Graphs Traversal







Lecture Contents

- Traversing a Graph
- Depth First Search
- Breadth First Search
- Minimum Spanning Trees



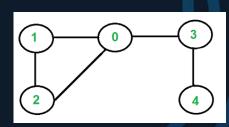


- There's no point in storing information in a graph unless you want to explore the relationships between nodes.
- We calculate this information by traversing the graph.
- We can find out all sorts of things by traversing a graph:
 - How to get from one node to another, when they aren't directly connected
 - How far away one node is from another
 - How many once removed connections (friends of friends), thrice removed connections, etc, two nodes share.
 - Check if a graph is connected or unconnected.





 Traversing a graph is just, when starting at a given node, jumping along edge to edge touching every connected node in the graph, performing some processing at each node.



- Because a node in a graph can have more than one incoming edge, traversing a graph has some problems not found in traversing lists or trees.
- We can come to a node from multiple directions as we traverse the graph. In cyclic or non-directed graphs, this could lead to an infinite loop.



Specifically we want to make sure we only touch each node once.



- The typical solution to this is quite simple.
- Just use a bool as a visited flag inside each node.
- Before traversing the graph, loop through every node, setting their visited flags to false.
- Then, when traversing, as we reach each node, set its visited flag to true.

There are two common algorithms for traversing a graph:

- Depth First Search (DFS)
- Breadth First Search (BFS)





 Depth first search involves searching as far down a path as possible before backtracking.

Can be done recursively, or by using a stack.

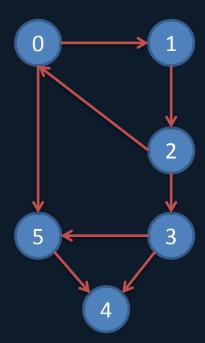




- The algorithm is:
 - Push first node on stack
 - While stack not empty
 - Get the top off the stack and remove it
 - Process it.
 - Mark it as traversed
 - Loop through its edges
 - If end node of edge not traversed or on the stack
 - » Push end node onto the stack





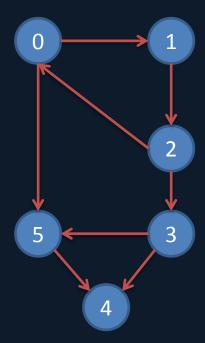










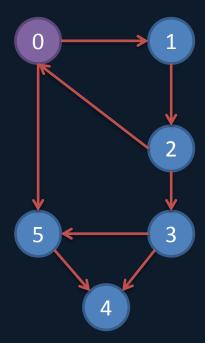










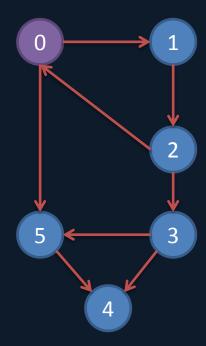












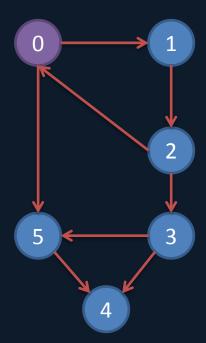










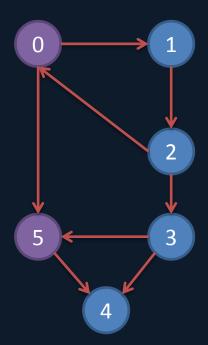












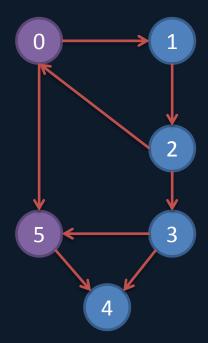










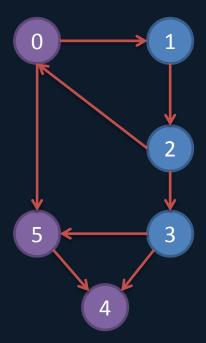












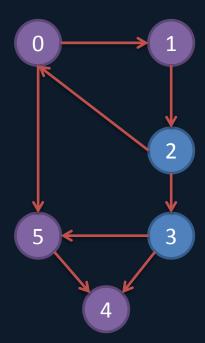










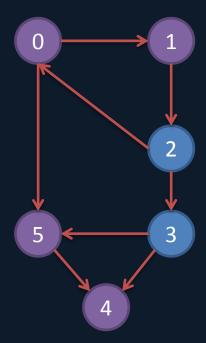




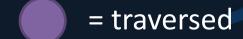






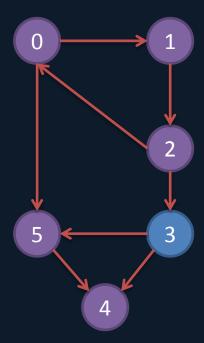










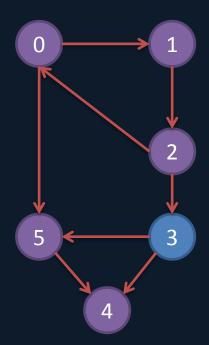




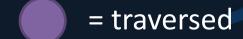








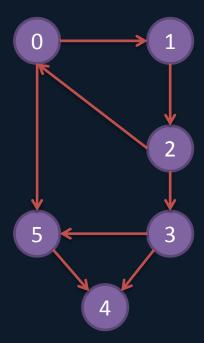




















 Breadth-First Search involves processing all of the neighbours of each node before processing their neighbours and so on.

