

Numeriske Metoder

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Exercise 1

i)

Find the Singular Value Decomposition and State the diagonal elements in W.

Solution

The code reads the data file NUM_S25_Ex1A.dat for the matrix A and uses numerical recipes SVD method to print svd.w.

```
----- Problem i -----  
Diagonal elements of W:  
11.951932409770585    5.397266515466192    4.719596639028399    3.9539065956033674    3.623090993000244    3.368300112475189    3.091666468243567    4.729403607652192e-15
```

ii)

There is a single element in W that is basically zero. Use the information from the SVD matrices to state a unit vector in the null space of A.

Solution

The code uses numerical recipes SVD method `svd.nullspace` to find the unit vector in the null space of A. The threshold is there to find the element near zero.

```
void problemII(MatDoub A) {  
    SVD svd(a: A);  
  
    util::print(mat: svd.nullspace(thresh: 1e-10));  
}  
  
----- Problem ii -----  
  
-0.3041495323362373  
0.6995439243733442  
4.862063999926544e-17  
3.9381502970548994e-16  
-0.42580934527073155  
1.7340582620100244e-17  
-9.82417271311071e-17  
0.48663925173797906
```

iii)

Use the Singular Value Decomposition to compute the solution x to $Ax = b$. State the solution x.

Solution

Using SVD to find the best-fit least squares solution and returns the vector x

```
----- Problem iii -----  
Best fit solution parameters x:  
-47.24836361643928    0.36884252263498496    79.65376424734222    -4.711970963467443    40.404271525143045    69.74266521165167    -42.73505350336738    5.293299197937798
```

iv)

State an estimate of the accuracy on the solution x . State an explanation of how you computed the accuracy.

Solution

The relative residual error was computed in the `residualError()` function. This measures how closely the solution satisfies the original system.

The `randomFittingError()` gives an estimate of the expected residual error if the data were purely random.

The `sigErrorEstimate()` function estimates the standard deviation σ on each component of the solution vector x , based on the values in W .

```
----- Problem iV -----  
  
Relative residual error epsilon_residual = 5.42797e-06  
Random fit Error= 0.912871  
  
sigma   Vector 80:  
0.0846856316939977    0.16099885651146364    0.2770351882338667    0.27503010240108106    0.2266191205749653    0.2597660651878675    0.25037451202513783    0.22830996340629964
```

Exercise 2

i)

With $x_0 = -0.7$, $x_1 = 1.2$, $x_2 = 2.3$, $x_3 = -4.1$ state (with at least 7 digits) the values of the left-hand side of the four equations. (HINT: you should get something around (2.36, 6.03, 49.32, -14.12)).

Solution

```
----- Problem I -----
2.360427776065722      6.033039085967225      49.322999999999999      -14.118275390737853
```

ii)

Search for a solution to the equations by performing 7 iterations with the globally convergent Newton method with initial guess $(x_0, x_1, x_2, x_3) = (0, 0, 0, 0)$. State for each iteration the values of x_0, x_1, x_2, x_3 and for each iteration whether backtracking was applied, and if so, what the value of λ was. Submit the used code.

Solution

Looking at the table below you can see backtracking is happening at $k = 3$ because lambda value is lower than 1 and at $k = 4$ the convergence and error gets a spike as a result.

```
-----Problem II & III-----
k      x0      x1      x2      x3      dx_k      lambda      convergence      error
1      -1.400000  1.275000  -1.733333  0.900000  0.000000      nan      nan      nan
2      -2.529812  0.206707  -1.659476  0.892282  -1.129812      nan      nan      nan
3      -2.374943  0.382163  -1.699814  0.772997  0.154870  0.111687  0.109669  0.007745
4      -1.274613  1.222814  -1.368963  0.577609  1.100330      nan  20.347122  42.017974
5      -0.971073  1.118543  -1.118002  0.724769  0.303540      nan  0.209767  0.039362
6      -0.966679  1.134405  -1.102446  0.741389  0.004394      nan  0.149706  0.000118
7      -0.966346  1.134616  -1.102211  0.741495  0.000332      nan  0.596128  0.000000
```

iii)

State an estimate the accuracy after 7 iterations. The estimate must be based on the data obtained from the 7 iterations and must be stated with a clear argument of how you computed it. Without such an argument, there is no points for the answer.

