

Processing Unit with MSP430

QueenField

1. INTRODUCTION

A Processing Unit (PU) is an electronic system within a computer that carries out instructions of a program by performing the basic arithmetic, logic, controlling, and I/O operations specified by instructions. Instruction-level parallelism is a measure of how many instructions in a computer can be executed simultaneously. The PU is contained on a single Metal Oxide Semiconductor (MOS) Integrated Circuit (IC).

2. PROJECTS

2.1. CORE-MSP430

2.1.1. Definition

The MSP430 implementation has a 16 bit Microarchitecture, 3 stages data pipeline and an Instruction Set Architecture based on Reduced Instruction Set Computer. Compatible with Wishbone Bus. Only For Researching.

2.1.2. Parameters

2.1.2.1. Basic System Configuration

| Description | Parameter | Type | Default |
|--|-------------|---------|---------|
| Program Memory Size | PMEM_SIZE | integer | 16384 |
| Data Memory Size | DMEM_SIZE | integer | 4096 |
| Include/Exclude Hardware Multiplier | MULTIPLYING | bit | 1 |
| Include/Exclude Serial Debug interface | DBG_ON | bit | 1 |

2.1.2.2. Advanced System Configuration (for experienced users)

| Description | Parameter | Type | Default |
|--------------------------------|--------------|------------|---------|
| Peripheral Memory Space | PER_SIZE | integer | 512 |
| Custom user version number | USER_VERSION | bit vector | 0 |
| Watchdog timer | WATCHDOG | bit | 1 |
| Non-Maskable-Interrupt support | NMI_EN | bit | 1 |
| Number of available IRQs | IRQ_16 | bit | 1 |
| Number of available IRQs | IRQ_32 | bit | 0 |
| Number of available IRQs | IRQ_64 | bit | 0 |
| Input synchronizers | SYNC_NMI | bit | 1 |
| Input synchronizers | SYNC_CPU_EN | bit | 0 |

| Description | Parameter | Type | Default |
|---------------------|----------------|------|---------|
| Input synchronizers | SYNC_DBG_EN | bit | 0 |
| Debugger definition | DBG_RST_BRK_EN | bit | 0 |

2.1.2.3. Expert System Configuration (experts only)

| Description | Parameter | Type | Default |
|--|--------------------|------------|---------|
| Hardware breakpoint/watchpoint units | DBG_HWBRK | bit vector | 1 |
| Select serial debug interface protocol | DBG_UART | bit | 0 |
| Select serial debug interface protocol | DBG_I2C | bit | 1 |
| I2C broadcast address | DBG_I2C_BROADCASTC | bit | 1 |
| Hardware breakpoint RANGE mode | HWBRK_RANGE | bit | 1 |
| ASIC version | ASIC | bit | 1 |

2.1.2.4. ASIC System Configuration (experts/professionals only)

| Description | Parameter | Type | Default |
|---------------------------------|---------------------|------------|---------|
| LOW POWER MODE: SCG | SCG_EN | bit vector | 1 |
| FINE GRAINED CLOCK GATING | CLOCK_GATING | bit | 1 |
| ASIC CLOCKING | ASIC_CLOCKING | bit | 1 |
| LFXT CLOCK DOMAIN | LFXT_DOMAIN | bit | 1 |
| MCLK: Clock Mux | MCLK_MUX | bit | 1 |
| SMCLK: Clock Mux | SMCLK_MUX | bit | 1 |
| WATCHDOG: Clock Mux | WATCHDOG_MUX | bit | 1 |
| WATCHDOG: Clock No-Mux | WATCHDOG_NOMUX_ACLK | bit | 0 |
| MCLK: Clock divider | MCLK_DIVIDER | bit | 1 |
| SMCLK: Clock divider (/1/2/4/8) | SMCLK_DIVIDER | bit | 1 |
| ACLK: Clock divider (/1/2/4/8) | ACLK_DIVIDER | bit | 1 |
| LOW POWER MODE: CPUOFF | CPUOFF_EN | bit | 1 |
| LOW POWER MODE: OSCOFF | OSCOFF_EN | bit | 1 |

