

## Contents

---

- [for FS greater then 2FM](#)
- [For FS less then 2FM](#)
- [Quantisation](#)
- [part 5](#)

```
% Assignment 3
% Pallav Singla
% 2020225

[y, fs] = input_2020225();

% sound(y,fs)

%
t = 0:(1/fs):(length(y)*(1/fs))-(1/fs); % Time for plotting purpose
figure(1)
plot(t,y);
title('Msg Signal'); % Plotting the message signal
xlabel('Seconds');
ylabel('Amplitude of Msg Signal');

% figure
% plot(t,abs(y));
% title('Amplitude Plot');
% xlabel('Seconds');

figure(2)
plot(t,angle(y)*180/pi);
title('Phase Plot in time'); % plot of phase in time domain
xlabel('Time');
ylabel('Phase of Msg Signal');

len = length(y);
Y = abs(fftshift(fft(y))); % frequency representation of message signal
F = (-(1-1/len)/2:1/len:(1-1/len)/2)*fs;
figure(3);
plot(F,Y);
title('Message in freq');
xlabel('Frequency');
ylabel('Phase of Msg Signal');

figure(4)
plot(F,angle(fft(y))*180/pi); %phase in Frequency domain
title('Phase Plot in freq');
xlabel('Frequency');
ylabel('Phase of Msg Signal');

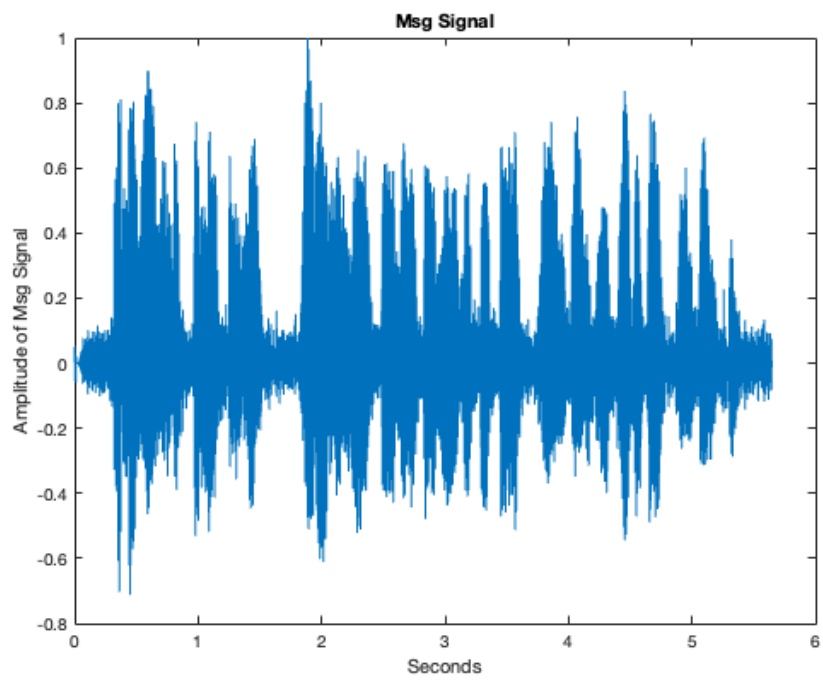
% used for displaying the frequency which is end point in the frequency
% plot

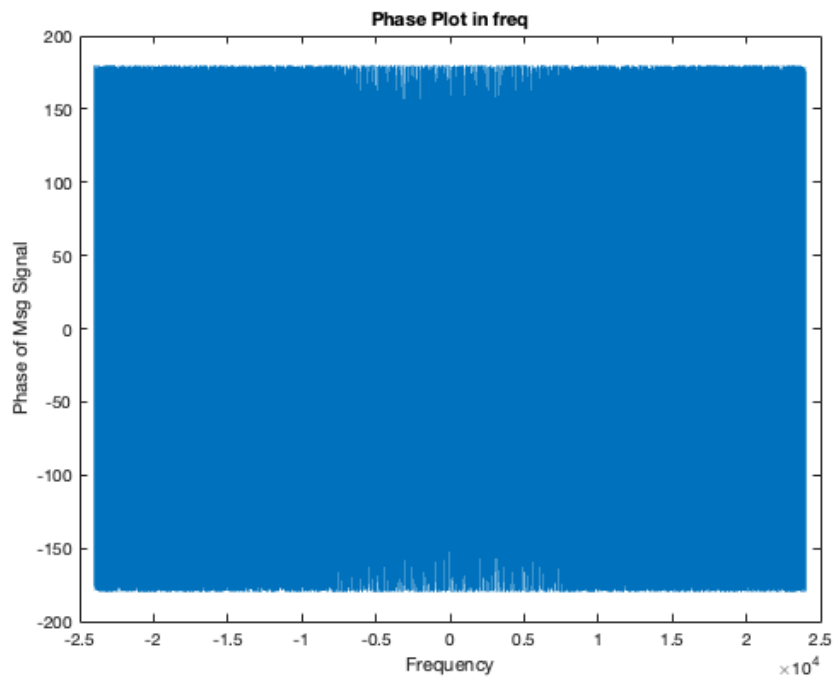
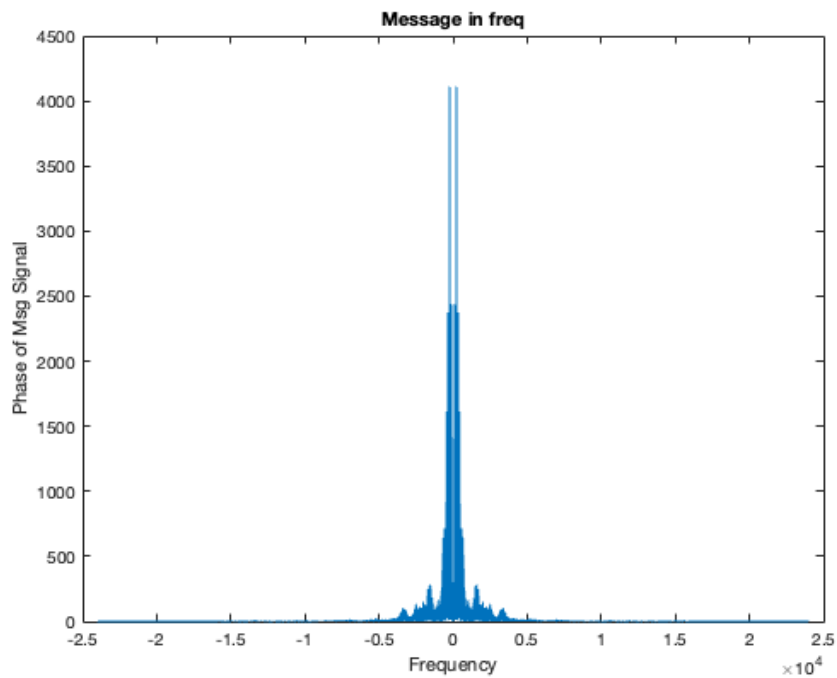
display_2020225(); % Display Function for displaying the max freq

info = audiointo('rec2.m4a');

f = 5000; % max frequency of msg signal

% [k,n] = size(y);
```





