

Design and Analysis of Algorithms

Presented by Dr. Li Ning

Shenzhen Institutes of Advanced Technology, Chinese Academy of Science
Shenzhen, China



Algorithm with Graphs

- 1 Graph: The Abstract Data Structure
- 2 Graph Traversal
- 3 Shortest Path
- 4 Minimum Spanning Tree
- 5 Independent Set

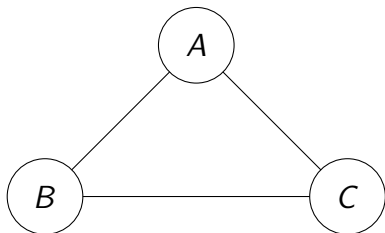
Graph: The Abstract Data Structure

Graph

Graph: a set of **nodes** connected by the **edges**.

$$G = (V, E)$$

- V : the set of nodes
 - A , B , and C
- E : the set of edges
 - (A, B) , (B, C) , and (C, A)

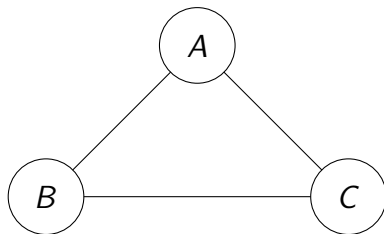


The Undirected Edges

- $(A, B) = (B, A)$
- $(B, C) = (C, B)$
- $(C, A) = (A, C)$

The Cycle

- $A - B - C - A$
- $(A, B), (B, C), (C, A)$

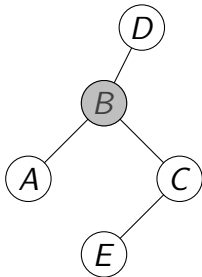


Tree

Tree: The (connected) graph containing no cycle

Take any node as the root, e.g. B

- root B has no parent

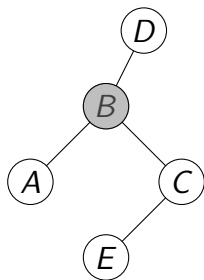


Tree

Tree: The (connected) graph containing no cycle

Take any node as the root, e.g. B

- root B has no parent
- B 's children
 - A
 - parent: B
 - C
 - parent: B
 - child: E
 - D
 - parent: B

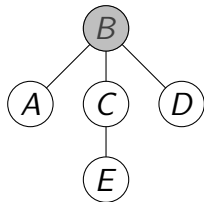


Tree

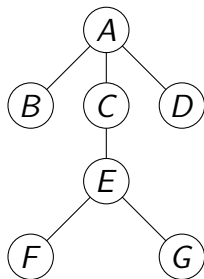
Tree: The (connected) graph containing no cycle

Take any node as the root, e.g. B

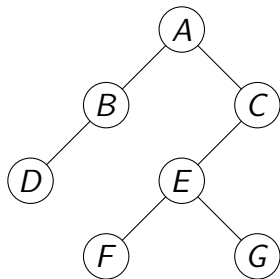
- root B has no parent
- B 's children
 - A
 - parent: B
 - C
 - parent: B
 - child: E
 - D
 - parent: B



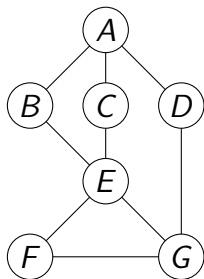
Examples



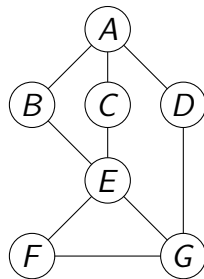
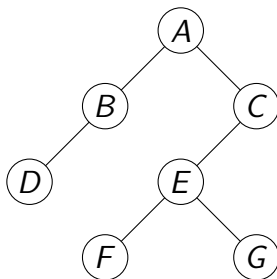
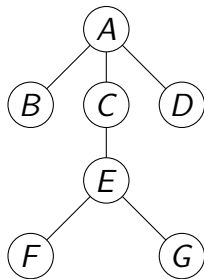
Examples



Examples



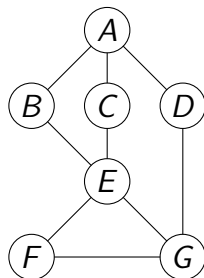
Examples



Graph in Code

Listing 1: graph.py

```
G = {  
    "A" : ["B", "C", "D"],  
    "B" : ["A", "E"],  
    "C" : ["A", "E"],  
    "D" : ["A", "G"],  
    "E" : ["B", "C", "F", "G"],  
    "F" : ["E", "G"],  
    "G" : ["D", "E", "F"],  
}  
  
print("Node D's neighbors:")  
for n in G["D"] :  
    print(n)
```

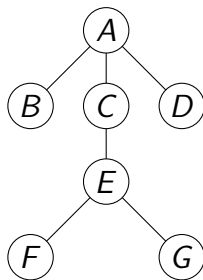


```
>> python graph.py  
Node D's neighbors:  
A  
G
```