2.1.2.5. System Constants (do not edit)

| Description | Parameter | Type | Default |
|---------------------------|-------------|---------|---------|
| Program Memory Size | PMEM_AWIDTH | integer | 13 |
| Data Memory Size | DMEM_AWIDTH | integer | 11 |
| Peripheral Memory Size | PER_AWIDTH | integer | 8 |
| Data Memory Base Adresses | DMEM_BASE | integer | N |
| Program Memory | PMEM_MSB | integer | N |
| Data Memory | DMEM_MSB | integer | N |
| Peripheral Memory | PER_MSB | integer | N |
| Number of available IRQs | IRQ_NR | integer | 16 |
| Instructions type | INST_SOC | integer | 0 |
| Instructions type | INST_JMPC | integer | 1 |
| Instructions type | INST_TOC | integer | 2 |
| Single-operand arithmetic | RRC | integer | 0 |
| Single-operand arithmetic | SWPB | integer | 1 |
| Single-operand arithmetic | RRA | integer | 2 |

| Description | Parameter | Type | Default |
|---------------------------|-------------|------------|---------|
| Single-operand arithmetic | SXTC | integer | 3 |
| Single-operand arithmetic | PUSH | integer | 4 |
| Single-operand arithmetic | CALL | integer | 5 |
| Single-operand arithmetic | RETI | integer | 6 |
| Single-operand arithmetic | IRQX | integer | 7 |
| Conditional jump | JNE | integer | 0 |
| Conditional jump | JEQ | integer | 1 |
| Conditional jump | JNC | integer | 2 |
| Conditional jump | JC | integer | 3 |
| Conditional jump | JN | integer | 4 |
| Conditional jump | JGE | integer | 5 |
| Conditional jump | JL | integer | 6 |
| Conditional jump | JMP | integer | 7 |
| Two-operand arithmetic | MOV | integer | 0 |
| Two-operand arithmetic | ADD | integer | 1 |
| Two-operand arithmetic | ADDC | integer | 2 |
| Two-operand arithmetic | SUBC | integer | 3 |
| Two-operand arithmetic | SUBB | integer | 4 |
| Two-operand arithmetic | CMP | integer | 5 |
| Two-operand arithmetic | DADD | integer | 6 |
| Two-operand arithmetic | BITC | integer | 7 |
| Two-operand arithmetic | BIC | integer | 8 |
| Two-operand arithmetic | BIS | integer | 9 |
| Two-operand arithmetic | XORX | integer | 10 |
| Two-operand arithmetic | ANDX | integer | 11 |
| Addressing modes | DIR | integer | 0 |
| Addressing modes | IDX | integer | 1 |
| Addressing modes | INDIR | integer | 2 |
| Addressing modes | INDIR_I | integer | 3 |
| Addressing modes | SYMB | integer | 4 |
| Addressing modes | IMM | integer | 5 |
| Addressing modes | ABSC | integer | 6 |
| Addressing modes | CONST | integer | 7 |
| Instruction state machine | I_IRQ_FETCH | bit vector | 000 |
| Instruction state machine | I_IRQ_DONE | bit vector | 001 |
| Instruction state machine | I_DEC | bit vector | 010 |
| Instruction state machine | I_EXT1 | bit vector | 011 |
| Instruction state machine | I_EXT2 | bit vector | 100 |
| Instruction state machine | I_IDLE | bit vector | 101 |
| Execution state machine | E_SRC_AD | bit vector | X5 |
| Execution state machine | E_SRC_RD | bit vector | X6 |
| Execution state machine | E_SRC_WR | bit vector | X7 |
| Execution state machine | E_DST_AD | bit vector | X8 |
| Execution state machine | E_DST_RD | bit vector | X9 |
| Execution state machine | E_DST_WR | bit vector | XA |
| Execution state machine | E_EXEC | bit vector | XB |
| Execution state machine | E_JUMP | bit vector | XC |
| Execution state machine | E_IDLE | bit vector | XD |
| Execution state machine | E_IRQ_0 | bit vector | X2 |
| Execution state machine | E_IRQ_1 | bit vector | X1 |
| Execution state machine | E_IRQ_2 | bit vector | X0 |
| Execution state machine | E_IRQ_3 | bit vector | X3 |

