

Quantum Field Theory

Problem Sheet 1

Problem 1.

The Klein-Gordon equation is

$$(\partial^\mu \partial_\mu - m^2) \phi = 0$$

$$\therefore \phi^* (\partial^\mu \partial_\mu - m^2) \phi = 0 \quad (1)$$

Taking complex conjugate

$$\phi (\partial^\mu \partial_\mu - m^2) \phi^* = 0 \quad (2)$$

Subtracting (1) from (2)

$$\phi (\partial^\mu \partial_\mu) \phi^* - \phi^* (\partial^\mu \partial_\mu) \phi = 0$$

$$\therefore \phi \frac{\partial^2}{\partial t^2} \phi^* - \phi^* \frac{\partial^2}{\partial t^2} \phi + \phi^* \nabla^2 \phi - \phi \nabla^2 \phi^* = 0$$

$$\therefore \frac{\partial}{\partial t} \left(\phi \frac{\partial \phi^*}{\partial t} - \phi^* \frac{\partial \phi}{\partial t} \right) + \nabla \cdot (\phi^* \nabla \phi - \phi \nabla \phi^*) = 0 \quad (3)$$

$$\text{Since } \frac{\partial}{\partial t} \left(\phi \frac{\partial \phi^*}{\partial t} - \phi^* \frac{\partial \phi}{\partial t} \right) = \frac{\partial \phi}{\partial t} \frac{\partial \phi^*}{\partial t} + \phi \frac{\partial^2 \phi^*}{\partial t^2} - \frac{\partial \phi^*}{\partial t} \frac{\partial \phi}{\partial t} - \phi^* \frac{\partial^2 \phi}{\partial t^2}$$

and similarly for $\nabla \cdot (\phi^* \nabla \phi - \phi \nabla \phi^*)$.

$$\text{but } \mathcal{J}^\mu = i \left(\phi^* \frac{\partial \phi}{\partial t} - \phi \frac{\partial \phi^*}{\partial t}, -(\phi^* \nabla \phi - \phi \nabla \phi^*) \right)$$

$$\therefore \partial_\mu \mathcal{J}^\mu = i \left[\frac{\partial}{\partial t} \left(\phi^* \frac{\partial \phi}{\partial t} - \phi \frac{\partial \phi^*}{\partial t} \right) - \nabla \cdot (\phi^* \nabla \phi - \phi \nabla \phi^*) \right]$$

$$\therefore \partial_\mu \mathcal{T}^\mu = 0 \rightarrow -i \left[\frac{\partial}{\partial t} \left(\phi \frac{\partial \phi^*}{\partial t} - \phi^* \frac{\partial \phi}{\partial t} \right) + \frac{\partial}{\partial x} \left(\phi^* \frac{\partial \phi}{\partial x} - \phi \frac{\partial \phi^*}{\partial x} \right) \right] = 0$$

$$\therefore \text{From (3)} \quad \underline{\underline{\partial_\mu \mathcal{T}^\mu = 0}}$$

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Problem 2

$$\text{For } x < 0, \quad \phi = e^{-iE_p t + ipx} + a e^{-iE_p t - ipx}$$

$$\therefore \frac{\partial \phi}{\partial x} = ip \left(e^{-iE_p t + ipx} - a e^{-iE_p t - ipx} \right)$$

$$\phi^* = e^{+iE_p t - ipx} + a e^{+iE_p t + ipx}$$

$$\frac{\partial \phi^*}{\partial x} = -ip \left(e^{+iE_p t - ipx} + a e^{+iE_p t + ipx} \right)$$

$$\mathcal{T}_x = -i \left(\phi^* \frac{\partial \phi}{\partial x} - \phi \frac{\partial \phi^*}{\partial x} \right)$$

$$= p \left[1 + a \left(e^{iE_p t + ipx} - e^{-iE_p t - ipx} \right) - a^2 \right. \\ \left. + 1 - a \left(e^{iE_p t + ipx} - e^{-iE_p t - ipx} \right) - a^2 \right]$$

$$\therefore \mathcal{T}_x = 2p(1 - a^2)$$

$$\text{But } |a| > 1 \quad \therefore 1 - a^2 < 0$$

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$$\therefore \underline{\underline{\mathcal{T}_x < 0}}$$

$$\mathcal{L} = \phi^* \left(i \frac{\partial}{\partial t} - V \right) \phi + \phi \left(-i \frac{\partial}{\partial t} + V \right) \phi^*$$