for FS greater then 2FM

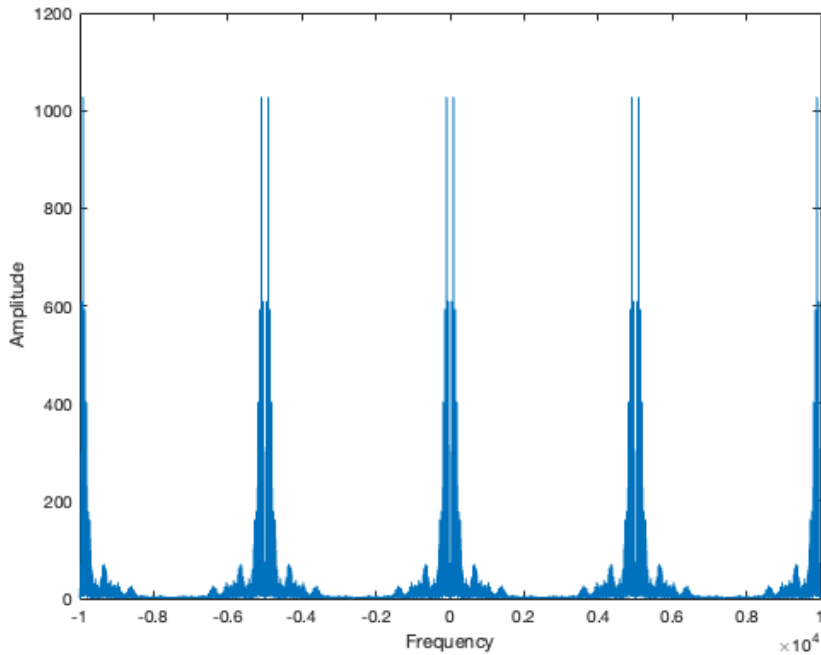
```
fs1 = 2*f*2;    % Sampling frequency
fac = 2;
% %
tr = zeros(size(t));    % Making Matrix and Assigning 0 to each value
tr(1:fs1/f:end) = 1;    % impulse train

trr = transpose(tr);    % taking transpose of the impulse train
Z = y.*trr;
ZZ = fftshift(fft(Z));    % sampled output

freq1 = (-(1-1/len)/2:1/len:(1-1/len)/2)*fs1;

figure(5);

plot(freq1,abs(ZZ));    % plot of sampled output wrt to freq %https://in.mathworks.com/matlabcentral/answers
xlabel('Frequency');
ylabel('Amplitude');
```



### For FS less then 2FM

```

fs2 = 2*f*(1/10);          % Sampling Freq

tr2 = zeros(size(t));       % Making Matrix and Assigning 0 to each Value