| Description | Parameter | Type | Default |
|--|---------------------|------------|----------|
| Execution state machine | E_IRQ_4 | bit vector | X4 |
| ALU control signals | ALU_SRC_INV | integer | 0 |
| ALU control signals | ALU_INC | integer | 1 |
| ALU control signals | ALU_INC_C | integer | 2 |
| ALU control signals | ALU_ADD | integer | 3 |
| ALU control signals | ALU_AND | integer | 4 |
| ALU control signals | ALU_OR | integer | 5 |
| ALU control signals | ALU_XOR | integer | 6 |
| ALU control signals | ALU_DADD | integer | 7 |
| ALU control signals | ALU_STAT_7 | integer | 8 |
| ALU control signals | ALU_STAT_F | integer | 9 |
| ALU control signals | ALU_SHIFT | integer | 10 |
| ALU control signals | EXEC_NO_WR | integer | 11 |
| Debug interface | DBG_UART_WR | integer | 18 |
| Debug interface | DBG_UART_BW | integer | 17 |
| Debug interface CPU_CTL register | HALT | integer | 0 |
| Debug interface CPU_CTL register | RUN | integer | 1 |
| Debug interface CPU_CTL register | ISTEP | integer | 2 |
| Debug interface CPU_CTL register | SW_BRK_EN | integer | 3 |
| Debug interface CPU_CTL register | FRZ_BRK_EN | integer | 4 |
| Debug interface CPU_CTL register | RST_BRK_EN | integer | 5 |
| Debug interface CPU_CTL register | CPU_RST | integer | 6 |
| Debug interface BRKx_CTL register | BRK_MODE_RD | integer | 0 |
| Debug interface BRKx_CTL register | BRK_MODE_WR | integer | 1 |
| Debug interface BRKx_CTL register | BRK_EN | integer | 2 |
| Debug interface BRKx_CTL register | BRK_I_EN | integer | 3 |
| Debug interface BRKx_CTL register | BRK_RANGE | integer | 4 |
| Basic clock module: BCSCTL2 Control Register | SELMX | integer | 7 |
| Basic clock module: BCSCTL2 Control Register | SELS | integer | 3 |
| MCLK Clock gate | MCLK_CGATE | bit | 1 |
| SMCLK Clock gate | SMCLK_CGATE | bit | 1 |
| Debug interface: CPU version | CPU_VERSION | bit vector | 010 |
| Debug interface: Software breakpoint opcode | DBG_SWBRK_OP | bit vector | X4343 |
| UART interface auto data synchronization | DBG_UART_AUTO_SYNC | bit | 1 |
| Counter width for the debug interface UART | DBG_UART_XFER_CNT_W | integer | 16 |
| Debug UART interface data rate | DBG_UART_BAUD | integer | 2000000 |
| Debug UART interface data rate | DBG_DCO_FREQ | integer | 20000000 |
| Debug UART interface data rate | DBG_UART_CNT | integer | N |
| Debug UART interface data rate | DBG_UART_CNTB | bit vector | N |
| Debug interface input synchronizer | SYNC_DBG_UART_RXD | bit | 1 |
| MULTIPLIER CONFIGURATION | MPY_16X16 | bit | 1 |

2.2. INSTRUCTION CACHE

2.2.1 Instruction INPUTS/OUTPUTS AMBA4 AXI-Lite Bus

2.2.1.1. Signals of the Read and Write Address channels

| Write Port | Read Port | Size | Direction | Description |
|------------|-----------|----------------|-----------|--|
| AWID | ARID | AXI_ID_WIDTH | Output | Address ID, to identify multiple streams |
| AWADDR | ARADDR | AXI_ADDR_WIDTH | Output | Address of the first beat of the burst |

| Write Port | Read Port | Size | Direction | Description |
|------------|-----------|----------------|-----------|--|
| AWLEN | ARLEN | 8 | Output | Number of beats inside the burst |
| AWSIZE | ARSIZE | 3 | Output | Size of each beat |
| AWBURST | ARBURST | 2 | Output | Type of the burst |
| AWLOCK | ARLOCK | 1 | Output | Lock type, to provide atomic operations |
| AWCACHE | ARCACHE | 4 | Output | Memory type, progress through the system |
| AWPROT | ARPROT | 3 | Output | Protection type |
| AWQOS | ARQOS | 4 | Output | Quality of Service of the transaction |
| AWREGION | ARREGION | 4 | Output | Region identifier, physical to logical |
| AWUSER | ARUSER | AXI_USER_WIDTH | Output | User-defined data |
| AWVALID | ARVALID | 1 | Output | xVALID handshake signal |
| AWREADY | ARREADY | 1 | Input | xREADY handshake signal |

