

# Behaviour Trees – Part 1

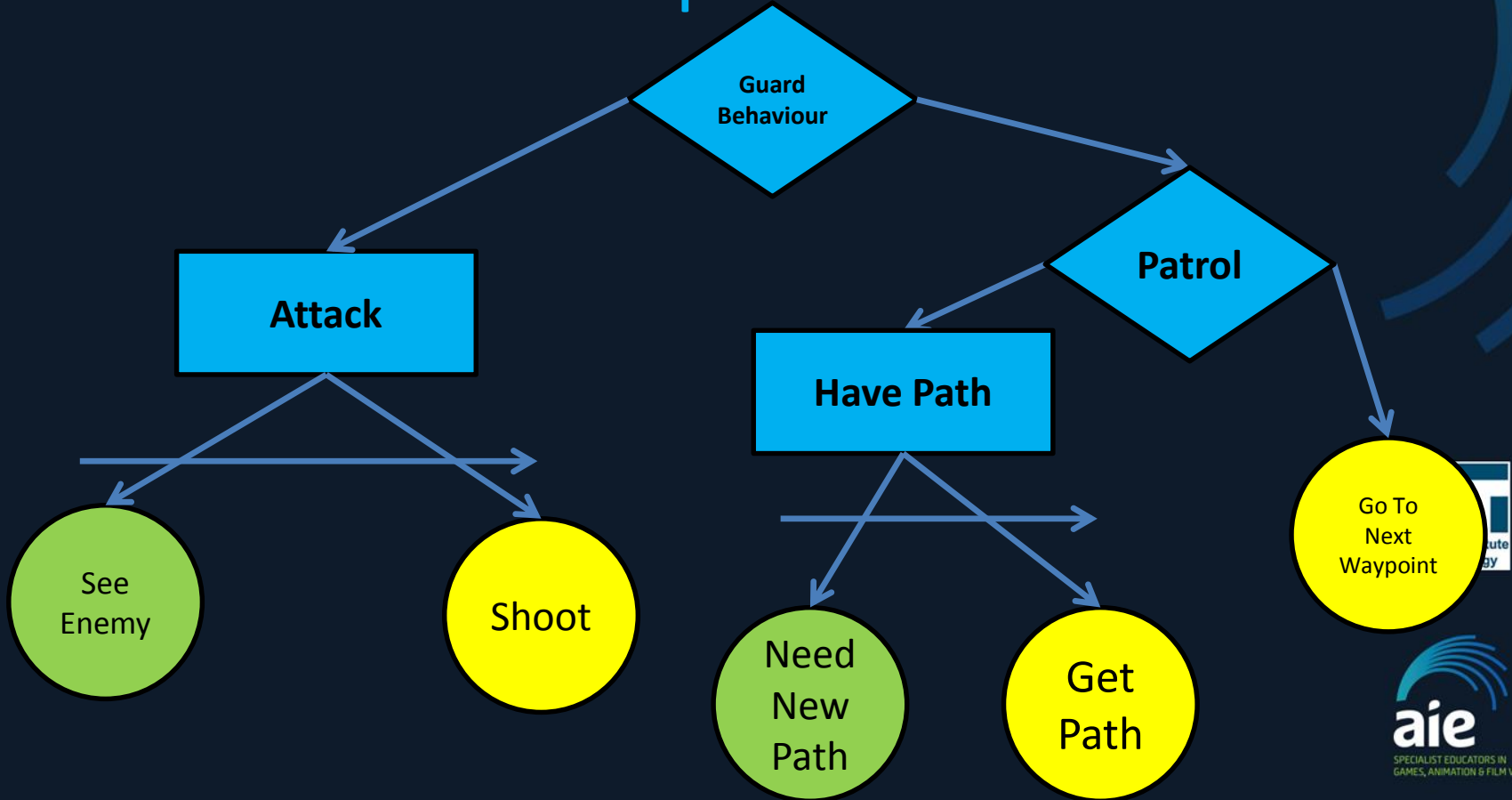
Complex decision making through discrete modular behaviours



