#!/usr/bin/python

import time

import os

def set\_angle(servo, angle):

angle = angle/60.0;

args = (str(servo), str(angle))

os.system("./rc\_move\_servos " + str(servo) + " " + str(angle) + "&")

# Step right

set\_angle(5, -70)

time.sleep(.5)

set\_angle(3, -30)

time.sleep(.5)

set\_angle(4, 30)

time.sleep(.5)

set\_angle(5, 0)

time.sleep(.5)

set\_angle(3, 0)

time.sleep(2)

# step left

set\_angle(3, 70)

time.sleep(.5)

set\_angle(5, 20)

time.sleep(.5)

set\_angle(6, -20)

time.sleep(.5)

set\_angle(3, 0)

time.sleep(.5)

set\_angle(5, 0)

time.sleep(2)

os.system("rc\_test\_servos -v -p 0.0")