

Lecture 3: Region Based Vision

Spring 2021

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Handouts & Lecture Notes

- Report in Scientific American (June 2014):
“In each study, however, those who wrote out their notes by hand had a stronger conceptual understanding and were more successful in applying and integrating the material than those who used [sic] took notes with their laptops.”

The Pen Is Mightier Than the Keyboard

P. A. Mueller, D. M. Oppenheimer, *Psychological Science*, Vol 25, Issue 6, pp. 1159 – 1168, April-23-2014.

- Handouts are to aid note taking, not a total replacement for note taking
- Podcasts, slides, pdfs etc on BlackBoard

Segmenting an Image

Assigning labels to pixels (cat, ball, floor)

- **Point processing:**

- colour or grayscale values, thresholding

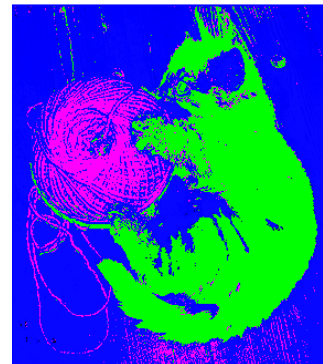
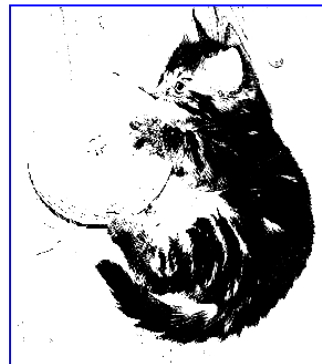
- **Neighbourhood Processing:**

- Regions of similar colours or textures

- **Edge information (next lecture)**

- **Prior information: (model-based vision)**

- I know what I expect a cat to look like

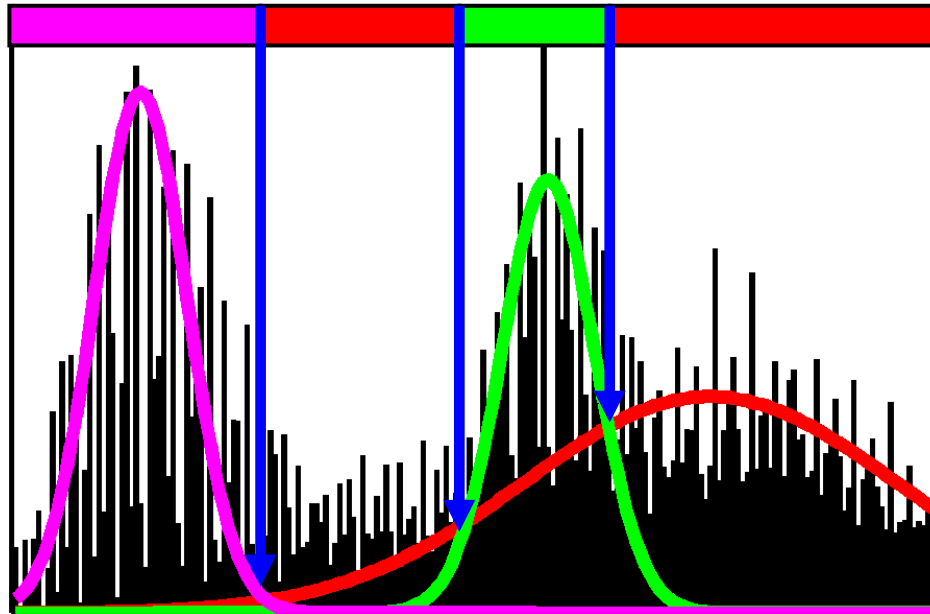


Overview

- **Automatic threshold detection**
 - Earlier, we did this by inspection/guessing
- **Multi-Spectral segmentation**
 - Satellite & medical image data
- **Split and Merge**
 - Hierarchical, region-based approach
- **Relaxation labelling**
 - Probabilistic, learning approach
- **Segmentation as optimisation**

Automatic Threshold Selection

Automatic Thresholding: GMM

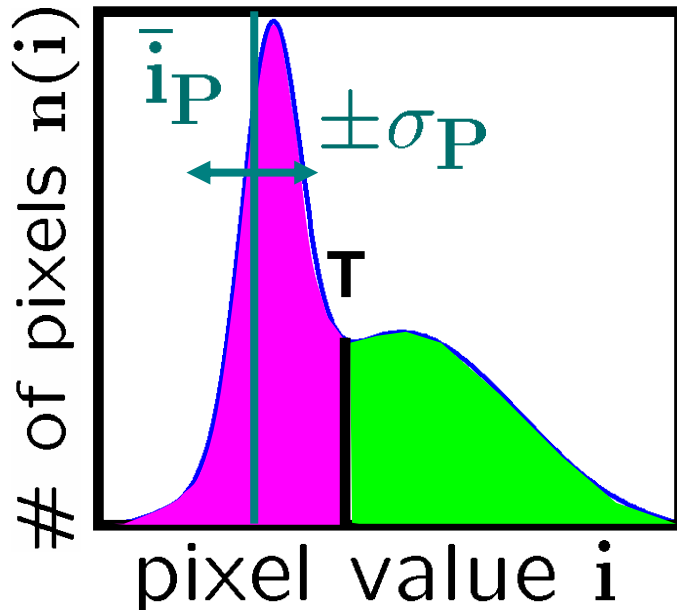


Segmentation Rule

Image
Histogram

- Assume scene mixture of substances, each with normal/gaussian distribution of possible image values
- Minimum error in probabilistic terms
- But mixture of gaussians not easy to find
- Doesn't always fit actual distribution

