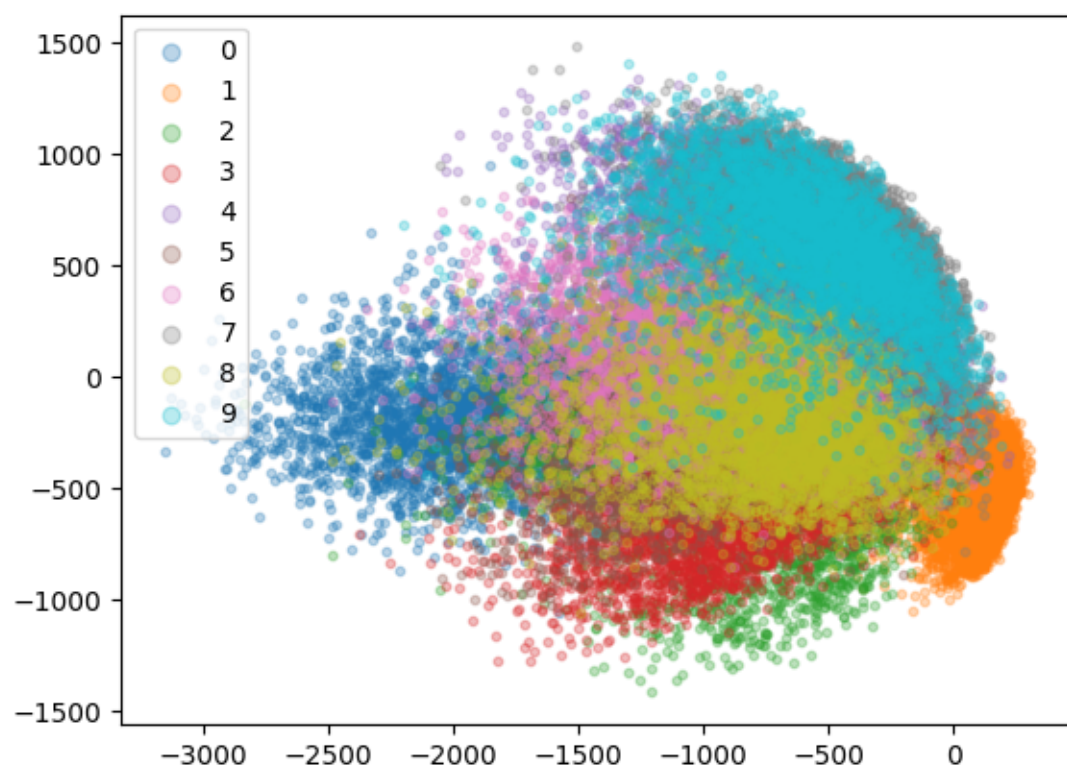


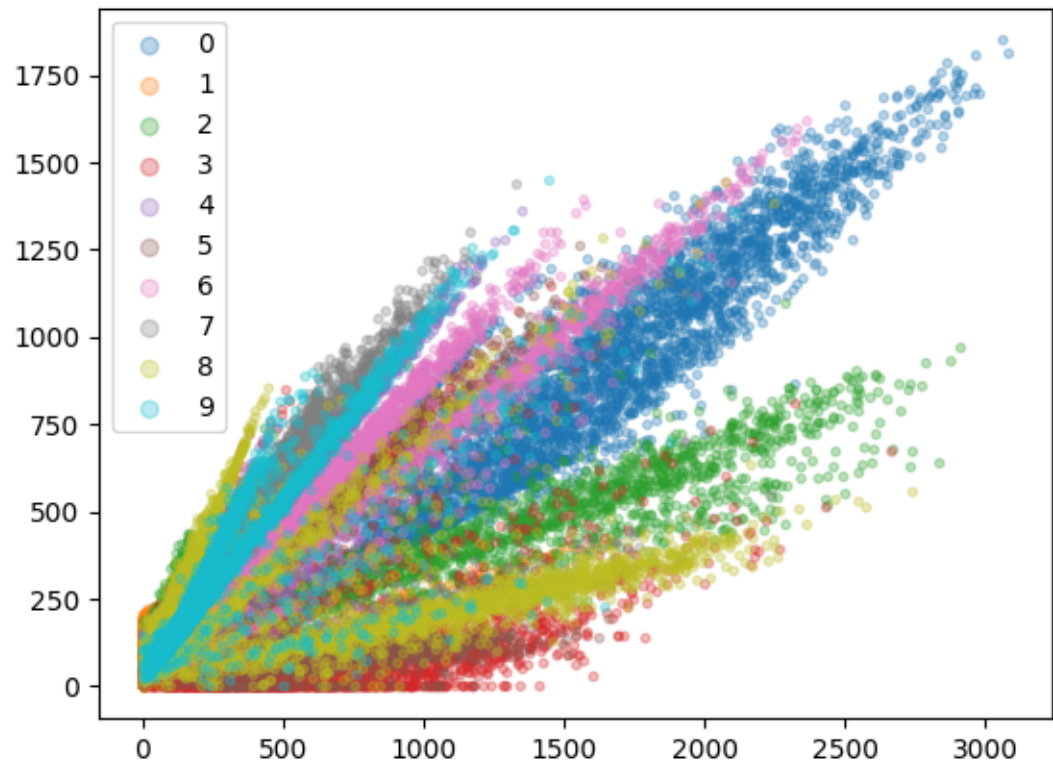
GMDL212, HW6

Yuval Margalit

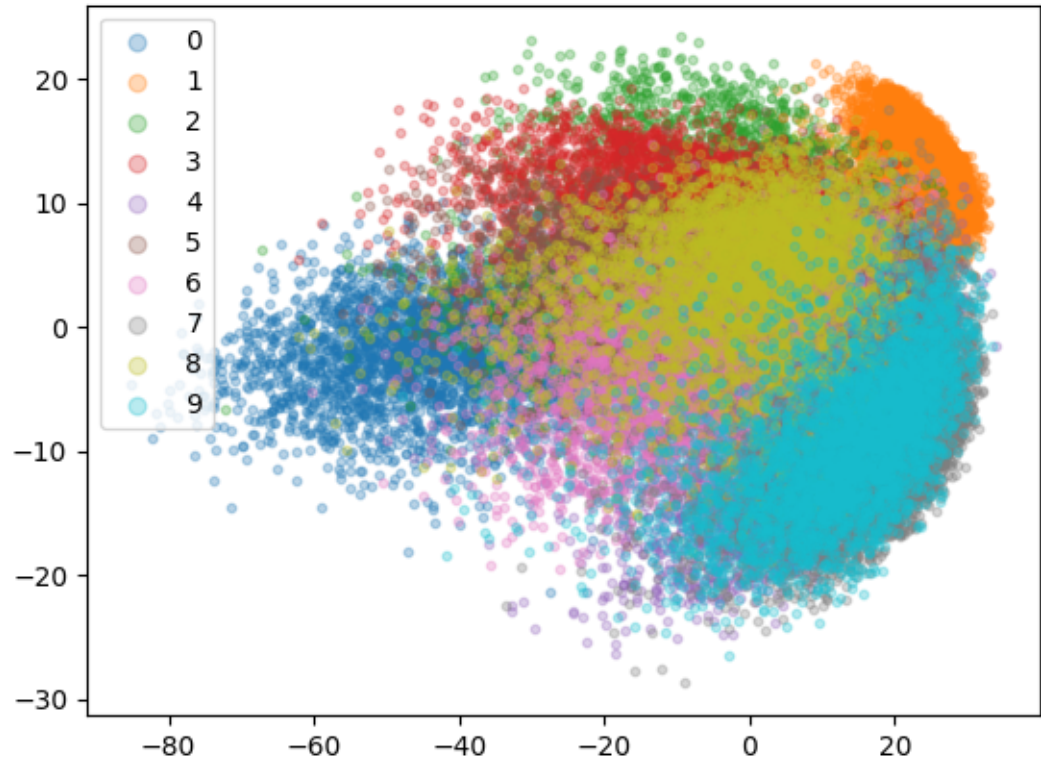
Computer Exercise 2:



Computer Exercise 4:



Computer Exercise 5:



problem 1:

As we can see fiduers 1 and 3 are almost identical and the major difference between them is a rotation and scale both are linear transformations. That means the linear autoencoder converged into something similar to the PCA which is possible because it does not use activation function meaning it can be represented as matrix multiplication. Also, we can recall that PCA is the argmin in relation to Frobenius norm and I choose MSE as my loss. MSE and Frobenius norm have the same argmin so it makes sense that the network converged into something similar to the PCA. There is however a major difference between the autoencoder and the linear autoencoder and the PCA, I believe the activation function I use (ReLU for all layers) made the difference and the encoder learned a non-linear reduction.