

# SDN based Deterministic Time-Sensitive Networking

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# Overview

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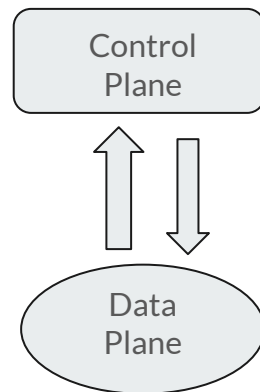
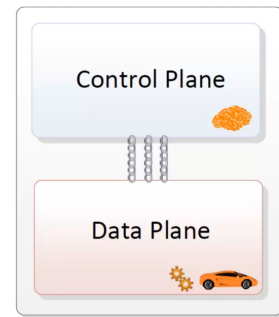


# Introduction

- Deterministic Networking
  - Provide guaranteed performance.
  - Guaranteed Quality of Service(QoS).
  - Reduced latency and Jitter.
- Commonly used in modern applications
  - Industrial Automation
  - Autonomous Vehicles
  - Telemedicine

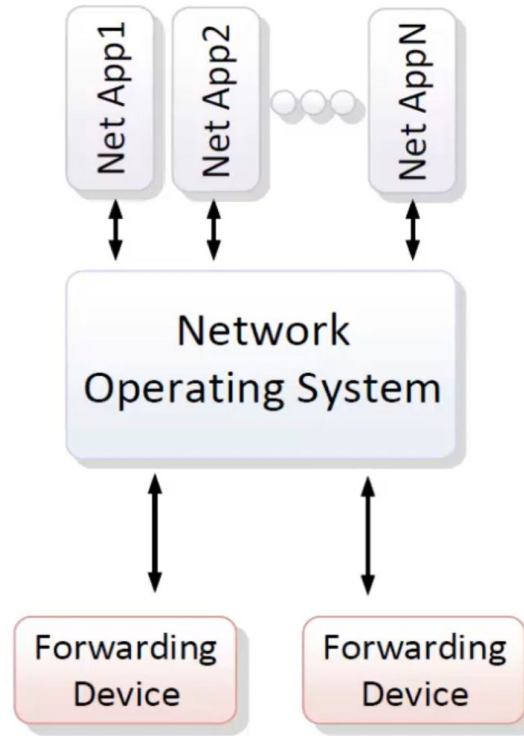
# What is SDN?

- In traditional network, the control and the data plane are tightly integrated into same device.
- Scaling a traditional network requires adding more devices and manually configuring each one, which can be time-consuming and error-prone.
- In the Software Defined Networking (SDN) architecture, the control and data planes are decoupled, network intelligence and state are logically centralized, and the underlying network infrastructure is abstracted from the applications.\*
- In other words in the SDN paradigm, not all the processing happens inside the same device.



\* Software-Defined Networking: The New Norm for Networks ONF White Paper, April 13, 2012

# Layers of SDN



## Network Applications

### Application Interfaces

- Java API
- Northbound (e.g. RESTConf)