Automatic Thresholding: Otsu's Method



Mean across purples:

$$\bar{i}_P = \frac{1}{N_P} \sum_{i=0}^T i \times n(i)$$

Variance for purples:

$$\sigma_P^2 = \frac{1}{N_P} \sum_{i=0}^T n(i) [i - \bar{i}_P]^2$$

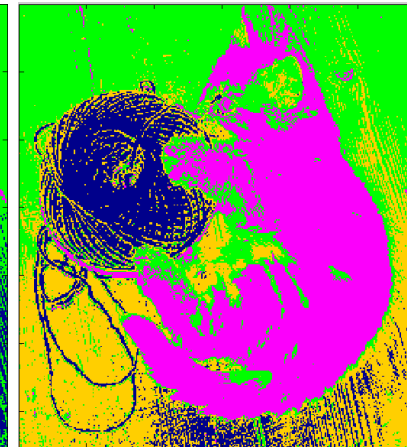
Choose T to minimize:

$$N_P \sigma_P^2 + N_G \sigma_G^2$$

- Extend to multiple classes

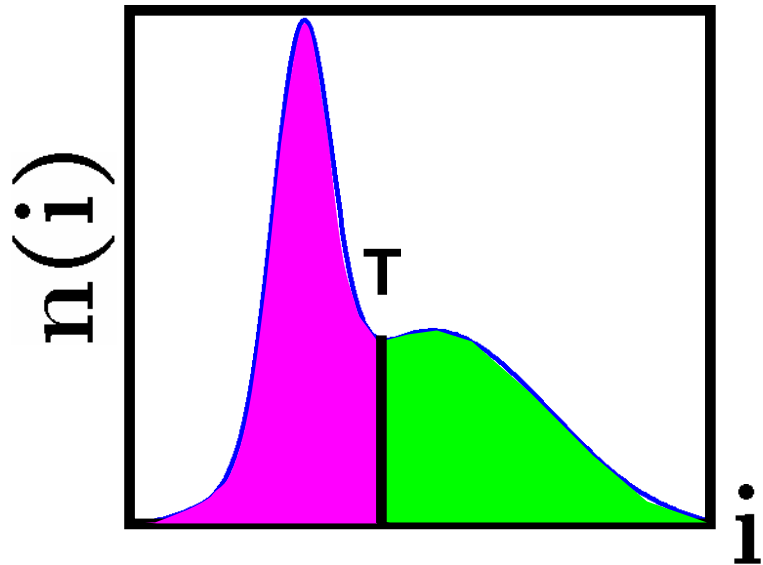


3



4

Automatic Thresholding: Max Entropy



For two sub-populations:

$$p_P(i) = \frac{n(i)}{N_P}, \quad i < T,$$

$$p_G(i) = \frac{n(i)}{N_G}, \quad i \geq T.$$

Entropy: $-\sum p \ln p$

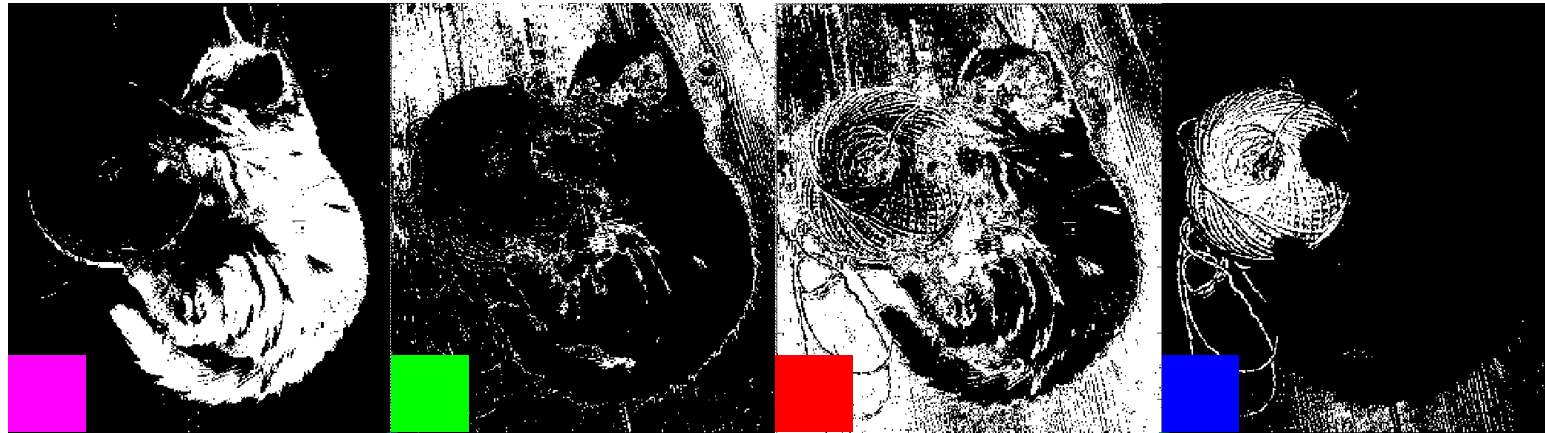
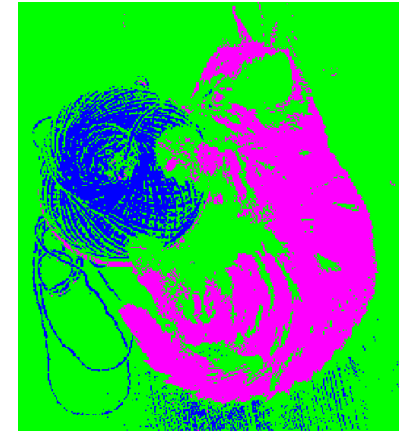
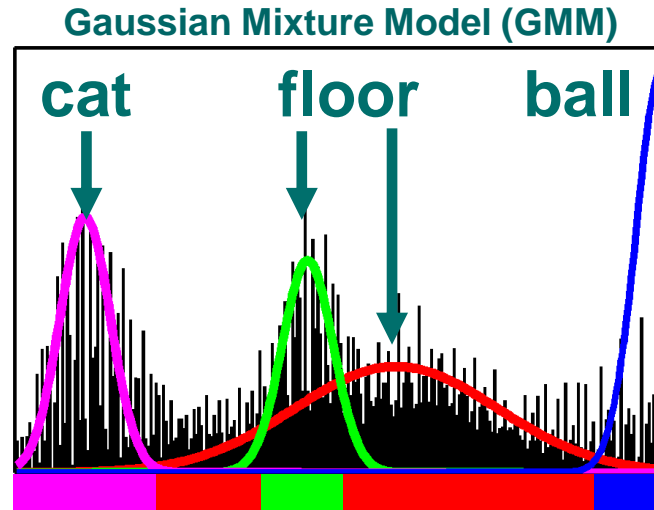
Two Entropies:

$$H_P = - \sum_{i < T} p_P(i) \ln p_P(i) \quad \& \quad H_G = - \sum_{i \geq T} p_G(i) \ln p_G(i)$$

Minimise: $H_G + H_P$ to find T .