2.2.1.2. Signals of the Read and Write Data channels

| Write Port | Read Port | Size | Direction | Description |
|------------|-----------|----------------|-----------|---------------------------------------|
| WID | RID | AXI_ID_WIDTH | Output | Data ID, to identify multiple streams |
| WDATA | RDATA | AXI_DATA_WIDTH | Output | Read/Write data |
| -- | RRESP | 2 | Output | Read response, current RDATA status |
| WSTRB | -- | AXI_STRB_WIDTH | Output | Byte strobe, WDATA signal |
| WLAST | RLAST | 1 | Output | Last beat identifier |
| WUSER | RUSER | AXI_USER_WIDTH | Output | User-defined data |
| WVALID | RVALID | 1 | Output | xVALID handshake signal |
| WREADY | RREADY | 1 | Input | xREADY handshake signal |

2.2.1.3. Signals of the Write Response channel

| Write Port | Size | Direction | Description |
|------------|----------------|-----------|---|
| BID | AXI_ID_WIDTH | Input | Write response ID, to identify multiple streams |
| BRESP | 2 | Input | Write response, to specify the burst status |
| BUSER | AXI_USER_WIDTH | Input | User-defined data |
| BVALID | 1 | Input | xVALID handshake signal |
| BREADY | 1 | Output | xREADY handshake signal |

2.2.2. Instruction INPUTS/OUTPUTS AMBA3 AHB-Lite Bus

| Port | Size | Direction | Description |
|---------|------|-----------|---------------------------------------|
| HRESETn | 1 | Input | Asynchronous Active Low Reset |
| HCLK | 1 | Input | System Clock Input |
| IHSEL | 1 | Output | Instruction Bus Select |
| IHADDR | PLEN | Output | Instruction Address Bus |
| IHRDATA | XLEN | Input | Instruction Read Data Bus |
| IHWDATA | XLEN | Output | Instruction Write Data Bus |
| IHWRITE | 1 | Output | Instruction Write Select |
| IHSIZE | 3 | Output | Instruction Transfer Size |
| IHBURST | 3 | Output | Instruction Transfer Burst Size |
| IHPROT | 4 | Output | Instruction Transfer Protection Level |

| Port | Size | Direction | Description |
|------------|------|-----------|-----------------------------------|
| IHTRANS | 2 | Output | Instruction Transfer Type |
| IHMASTLOCK | 1 | Output | Instruction Transfer Master Lock |
| IHREADY | 1 | Input | Instruction Slave Ready Indicator |
| IHRESP | 1 | Input | Instruction Transfer Response |

2.2.3. Instruction INPUTS/OUTPUTS Wishbone Bus

| Port | Size | Direction | Description |
|-------|------|-----------|---------------------------------|
| rst | 1 | Input | Synchronous Active High Reset |
| clk | 1 | Input | System Clock Input |
| iadr | AW | Input | Instruction Address Bus |
| idati | DW | Input | Instruction Input Bus |
| idato | DW | Output | Instruction Output Bus |
| isel | DW/8 | Input | Byte Select Signals |
| iwe | 1 | Input | Write Enable Input |
| istb | 1 | Input | Strobe Signal/Core Select Input |
| icyc | 1 | Input | Valid Bus Cycle Input |
| iack | 1 | Output | Bus Cycle Acknowledge Output |
| ierr | 1 | Output | Bus Cycle Error Output |
| iint | 1 | Output | Interrupt Signal Output |

2.3. DATA CACHE

2.3.1. Data INPUTS/OUTPUTS AMBA4 AXI-Lite Bus

2.3.1.1. Signals of the Read and Write Address channels

| Write Port | Read Port | Size | Direction | Description |
|------------|-----------|----------------|-----------|--|
| AWID | ARID | AXI_ID_WIDTH | Output | Address ID, to identify multiple streams |
| AWADDR | ARADDR | AXI_ADDR_WIDTH | Output | Address of the first beat of the burst |
| AWLEN | ARLEN | 8 | Output | Number of beats inside the burst |
| AWSIZE | ARSIZE | 3 | Output | Size of each beat |
| AWBURST | ARBURST | 2 | Output | Type of the burst |
| AWLOCK | ARLOCK | 1 | Output | Lock type, to provide atomic operations |
| AWCACHE | ARCACHE | 4 | Output | Memory type, progress through the system |
| AWPROT | ARPROT | 3 | Output | Protection type |
| AWQOS | ARQOS | 4 | Output | Quality of Service of the transaction |
| AWREGION | ARREGION | 4 | Output | Region identifier, physical to logical |
| AWUSER | ARUSER | AXI_USER_WIDTH | Output | User-defined data |
| AWVALID | ARVALID | 1 | Output | xVALID handshake signal |
| AWREADY | ARREADY | 1 | Input | xREADY handshake signal |

