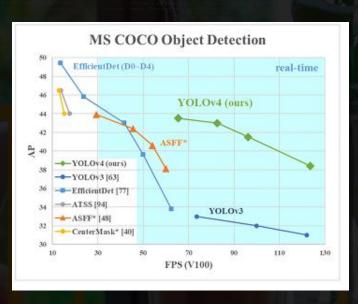


### **ABOUT YOLO V4**

- The actual author of the YOLO Object detector is Joseph Chet Redmon. (The first author of Darknet)
- In Feb 2020, Joseph Redmon announced he was leaving the field of computer vision.
- Later YOLO v4, a more fast and efficient version of YOLO v3 was released in April 2020 by three authors: Alexey Bochkovskiy, Chien-Yao Wang, and Hong-Yuan Mark Liao.
- YOLO v4 is officially maintained in in Alexey's git repository





## **CHECKING OPENCY VERSION**

- OpenCV needs to be updated to latest version (4.4 or above) for YOLOv4
- Verify the version. Uninstall current OpenCV if it's a lower version

```
: \ABHIS\tech\OCR and Object Recognition\code\test_env.py
                                                                 Console 1/A
                                                                 Python 3.7.6 (defa
                                                                 Type "copyright",
         # -*- coding: utf-8 -*-
                                                                 IPython 7.12.0 --
                                                                 In [1]: runfile('C
        @author: abhilash
                                                                 Recognition/code')
        #import the libraries
                                                                 4.3.0
        import pytesseract
        import pkg_resources
        import cv2
        #declaring the exe path for tesseract
        pytesseract.pytesseract.tesseract cmd = C: \P
        #printing the tesseract version
        print(pkg resources.working set.by key['pytess
        #print the opency version
        print(cv2. version )
  18
```

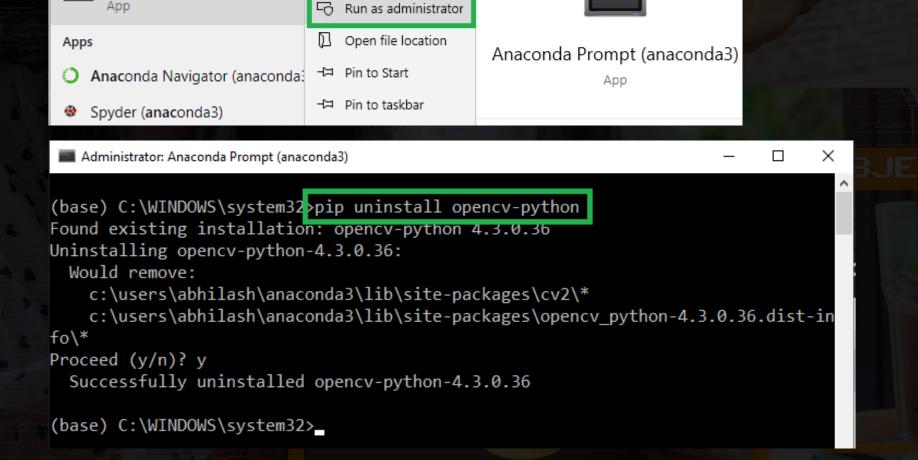
 Skip the 'OpenCV updating' part if the OpenCV version is 4.4 or above and proceed to 'Downloading YOLOv4 weights & config' section

## **UPDATING OPENCY VERSION**

If the version is below 4.4:

Anaconda Prompt (anaconda3)

Close all Spyder or Anaconda Navigator windows and run uninstall command



## **UPDATING OPENCY VERSION**

And check if the OpenCV version in the conda package list is an updated (4.4 or above) version

```
Administrator: Anaconda Prompt (anaconda3)

(base) C:\WINDOWS\system32>conda list
```

If YES, proceed with installation using 'pip install opency-python'

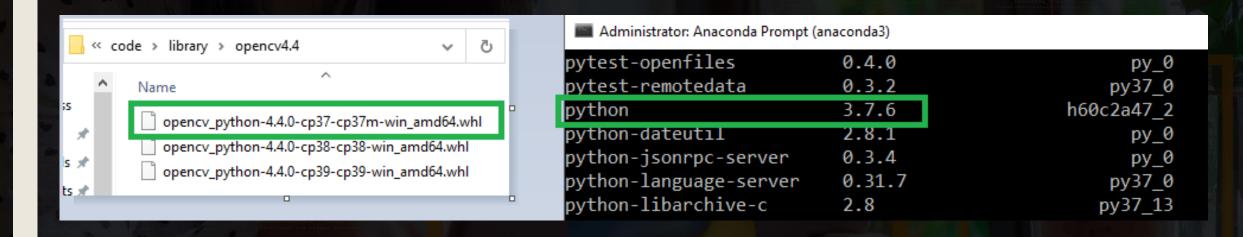
#### OBJECT

If NOT, proceed with a manual installation using a wheel file

numpy-base	1.18.1	py37hc3f5095_1	
numpydoc	0.9.2	py_0	
olefile	0.46	ру37_0	
opencv-python	4.3.0.36	pypi_0	pypi
openpyxl	3.0.3	ру_0	
openssl	1.1.1d	he774522_4	
packaging	20.1	py_0	