### SDN Controller/Control Plane

- Topology Service
- Inventory Service
- Statistics Service
- Host Tracking

### SouthBound Interface

- OpenFlow
- OVSDB
- NETCONF
- SNMP

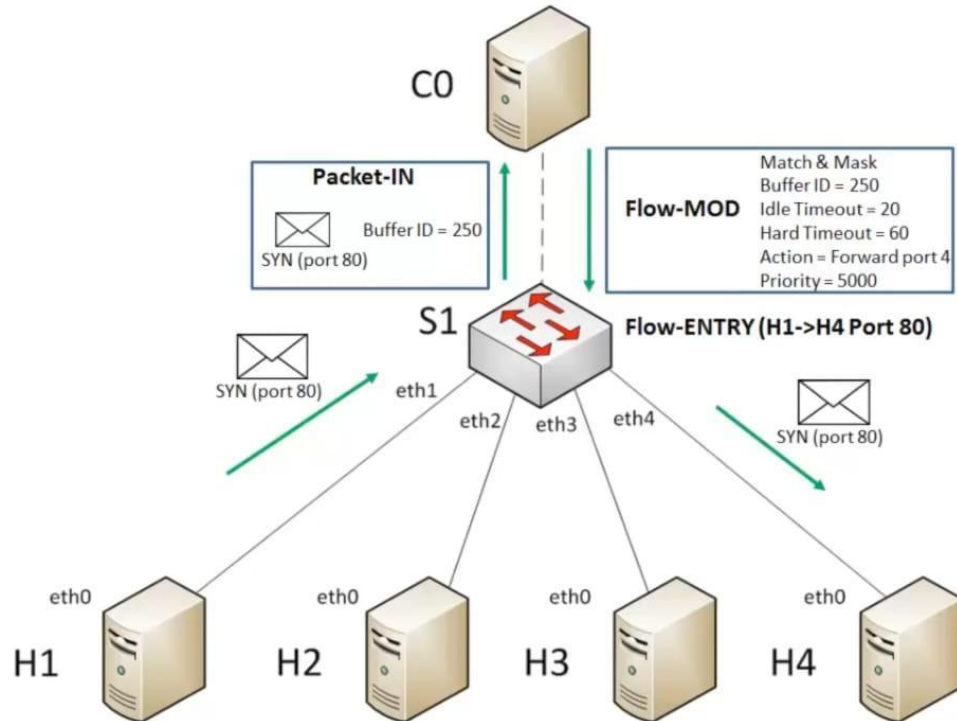
## Forwarding Devices/ Data Plane



# OpenFlow

- OpenFlow is a communication protocol which enables the network controller to interact with the data plane devices such as switches, routers etc.
- This gives control plane a way to control the behaviour of switches in the network dynamically and programmatically.
- OpenFlow facilitates centralized network management and automation, enhancing network flexibility and scalability.
- OpenFlow allows dynamic, real-time updates to network policies.
- OpenFlow does not equal SDN. It is a flavor, or a subset of SDN.

# OpenFlow (Contd.)



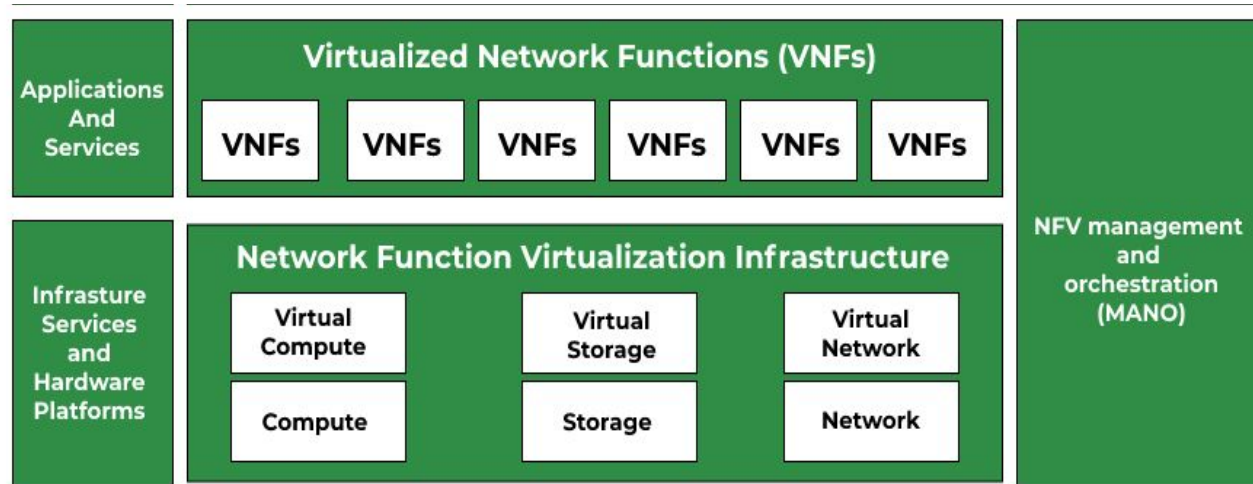


# Network Function Virtualization (NFV)

- Network Function Virtualization (NFV) is replacement of hardware networking components with virtual (software) networking functions.
- These virtual networking functions can be run on different virtual machines.
- The virtual machines require hypervisor to run networking software and processes such as routing and load balancing.
- A hypervisor or software-defined networking controller allows network engineers to program all of the different segments of the virtual network, and even automate the provisioning of the network.