2.3.1.2. Signals of the Read and Write Data channels

| Write Port | Read Port | Size | Direction | Description |
|------------|-----------|--------------|-----------|---------------------------------------|
| WID | RID | AXI_ID_WIDTH | Output | Data ID, to identify multiple streams |

| Write Port | Read Port | Size | Direction | Description |
|------------|-----------|----------------|-----------|-------------------------------------|
| WDATA | RDATA | AXI_DATA_WIDTH | Output | Read/Write data |
| -- | RRESP | 2 | Output | Read response, current RDATA status |
| WSTRB | -- | AXI_STRB_WIDTH | Output | Byte strobe, WDATA signal |
| WLAST | RLAST | 1 | Output | Last beat identifier |
| WUSER | RUSER | AXI_USER_WIDTH | Output | User-defined data |
| WVALID | RVALID | 1 | Output | xVALID handshake signal |
| WREADY | RREADY | 1 | Input | xREADY handshake signal |

2.3.1.3. Signals of the Write Response channel

| Write Port | Size | Direction | Description |
|------------|----------------|-----------|---|
| BID | AXI_ID_WIDTH | Input | Write response ID, to identify multiple streams |
| BRESP | 2 | Input | Write response, to specify the burst status |
| BUSER | AXI_USER_WIDTH | Input | User-defined data |
| BVALID | 1 | Input | xVALID handshake signal |
| BREADY | 1 | Output | xREADY handshake signal |

2.3.2. Data INPUTS/OUTPUTS AMBA3 AHB-Lite Bus

| Port | Size | Direction | Description |
|------------|------|-----------|--------------------------------|
| HRESETn | 1 | Input | Asynchronous Active Low Reset |
| HCLK | 1 | Input | System Clock Input |
| DHSEL | 1 | Output | Data Bus Select |
| DHADDR | PLEN | Output | Data Address Bus |
| DHRDATA | XLEN | Input | Data Read Data Bus |
| DHWDATA | XLEN | Output | Data Write Data Bus |
| DHWRITE | 1 | Output | Data Write Select |
| DHSIZE | 3 | Output | Data Transfer Size |
| DHBURST | 3 | Output | Data Transfer Burst Size |
| DHPROT | 4 | Output | Data Transfer Protection Level |
| DHTRANS | 2 | Output | Data Transfer Type |
| DHMASTLOCK | 1 | Output | Data Transfer Master Lock |
| DHREADY | 1 | Input | Data Slave Ready Indicator |
| DHRESP | 1 | Input | Data Transfer Response |

2.3.3. Data INPUTS/OUTPUTS Wishbone Bus

| Port | Size | Direction | Description |
|-------|------|-----------|-------------------------------|
| rst | 1 | Input | Synchronous Active High Reset |
| clk | 1 | Input | System Clock Input |
| dadr | AW | Input | Data Address Bus |
| ddati | DW | Input | Data Input Bus |
| ddato | DW | Output | Data Output Bus |
| dsel | DW/8 | Input | Byte Select Signals |
| dwe | 1 | Input | Write Enable Input |

| Port | Size | Direction | Description |
|-------------------|------|-----------|---------------------------------|
| <code>dstb</code> | 1 | Input | Strobe Signal/Core Select Input |
| <code>dcyc</code> | 1 | Input | Valid Bus Cycle Input |
| <code>dack</code> | 1 | Output | Bus Cycle Acknowledge Output |
| <code>derr</code> | 1 | Output | Bus Cycle Error Output |
| <code>dint</code> | 1 | Output | Interrupt Signal Output |

2.4. OPENRISC ARCHITECTURE

2.4.1. Library

2.4.2. Toolchain

2.4.3. Software

3. WORKFLOW

1. System Level (SystemC/SystemVerilog)

The System Level abstraction of a system only looks at its biggest building blocks like processing units or peripheral devices. At this level the circuit is usually described using traditional programming languages like SystemC or SystemVerilog. Sometimes special software libraries are used that are aimed at simulation circuits on the system level. The IEEE 1685-2009 standard defines the IP-XACT file format that can be used to represent designs on the system level and building blocks that can be used in such system level designs.