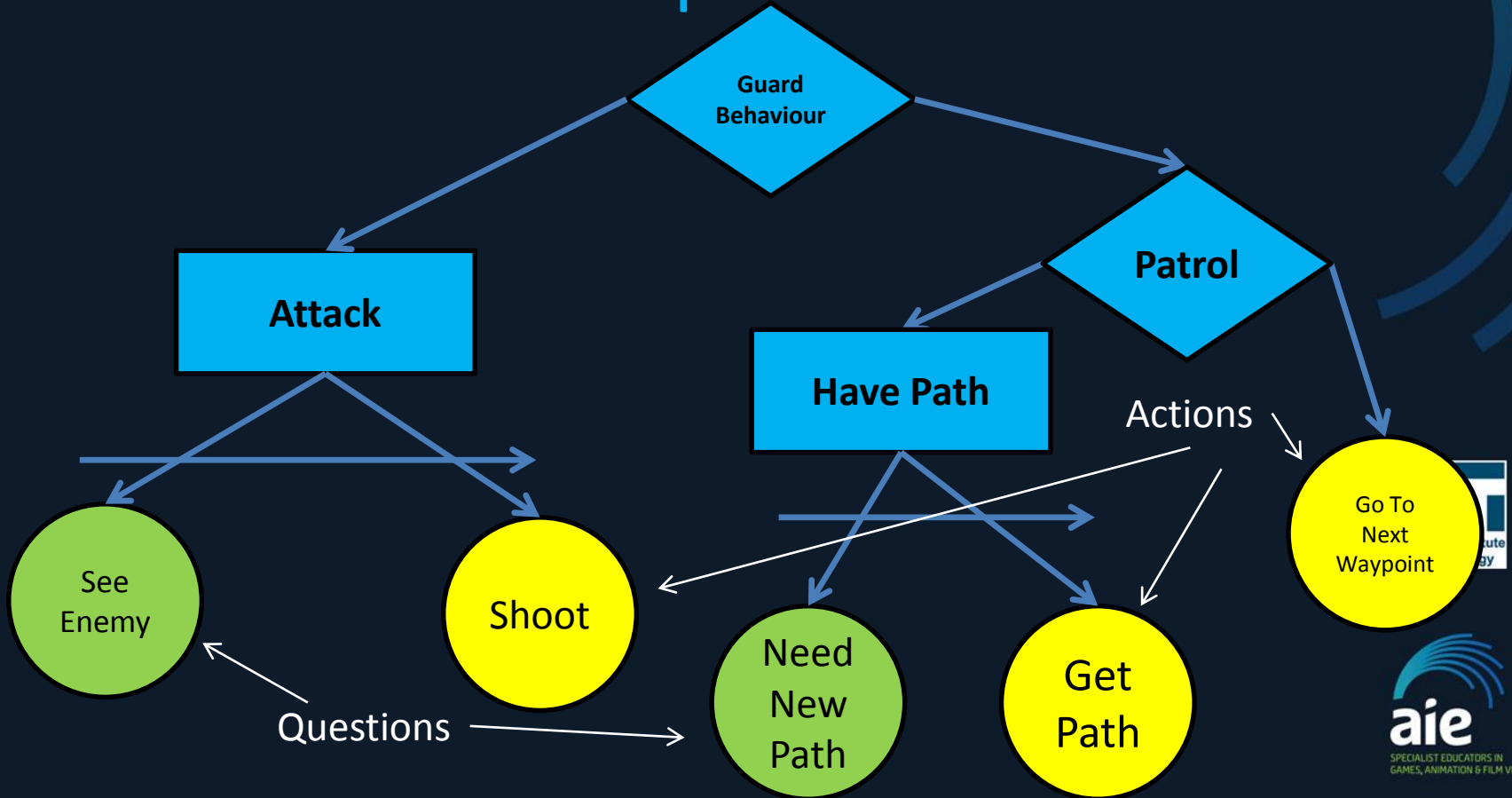
# Behaviour Trees

- Behaviour Trees are a more complicated form of Decision Tree
- Decisions are made based on a composite of “questions” and “actions” rather than a single **YES / NO** question
  - Allows for **AND** and **OR** logic
- Actions are typically broken down into discrete parts
  - **Animate** would be a separate discrete action, as would **Move**, rather than an action that both **Moves** and **Animates** the A.I. agent
  - Multiple Actions may be triggered in one Decision

# Behaviour Tree Example



# Behaviour Tree Example



# Behaviour Tree Nodes

- Behaviour Trees are a tree structure made up of nodes called **Behaviours**
- Behaviours typically come in three types
  - **Composites**, which are Branch nodes that contain child Behaviours
  - **Actions**, which are Leaf nodes in the tree
  - **Conditions**, which are also Leaf nodes in the tree
- All Behaviours, when executed, return if the behaviour was successful
  - **Success** and **Failure** are typical results
  - Some behaviours can return “on-going”

```
enum BehaviourResult
    Success
    Failure

class Behaviour
    func execute(Agent agent) = 0
```

```
class Agent
    Behaviour behaviour

    func update()
        behaviour.execute(this)
```



# Behaviour Tree Actions and Conditions

- An **Action** Behaviour is a behaviour that “does” something
  - Like “Animate”, or “Move a step forward”
  - Typically always return **Success**
- A **Condition** Behaviour is a behaviour that “asks” something
  - For example, “is health almost empty”, “can see enemy”
  - Returns **Success** or **Failure**



```
class AttackAction : Behaviour
    integer damageToApply
    float range

    func execute(Agent agent)
        for each enemy within range of agent
            enemy.damage -= damageToApply
        return BehaviourResult.Success
```



```
class EnemiesCloseCondition : Behaviour
    float range

    func execute(Agent agent)
        for each enemy
            if distance(enemy, agent) < range
                return BehaviourResult.Success
        return BehaviourResult.Failure
```

# Behaviour Tree Composite Nodes

- **Composite** Behaviours have multiple child Behaviours
  - For example, a Decision in a Decision Tree would be a Composite with 2 children
  - Composites return a result based off their child nodes
  - There are a few types of Composite, two common types being **Selector** and **Sequence**
- Composites are what differentiate a behaviour Tree from a Decision Tree
  - They add the **AND** and **OR** logic
  - Allow multiple conditions and actions

```
class CompositeBehaviour : Behaviour
    list childBehaviours

    func execute(Agent agent) = 0
```



# Selector Composite Nodes

- A **Selector** is a **Composite** node that returns Success if one of its child nodes returns Success
  - For example:
    - If a child returns Success then the Selector returns Success without executing its remaining child Behaviours
    - If a child returned Failure then it would execute the next child Behaviour
    - If all child behaviours return Failure then the Selector returns Failure
- A **Selector** acts as an **OR**
  - Result = A **OR** B **OR** C **OR** etc etc

