

Computer Vision for Visual Perception

HydraNets

Learning Objectives

- **HydraNet**
 - Introduction
 - Definition
 - Background
- == • **Tesla HydraNet**
- **HydraNet for Self-Driving Cars**
- **Data Augmentation for Regression Neural Networks**
- **Summary**
- **References**



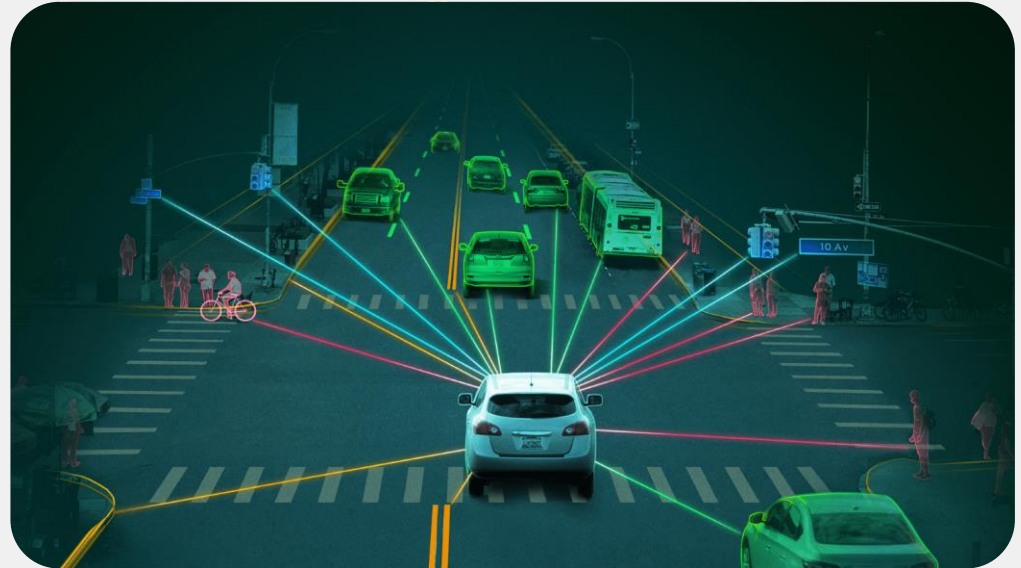
HydraNet – Introduction

- Introduced by Ravi et al. in 2018
- • Developed for Semantic Segmentation, for improving computational efficiency during inference time.