$$\text{For } x > 0 \quad \psi = b e^{-iE_p t + i k x}, \quad \psi^* = b e^{+iE_p t - i k x}$$

$$\therefore i \frac{\partial \psi}{\partial t} = E_p b e^{-iE_p t + i k x}, \quad -i \frac{\partial \psi^*}{\partial t} = E_p b e^{+iE_p t - i k x}$$

$$\therefore \rho = b^2 (E_p - V) + b^2 (E_p - V)$$

$$\therefore \rho = 2b^2 (E_p - V).$$

$$\text{But } E_p < V \quad \therefore \underline{\underline{\rho < 0.}} \quad 2$$

$\therefore \rho$ cannot be a probability density and $J_x < 0$ implies more particles reflected than incident. $\therefore \rho$ must be a density of some quantum number, e.g., charge where antiparticles carry opposite to particles, and antiparticles must be created at the boundary. \therefore antiparticles for $x > 0$ and both incident and new particles created at boundary reflected for $x < 0$. 2.

Question 3

In spherical polar coordinates kinetic energy

$$\frac{1}{2} m \dot{r}^2 \quad - \text{ radial}$$

$$\frac{1}{2} m r^2 \dot{\theta}^2 \quad - \text{ motion in } \theta \text{-direction}$$

$$\frac{1}{2} m r^2 \sin^2 \theta \dot{\phi}^2 \quad - \text{ motion in } \phi \text{ direction}$$

$$L = T - V = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2 + r^2 \sin^2 \theta \dot{\phi}^2) - V(r) \quad |$$

Equation of motion $\frac{\partial L}{\partial r} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right)$

$$\frac{\partial L}{\partial \dot{r}} = m\dot{r} \quad \therefore \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) = m\ddot{r}$$

$$\frac{\partial L}{\partial r} = m\dot{\theta}^2 + mr\sin^2\theta\dot{\phi}^2 - \frac{\partial V}{\partial r}$$

$$\therefore \underline{\underline{m\ddot{r} - r(\dot{\theta}^2 + \sin^2\theta\dot{\phi}^2) + \frac{\partial V}{\partial r} = 0}} \quad 2$$

$$H = \sum_i p_i \dot{q}_i - L$$

$$p_r = \frac{\partial L}{\partial \dot{r}} = m\dot{r}, \quad p_\theta = \frac{\partial L}{\partial \dot{\theta}} = mr^2\dot{\theta}, \quad p_\phi = \frac{\partial L}{\partial \dot{\phi}} = mr^2\sin^2\theta\dot{\phi}$$

$$\therefore H = m\dot{r}^2 + mr^2\dot{\theta}^2 + mr^2\sin^2\theta\dot{\phi}^2 - \frac{1}{2}(m\dot{r}^2 + mr^2\dot{\theta}^2 + mr^2\sin^2\theta\dot{\phi}^2) + V(r)$$

$$= \frac{1}{2} (m\dot{r}^2 + mr^2\dot{\theta}^2 + mr^2\sin^2\theta\dot{\phi}^2) + V(r)$$

Now writing in terms of p_r, p_θ, p_ϕ

$$H = \underline{\underline{\frac{p_r^2}{2m} + \frac{p_\theta^2}{2r^2} + \frac{p_\phi^2}{2r^2\sin^2\theta} + V(r)}} \quad 3$$

$$H \text{ independent of } \phi. \quad \therefore \underline{\underline{p_\phi = -\frac{\partial H}{\partial \phi} = 0}}$$

But $p_z =$ angular momentum about z -axis 2 .

4. $a^+ |n\rangle = c_n |n+1\rangle$, where c_n is a normalisation constant.

$$\therefore \langle n | a = \langle n+1 | c_n^*$$

$$\therefore \langle n | a a^+ | n \rangle = \langle n+1 | c_n^* c_n | n+1 \rangle = |c_n|^2.$$

$$a a^+ = 1 + a^+ a$$

$$\text{and } \hat{H} = \omega (a^+ a + \frac{1}{2})$$

$$\therefore a a^+ = 1 + \left(\frac{\hat{H}}{\omega} - \frac{1}{2} \right)$$

$$\text{But } \hat{H} |n\rangle = \omega (n + \frac{1}{2}) |n\rangle$$

$$\begin{aligned} \therefore \langle n | a a^+ | n \rangle &= \langle n | \left(\frac{1}{2} + \frac{\hat{H}}{\omega} \right) | n \rangle \\ &= (n+1) \langle n | n \rangle = n+1 \end{aligned}$$