Solution

The accuracy after 7 Newton iterations was estimated using $\epsilon_k \approx C_k * \|dx_k\|^2$

- Where $dx_k = x_k - x_{k-1}$ is the difference
- Where C_k is the estimated convergence

These values are computed in printRoots()

```
-----Problem II & III-----
k      x0      x1      x2      x3      dx_k      lambda      convergence      error
1      -1.400000  1.275000  -1.733333  0.900000  0.000000      nan      nan      nan
2      -2.529812  0.206707  -1.659476  0.892282  -1.129812      nan      nan      nan
3      -2.374943  0.382163  -1.699814  0.772997  0.154870  0.111687  0.109669  0.007745
4      -1.274613  1.222814  -1.368963  0.577609  1.100330      nan  20.347122  42.017974
5      -0.971073  1.118543  -1.118002  0.724769  0.303540      nan  0.209767  0.039362
6      -0.966679  1.134405  -1.102446  0.741389  0.004394      nan  0.149706  0.000118
7      -0.966346  1.134616  -1.102211  0.741495  0.000332      nan  0.596128  0.000000
```

Exercise 3

i)

- Rewrite Eq. (1) into a set of two first order ODE's. State the two first order ODE's.

$$x''(t) = a_{max} \left[1 - \left[\frac{x'(t)}{v_{des}} \right]^4 - \left(\frac{D_0 + \text{Max} \left\{ 0, x'(t) * T_{react} + \frac{x'(t)(x'(t) - X'_F(t))}{2 * a_{com}} \right\}}{X_F(t) - x(t)} \right)^2 \right]$$

Solution

To convert the equation into a set of two first order ODE's I introduce a new variable:

$$x_1(t) = x_0'(t)$$

This means that: $x_0''(t) = x_1'(t)$

Substituting this into the equation we get the two first order ODE's:

$$\begin{aligned} 1. \quad & x_0'(t) = x_1(t) \\ 2. \quad & x_1'(t) = a_{max} \left[1 - \left[\frac{x_1(t)}{v_{des}} \right]^4 - \left(\frac{D_0 + \text{Max} \left\{ 0, x_1(t) * T_{react} + \frac{x_1(t)(x_1(t) - X'_F(t))}{2 * a_{com}} \right\}}{X_F(t) - x(t)} \right)^2 \right] \end{aligned}$$

ii)

State with at least 7 digits the value of $x''(t_0)$. Submit the used code. HINT: You should get $x''(t_0) \simeq -1.20$.

Solution

```
-----Problem II-----
15          -1.2035371846808856
```

iii)

Use the Midpoint method with $N = 80$; $h = 0.25$ to generate a solution for $x(t)$; $-10 \leq t \leq 10$. State the value of $x(t)$ at $t = 10$. State plots of $x(t)$, $x'(t)$ and $X_F(t) - x(t)$. Submit the used code.

Solution

If I knew how to save the data in a file and then maybe use python or MATLAB to read and process it I would have continued with the problem. In the code I also print out the 80 steps.

```
-----Problem III-----
284.3842345949725      10.092177946269342
```

Exercise 4

i)

With $N-1 = 2^k$; $k = 1, \dots, 20$ use the Simpson Method method to approximate the integral. State the results in a table similar to those used during the course. Submit the used code.