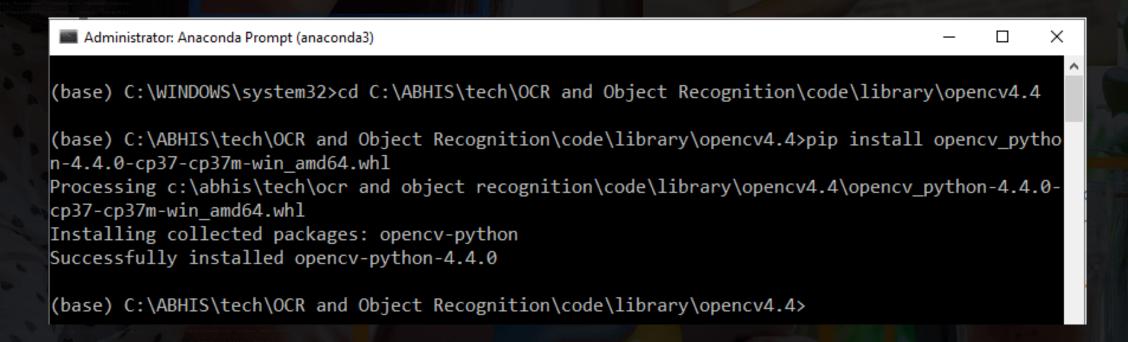
### MANUAL OPENCV SETUP USING .WHL FILE

- Already downloaded and verified the OpenCV 4.4 version wheel file for Python 3.7 (or) 3.8 (or) 3.9 from <a href="https://www.lfd.uci.edu/~gohlke/pythonlibs/#opencv">https://www.lfd.uci.edu/~gohlke/pythonlibs/#opencv</a>
- Downloaded into 'code/library' folder
- Find the appropriate version



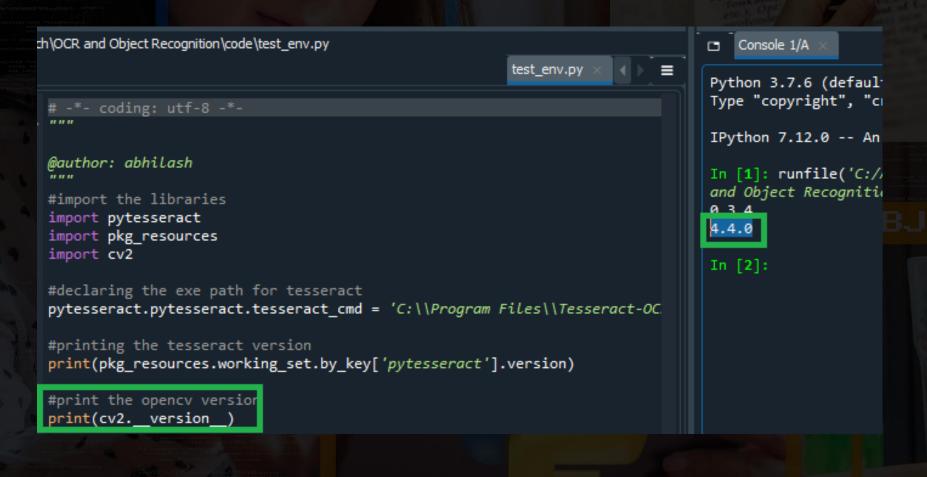
#### MANUAL OPENCY SETUP USING .WHL FILE

- Then go inside that folder using 'cd' command
- And using pip install, install opency-python



#### **VERIFY OPENCY VERSION**

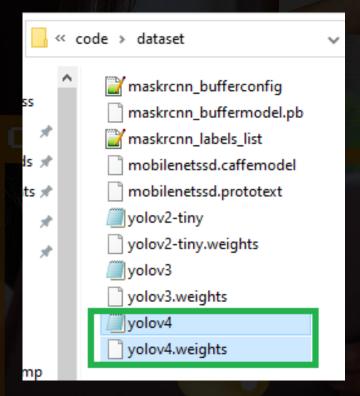
Now, open Spyder and Verify the OpenCV version



# DOWNLOADING YOLOV4 WEIGHTS & CONFIG



- Already downloaded both version-4 weights and config into /dataset folder from the github <a href="https://github.com/AlexeyAB/darknet">https://github.com/AlexeyAB/darknet</a>
- Tested and verified.





## SAVE A COPY AND MAKE CHANGES IN THE CODE FOR THE FILE PATHS

Do the same change for image, real-time and pre-saved video exercises

```
pretrained volov4 image nms.pv
                                                                                                                       In |I|: runTile( C:/ABHIS/TECN/UC
                                                                                                                       Recognition/code/test env.py', wd
       #Green, Blue, Red, cyan, yellow, purple
                                                                                                                       tech/OCR and Object Recognition/c
       #Split based on ',' and for every split, change type to int
                                                                                                                       0.3.4
                                                                                                                       4.4.0
       #convert that to a numpy array to apply color mask to the image numpy array
       class_colors = ["0,255,0","0,0,255","255,0,0","255,255,0","0,255,255"]
                                                                                                                       In [2]: runfile('C:/ABHIS/tech/OC
       class_colors = [np.array(every_color.split(",")).astype("int") for every_color in class_colors
                                                                                                                       Recognition/code/pretrained yolo
                                                                                                                       wdir='C:/ABHIS/tech/OCR and Objec
       class colors = np.array(class colors)
       class_colors = np.tile(class_colors,(16,1))
                                                                                                                       predicted object person: 99.59%
41
                                                                                                                       predicted object car: 99.56%
42
       # Loading pretrained model
                                                                                                                       predicted object person: 98.82%
                                                                                                                       predicted object car: 98.62%
       # input preprocessed blob into model and pass through the model
43
                                                                                                                       predicted object bicycle: 98.30%
                                                                                                                       predicted object bicycle: 97.12%
       yolo_model = cv2.dnn.readNetFromDarknet('dataset/yolov4.cfg',|'dataset/yolov4.weights')
45
                                                                                                                       predicted object bus: 96.59%
                                                                                                                       predicted object car: 95.68%
```