- Makes two sub-populations as peaky as possible

Automatic Thresholding: Example



combine

Automatic Thresholding: Summary

- **Geometric shape of histogram (bumps, curves etc)**
 - Algorithm or just by inspection
- **Statistics of sub-populations**
 - Otsu & variance
 - Entropy methods
- **Model-based methods:**
 - Sum of gaussians, gaussians & partial voluming etc.
- **Detailed comparative evaluations for 40 methods**
 - Sezgin M, Sankur B; Survey over image thresholding techniques and quantitative performance evaluation.
Journal of Electronic Imaging, 13(1): pages 146-168, (2004).
- **Fundamental limit on effectiveness:**
 - Never be perfect if distributions overlap (two objects, shared colour!)
- **Whatever method, need further processing**

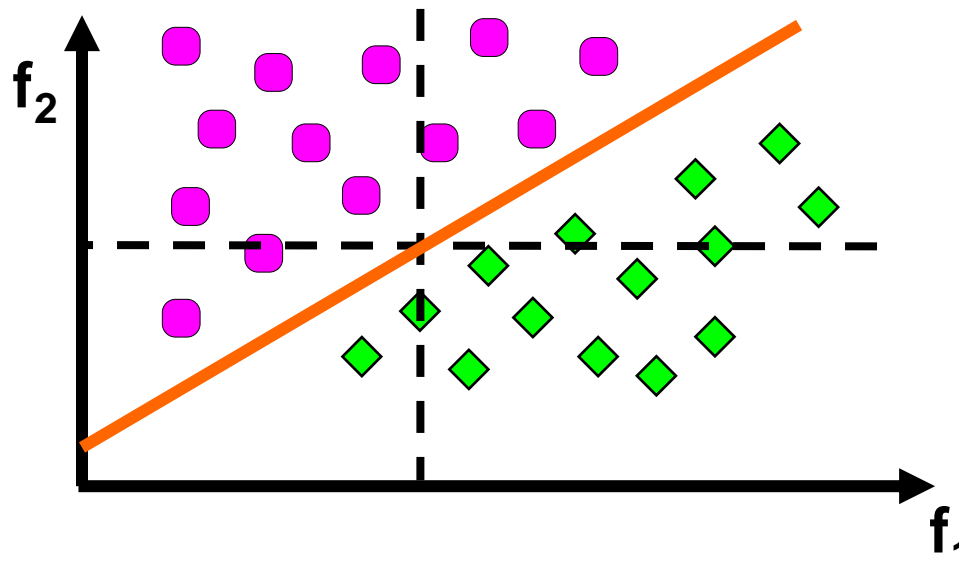
Multi-Spectral Segmentation

Multi-spectral Segmentation

- Multiple measurements at each pixel:

- Satellite remote imaging, various wavebands
- MR imaging, various imaging sequences
- Colour (RGB channels, HSV etc)
- Multispectral imaging of historical documents (visible+IR+UV)

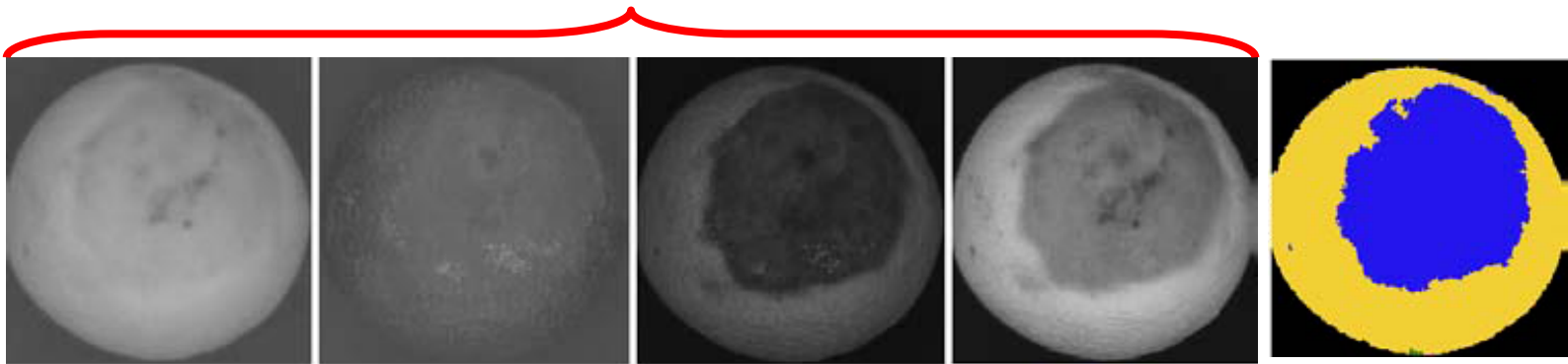
- Scattergram of pixels in vector space:



