

Tensor Product Representation for Machine Comprehension: version 0.0

This note is a summary of what we have so far which will be the basis for implementation of primary baseline.

We have started with bi-directional attention flow model [BidirAtt16] proposed by AI2. This is the model that is one of the top ranked models in Stanford's SQUAD leader board [Squad16, Leaderboard17]. The model proposed by [Squad16] is shown in Fig. 1.1.

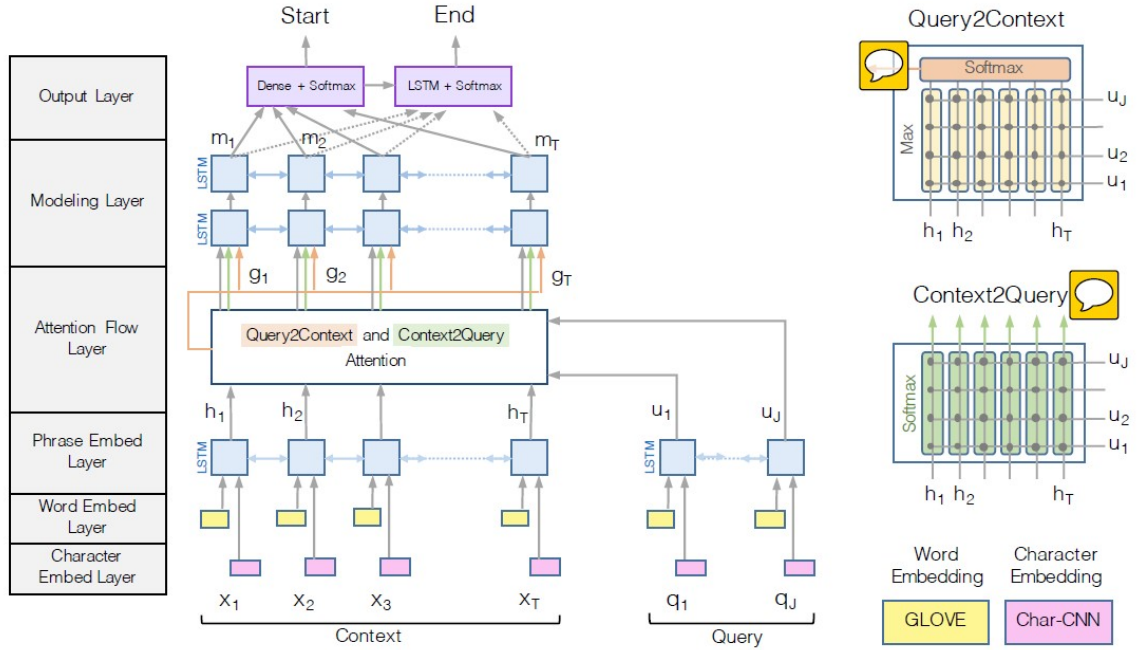


Figure 1.1: Model proposed by [Squad16] for machine comprehension. Figure from [Squad16].

The idea, proposed by Paul, is to have a TPR model along with the current model shown in Fig. 1.1. As a version 0.0, this TPR model is added before the Attention Flow layer. The idea is shown in Fig. 1.2 (from Paul's whiteboard).

The inputs to the TPR model at time " t " are the following:

1. \mathbf{x}_t : The output from Word Embed Layer for t -th word in Fig. 1.1.
2. \mathbf{h}_{t-1} : The output from Phrase Embed Layer for $t - 1$ -th word in Fig. 1.1.
3. \mathbf{T}_{t-1} : The TPR representation from previous word in the sequence, i.e., $t - 1$ -th word.

