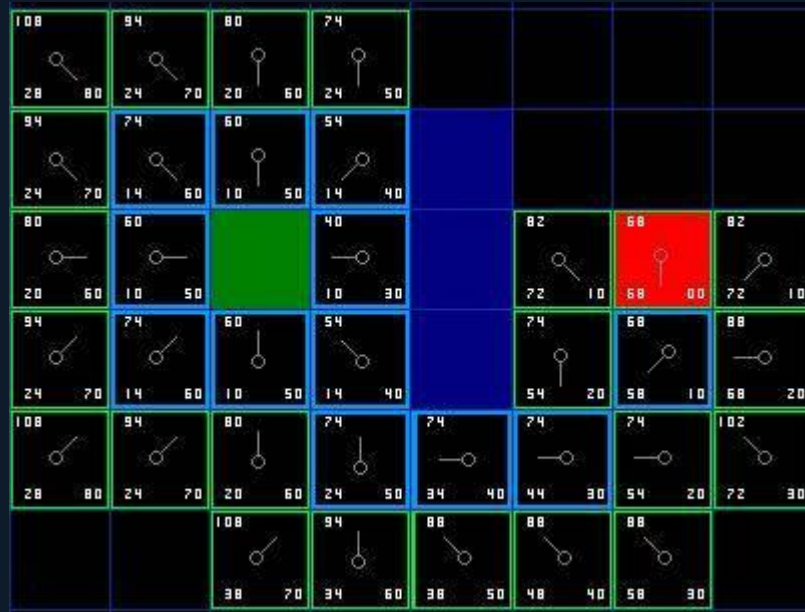


# A\* - Part 2



# Lecture Contents

- More Advanced A\* Graphs
  - Choosing edge weights
  - One way paths
- A Variety of Heuristics
  - Grid Based Graphs
  - 8 Way Graphs
- Arbitrary Position Nodes
- Admissible and Nonadmissible Heuristics
- Breaking Ties

# More Advanced A\* Graphs

- So far we've described simple pathfinding graphs, where each edge weight is the distance between the two nodes.
- We can add a lot more variety to our graphs by adding a few more options.

# Choosing Edge Weights

- So far we've only covered using the distances between nodes as the cost of the edges.
- There are many other weightings we could apply to our graphs.
  - Weightings based on *terrain types*
    - Swamps would be much slower than dry land.
  - Weightings based on danger levels
    - You might want your agents to avoid the enemy base or other dangerous areas.
  - Different types of agents
    - You might not store the weightings directly in the edges themselves.
      - Instead just store what kind of terrain it is
    - Different agents in the game could have their own table of weightings based on terrain types
      - A tank would have very different weightings to a bicycle

# Choosing a Heuristic

- The Heuristic for an A\* search has a huge impact on how fast the algorithm runs, as well as what your final path is.
- As such we want to be able to understand all the options of heuristic available to us.

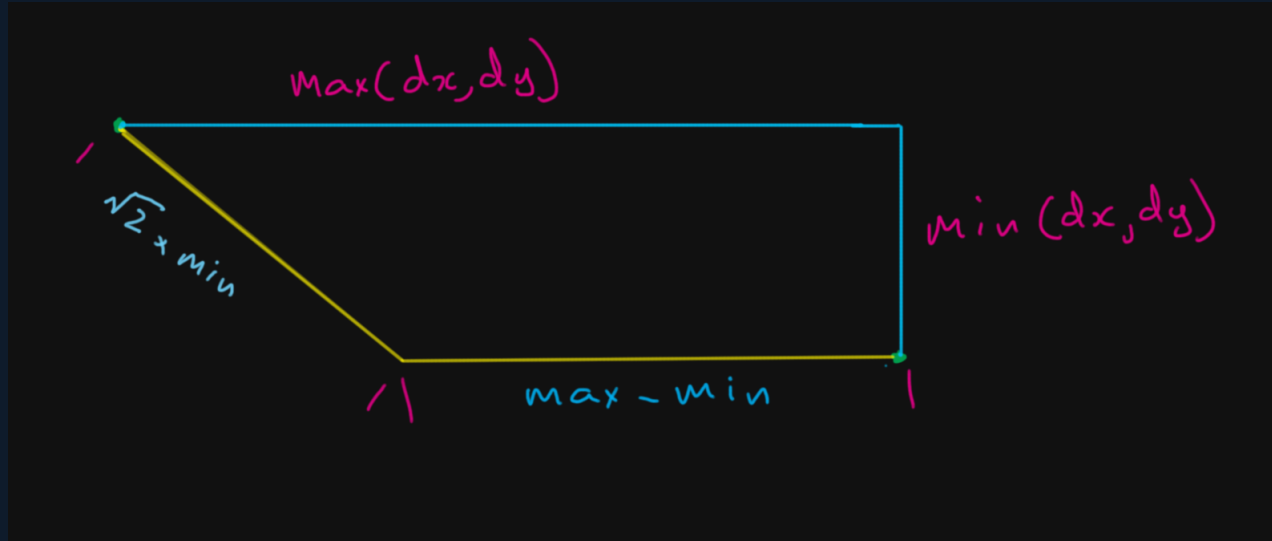


# Heuristics for Different Graph Types

- 8-way grids
  - For 8 way grids, we think about the fact that we can only move in straight lines or at 45 degree angles.
  - We have more freedom than 4 way grids, but using the straight line heuristic still isn't quite accurate.
  - Diagonal movement is efficient, so we want to move as far as we can diagonally and then add the rest of the trip length to the end.