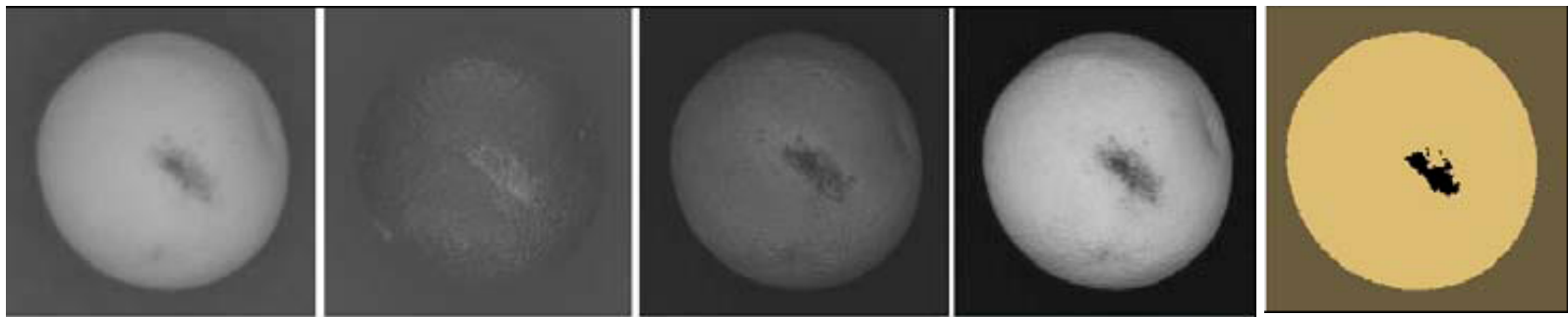
- Can't separate using single measurement
- Can using multiple

Multi-Spectral Segmentation: Example

Spectral Bands



Over-ripe Orange



Scratched Orange

Multispectral Image Segmentation by Energy Minimization for Fruit Quality Estimation:
Martínez-Usó, Pla, and García-Sevilla, Pattern Recognition and Image Analysis , 2005

Split and Merge

Split and Merge/Quadtree Segmentation

- Obvious approaches to segmentation:

- Start from small regions and stitch them together
- Start from large regions and split them

} **Combine**

- Start with large regions , **split** non-uniform regions

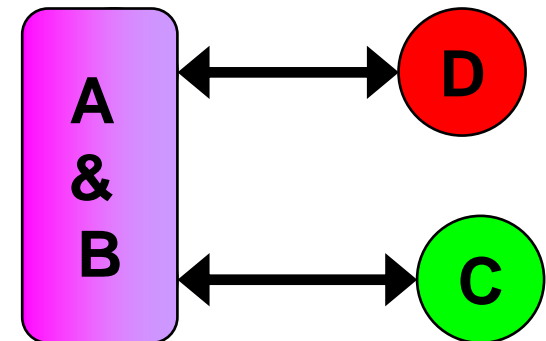
- e.g. variance $\sigma^2 > \text{threshold}$

- **Merge** similar adjacent regions

- e.g. combined variance $\sigma^2 < \text{threshold}$

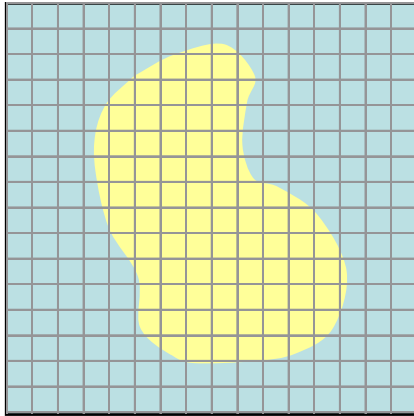
- Region adjacency graph

- housekeeping for adjacency as regions become irregular
- regions are nodes, adjacency relations arcs
- simple update rules during splitting and merging