2. Behavioral & Register Transfer Level (VHDL/Verilog)

At the Behavioural Level abstraction a language aimed at hardware description such as Verilog or VHDL is used to describe the circuit, but so-called behavioural modeling is used in at least part of the circuit description. In behavioural modeling there must be a language feature that allows for imperative programming to be used to describe data paths and registers. This is the `always`-block in Verilog and the `process`-block in VHDL.

A design in Register Transfer Level representation is usually stored using HDLs like Verilog and VHDL. But only a very limited subset of features is used, namely minimalistic `always` blocks (Verilog) or `process` blocks (VHDL) that model the register type used and unconditional assignments for the datapath logic. The use of HDLs on this level simplifies simulation as no additional tools are required to simulate a design in Register Transfer Level representation.

3. Logical Gate

At the Logical Gate Level the design is represented by a netlist that uses only cells from a small number of single-bit cells, such as basic logic gates (AND, OR, NOT, XOR, etc.) and registers (usually D-Type Flip-flops). A number of netlist formats exists that can be used on this level such as the Electronic Design Interchange Format (EDIF), but for ease of simulation often a HDL netlist is used. The latter is a HDL file (Verilog or VHDL) that only uses the most basic language constructs for instantiation and connecting of cells.

4. Physical Gate

On the Physical Gate Level only gates are used that are physically available on the target architecture. In some cases this may only be NAND, NOR and NOT gates as well as D-Type registers. In the case of an FPGA-based design the Physical Gate Level representation is a netlist of LUTs with optional output registers, as these are the basic building blocks of FPGA logic cells.

5. Switch Level

A Switch Level representation of a circuit is a netlist utilizing single transistors as cells. Switch Level modeling is possible in Verilog and VHDL, but is seldom used in modern designs, as in modern digital ASIC or FPGA flows the physical gates are considered the atomic build blocks of the logic circuit.

3.1. FRONT-END OPEN SOURCE TOOLS

3.1.1. Modeling System Level of Hardware

A System Description Language Editor is a computer tool that allows to generate software code. A System Description Language is a formal language, which comprises a Programming Language (input), producing a Hardware Description (output). Programming languages are used in computer programming to implement algorithms. The description of a programming language is split into the two components of syntax (form) and semantics (meaning).

System Description Language Editor

type:

```
git clone https://github.com/emacs-mirror/emacs
```

3.1.2. Simulating System Level of Hardware

A System Description Language Simulator (translator) is a computer program that translates computer code written in a Programming Language (the source language) into a Hardware Description Language (the target language). The compiler is primarily used for programs that translate source code from a high-level programming language to a low-level language to create an executable program.

SystemVerilog System Description Language Simulator

type:

```
git clone http://git.veripool.org/git/verilator
```

```
cd verilator
autoconf
./configure
make
sudo make install

cd sim/verilog/regression/wb/vtor
source SIMULATE-IT

cd sim/verilog/regression/ahb3/vtor
source SIMULATE-IT

cd sim/verilog/regression/axi4/vtor
source SIMULATE-IT
```

3.1.3. Verifying System Level of Hardware

A UVM standard improves interoperability and reduces the cost of repurchasing and rewriting IP for each new project or Electronic Design Automation tool. It also makes it easier to reuse verification components. The UVM Class Library provides generic utilities, such as component hierarchy, Transaction Library Model or configuration database, which enable the user to create virtually any structure wanted for the testbench.

SystemVerilog System Description Language Verifier

type:

```
git clone https://github.com/QueenField/UVM
```

3.1.4. Describing Register Transfer Level of Hardware

A Hardware Description Language Editor is any editor that allows to generate hardware code. Hardware Description Language is a specialized computer language used to describe the structure and behavior of digital logic circuits. It allows for the synthesis of a HDL into a netlist, which can then be synthesized, placed and routed to produce the set of masks used to create an integrated circuit.

Hardware Description Language Editor

type:

```
git clone https://github.com/emacs-mirror/emacs
```

3.1.5. Simulating Register Transfer Level of Hardware

A Hardware Description Language Simulator uses mathematical models to replicate the behavior of an actual hardware device. Simulation software allows for modeling of circuit operation and is an invaluable analysis tool. Simulating a circuit's behavior before actually building it can greatly improve design efficiency by making faulty designs known as such, and providing insight into the behavior of electronics circuit designs.