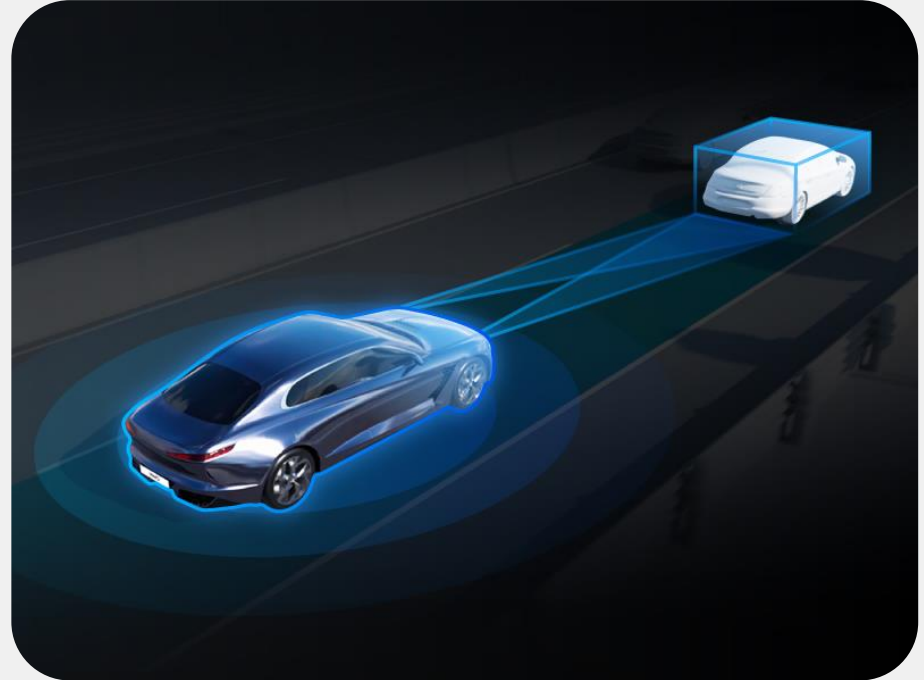
HydraNet – Definition

- **Dynamic Architecture**
- **Different CNN**
- **Various Inputs**

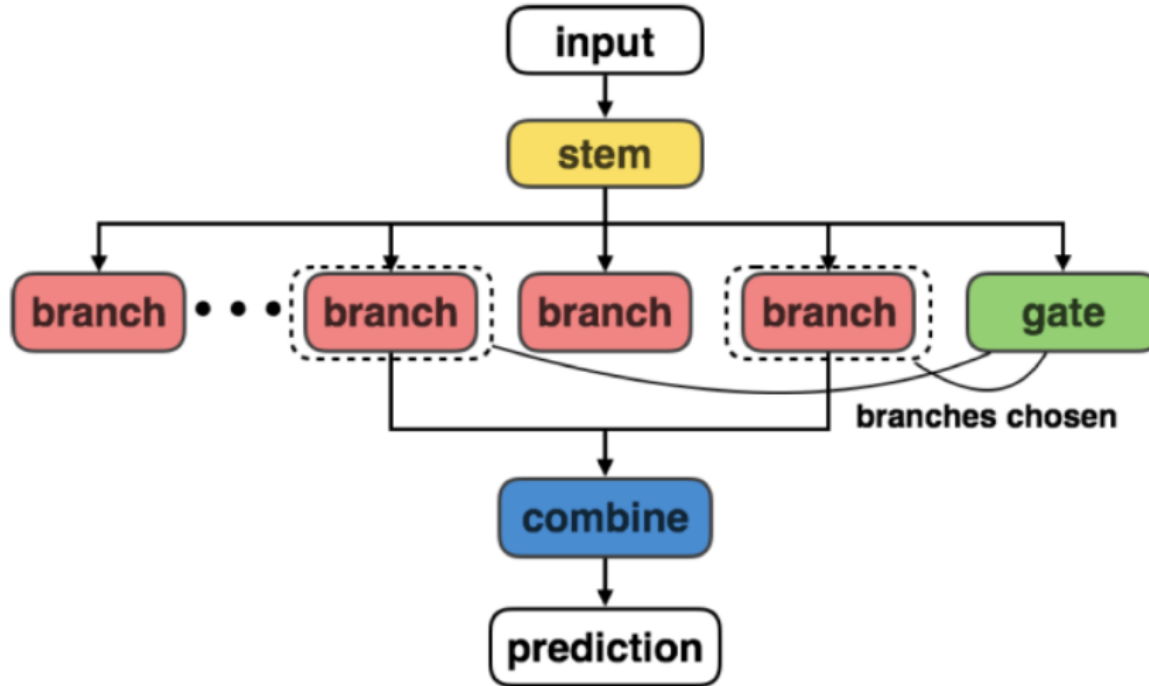


HydraNet – Background

- **Input from Static Environments**
- **Input from Road and Lanes**
- **Input from Traffic Lights**