$$\therefore |c_n|^2 = n+1 \quad \therefore c_n = \sqrt{n+1}.$$

$$\therefore \text{if } |n\rangle = \frac{1}{\sqrt{n!}} (a^+)^n |0\rangle \text{ then } |n+1\rangle = \frac{1}{\sqrt{(n+1)!}} (a^+)^{n+1} |0\rangle$$

$$\text{Consider } |1\rangle = a^+ |0\rangle$$

$$\therefore \langle 1 | 1 \rangle = \langle 0 | a a^+ | 0 \rangle = \langle 0 | 0 \rangle \text{ from above.}$$

\therefore true for $|1\rangle \therefore$ true for all n by induction.

Question 5

The momentum space fields are defined by

$$\tilde{\phi}(p) = \int d^3x \phi(x) e^{-ip \cdot x}$$

$$\tilde{\pi}(p) = \int d^3x \pi(x) e^{-ip \cdot x}$$

$$\therefore [\tilde{\phi}(p), \tilde{\pi}(q)] = \int d^3x d^3y [\phi(x), \pi(y)] e^{-ip \cdot x - iq \cdot y}$$

$$\text{Using } [\phi(x), \pi(y)] = i \delta^3(x-y)$$

$$\rightarrow [\tilde{\phi}(p), \tilde{\pi}(q)] = i \int d^3x d^3y \delta^3(x-y) e^{-ip \cdot x - iq \cdot y}$$

$$= i \int d^3x e^{-ip \cdot x - iq \cdot y}$$

$$= \underline{\underline{i (2\pi)^3 \delta(p+q)}}$$

(using our convention for normalization of Fourier transforms).

$$a_p = E(p) \tilde{\phi}(p) + i \tilde{\pi}(p)$$

$$a_p^\dagger = E(-p) \tilde{\phi}(-p) - i \tilde{\pi}(-p) = E(p) \tilde{\phi}(p) - i \tilde{\pi}(p)$$

Hence,

$$[a_p, a_q^\dagger] = a_p a_q^\dagger - a_q^\dagger a_p$$

$$= (E(q) \tilde{\phi}(q) + i \tilde{\pi}(q)) (E(p) \tilde{\phi}(p) - i \tilde{\pi}(p)) \\ - (E(p) \tilde{\phi}(p) - i \tilde{\pi}(p)) (E(q) \tilde{\phi}(q) + i \tilde{\pi}(q))$$

$$= E(p)E(z) (\tilde{\phi}(p)\tilde{\phi}(z) - \tilde{\phi}(z)\tilde{\phi}(p) + (\tilde{\pi}(z)\tilde{\pi}(p) - \tilde{\pi}(p)\tilde{\pi}(z)) - iE(z) (\tilde{\phi}(z)\tilde{\pi}(p) - \tilde{\pi}(p)\tilde{\phi}(z)) - iE(p) (\tilde{\phi}(p)\tilde{\pi}(z) - \tilde{\pi}(z)\tilde{\phi}(p))$$

$$\text{But } (\tilde{\phi}(p)\tilde{\phi}(z) - \tilde{\phi}(z)\tilde{\phi}(p)) = (\tilde{\pi}(z)\tilde{\pi}(p) - \tilde{\pi}(p)\tilde{\pi}(z)) = 0$$

$$\therefore [\alpha_z, \alpha_p^\dagger] = -iE(z) [\tilde{\phi}(z), \tilde{\pi}(p)] - iE(p) [\tilde{\phi}(p), \tilde{\pi}(z)] \\ = -iE(z) (i(2\pi)^3 \delta^3(p-z)) - iE(p) (i(2\pi)^3 \delta^3(p-z))$$

The delta-function enforces $E(z) = E(p)$

$$\therefore \underline{[\alpha_z, \alpha_p^\dagger] = (2\pi)^3 2E(p) \delta^3(p-z)}$$

Question 6

$$\langle z | p \rangle = \langle 0 | \alpha_z \alpha_p^\dagger | 0 \rangle$$

$$= \langle 0 | \alpha_p^\dagger \alpha_z | 0 \rangle + \langle 0 | [\alpha_z, \alpha_p^\dagger] | 0 \rangle$$

$\alpha_z | 0 \rangle = 0$ so first term $= 0$.