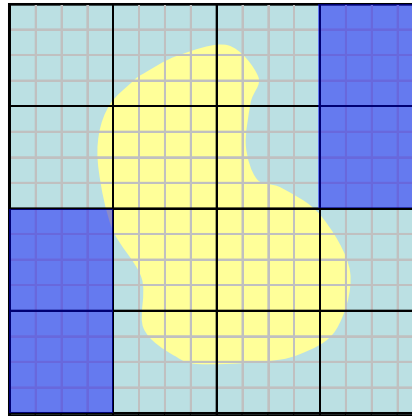


Split and Merge/Quadtree Segmentation

Original

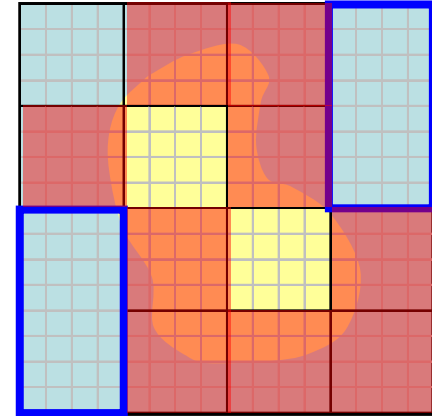


Split



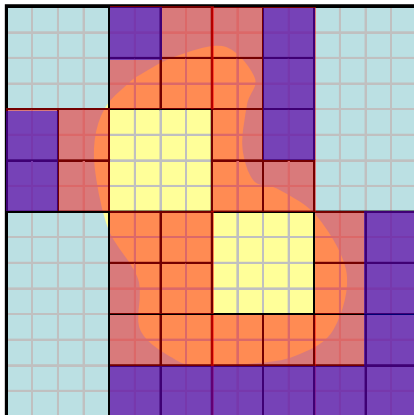
Low Variance Regions

Merge



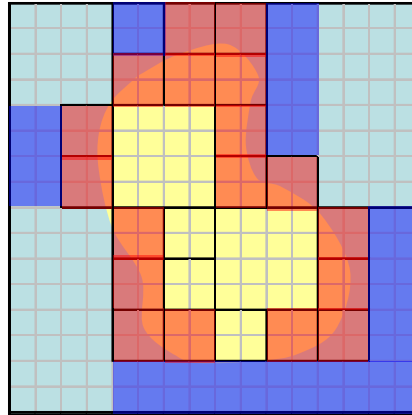
High Variance Regions

Split



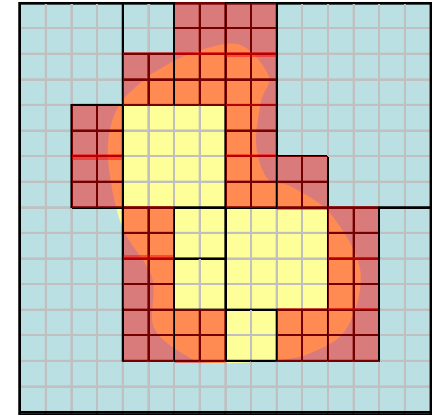
Low Variance Regions

Merge



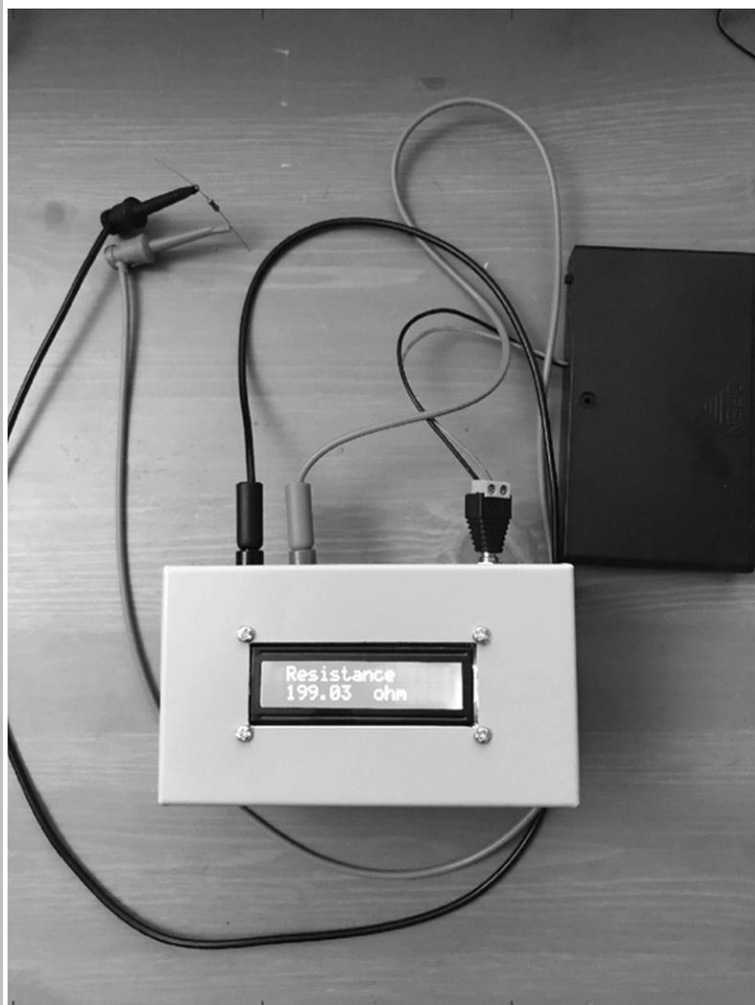
High Variance Regions

Split

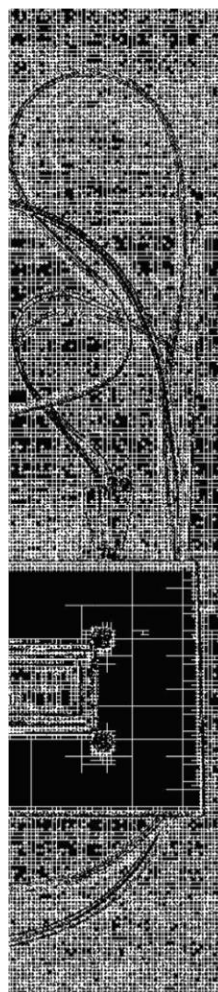


Split & Merge: Example

Result



Original



Detail of Blocks



Relaxation Labelling

Aside: Conditional Probability

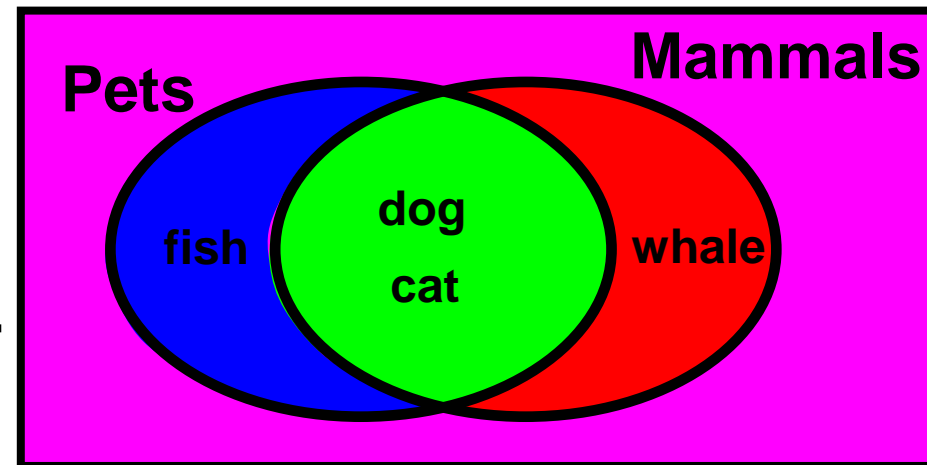
probability of A given that B is the case

$$P(A | B)$$

- $P(\text{pet}) = \frac{(\text{green} + \text{blue})}{\text{ALL}}$ etc
- $P(\text{pet} | \text{mammal}) = \frac{\text{green}}{(\text{green} + \text{red})}$
- $P(\text{mammal} | \text{pet}) = \frac{\text{green}}{(\text{green} + \text{blue})}$
- Bayes Theorem:

