1. A unit square is transformed by a 2 × 2 transformation matrix. The resulting position vectors are

$$\begin{pmatrix}
0 & 2 & 8 & 6 \\
0 & 3 & 4 & 1
\end{pmatrix}$$

What is the transformation matrix?

$$3$$
 A triangle is defined by  $\begin{pmatrix} 2 & 4 & 4 \\ 2 & 2 & 4 \end{pmatrix}$ 

Find the transformed coordinates after the following transformations.

- (1) 90° rotation about origin.
- (2) reflection about line y = -x
- 4. / Give the explicit form of the 3 × 3 matrix representing the transformation: scaling by a factor of 2 in the X direction and then rotation about (2, 1)
- 5. A polygon has 4 vertices located at A(20, 10), B(60, 10), C(60, 30), D(20, 30). Indicate a transformation matrix to double the size of the polygon with point A located at the same place.
- 6. A triangle PQR has its vertices focated at P(80,50), Q(60,10), R(100,10). It is desired to obtain its reflection about an axis, parallel to the Y axis and passing through the point A (30,10). Work out the necessary transformation matrix and also the coordinates of the vertices of the reflected triangle.
- 7 A mirror is vertically placed such that it passes through (20,0) and (0,20). Find the reflected view of a triangle with vertices (30,40), (50,50) and (40,70) in this mirror.
- Show that a 2D reflection through X axis followed by a 2D reflection through the line y = -x is equivalent to pure rotation about the origin.
- The reflection along the line y = x is equivalent to the reflection along the X axis followed by counter clockwise rotation by  $\theta$  degrees. Find the value of  $\theta$ .
- 10 In 2D graphics the following transformation matrix would reflect a point about the diagonal line passing through the origin and (10,10)

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Show that this is same as coordination of matrix for 45 degree clockwise rotation followed by reflection about X axis and finally by counter clockwise rotation by 45 degrees (about origin).

 $\sqrt{\text{Prove that if rotation angle is } \theta}$  the transformation matrix formed when multiplied by the transformation matrix formed when angle is  $-\theta$  is equal to identity matrix.