# NFV Architecture





## NFV vs. SDN

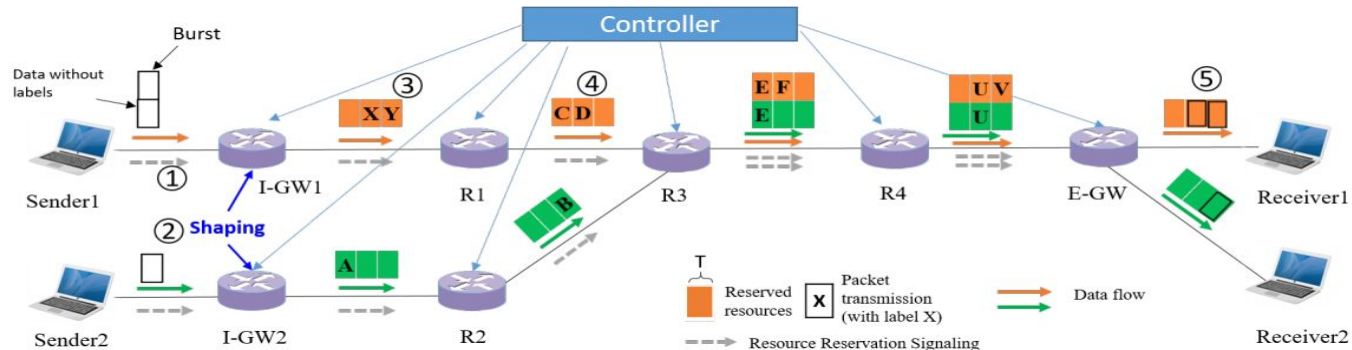
- NFV and SDN are not dependent on each other, but they do have similarities.
- Both rely on virtualization and use network abstraction, but how they separate functions and abstract resources is different.
- While NFV separates networking services from dedicated hardware appliances, software-defined networking, or SDN, separates the network control functions such as routing, policy definition and applications from network forwarding functions.
- A software-defined network can sit on top of either a virtual network or a physical network, but a virtual network does not require SDN to operate.

# Literature Review

**Title:** Towards Large-Scale Deterministic IP Networks<sup>[1]</sup>

**Author:** Bingyang Liu, Shoushou Ren, Chuang Wang, Vincent Angilella, Paolo Medagliani, Sebastien Martin, Jeremie Leguay

**Contribution:** Presented a realistic implementation of a Large-Scale Deterministic Network (LDNs) to provide E2E latency and bounded jitter in large-scale IP networks.



# Literature Review (Contd.)



## Motivation

- Traditional IP networks work on a best-effort delivery model, which does not guarantee when data will arrive.
  - Latency upper bound is nearly  $980\mu\text{s}$ .
  - Latency lower bound is  $19\mu\text{s}$ .
  - Resulting jitter of  $961\mu\text{s}$ .
- Scaling deterministic networks to a large scale.
- Integration with existing IP infrastructure.



# Methodology

- The LDN architecture, designed to bring deterministic performance to large scale.
- It is scalable unlike TSN.
- By carefully controlling how and when data is transmitted through the network, LDN ensures low and consistent latency, as well as minimal jitter—key factors for real-time communication.
- The three core components are **fine-grained traffic shaping**, **asynchronous cyclic queuing** and **label-based forwarding**, which together make this solution feasible and effective.

# Fine-Grained Traffic Shaping at Ingress Nodes

- Traffic bursts management.
- Gate-Controlled queues manage how traffic is released into the network.
- Granularity of traffic shaping.

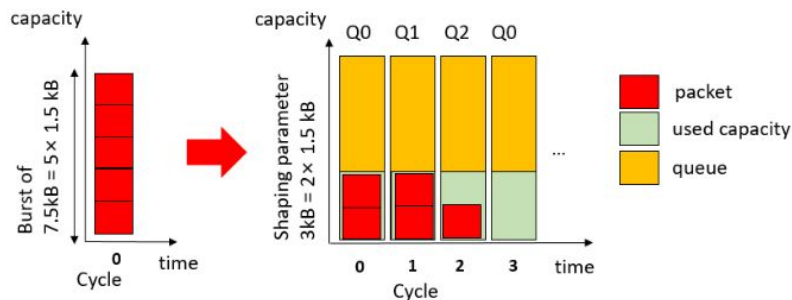


Fig. 2. Example of shaping of a burst of size  $b_f = 7.5$  kB with a shaping parameter  $b'_f = 3$  kB/cycle, 3 kB used on each cycle and shaping delay  $3T$ .

# Asynchronous Cyclic Queuing and Forwarding

- LDN divides time into fixed cycles, and each cycle is responsible for processing traffic, ensuring that packets are scheduled and transmitted predictably.
- Unlike other methods, LDN operates asynchronously.
- Three FIFO queues per node, used in a round-robin fashion.
- This round-robin method ensures that all packets are sent in an orderly, predictable manner.