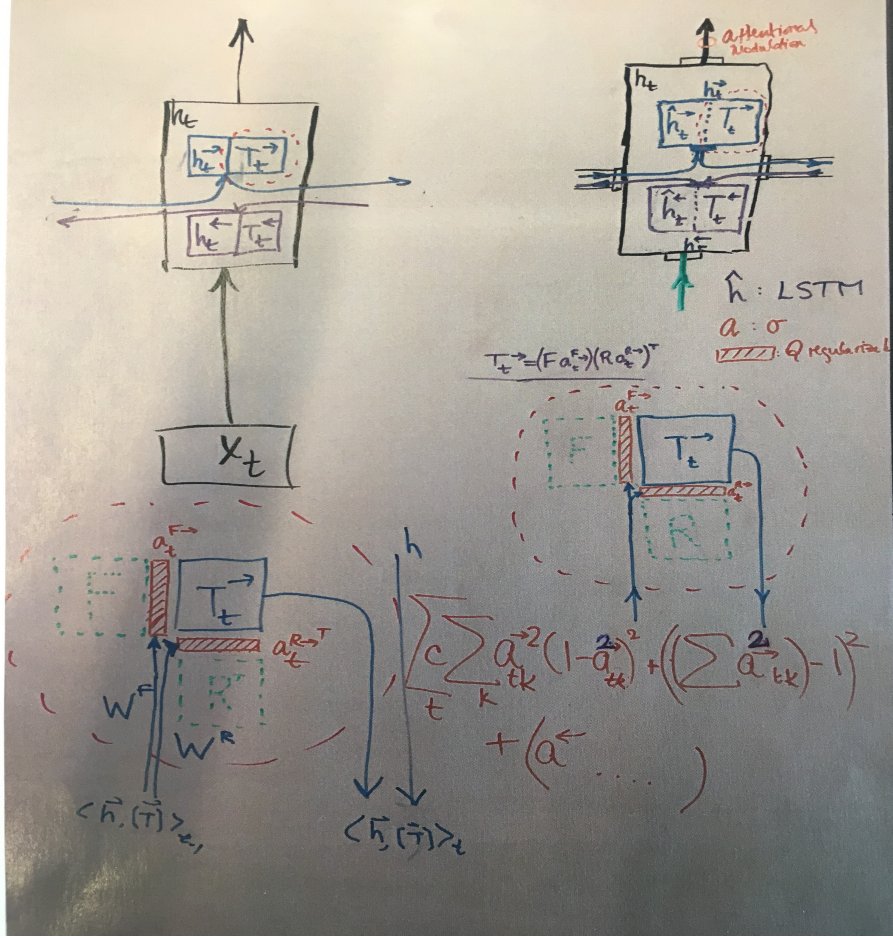


Figure 1.2: TPR model proposed by Paul. Figure from Paul's white board.

The inputs to the LSTM in phrase embed layer at time “ t ” are as before but there is also an extra input from \mathbf{T}_{t-1} .

A TPR forward pass will be as follows:

$$\mathbf{a}_t^F = f(\mathbf{W}^F \mathbf{x}_t + \mathbf{W}_{\text{rec1}}^F \mathbf{h}_{t-1} + \mathbf{W}_{\text{rec2}}^F \text{vec}(\mathbf{T}_{t-1})) \quad (1.1)$$

$$\mathbf{a}_t^R = f(\mathbf{W}^R \mathbf{x}_t + \mathbf{W}_{\text{rec1}}^R \mathbf{h}_{t-1} + \mathbf{W}_{\text{rec2}}^R \text{vec}(\mathbf{T}_{t-1})) \quad (1.2)$$

$$\mathbf{T}_t = \mathbf{F} \underbrace{\mathbf{a}_t^F (\mathbf{a}_t^R)^T}_{\mathbf{B}_t} \mathbf{R}^T \quad (1.3)$$

where \mathbf{F} and \mathbf{R} refer to filler and roles matrices, \mathbf{B}_t refers to the binding matrix and $\text{vec}(\cdot)$ vectorizes the given matrix. The parameters that should be learned during training in above equations are $\{\mathbf{W}^F, \mathbf{W}^R, \mathbf{W}_{\text{rec1}}^F, \mathbf{W}_{\text{rec1}}^R, \mathbf{W}_{\text{rec2}}^F, \mathbf{W}_{\text{rec2}}^R, \mathbf{F}, \mathbf{R}\}$.

In a bidirectional version, the same set of equations with different parameters are used for left-to-right and right-to-left models.

To make the final binding matrix \mathbf{B}_t as sparse as possible (ideally constructed by two one-hot vectors \mathbf{a}_t^F and

$\mathbf{a}_t^{\mathbf{R}}$), the following regularization term or a variant of it will be added to the cost function, i.e., to equation (5) of [BidirAtt16]:

$$\begin{aligned} & C^F \sum_t \left[\sum_k (\mathbf{a}_{tk}^{\mathbf{F}})^2 (1 - (\mathbf{a}_{tk}^{\mathbf{F}})^2)^2 + \left(\left[\sum_k (\mathbf{a}_{tk}^{\mathbf{F}})^2 \right] - 1 \right)^2 \right] + \\ & C^R \sum_t \left[\sum_k (\mathbf{a}_{tk}^{\mathbf{R}})^2 (1 - (\mathbf{a}_{tk}^{\mathbf{R}})^2)^2 + \left(\left[\sum_k (\mathbf{a}_{tk}^{\mathbf{R}})^2 \right] - 1 \right)^2 \right] \end{aligned} \quad (1.4)$$

where C^F and C^R are used to adjust the effect of the regularization terms. This is to force the model to ideally assign one symbol to one role at each time step. In a bidirectional version, another two terms from right-to-left direction will also be added to above equations.

References

- [BidirAtt16] M. SEO, et al, “Bidirectional Attention Flow for Machine Comprehension”,
<https://arxiv.org/abs/1611.01603>, November 2016.
- [Squad16] P. RAJPURKAR, et al, “SQuAD: 100,000+ Questions for Machine Comprehension of Text”,
<https://arxiv.org/abs/1606.05250>, November 2016.
- [Leaderboard17] <https://rajpurkar.github.io/SQuAD-explorer/>, accessed on Jan. 26, 2017.