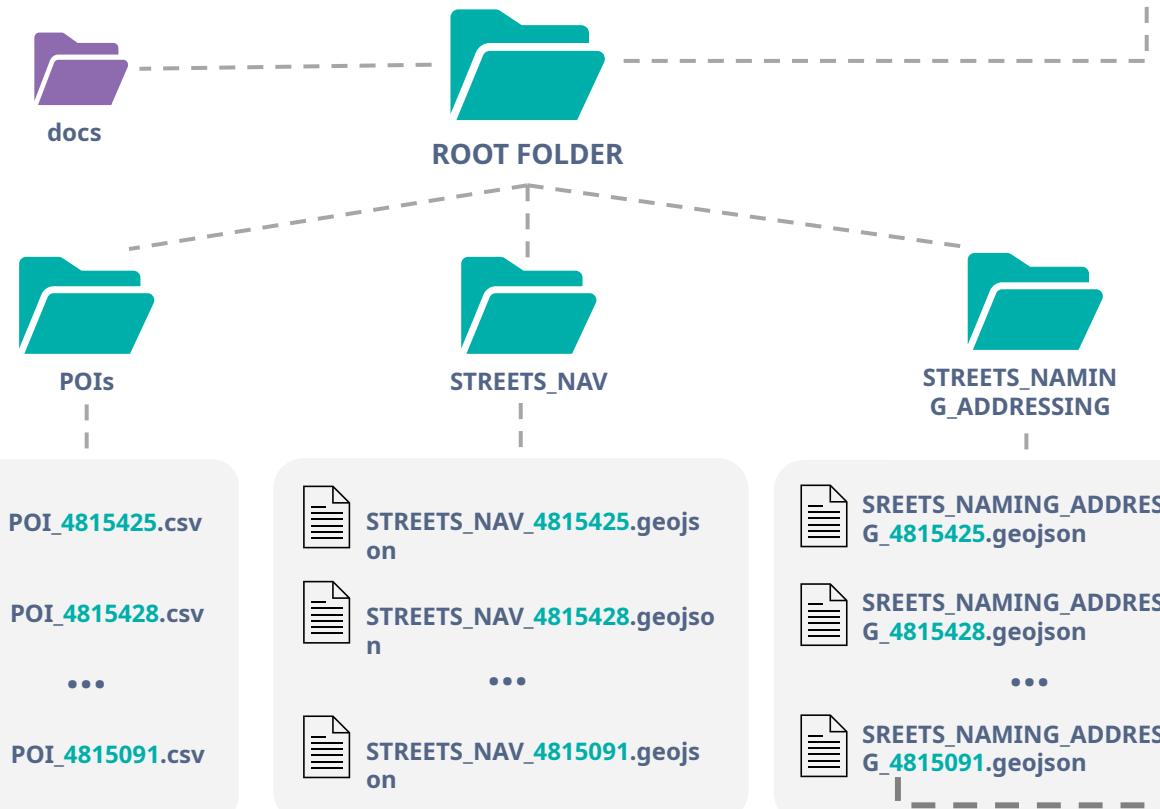
Provided python script



Output png image

# The Datasets

## Folder & file structure



# Critical Attributes (1/3)

## Reference & Non-Reference Nodes of Links

HERE NAVSTREETS Reference Guide page 74

### Definitions

- **The Reference Node** is the node with the lower latitude.
- If the latitudes of both end nodes are identical and their longitudes differ, the Reference Node is determined by the end node with the lower longitude.
- If, however, the latitudes and longitudes of both end nodes are identical but their Z-Levels are different, the Reference Node is determined by the end node with the lower Z-Level.

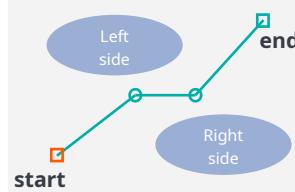
### Navstreets feature type: Link



- **SHAPE POINTS** = defines geometric curvature of the road
- **END NODES** = last coord pairs at each ends
- **REFERENCE NODE** = end node with the lower latitude **OR** lower longitude if lats are the same.\*

\*See additional rules in the Navstreets Guide

### The importance of the Reference Node



**Side Orientation** is established using the Reference Node and Non-Reference Nodes.

The Reference Node is located at the "beginning" of a link.

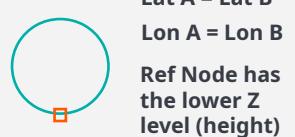
I.e.: the right side of a link is the side on the right when facing the Non-Reference Node.

### CASES



Lat A = Lat B  
Lon A < Lon B

REFERENCE NODE      NON-REFERENCE NODE



# Critical Attributes (2/3)

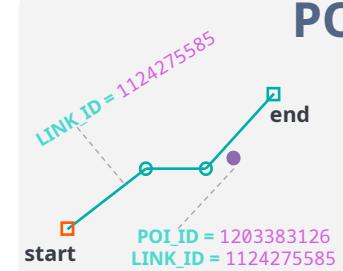
## POI Road Side & Distance From Reference Node

HERE NAVSTREETS Reference Guide page 52

### Definitions

- **Link ID (LINK\_ID)** defines which Link the POI is associated to.
- **Percent From Reference Node (PERCFFREF)** is an attribute to a Point Of Interest (POI) and indicates the location of the POI on the link in terms of percent from the reference node.
- **Side (POI\_ST\_SD):** The side of the street the POI is located on.