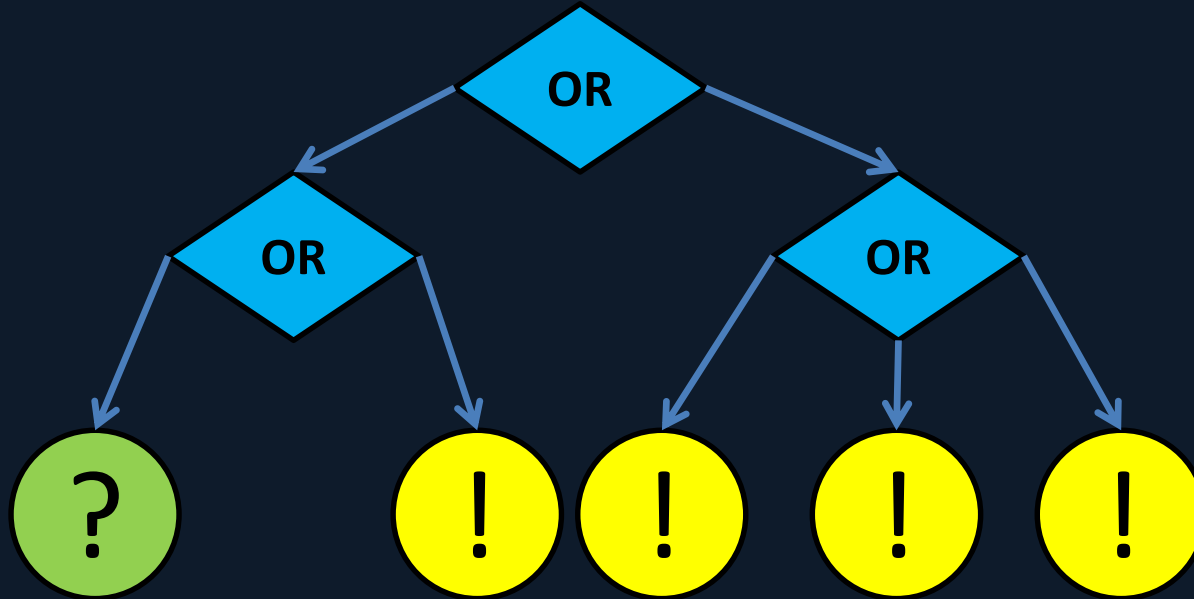


```
class Selector : CompositeBehaviour

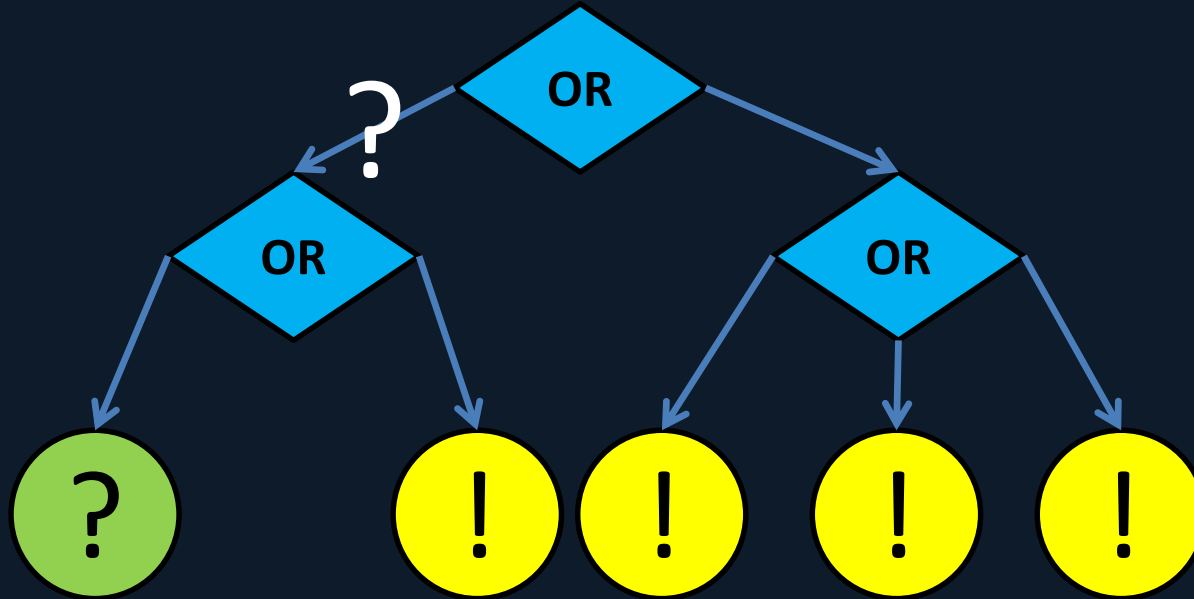
    func execute(Agent agent)
        for each child in childBehaviours
            if child.execute(agent) == BehaviourResult.Success
                return BehaviourResult.Success
        return BehaviourResult.Failure
```