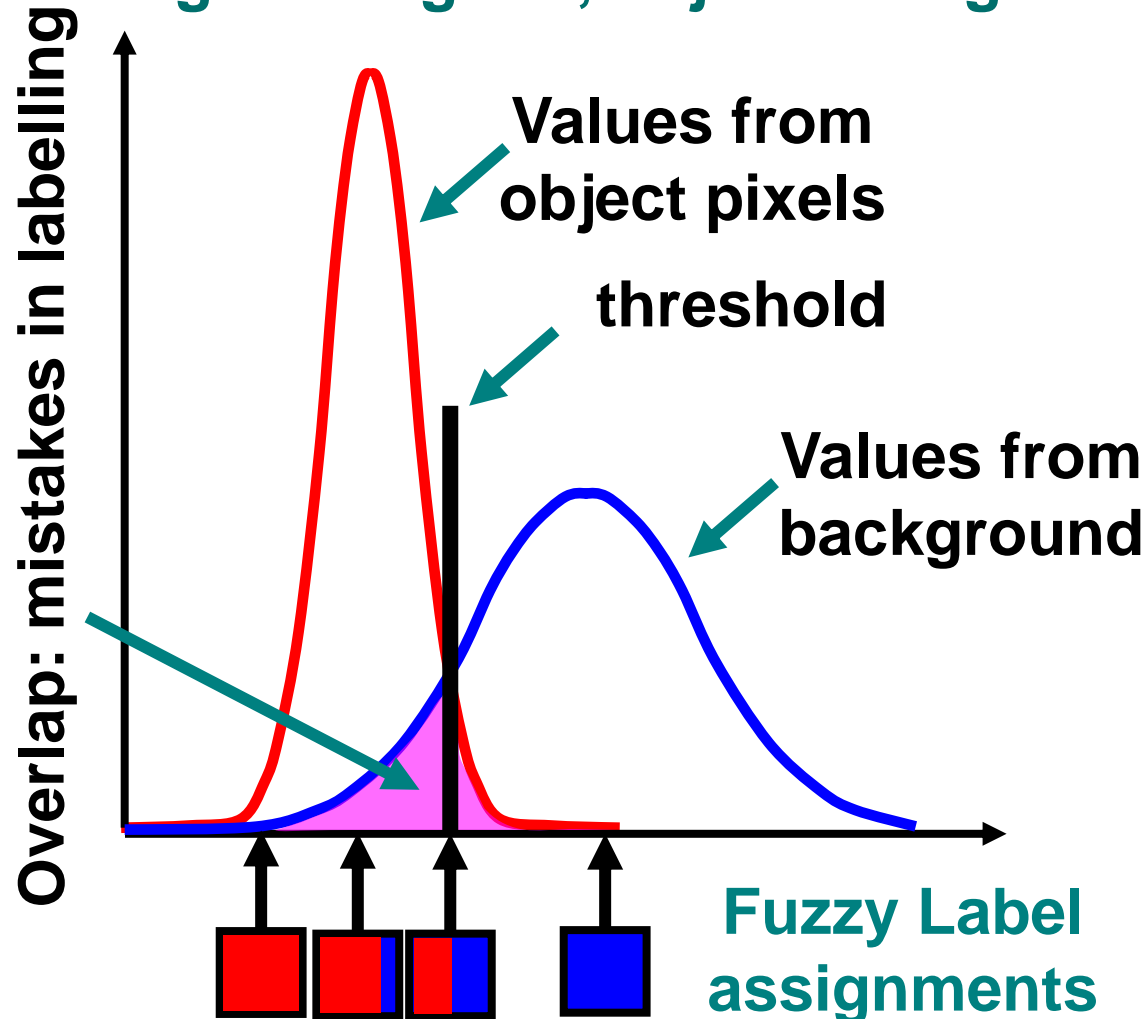
$$\frac{\text{green}}{(\text{green} + \text{red})} \times \frac{(\text{green} + \text{red})}{\text{ALL}} = \frac{\text{green}}{(\text{green} + \text{blue})} \times \frac{(\text{green} + \text{blue})}{\text{ALL}}$$

- $P(\text{pet} | \text{mammal})P(\text{mammal}) = P(\text{mammal} | \text{pet})P(\text{pet})$

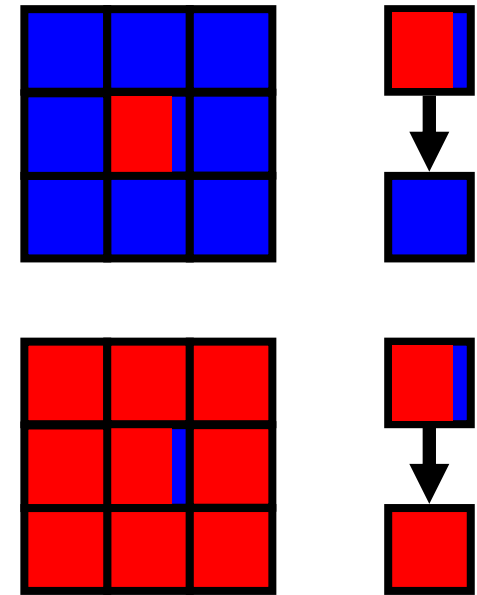


Relaxation Labelling:

- Image histogram, object/background



Context:



Relaxation Labelling

- Evidence for a label at a pixel:
 - Measurements at that pixel (e.g., pixel value)
 - Context for that pixel (i.e., what neighbours are doing)
- Iterative approach, labelling evolves
- Soft-assignment of labels:

Possible labels: $\{l_\mu : \mu = 1, \dots, n\}$

$P_i(\mu)$: Probability that pixel i has label l_μ .

$\sum_\mu P_i(\mu) \equiv 1$. normalised probability.