Tree in Code

Listing 2: tree.py

```
T = {  
    "A" : (None, ["B", "C", "D"]),  
    "B" : ("A", []),  
    "C" : ("A", ["E", ]),  
    "D" : ("A", []),  
    "E" : ("C", ["F", "G"]),  
    "F" : ("E", []),  
    "G" : ("E", []),  
}  
  
print("Node E's parent:",  
      T["E"][0])  
print("Node E's children:")  
for c in T["E"][1] :  
    print(c)
```



```
>> python tree.py  
Node E's parent: C  
Node E's children:  
F  
G
```

Graph Traversal

Visit The Nodes

Given a graph $G = (V, E)$.

Traversal: starting at node v , visit all the nodes of the graph in a sequence.

Visit The Nodes

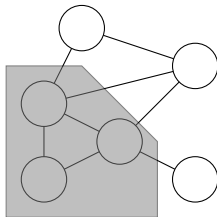
Given a graph $G = (V, E)$.

Traversal: starting at node v , visit all the nodes of the graph in a sequence.

Idea: select the next node to visit among the neighbors of the visited nodes.

Select The Next Node

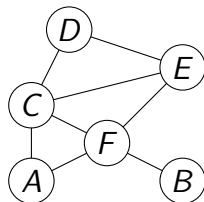
Which neighbor to visit next?



DFS: Depth First Search

Depth-First: go as deep/far as possible.

- visit a node v
 - for each u , s.t. $(v, u) \in E$
 - DFS(u) if not visited

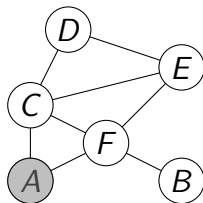


start at A

DFS: Depth First Search

Depth-First: go as deep/far as possible.

- visit a node v
 - for each u , s.t. $(v, u) \in E$
 - DFS(u) if not visited

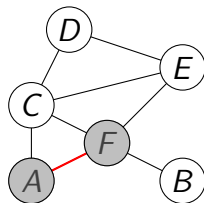


start at A

DFS: Depth First Search

Depth-First: go as deep/far as possible.

- visit a node v
 - for each u , s.t. $(v, u) \in E$
 - DFS(u) if not visited

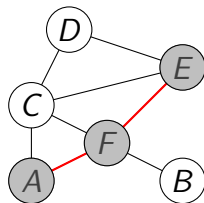


start at A

DFS: Depth First Search

Depth-First: go as deep/far as possible.

- visit a node v
 - for each u , s.t. $(v, u) \in E$
 - DFS(u) if not visited

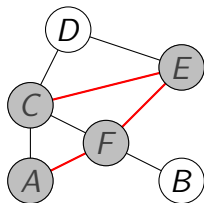


start at A

DFS: Depth First Search

Depth-First: go as deep/far as possible.

- visit a node v
 - for each u , s.t. $(v, u) \in E$
 - DFS(u) if not visited

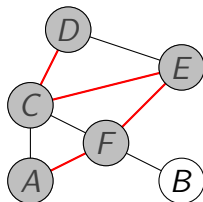


start at A

DFS: Depth First Search

Depth-First: go as deep/far as possible.

- visit a node v
 - for each u , s.t. $(v, u) \in E$
 - DFS(u) if not visited

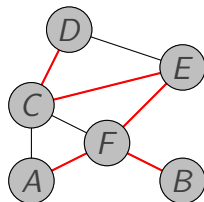


start at A

DFS: Depth First Search

Depth-First: go as deep/far as possible.