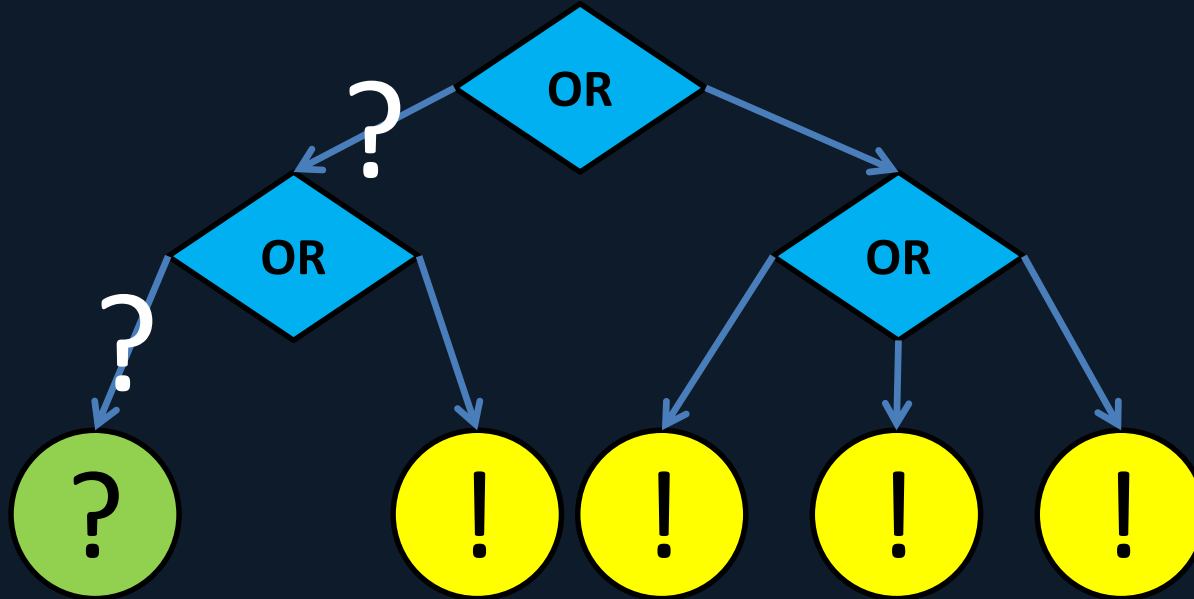
# Selector Composite Nodes



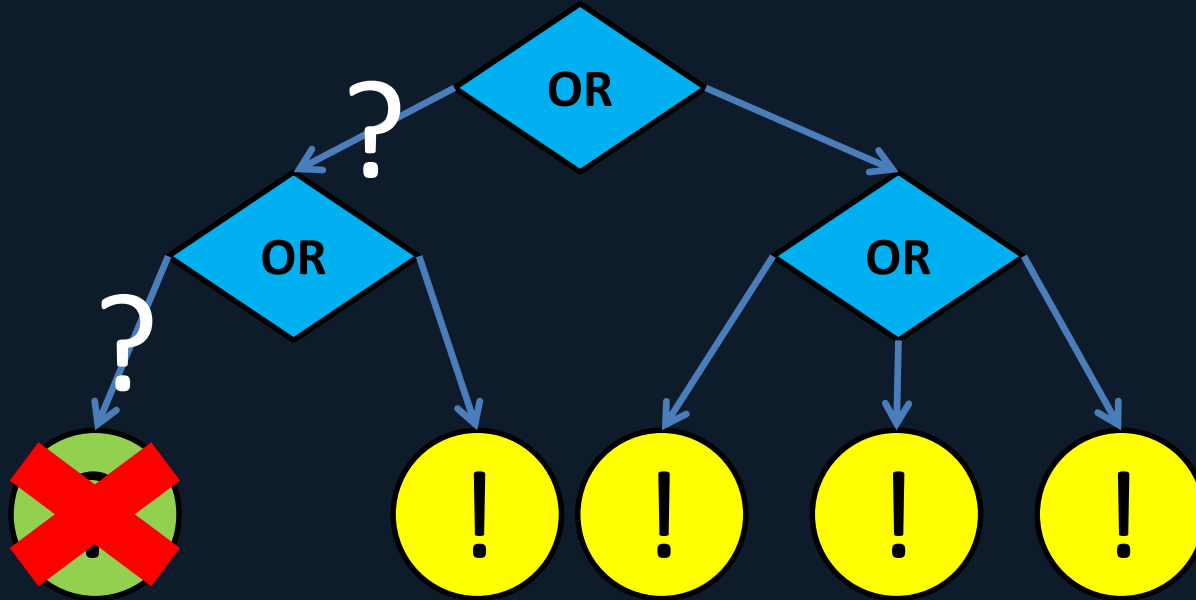
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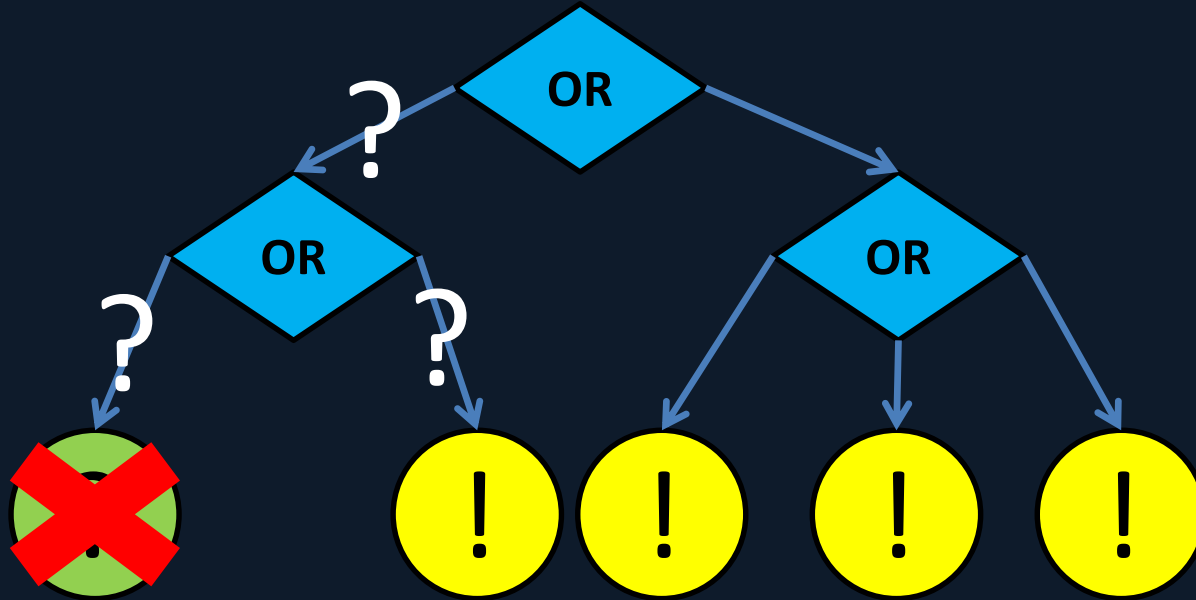
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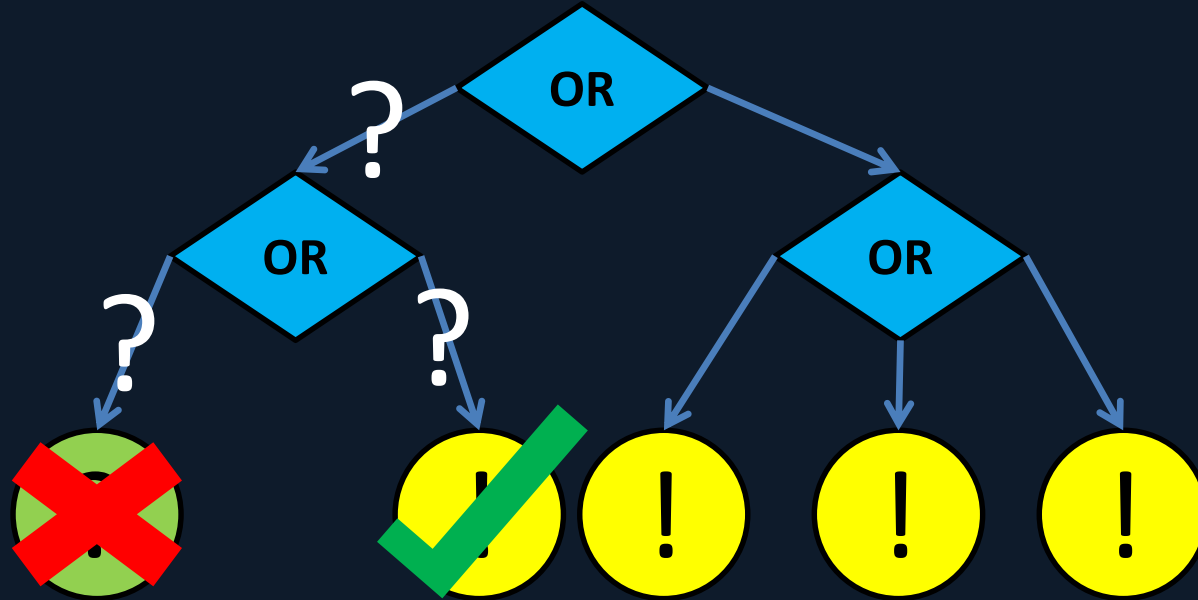
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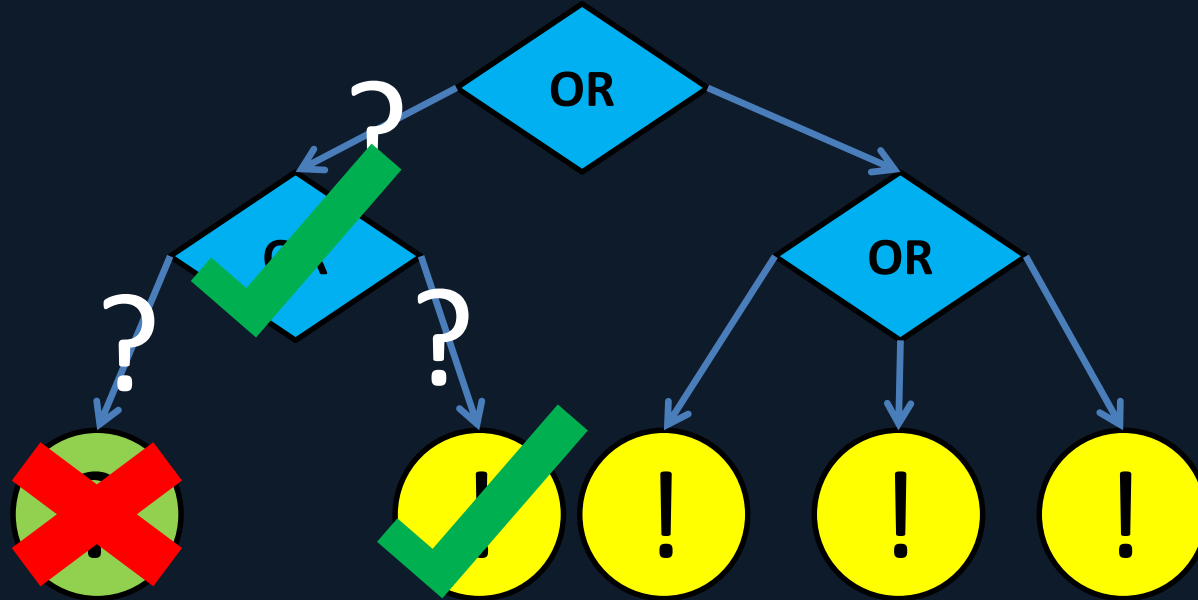
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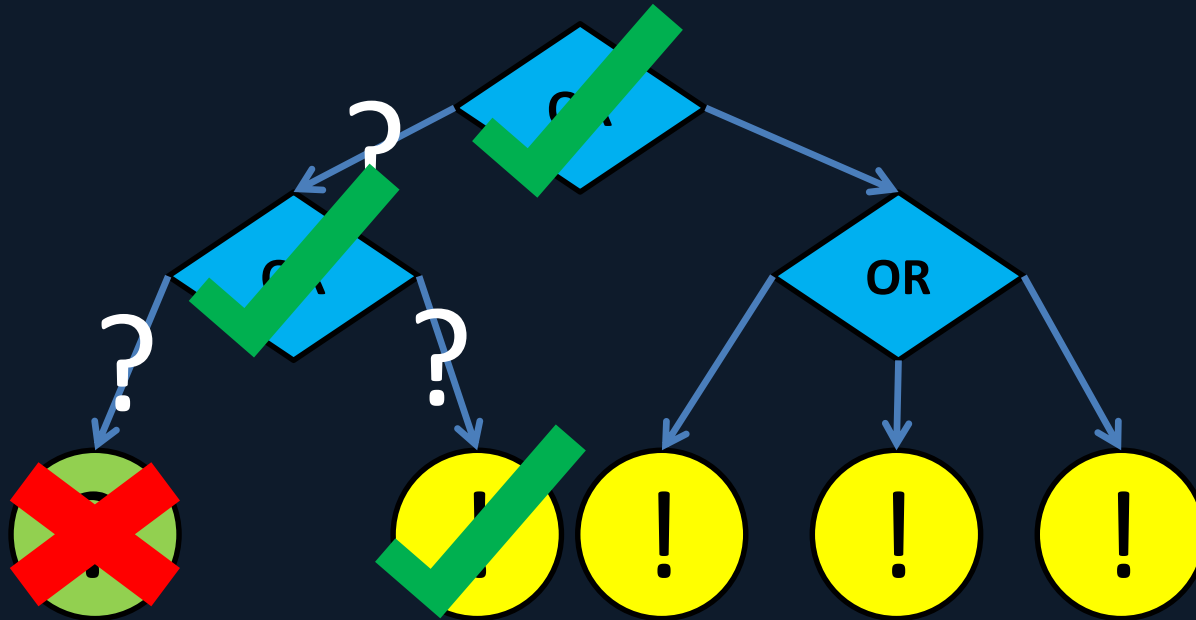
# Selector Composite Nodes