VHDL Hardware Description Language Simulator

type:

```
git clone https://github.com/ghdl/ghdl
```

```
cd ghdl
./configure --prefix=/usr/local
make
sudo make install

cd sim/vhdl/regression/wb/ghdl
source SIMULATE-IT

cd sim/vhdl/regression/ahb3/ghdl
source SIMULATE-IT

cd sim/vhdl/regression/axi4/ghdl
source SIMULATE-IT
```

Verilog Hardware Description Language Simulator

type:

```
git clone https://github.com/steveicarus/iverilog
```

```
cd iverilog
sh autoconf.sh
./configure
make
sudo make install

cd sim/verilog/regression/wb/iverilog
source SIMULATE-IT
```

```
cd sim/verilog/regression/ahb3/iverilog
source SIMULATE-IT

cd sim/verilog/regression/axi4/iverilog
source SIMULATE-IT
```

3.1.6. Synthesizing Register Transfer Level of Hardware

A Hardware Description Language Synthesizer turns a RTL implementation into a Logical Gate Level implementation. Logical design is a step in the standard design cycle in which the functional design of an electronic circuit is converted into the representation which captures logic operations, arithmetic operations, control flow, etc. In EDA parts of the logical design is automated using synthesis tools based on the behavioral description of the circuit.

Verilog Hardware Description Language Synthesizer

type:

```
git clone https://github.com/YosysHQ/yosys

cd yosys
make
sudo make install

cd synthesis/yosys
source SYNTHESIZE-IT
```

3.1.7. Optimizing Register Transfer Level of Hardware

A Hardware Description Language Optimizer finds an equivalent representation of the specified logic circuit under specified constraints (minimum area, pre-specified delay). This tool combines scalable logic optimization based on And-Inverter Graphs (AIGs), optimal-delay DAG-based technology mapping for look-up tables and standard cells, and innovative algorithms for sequential synthesis and verification.

Verilog Hardware Description Language Optimizer

type:

```
git clone https://github.com/YosysHQ/yosys

cd yosys
make
sudo make install

cd synthesis/yosys
source SYNTHESIZE-IT
```

3.1.8. Verifying Register Transfer Level of Hardware

A Hardware Description Language Verifier proves or disproves the correctness of intended algorithms underlying a hardware system with respect to a certain formal specification or property, using formal methods of mathematics. Formal verification uses modern techniques (SAT/SMT solvers, BDDs, etc.) to prove correctness by essentially doing an exhaustive search through the entire possible input space (formal proof).

Verilog Hardware Description Language Verifier

type:

```
git clone https://github.com/YosysHQ/SymbiYosys
```

3.2. BACK-END OPEN SOURCE TOOLS

Library

type:

```
sudo apt update
sudo apt upgrade
```

```
sudo apt install bison cmake flex freeglut3-dev libcairo2-dev libgsl-dev \
libncurses-dev libx11-dev m4 python-tk python3-tk swig tcl tcl-dev tk-dev tcsh
```

Back-End Workflow Qflow

type:

```
git clone https://github.com/RTimothyEdwards/qflow
```

```
cd qflow
./configure
make
sudo make install

mkdir qflow
cd qflow
```

3.2.1. Planning Switch Level of Hardware

A Floor-Planner of an Integrated Circuit (IC) is a schematic representation of tentative placement of its major functional blocks. In modern electronic design process floor-plans are created during the floor-planning design stage, an early stage in the hierarchical approach to Integrated Circuit design. Depending on the design methodology being followed, the actual definition of a floor-plan may differ.

Floor-Planner

type:

```
git clone https://github.com/RTimothyEdwards/magic
```

```
cd magic
./configure
make
sudo make install
```

3.2.2. Placing Switch Level of Hardware

A Standard Cell Placer takes a given synthesized circuit netlist together with a technology library and produces a valid placement layout. The layout is optimized according to the aforementioned objectives and ready for cell resizing and buffering, a step essential for timing and signal integrity satisfaction. Physical design flow are iterated a number of times until design closure is achieved.

Standard Cell Placer

type:

```
git clone https://github.com/rubund/graywolf
```

```
cd graywolf
mkdir build
cd build
cmake ..
make
sudo make install
```

3.2.3. Timing Switch Level of Hardware

A Standard Cell Timing-Analyzer is a simulation method of computing the expected timing of a digital circuit without requiring a simulation of the full circuit. High-performance integrated circuits have traditionally been characterized by the clock frequency at which they operate. Measuring the ability of a circuit to operate at the specified speed requires an ability to measure, during the design process, its delay at numerous steps.

