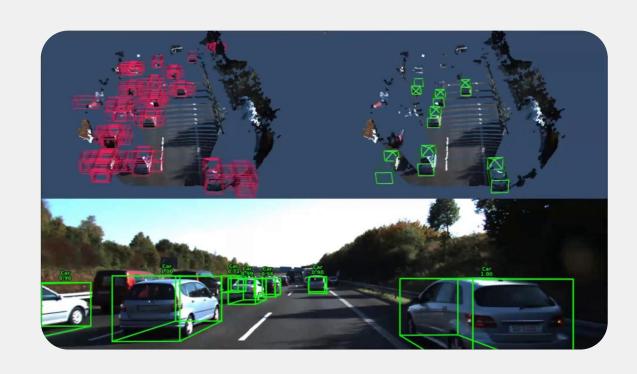
3D Object Detection Techniques



- LiDAR-Based
- Camera Based
- Temporal
- Label-Efficient
- Multi-Modal



3D Object Detection – LiDAR Based



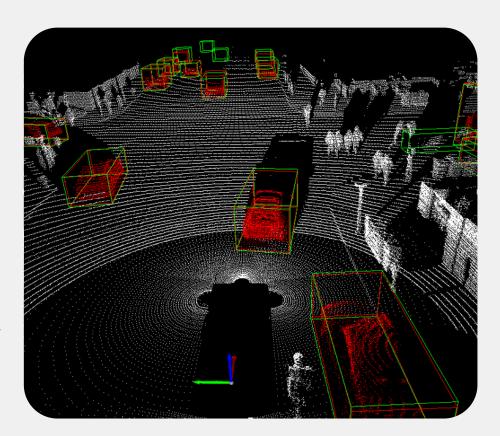
- Based on Data Representation
 - Point-Based Detection
 - Grid-Based Detection
 - Point-Voxel Based Detection
 - Range-Based Detection



3D Object Detection – LiDAR Based



- Based on Learning Objective
 - Anchor-BasedDetection
 - Anchor-Free Detection
 - Detection with Auxiliary Tasks



3D Object Detection – Camera Based Augmen



- Monocular
 - Image-only
 - Depth-assisted
 - Prior-guided
- Stereo-Based
- Multi-Camera



3D Object Detection - Multi-Modal Augmented Startups

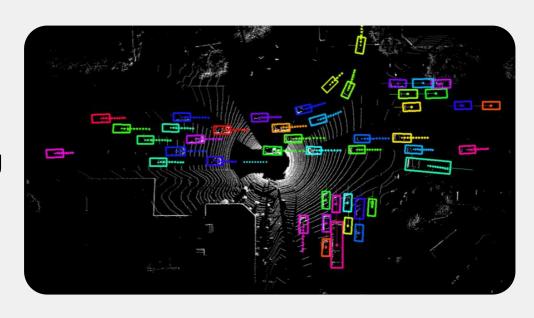
- Multi-Modal with LiDAR
 - Early Fusion Based
 - Intermediate Fusion Based
 - Late Fusion Based
- Multi-Modal with Radar Signals
- Multi-Modal with High Definition Maps



3D Object Detection – Temporal



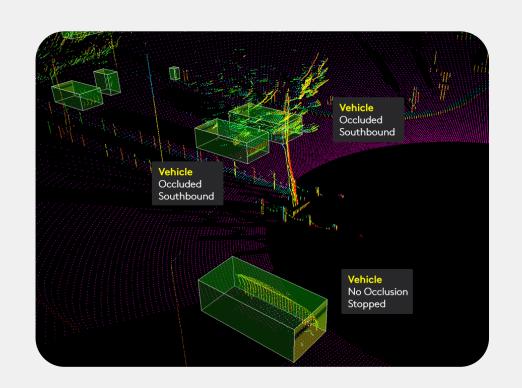
- Detection from LiDAR Sequences
- Detection from Streaming Data
- Detection from Videos



3D Object Detection – Label-Efficient AUGMEN



- Domain Adaption
- - Semi-Supervised
 - Self-Supervised



3D Object Detection – Label-Efficient AUGMEN



- Domain Adaption
- - Semi-Supervised
 - Self-Supervised