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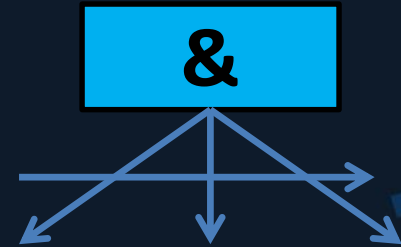
# Selector Composite Nodes





# Sequence Composite Nodes

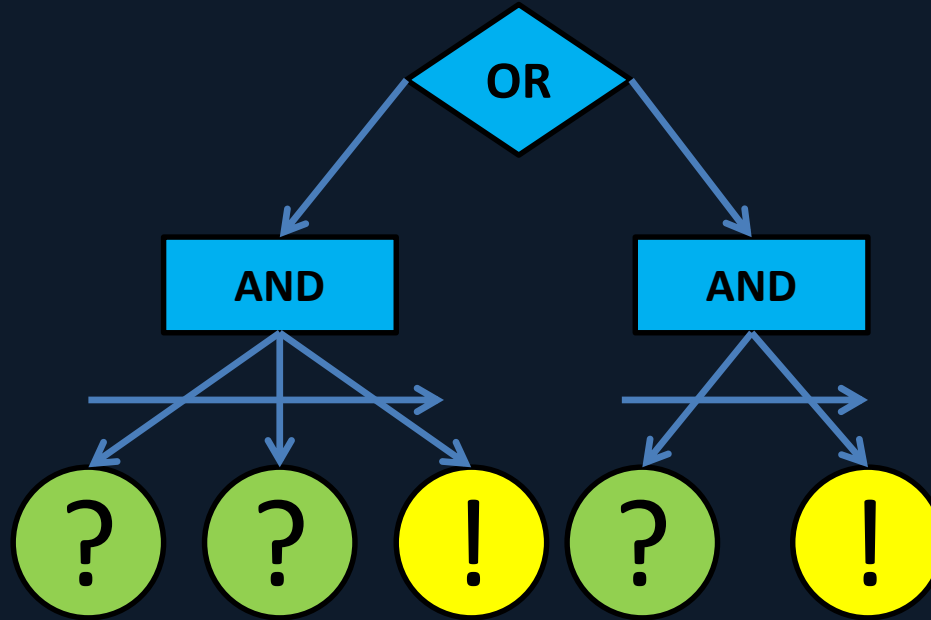
- A **Sequence** is a **Composite** node that returns Success if all of its child nodes returns Success
  - For example:
    - If a child returned Failure then it would return Failure and not execute the remaining child behaviours
    - If all child behaviours return Success then the Sequence returns Success
  - Typically executes in a set order, commonly denoted with an arrow across the branches
- A **Sequence** acts as an **AND**
  - Result = A **AND** B **AND** C **AND** etc