tr2(1:fs2/f:end) = 1;      % impulse train

tr2r = transpose(tr2);      % taking transpose of the impulse train
Z1 = y.*tr2r;

freq = (-(1-1/len)/2:1/len:(1-1/len)/2)*fs2; % Frequency same as above

Z2 = fftshift(fft(Z1));     % Sampled Output

figure(6);

plot(freq,abs(Z2));
xlabel('Frequency');
ylabel('Amplitude');

%%part4 quantisation

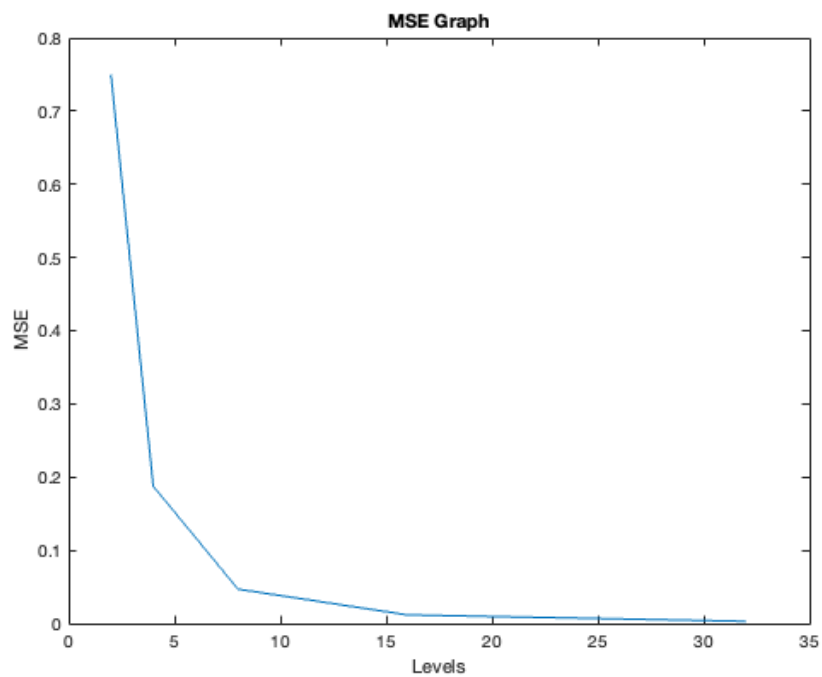
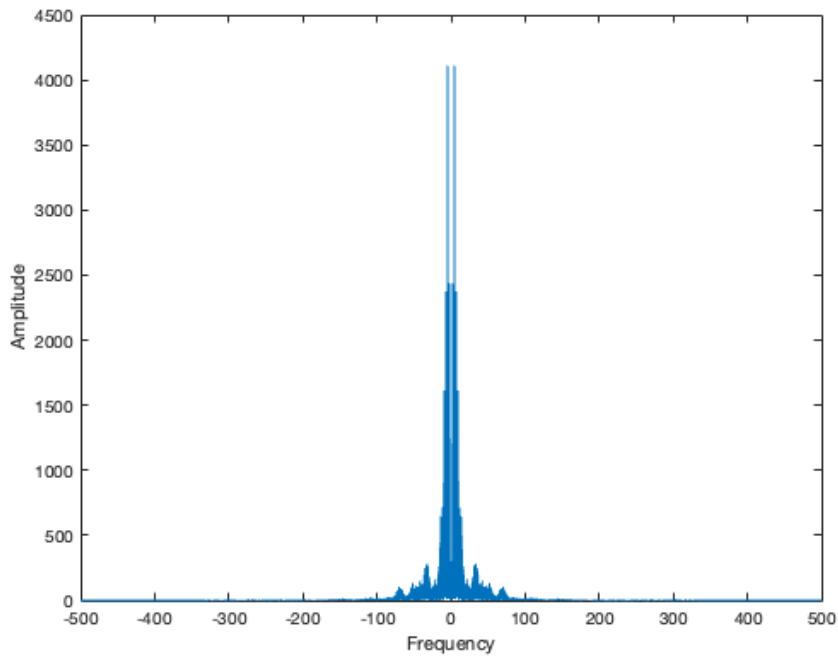
quantise_2020225();        %% quantise fuction made in function

L =32; %% Because MSE is tending to zero( almost) at the end i have seen it from graph of MSE given
      % code in quantise_2020225()
      % mse = 3*1/32*32 it is very very samll almost to 0

mse_32 = 3*1/(32*32);      % for showing the value at 32
disp(mse_32);