- Soft-assignment allows you to consider all possibilities
- Let context act to find stable solution

Relaxation Labelling

● Compatibility:

Pixels i and j , labels μ and ν :

no effect $c_{i,j}(\mu, \nu) = 0$

If not neighbours

support (+ve) $c_{i,j}(\mu, \mu) = \alpha$

Neighbours & same label

oppose (-ve) $c_{i,j}(\mu, \nu) = -\alpha$ if $\mu \neq \nu$

Neighbours & different label

● Contextual support for label μ at pixel i :

$$s_i(\mu) \propto \sum_{j \neq i} \sum_{\nu} c_{i,j}(\mu, \nu) P_j(\nu)$$

look at all
other pixels

degree of
compatibility

all possible
labels & how
strong

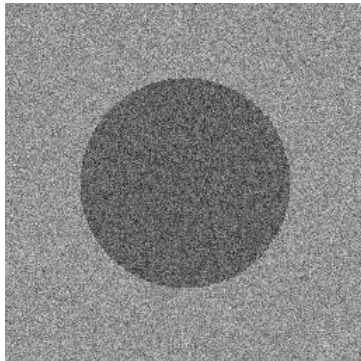
Relaxation Labelling:

- Update soft labelling given context:

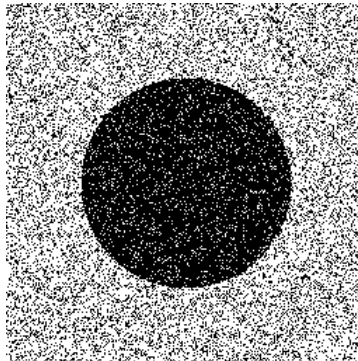
$$P_i(\mu) \leftarrow A_i P_i(\mu) (1 + s_i(\mu))$$

A_i chosen so sums to 1 at i .

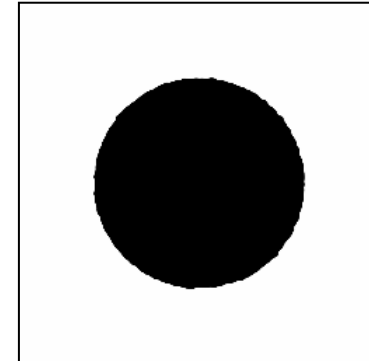
- The more support, more likely the label
- Iterate



Noisy
Image



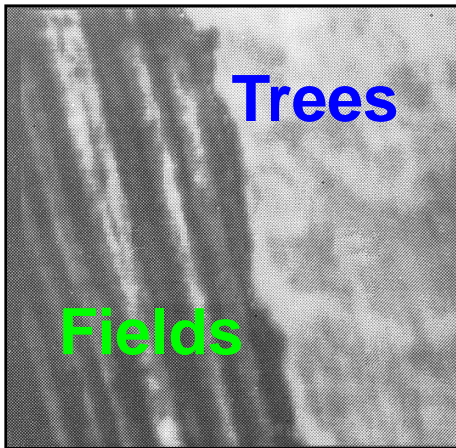
Threshold
labelling



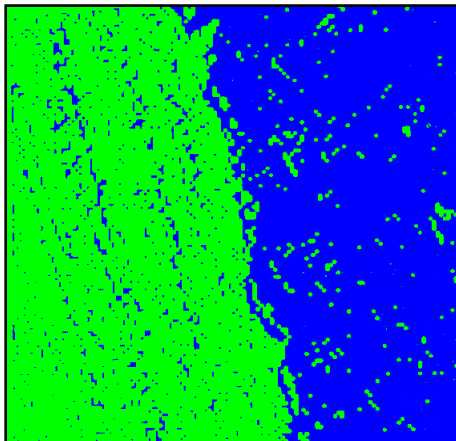
After
iterating

Relaxation Labeling:

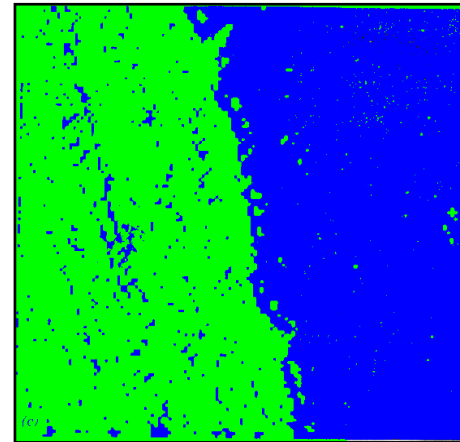
- Value of α alters final result



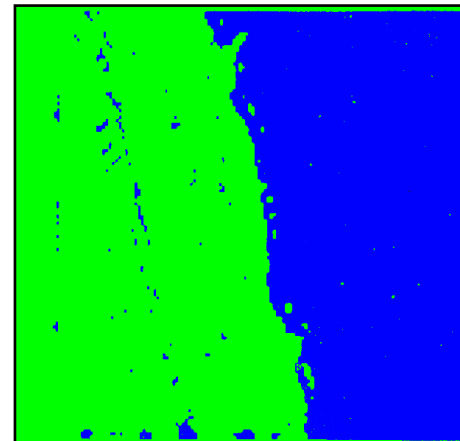
Initialisation



$\alpha = 0.75$



$\alpha = 0.90$



Segmentation as Optimisation

Segmentation as Optimisation

Image: \mathcal{I} , value at pixel i : $\mathcal{I}(i)$

Label Image: L , label at pixel i : $L(i)$

Label configuration in neighbourhood of i : $l(i)$

- Maximise probability of labelling given image:

$$P(L|\mathcal{I}) = \prod_i P(L(i)|\mathcal{I}(i)) P(L(i)|l(i))$$

i label at i given value at i label at i given labels in neighbourhood of i

- Re-write by taking logs, minimise cost function:

$$C(L, \mathcal{I}) = \sum_i [-\log P(L(i)|\mathcal{I}(i)) - \log P(L(i)|l(i))]$$

i label-data match label consistency

- How to find the appropriate form for the two terms?
- How to find the optimum?