Solution

```
----- Problem I -----
Using Simpson's rule
```

i	A(h_i)	A(h_{i-1}) - A(h_i)	alpha^k	Rich error	Order est.	f comps
1	3.624376	nan	nan	nan	nan	2
2	18.432966	-14.808590	nan	4.936197	nan	4
3	54.698586	-36.265621	0.408337	12.088540	-1.292168	8
4	86.718877	-32.020290	1.132583	10.673430	0.179616	16
5	100.111967	-13.393091	2.390807	4.464364	1.257497	32
6	104.354005	-4.242037	3.157231	1.414012	1.658660	64
7	105.706640	-1.352635	3.136128	0.450878	1.648984	128
8	106.159909	-0.453269	2.984177	0.151090	1.577333	256
9	106.316225	-0.156316	2.899703	0.052105	1.535905	512
10	106.370852	-0.054628	2.861479	0.018209	1.516761	1024
11	106.390059	-0.019207	2.844194	0.006402	1.508020	2048
12	106.396831	-0.006772	2.836107	0.002257	1.503912	4096
13	106.399222	-0.002391	2.832215	0.000797	1.501931	8192
14	106.400067	-0.000845	2.830308	0.000282	1.500959	16384
15	106.400366	-0.000299	2.829364	0.000100	1.500478	32768
16	106.400471	-0.000106	2.828895	0.000035	1.500238	65536
17	106.400509	-0.000037	2.828661	0.000012	1.500119	131072
18	106.400522	-0.000013	2.828544	0.000004	1.500060	262144
19	106.400526	-0.000005	2.828486	0.000002	1.500030	524288
20	106.400528	-0.000002	2.828454	0.000001	1.500014	1048576

ii)

Use Richardson extrapolation to estimate the order at $N-1 = 2^{20}$. State the result. Submit the used code.

Solution

Can also be seen in the table above.

```
-----Problem II-----
Order estimates for Problem II:
0: nan
1: nan
2: -1.292168
3: 0.179616
4: 1.257497
5: 1.658660
6: 1.648984
7: 1.577333
8: 1.535905
9: 1.516761
10: 1.508020
11: 1.503912
12: 1.501931
13: 1.500959
14: 1.500478
15: 1.500238
16: 1.500119
17: 1.500060
18: 1.500030
19: 1.500014
```

iii)

The estimated order is different than the expected order. State an explanation for the difference and your guess on the exact order that you have estimated.

Solution

The function has square roots at the ends, so its slope changes too fast at $x=0$ and $x=2$. Simpsons method needs the function slopes to not change this way, so the error wont go down as fast. This would be why the order is around 1.5 instead of 4.

iv)

State the estimated accuracy on the result at $N-1 = 2^{20}$ using the estimated order. State clearly how you compute the accuracy estimate.

Solution

The estimated accuracy is computed using Richardson extrapolation, equation 7 in Richardson.pdf from numerical methods course in itslearning resources.

```
-----Problem IV-----  
  
Estimated accuracy at N = 2^20: 9.018488e-07
```

v)

State what other method could have been used to achieve high accuracy with likely much fewer $f(x)$ computations?

Solution

The midpoint method could be better because it doesn't use the values at the edges like Simpson at $x=0$ and $x=2$. Midpoint evaluates the function inside the interval.

Exercise 5b

i)

Consider $N = 2$. State an analytical expression of the semi discrete form for this problem.

State also the value of $\frac{du_1(t)}{dt}$ for $t = 0$

Solution

I use the semidiscrete formula for $\frac{du_j(t)}{dt}$ explained in uge14pres.pdf slide 5.

$$\frac{du_j(t)}{dt} = \frac{4}{1} \left(u_{j-1}(t) - 2 * u_j(t) + u_{j+1}(t) \right) + f_j(t)$$

$$u_j(0) = g(x_j)$$

$$u_0(t) = a(t)$$

$$u_n(t) = b(t)$$

I use $j = 1$, which is the only inner point when $N=2$ and find $\frac{du_1(t)}{dt}$ at $t = 0$

$$\frac{du_1(t)}{dt} = \frac{4}{1} \left(u_{1-1}(t) - 2 * u_1(t) + u_{1+1}(t) \right) + f_j(t)$$

$$\frac{du_1(t)}{dt} = \frac{4}{1} \left(u_0(t) - 2 * u_1(t) + u_2(t) \right) + f_j(t)$$

$$f_j(t) = \sin(\pi * x) * \exp(-t)$$

$$\frac{du_1(t)}{dt} = \frac{4}{1} (0^2 - 2 * 0.5^2 + 1^2) + \sin(\pi * 0.5) * \exp(-0)$$

$$8 + \sin(\pi * 0.5) * \exp(-0)$$

$$8 + 1 * 1 = 9$$