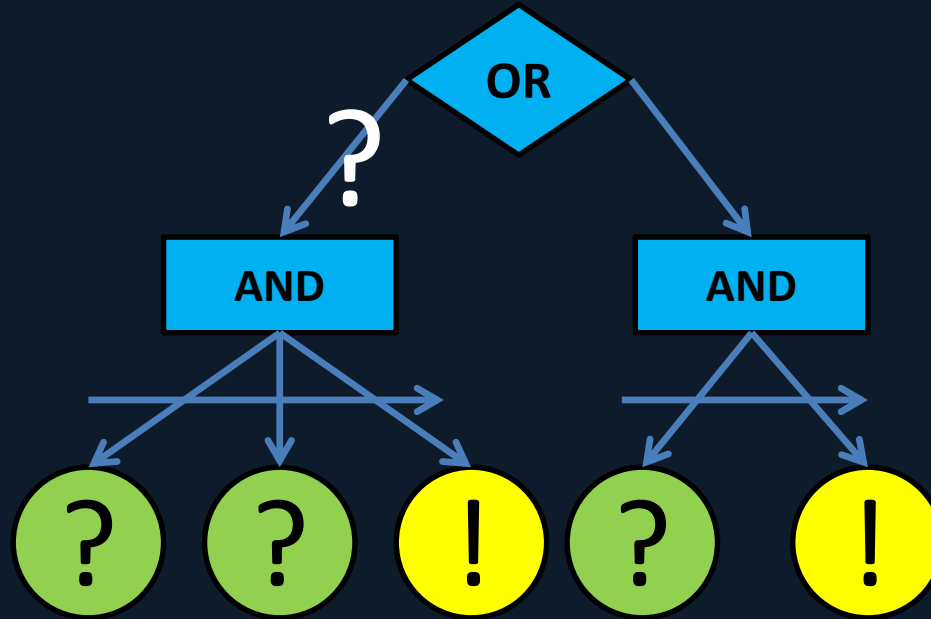
```
class Sequence : CompositeBehaviour

    func execute(Agent agent)
        for each child in childBehaviours
            if child.execute(agent) == BehaviourResult.Failure
                return BehaviourResult.Failure
        return BehaviourResult.Success
```

