

## Assembly file

First print every element on 3d printer. For better usage of feeder, you should glue two parts into one, so bunker is on upper part. Servomotor should be at side of a hole with cap, so it can close the hole. Circuit and servomotor placed at platform at side, but not the sensor. Put ultrasonic sensor above of the hole in bunker. First Arduino must be programmed by firmware file in our repository. It has to work with inputs and outputs. You can see the connections for circuit in gerber file, use it as guide.