```

Warning: Integer operands are required for colon operator when used as index.  
0.0029



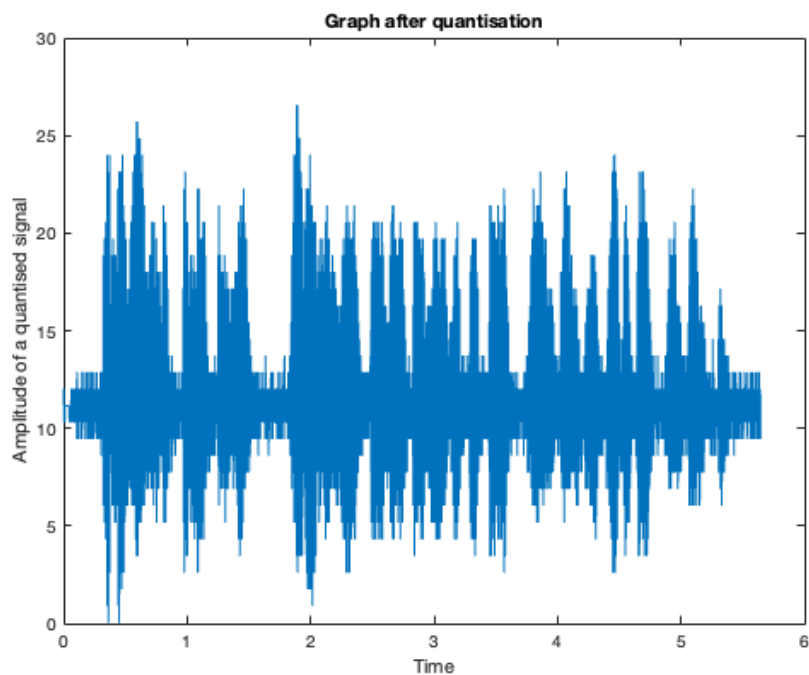
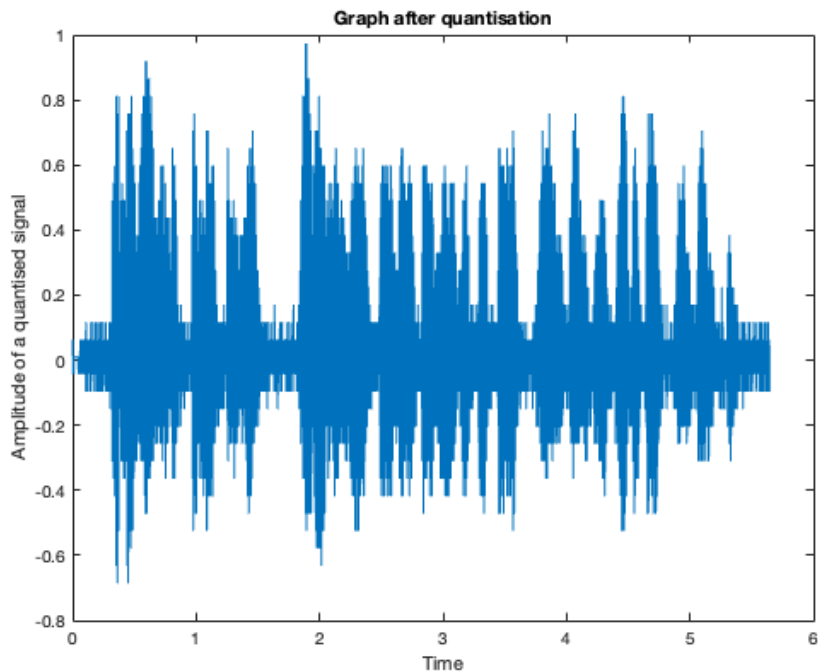
## Quantisation

```
% % s = quantisation_2020225(Z1);
% % plot(t,s*32/1.8);
% %
% % xlabel('Time');
% %
% % ylabel('Amplitude of a quantised signal');
% % title('Graph after quantisation');

L=32;                                % Number of Levels
[a,b] = quanta_2020225(Z1,L);        % using the function made in and output quantised signal is a

figure(8)                            % plotting the quantised signal
plot(t,a)
xlabel('Time');
ylabel('Amplitude of a quantised signal');
title('Graph after quantisation');
```

```
figure(9);
plot(t,(a*32/2)+11);           % Plotting the number of level vs time graph
xlabel('Time');
ylabel('Amplitude of a quantised signal');
title('Graph after quantisation');
```



## part 5

```
enc = dec2bin((a*32/2)+11);    % Converting decimal to binary using inbuilt function

%Here as I have to encode it so for this i have to use matlab inbuilt
%function de2bi
% n=5;
% m = dec2bin(s);
% so = 1;
%
% for k1=1:31                  % for iterating in the rows
```

```

%      for jp=1:n
%
%          mi(so) = m(kl,jp);          % Here converting into row vector
%
%          so=so+1;
%          jp=jp+1;
%
%      end
%      kl=kl+1;
%  end
%  Li =0:1:L-1;

%
%  Array = ['000','001','010','011','100','101','110','111'];
%
%  mp = 1;
%
%  delv = 1/4;
%
%  v1 = -1;
%  v2 = v1+1/4;
%  v3 = v2+1/4;
%  v4 = v3+1/4;
%  v5 = v4+1/4;
%  v6 = v5+1/4;
%  v7 = v6+1/4;
%  v8 = v7+1/4;
%
%  qy = zeros(size(y));
%
%  for i=1:length(y)
%      if v1<=y(i) || y(i)<v2
%          qy(i) = v1;
%      elseif v2<=y(i) || y(i)<v3
%          qy(i) = v2;
%      elseif v3<=y(i) || y(i)<v4
%          qy(i) = v3;
%      elseif v4<=y(i) || y(i)<v5
%          qy(i) = v4;
%      elseif v5<=y(i) || y(i)<v6
%          qy(i) = v5;
%      elseif v6<=y(i) || y(i)<v7
%          qy(i) = v6;
%      elseif v7<=y(i) || y(i)<v8
%          qy(i) = v7;
%      else
%          qy(i) = v8;
%      end
%  end
%
%  end
%
%  plot(qy);

```