TP2

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1 Q1

$$\pi(S_0): S_0 \to a_1, a_2$$

$$\pi(S_1): S_1 \to a_0$$

$$\pi(S_2): S_2 \to a_0$$

$$\pi(S_3): S_3 \to a_0$$

2 Q2

$$V^*(S_0) = R(S_0) + \max_a \gamma \left[T(S_0, a_1, S_1) V^*(S_1) \right]$$
$$= \max_a \gamma \left[V^*(S_1) \right]$$
$$= \max_a \gamma \left[V^*(S_2) \right]$$

$$V^*(S_1) = R(S_1) + \max_a \gamma [T(S_1, a_0, S_1)V^*(S_1) + T(S_1, a_0, S_3)V^*(S_3)]$$

$$= \max_a \gamma [(1 - x)V^*(S_1) + xV^*(S_3)]$$

$$= \gamma [(1 - x)V^*(S_1) + xV^*(S_3)]$$

$$= \frac{x\gamma}{1 - \gamma +} V^*(S_3)$$

$$= \frac{x\gamma}{1 - \gamma +} [10 + \gamma V^*(S_0)]$$

$$V^*(S_2) = R(S_2) + \max_a \gamma [T(S_2, a_0, S_0)V^*(S_0) + T(S_2, a_0, S_3)V^*(S_3)]$$

$$= 1 + \max_a \gamma [(1 - y)V^*(S_0) + yV^*(S_3)]$$

$$= 1 + \gamma [(1 - y)V^*(S_0) + yV^*(S_3)]$$

$$= 1 + 10y\gamma + (1 - y\gamma + y\gamma^2)V^*(S_0)$$

$$V^*(S_3) = R(S_3) + \max_a \gamma [T(S_3, a_0, S_0)V^*(S_0)]$$

= 10 + \max_a \gamma [V^*(S_0)]
= 10 + \gamma V^*(S_0)

3 Q3

If there exist a x that makes

$$\pi(S_0): S_0 \to a_2$$

so it means

$$V^*(S_2) > V^*(S_1)$$

Then we need to know

$$V^*(S_1) - V^*(S_2) = \frac{x\gamma}{1 - \gamma + x\gamma} [10 + \gamma V^*(S_0)] - [1 + 10y\gamma + (1 - y\gamma + y\gamma^2)V^*(S_0)]$$

Considering

$$V^*(S_0) = 0$$

so we can calculate

$$V^*(S_1) - V^*(S_2) = \frac{x\gamma}{1 - \gamma + x\gamma} * 10 - (1 + 10y\gamma)$$

$$= \frac{10x\gamma - (1 + 10y\gamma)(1 - \gamma + x\gamma)}{1 - \gamma + x\gamma}$$

$$= \frac{(9 - 10y)x\gamma - (1 + 10y\gamma)(1 - \gamma)}{1 - \gamma + x\gamma}$$

We need to discuss about different situation. Firstly, if y is greater than 0.9, so

$$9 - 10y \le 0$$

there always exists

$$V^*(S_2) \ge V^*(S_1)$$

If y is less than 0.9, we need to know the minimal value of x. With the value of y increasing, the function "9-10y" is monotonically decreasing and the function "1+10y γ " is monotonically increasing. We observe that if we want to have the minimal value of x, we need to increase the value of the function

"9-10y" and decrease the value of the function "1+10y γ ". In that case, we choose

$$y = 0$$

Then we can simplify our calculation

$$V^*(S_1) - V^*(S_2) = \frac{9x\gamma - (1 - \gamma)}{1 - \gamma + x\gamma}$$

As

$$V^*(S_2) \ge V^*(S_1)$$

so

$$x \le \frac{1 - \gamma}{9\gamma}$$

With γ is greater than 0 but less than 1, we can know

$$x = 0$$

There exist a value of x (x = 0) that for all y \in [0, 1] $and \gamma \in$ (0, 1), $\pi(S_0): S_0 \rightarrow a_2$

4 Q4

In the question Q3 we have

$$V^{*}(S_{1}) - V^{*}(S_{2}) = \frac{x\gamma}{1 - \gamma + x\gamma} * 10 - (1 + 10y\gamma)$$

$$= \frac{10x\gamma - (1 + 10y\gamma)(1 - \gamma + x\gamma)}{1 - \gamma + x\gamma}$$

$$= \frac{9x\gamma - 1 + \gamma - 10y\gamma(1 - \gamma + x\gamma)}{1 - \gamma + x\gamma}$$

If we want $\pi(S_0): S_0 \to a_1$ that means

$$V^{*}(S_{2}) \leq V^{*}(S_{1})$$

$$V^{*}(S_{1}) - V^{*}(S_{2}) \geq 0$$

$$\frac{9x\gamma - 1 + \gamma - 10y\gamma(1 - \gamma + x\gamma)}{1 - \gamma + x\gamma} \geq 0$$

With $1 - \gamma + x\gamma$ is always greater than 0, we can simplify it:

$$9x\gamma - 1 + \gamma - 10y\gamma(1 - \gamma + x\gamma) \ge 0$$
$$\frac{9x\gamma - 1 + \gamma}{10\gamma(1 - \gamma + x\gamma)} \ge y$$
$$\frac{1}{10\gamma}(9 - \frac{10 + 8\gamma}{1 - \gamma + x\gamma}) \ge y$$

With $x \in (0,1)$,

$$9 - \frac{10 + 8\gamma}{1 - \gamma + x\gamma} \in (9 - \frac{10 + 8\gamma}{1 - \gamma}, -1)$$

That means the value of y is always less than 0, so there isn't any value of y that satisfy the requirement.

5 Q5

$$\pi^* = \{a1, a0, a0, a0\}$$

 $V^* = \{14.18521119, 15.76139333, 15.69747038, 22.76664727\}$

 $python\ code:\ https://github.com/SummerOf15/machine-learning-in-robots$