 You can think of it as fanning out from the starting node, evenly in all directions.



It is typically implemented with a queue



- The algorithm is:
 - Push first node onto queue
 - While queue not empty
 - Get the end off the queue and remove it
 - Process it.
 - Mark it as traversed
 - Loop through its edges
 - If end node of edge not traversed or in the queue
 - » Push end node onto the queue



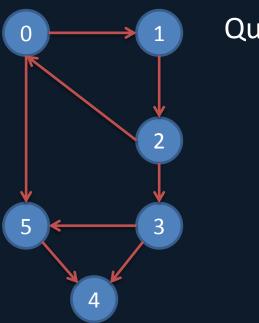


You'll notice this algorithm is very similar to the DFS search.

 The only difference is we are using a queue instead of a stack to pick the next node to traverse.





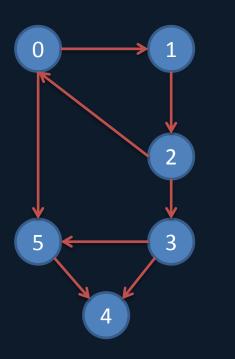






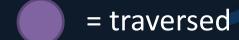






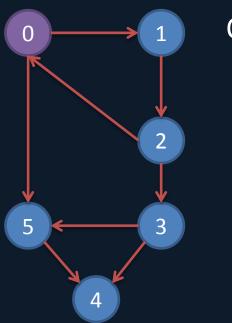










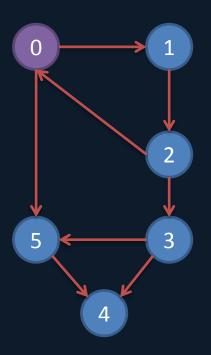






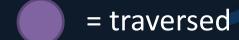






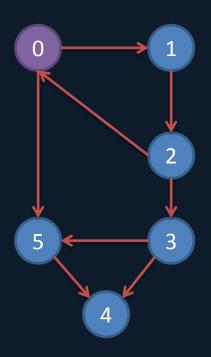












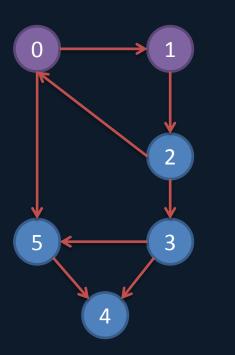
Queue:











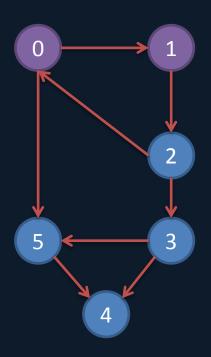
Queue:











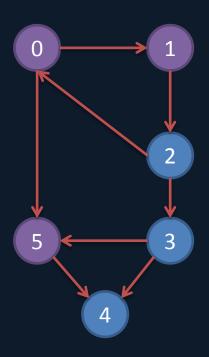
Queue:











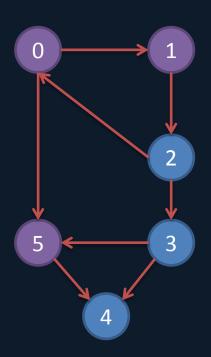
Queue:







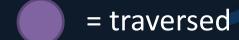




Queue:

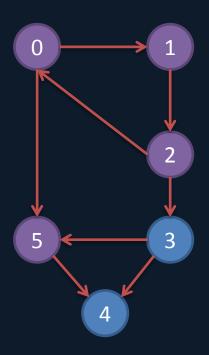
<u>-</u> 4











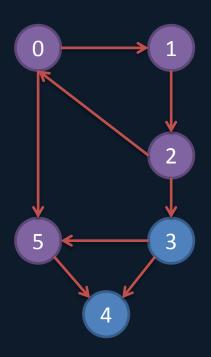












Queue:

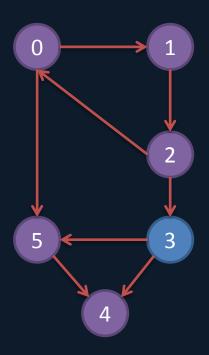
4











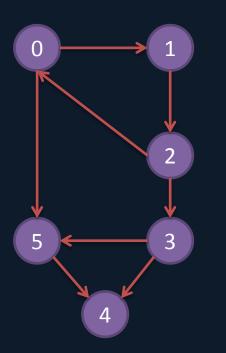




















Questions?