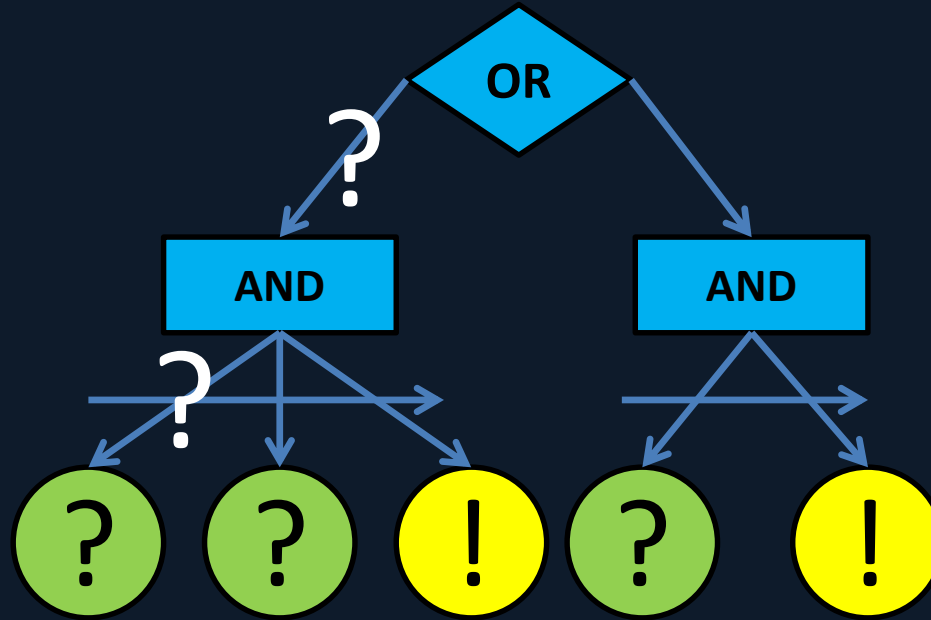
# Sequence Composite Nodes



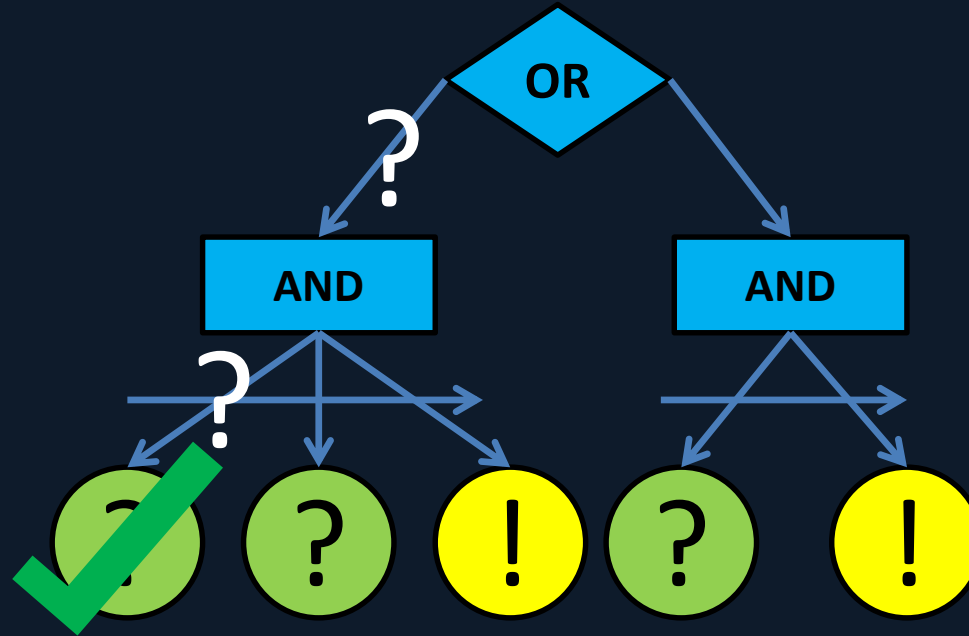
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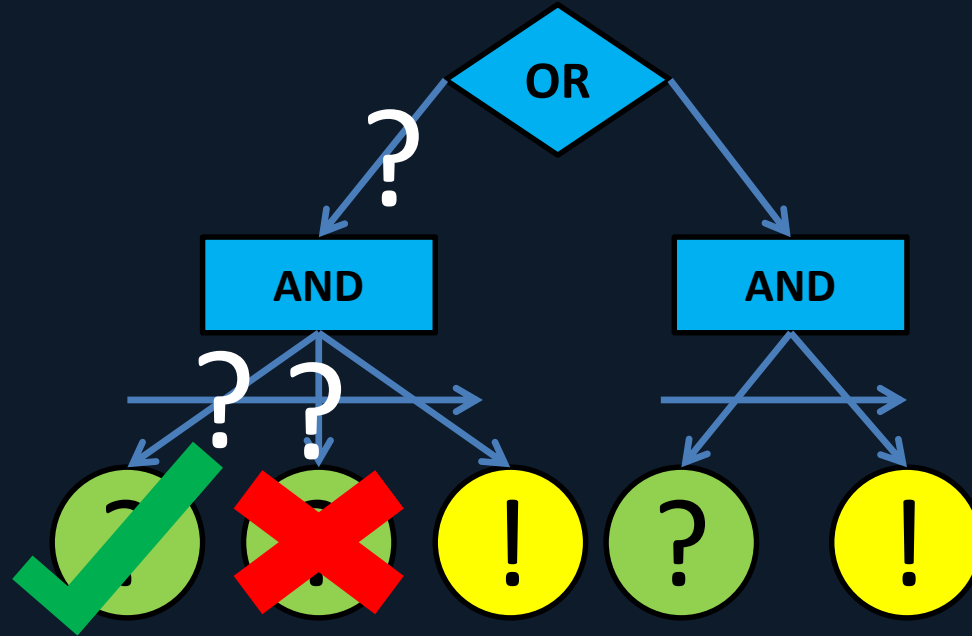
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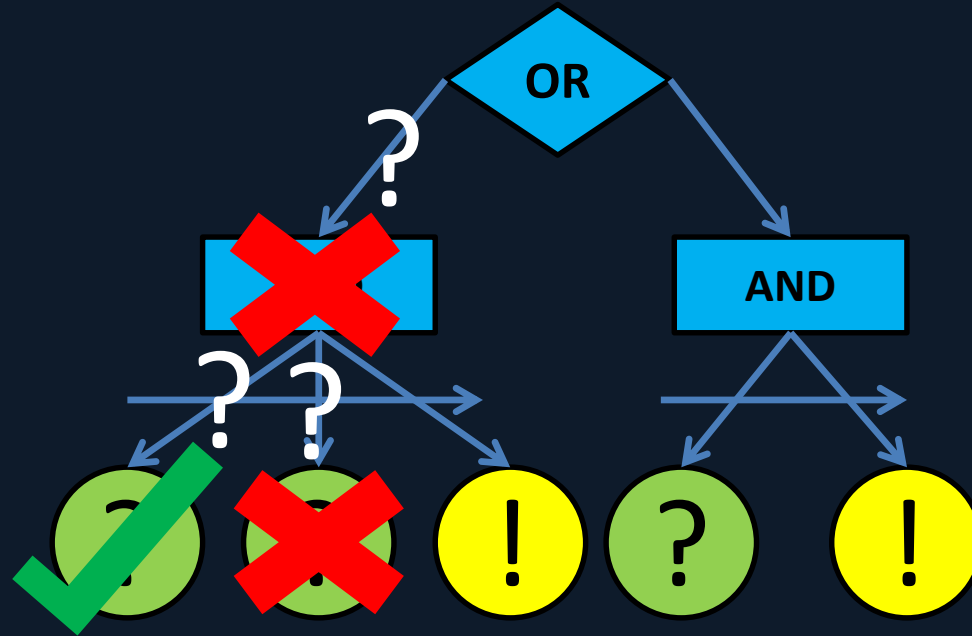
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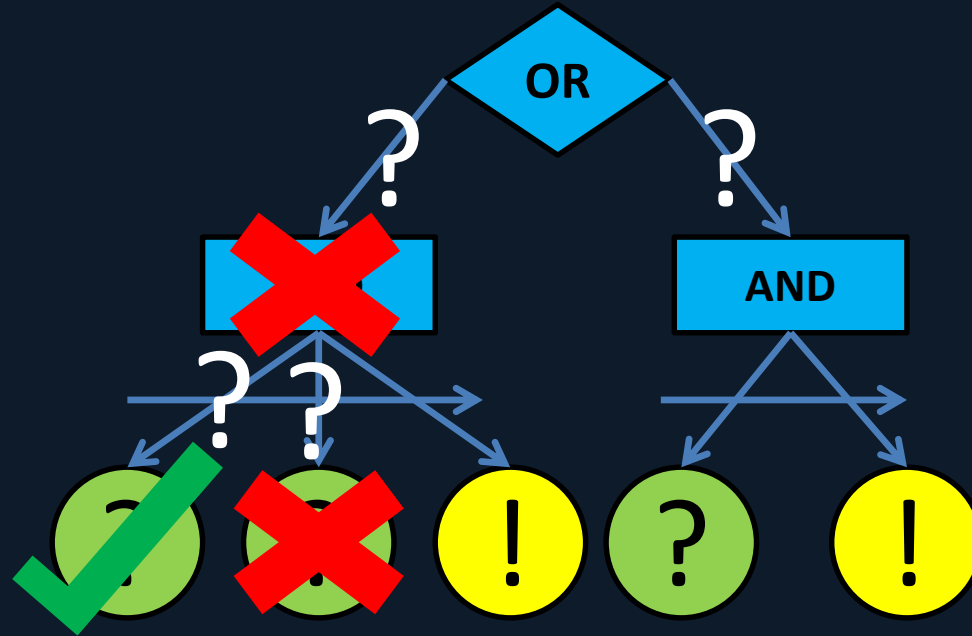
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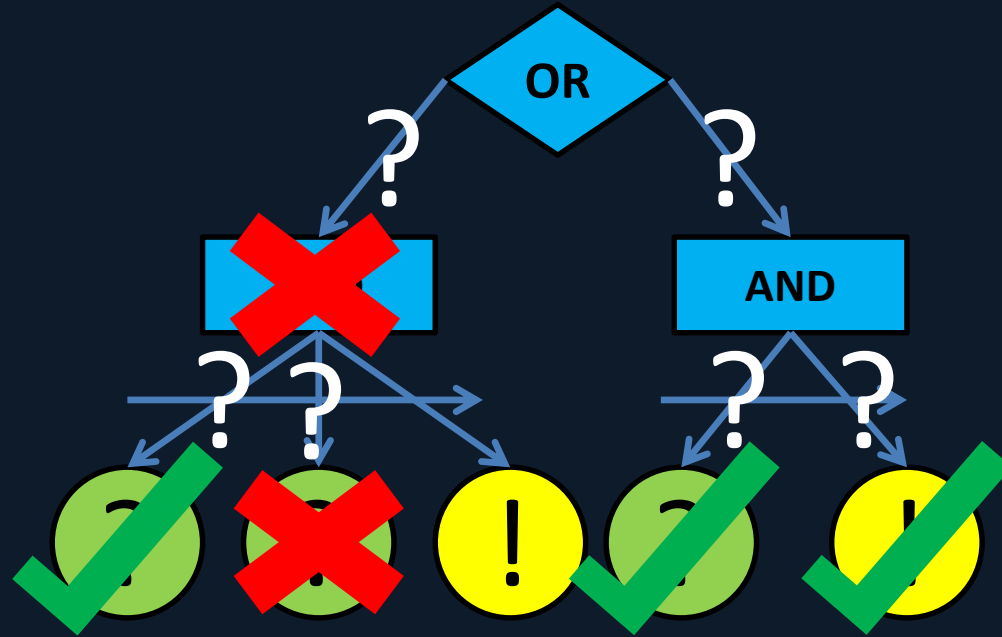