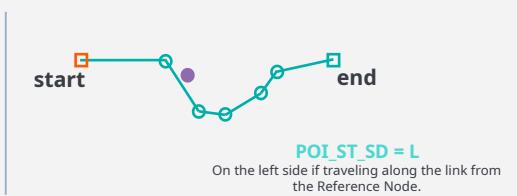
### POIs are associated to Links



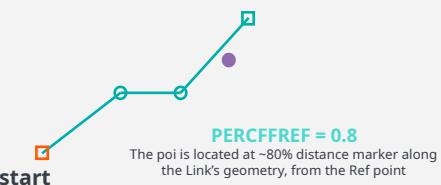
A **POI feature's location** needs to be defined based on its **LINK\_ID** (**LINK\_ID**) association.

The **LINK\_ID** attribute of a POI record identifies which Link it's associated to.

### POIs are “placed” with the **POI\_ST\_SD** attribute



### POI location is defined by the **PERCFRREF** attribute



**Percent From Reference** indicates the location of the POI on the link in terms of percent from the reference node.

**E.g.:** a POI that is approximately at the mid distance point along the geometry has PERCFRREF = 0.5

# Critical Attributes (3/3)

## Multiply Digitised

HERE NAVSTREETS Reference Guide page 468

### Definition:

- The Multiply Digitised attribute identifies links that are digitised with one line per direction of traffic instead of one line per road and using the rules listed below.

### Usage:

- For wide roads a link is digitised for each direction of traffic (instead of for each road) in order to improve map matching of the car to the road map.
- The Multiply Digitised attribute identifies these opposing lanes of traffic when it is reasonable to represent them as a single line on displays and printed maps.

### Conditions\*:

- Meets distance thresholds between the two roadbeds
- Road is not a Ramp, Bi-directional or a Manoeuvre Link
- No heavy vegetation and the Street Name is the same on both sides



**Multiply Digitised** requirements not met  
(heavy vegetation, large distance & different street names)



**Multiply Digitised** requirements are met

# Expectations

Find a way to fix the data in automated fashion.

The expected outcome is a presentation on how we can help to resolve violations reported by a particular validation rule code without manual intervention.

here

# Bonus opportunity

- **Goal:** Scale this solution for global use.
- **Challenge:** How to make this solution efficient across different countries and road systems.
- **Task:** Propose a **theoretical** approach to scale the model globally.
- **Extra Points:** Present a practical or innovative method for global scaling.



# Additional Resources

- Introduction to HERE Mapping Concepts: [User Guide](#)
- [HERE Platform](#) (free access available)
- [HERE Rest API](#) Information
- General [HERE Documentation Search](#)

## Questions?

[Chat via Teams](#)

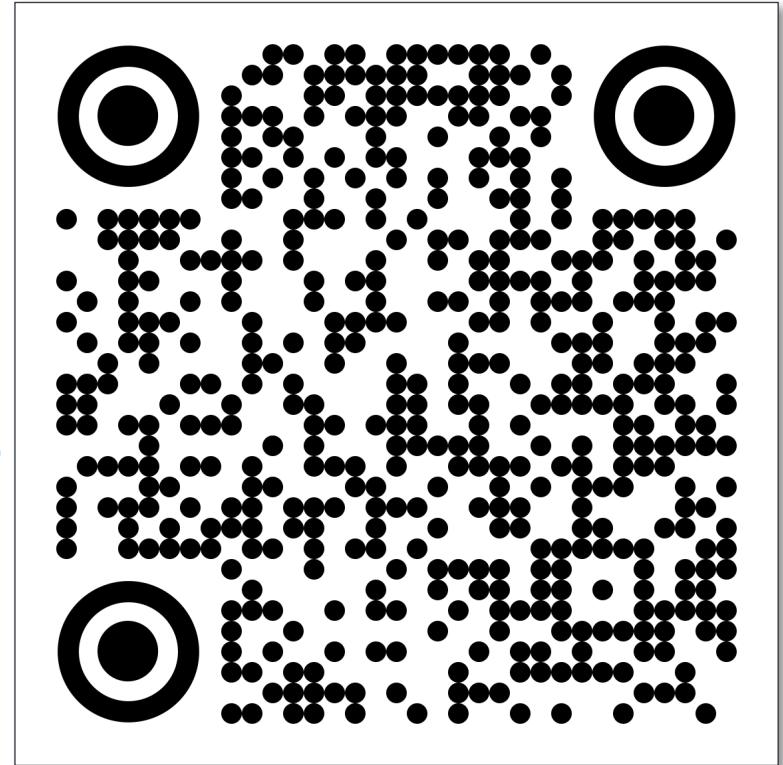
Email:

[kelli.vogt@here.com](mailto:kelli.vogt@here.com)

[akos.magdo@here.com](mailto:akos.magdo@here.com)



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