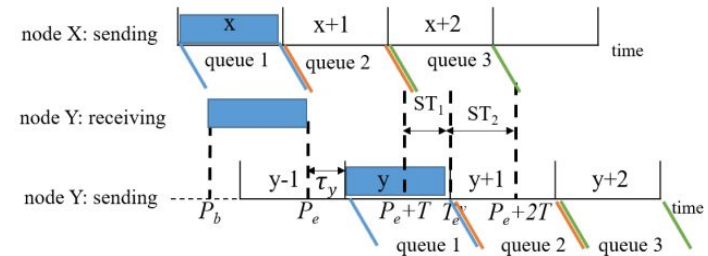


Fig. 3. Cyclic queue scheduling on core LDN nodes.



# Label-Based Packet Forwarding

- Each packet is tagged with a label that indicates which cycle it should be transmitted in.
- The label simplifies the forwarding process because each node just needs to look at the label to decide when to send the packet.
- Each node in the network maintains a mapping table that tells it how to convert an incoming label into an outgoing label.
- This table is “quasi-static,” meaning it doesn’t change often, which reduces the complexity of network management while still allowing for flexibility.



# Bounds on E2E latency and jitter

- The worst E2E queuing delay happens when a packet, sent at the first hop at  $T_b^1$ , is forwarded, at the last hop, at  $T_e^h$ .

○

$$D_{\text{worst}} = T + \sum_{i=2}^h (\tau_i + T)$$

- In the best case, a packet, sent at the first hop at time  $T_{e1}$ , is sent out at the last hop at time  $T_{bh}$ .

○

$$D_{\text{best}} = \sum_{i=2}^{h-1} (T + \tau_i) + \tau_h$$

- Jitter =  $D_{\text{worst}} - D_{\text{best}} = 2T$
- $(h - 2)T \leq \text{E2E queuing delay} \leq (2h - 1)T$ .

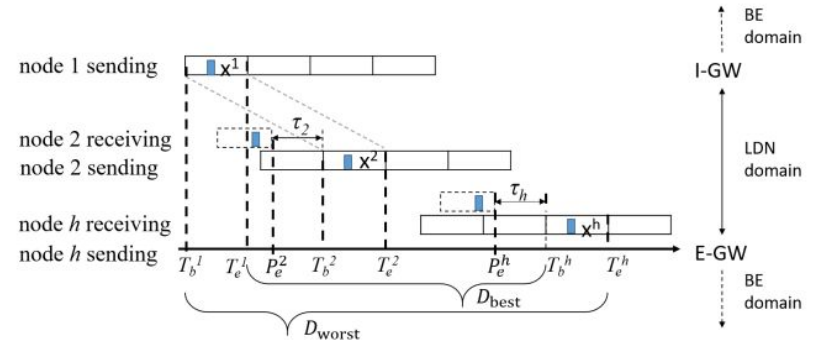


Fig. 4. End-to-end latency and jitter analysis.

# Implementation and Testing

- PoC implementation on a Huawei router.
  - $T = 10\mu\text{s}$
  - Worst case E2E queuing delay is  $67.046\mu\text{s}$ .
  - The best case delay is  $49.886\mu\text{s}$ .
  - Largest jitter experienced  $67.046 - 49.886 = 17.16\mu\text{s}$
- Simulations conducted using OMNeT++, a network simulator, on a real-world ISP topology (AS 1239 of Sprint).
- Compared the performance of LDN with traditional OSPF routing.

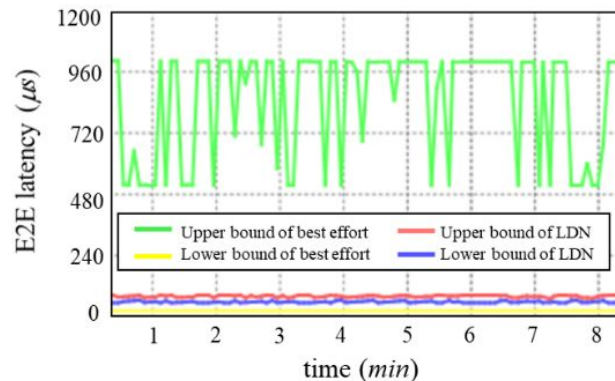


Fig. 6. Test results over the PoC implementation.



## References

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## Future Work

- Implement the paper “Towards Large-Scale Deterministic IP Networks”.
- In the implementation I will,
  - Create a mininet network with specified topology.
    - Currently working with RocketFuel topology
  - Randomly create a set of  $m$  Ingress and  $n$  Egress node.
  - Then try to build network as discussed in the paper.

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**Thank You**