# Heuristics for Different Graph Types

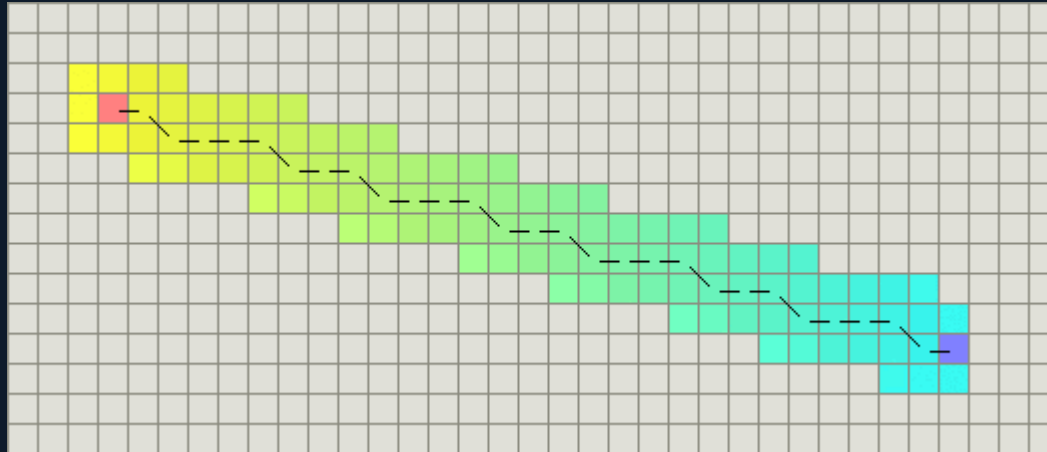
- 8-way grids





# Heuristics for Different Graph Types

- 8-way grids
  - $\text{Sqrt}(2) * \min( dx, dy ) + ( \max( dx, dy ) - \min( dx, dy ) )$



# Heuristics for Different Graph Types

- Arbitrary Nodes
  - Straight Line distance

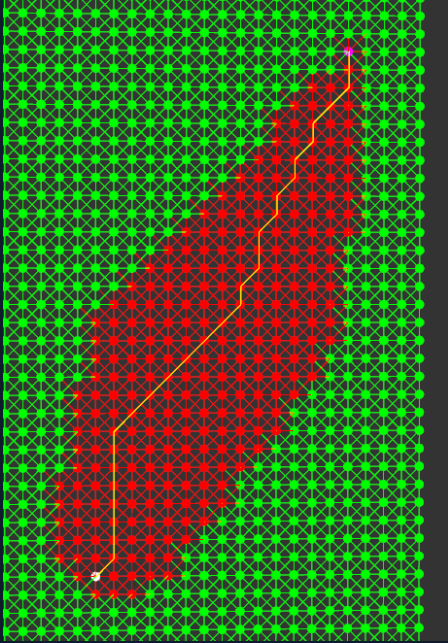
# Admissible Heuristics

- An admissible heuristic is one that always underestimates how close the node is to the goal.
- All the heuristics we've looked at so far have been admissible.
- An admissible heuristic will guarantee  $A^*$  gives the shortest path.

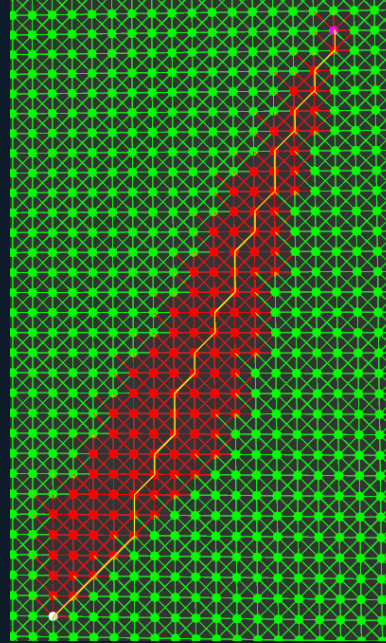
# Inadmissible Heuristics

- Inadmissible Heuristics are ones that sometimes overestimate how close you are to the goal
- Inadmissible heuristics no longer guarantee shortest path, however they can mean that A\* might pick fewer nodes, leading to faster execution.
- The simplest form of inadmissible heuristic is to just multiply your H value by a constant.
- This works really well in empty spaces, but can cause problems when navigating more complex areas.

# Inadmissible Heuristics



$$F = G + H$$



$$F = G + (H * 1.075)$$

# Choosing a Heuristic

- There is no one size fits all best heuristic
- You need to choose the best one for your graph and the entities that will be traversing it.

# Questions?