$$\therefore \langle z | p \rangle = \langle 0 | (2\pi)^3 2E(p) \delta^3(p-z) | 0 \rangle \\ = (2\pi)^3 2E(p) \delta^3(p-z).$$

$$\therefore \int \frac{d^3 p}{(2\pi)^3 2E(p)} \langle z | p \rangle = \int \frac{d^3 p}{(2\pi)^3 2E(p)} (2\pi)^3 2E(p) \delta^3(p-z)$$

$$= \int \frac{d^3 p}{(2\pi)^3} \delta^3(p-z) = 1.$$

Question 7

The unequal time commutator is given in the notes as

$$[\phi(x), \phi(y)] = \int \frac{d^3 p}{2E(p)(2\pi)^3} (e^{-ip \cdot (x-y)} - e^{ip \cdot (x-y)}).$$

For space-like separations we have $(x-y)^2 < 0$.

All possible values can be obtained by setting $t_1 = t_2$ and varying $|\mathbf{x} - \mathbf{y}|^2$. Since $[\phi(x), \phi(y)]$ is Lorentz invariant this will span all possible $(x-y)^2 < 0$ values.

$$\rightarrow [\phi(x), \phi(y)] = \int \frac{d^3 p}{2E(p)(2\pi)^3} (e^{ip \cdot (x-y)} - e^{-ip \cdot (x-y)})$$

$$= \int \frac{d^3 p}{(2\pi)^3 2E(p)} e^{ip \cdot (x-y)} - \int \frac{d^3 p}{2E(p)(2\pi)^3} e^{-ip \cdot (x-y)}.$$

Letting $p \rightarrow -p$ in second term $\int d^3 p$ unchanged

$$\rightarrow [\phi(x), \phi(y)] = \int \frac{d^3 p}{2E(p)(2\pi)^3} e^{ip \cdot (x-y)} - \int \frac{d^3 p}{(2E(p)(2\pi)^3} e^{ip \cdot (x-y)}$$

$$= 0.$$

$$\phi(x) = \int \frac{d^3 p}{2E(p)} \frac{1}{(2\pi)^3} (a_p e^{-ip \cdot x} + a_p^\dagger e^{ip \cdot x})$$

$$\pi(y) = i \int \frac{d^3 p}{2(2\pi)^3} (-a_p e^{-ip \cdot x} + a_p^\dagger e^{ip \cdot x})$$

$$\therefore [\phi(x), \pi(y)] = i \int \int \frac{d^3 p}{2E(p)(2\pi)^3} \frac{d^3 q}{2(2\pi)^3} [a_p e^{-ip \cdot x} + a_p^\dagger e^{ip \cdot x}] (a_q e^{-iq \cdot y} + a_q^\dagger e^{iq \cdot y})$$

$$= i \int \int \frac{d^3 p}{2E(p)(2\pi)^3} \frac{d^3 q}{2(2\pi)^3} (-[a_p^\dagger, a_q] e^{ip \cdot x - iq \cdot y} + [a_p, a_q^\dagger] e^{iq \cdot y - ip \cdot x})$$

Using the fact that $[a_p, a_q] = [a_p^\dagger, a_q^\dagger] = 0$

$$= i \int \int \frac{d^3 p}{2E(p)(2\pi)^3} \frac{d^3 q}{2(2\pi)^3} ((2\pi)^3 2E(p)) (e^{iq \cdot y - ip \cdot x} + e^{ip \cdot x - iq \cdot y}) \times \delta^3(p - q)$$

$$\therefore [\phi(x), \pi(y)] = i \int \frac{d^3 p}{2(2\pi)^3} (e^{-ip \cdot (x-y)} + e^{ip \cdot (x-y)})$$

Setting $t_1 = t_2$

$$[\phi(x), \pi(y)] = i \int \frac{d^3 p}{2(2\pi)^3} (e^{-ip \cdot (x-y)} + e^{ip \cdot (x-y)})$$

Again letting $p \rightarrow -p$ in the second term

$$[\phi(x), \pi(y)] = i \int \frac{d^3 p}{2(2\pi)^3} [e^{-ip \cdot (x-y)} + e^{-ip \cdot (x-y)}]$$

$$= i \int \frac{d^3 p}{(2\pi)^3} e^{-ip \cdot (x-y)}$$

$$= i (2\pi)^3 \delta(x-y) / (2\pi)^3$$

$$\therefore \underline{[\phi(x), \pi(y)] = i \delta(x-y)}$$