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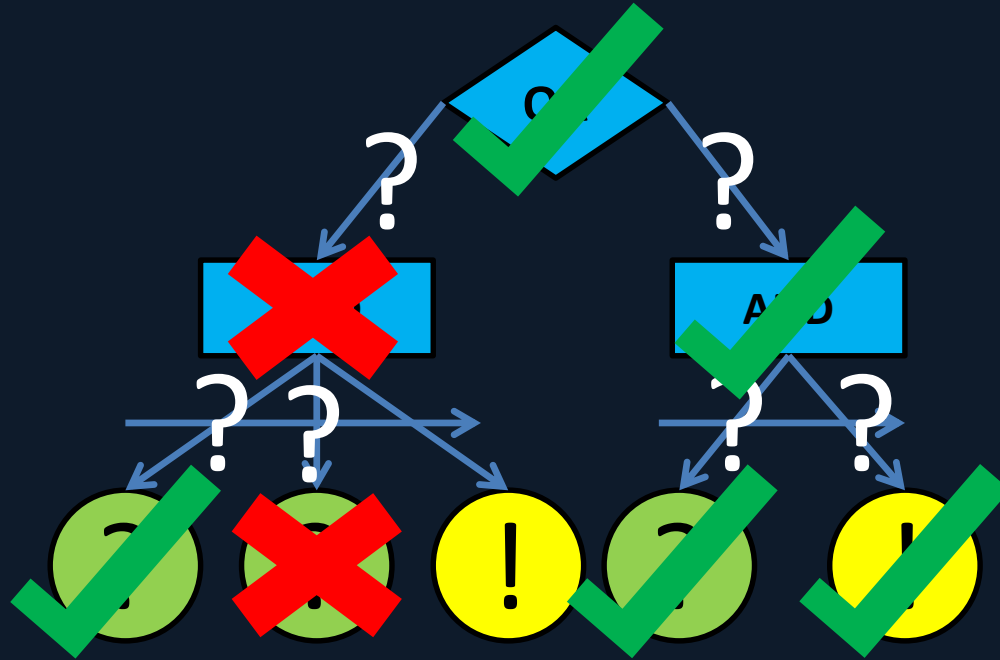




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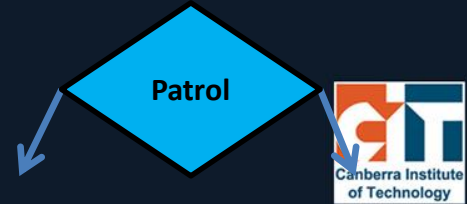
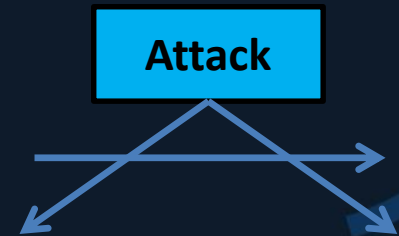


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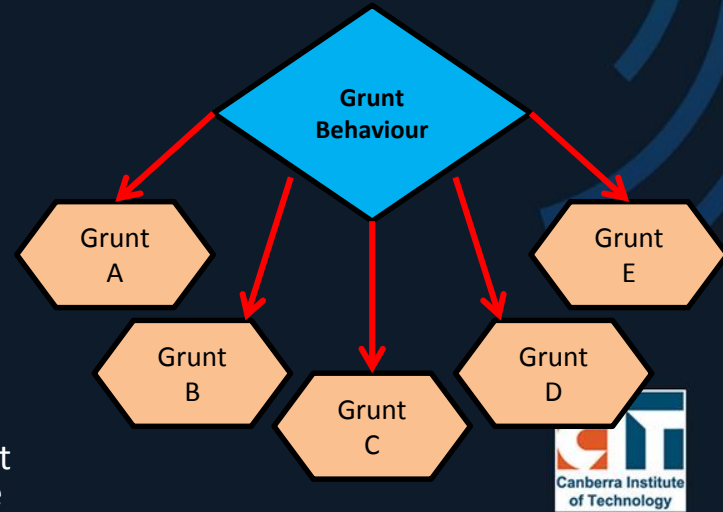
# Sub-Behaviours and Reusability

- Branches in a Behaviour Tree typically represent sub-behaviours
  - Abstract idea
  - **Attack**, **Patrol** etc
- Sub-behaviours can be designed and inserted in to multiple trees and reused
  - For example, a Patrol branch could be used in a **GruntSoldier's** Behaviour Tree and also a **BossSoldier's** Behaviour Tree



# Sub-Behaviours and Reusability

- A Behaviour Tree can also be used by multiple agents
  - Only works if the variables within a behaviour don't change!
    - Changeable data should be stored within the agents themselves
    - For example, the amount of damage that an attack action causes can be within the behaviour or, if it depends on the weapon being carried, the value comes from the attacking agent and not the behaviour
    - Or another example, if an Attack action has a timeout then the timer should be a part of the agent, and the length of the timeout duration would be a part of the behaviour



# Advantages

- Responds to interruptions
- Re-usable Behaviours
  - Sub-Trees of Behaviours (like a patrol tree) can be re-used within other trees (for example, in an **AngrySoldier** tree and a **ScaredGuard** tree)
- New Behaviours can be written as individual pieces of code without reliance on other behaviours
- Easily understood logic for designers
  - A tool could be written and given to a designer to build complex behaviours, with very little training required

# Disadvantages

- For small behaviours can be a complex initial setup
  - A simple FSM might be better
- Difficult to setup without a tool
  - Coding a Behaviour Tree is fine, but a designer would usually be setting up Behaviour Trees for Agents
- Executing a large tree from the top can take a lot of processing

# Summary

- Behaviour Trees have become the primary tool for A.I. in AAA games
  - Easily understood logic for designers and coders alike
- Behaviours can be broken down into discrete actions, sub-behaviours and constructed into overall behaviours