Standard Cell Timing-Analyzer

type:

```
git clone https://github.com/The-OpenROAD-Project/OpenSTA
```

```
cd OpenSTA
mkdir build
cd build
cmake ..
make
sudo make install
```

3.2.4. Routing Switch Level of Hardware

A Standard Cell Router takes pre-existing polygons consisting of pins on cells, and pre-existing wiring called pre-routes. Each of these polygons are associated with a net. The primary task of the router is to create geometries such that all terminals assigned to the same net are connected, no terminals assigned to different nets are connected, and all design rules are obeyed.

Standard Cell Router

type:

```
git clone https://github.com/RTimothyEdwards/qrouter
```

```
cd qrouter
./configure
make
sudo make install
```

3.2.5. Simulating Switch Level of Hardware

A Standard Cell Simulator treats transistors as ideal switches. Extracted capacitance and lumped resistance values are used to make the switch a little bit more realistic than the ideal, using the RC time constants to predict the relative timing of events. This simulator represents a circuit in terms of its exact transistor structure but describes the electrical behavior in a highly idealized way.

Standard Cell Simulator

type:

```
git clone https://github.com/RTimothyEdwards/irsim  
  
cd irsim  
./configure  
make  
sudo make install
```

3.2.6. Verifying Switch Level of Hardware LVS

A Standard Cell Verifier compares netlists, a process known as LVS (Layout vs. Schematic). This step ensures that the geometry that has been laid out matches the expected circuit. The greatest need for LVS is in large analog or mixed-signal circuits that cannot be simulated in reasonable time. LVS can be done faster than simulation, and provides feedback that makes it easier to find errors.

Standard Cell Verifier

type:

```
git clone https://github.com/RTimothyEdwards/netgen  
  
cd netgen  
./configure  
make  
sudo make install  
  
cd synthesis/qflow  
source FLOW-IT
```

3.2.7. Checking Switch Level of Hardware DRC

A Standard Cell Checker is a geometric constraint imposed on Printed Circuit Board (PCB) and Integrated Circuit (IC) designers to ensure their designs function properly, reliably, and can be produced with acceptable yield. Design Rules for production are developed by hardware engineers based on the capability of their processes to realize design intent. Design Rule Checking (DRC) is used to ensure that designers do not violate design rules.

Standard Cell Checker

type:

```
git clone https://github.com/RTimothyEdwards/magic  
  
cd magic  
./configure  
make  
sudo make install
```

3.2.8. Printing Switch Level of Hardware GDS

A Standard Cell Editor allows to print a set of standard cells. The standard cell methodology is an abstraction, whereby a low-level VLSI layout is encapsulated into a logical representation. A standard cell is a group of transistor and interconnect structures that provides a boolean logic function (AND, OR, XOR, XNOR, inverters) or a storage function (flipflop or latch).

Standard Cell Editor

type:

```
git clone https://github.com/RTimothyEdwards/magic
```

```
cd magic
./configure
make
sudo make install
```

4. CONCLUSION

4.1. FOR WINDOWS USERS!

1. Settings → Apps → Apps & features → Related settings, Programs and Features → Turn Windows features on or off → Windows Subsystem for Linux
2. Microsoft Store → INSTALL UBUNTU

Library type:

```
sudo apt update
sudo apt upgrade
```

```
sudo apt install bison cmake flex freeglut3-dev libcairo2-dev libgsl-dev \
libncurses-dev libx11-dev m4 python-tk python3-tk swig tcl tcl-dev tk-dev tcsh
```

4.1.1. Front-End

type:

```
sudo apt install verilator
sudo apt install iverilog
sudo apt install ghdl
```

```
cd /mnt/c/./sim/verilog/regression/wb/iverilog
source SIMULATE-IT
```

```
sudo apt install yosys
```

```
cd /mnt/c/./synthesis/yosys
source SYNTHESIZE-IT
```

4.1.2. Back-End

type:

```
mkdir qflow
cd qflow
```

```
git clone https://github.com/RTimothyEdwards/magic
git clone https://github.com/rubund/graywolf
git clone https://github.com/The-OpenROAD-Project/OpenSTA
git clone https://github.com/RTimothyEdwards/qrouter
git clone https://github.com/RTimothyEdwards/irsim
```

```
git clone https://github.com/RTimothyEdwards/netgen
git clone https://github.com/RTimothyEdwards/qflow

cd /mnt/c/./synthesis/qflow
source FLOW-IT
```