HydraNet – Background



HydraNet Workflow Diagram

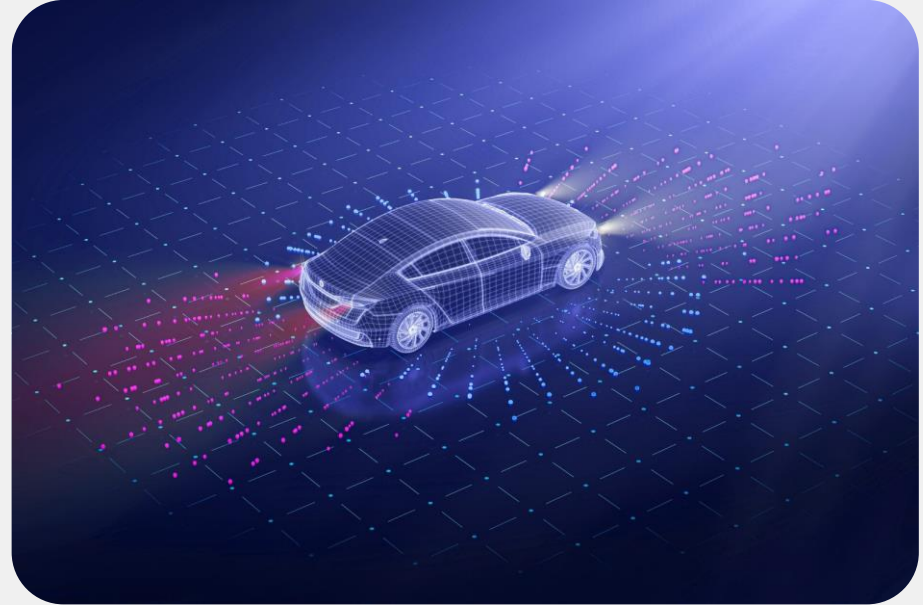
HydraNet – Tesla

- **Auto-Pilot**
- • **Smart Summons**
- **8 Cameras and Sensors Data**



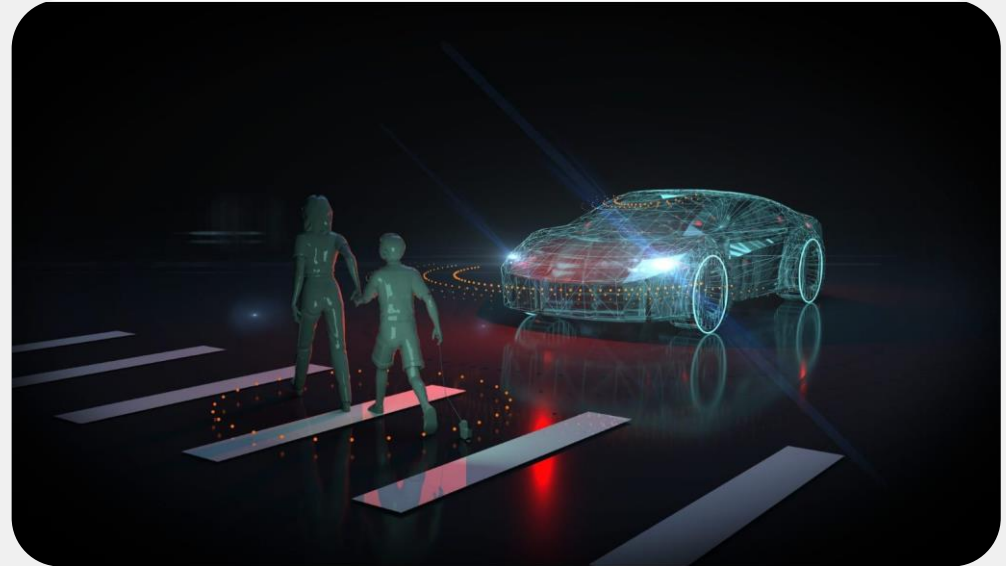
HydraNet – Tesla

- **Create 3D View**
- **Don't Use LiDAR**
- **Uses Camera & Radar**
- **Efficient**



Data Augmentation for Regression Neural Networks

- Problem with large quantity of labeled data
- ==
- Solution is – Creating a method by recombining existing ones.



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References

1. <https://saneryee-studio.medium.com/deep-understanding-tesla-fsd-part-1-hydranet-1b46106d57>
2. <https://siliconvalleyinsider.com/2020/03/08/waymo-chauffeurnet-versus-telsa-hydranet/>
3. <https://neptune.ai/blog/self-driving-cars-with-convolutional-neural-networks-cnn>



Thanks