Segmentation as Optimisation

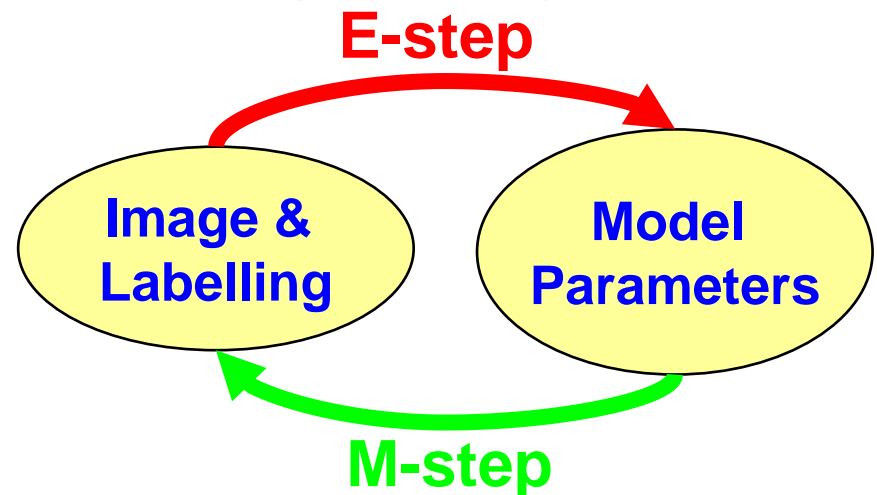
- $P(L(i)|l(i))$ ● Exact form depends on type of data
label consistency ● Histogram gives: $p(\mathcal{I}(i))$
 $P(L(i)|\mathcal{I}(i))$ ● Model of histogram $P(L(i)|\mathcal{I}(i))$
label-data match (e.g., sum of gaussians, relaxation case)

Learning approach:

- Explicit training data (i.e., similar labelled images)
- Unsupervised, from image itself (e.g., histogram model):

Expectation/Maximization

- Given labels, construct model
- Given model, update labels
- Repeat



Segmentation as Optimisation

- General case:

Cost function: $C(L, \mathcal{I}) =$ label-data
match term $+$ label
consistency

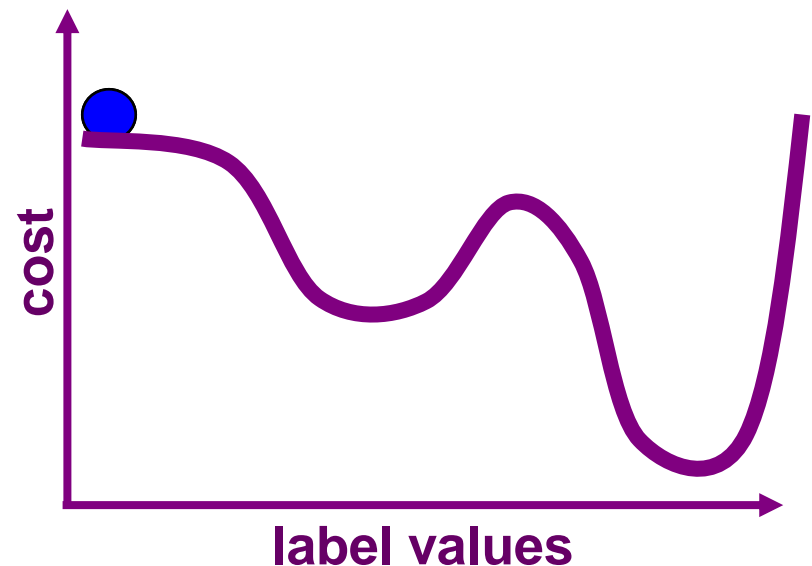
- High-dimensional search space, local minima

- Analogy to statistical mechanics

- crystalline solid finding minimum energy state
- stochastic optimisation
- simulated annealing

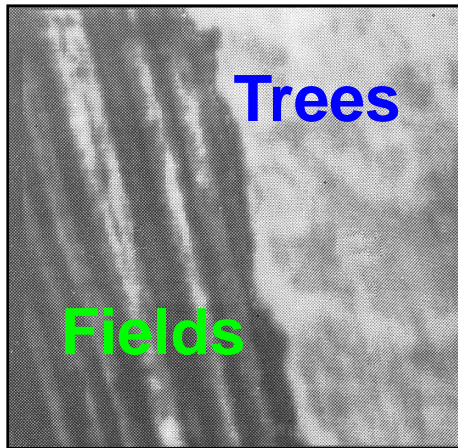
- Search:

- Downhill
- Allow slight uphill

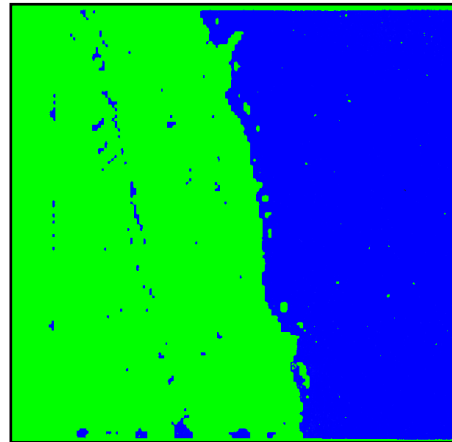


Segmentation as Optimisation

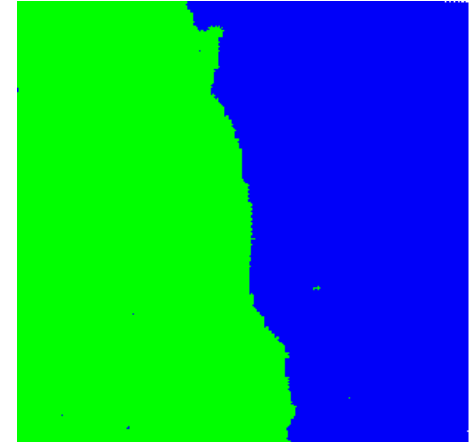
$$\alpha = 0.90$$



Original



Relaxation



Optimisation