- visit a node v
 - for each u , s.t. $(v, u) \in E$
 - DFS(u) if not visited

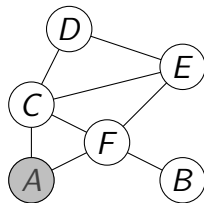


start at A

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

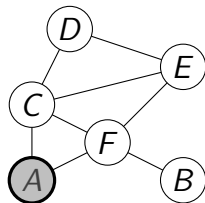


$$q = [A,]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

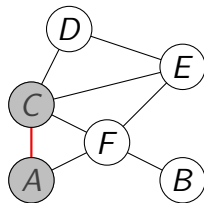


$q = []$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

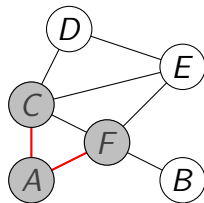


$$q = [C,]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

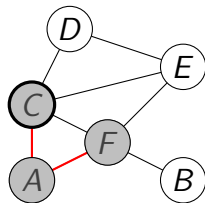


$$q = [C, F]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

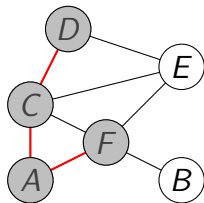


$$q = [F]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

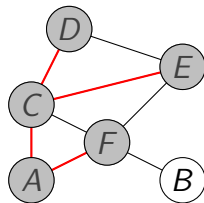


$$q = [F, D]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

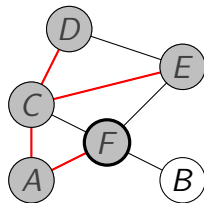


$$q = [F, D, E]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

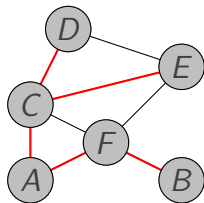


$$q = [D, E]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

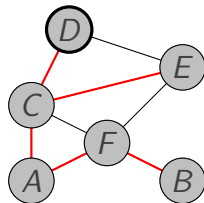


$$q = [D, E, B]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

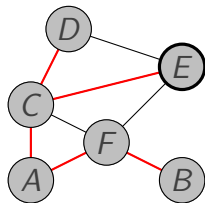


$$q = [E, B]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$

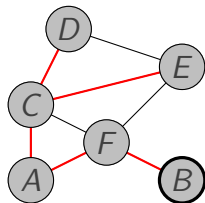


$$q = [B]$$

BFS: Breadth First Search

Breadth-First: explore the nodes layer by layer.

- Starting at the root r .
- Initialize $d = 0$.
- While there is node not visited:
 - visit the nodes that has distance d to the root.
 - $d = d + 1$



$q = []$

Complexity: $O(|V| + |E|)$

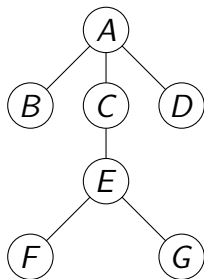
For each node v

- 1 : visit
 - ? : check if v is visited
-
- $O(|V|)$ visits
 - $O(|E|)$ checks

Traversal on Trees

Starting at root, visit the nodes in a sequence.

- **Idea 1:** visit the node before visiting its children
- **Idea 2:** visit the node after visiting its children



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

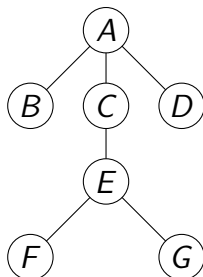
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

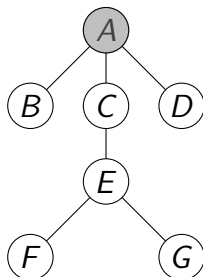
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

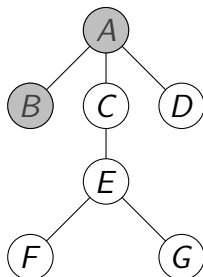
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

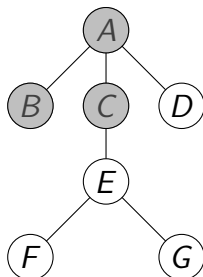
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

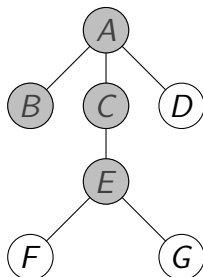
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

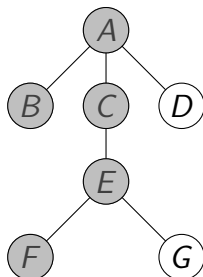
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

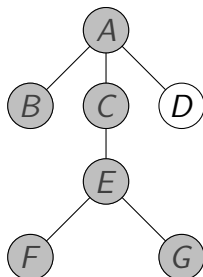
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Preorder Traversal on Trees

Preorder traversal: visit the node before visiting its children.

Algorithm: Preorder(v)

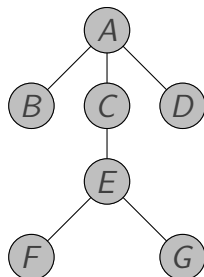
visit node v ;

for v 's each child u **do**

 | Preorder(u);

end

Preorder(A): A, B, C, E, F, G, D



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

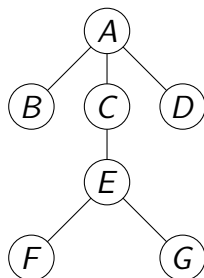
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

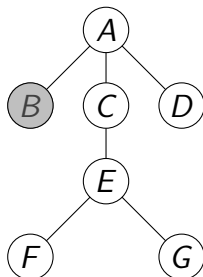
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

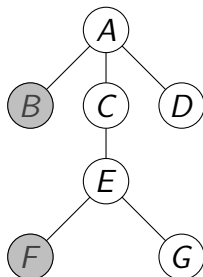
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

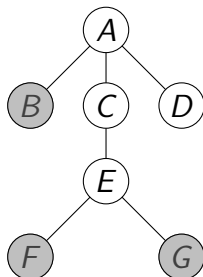
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

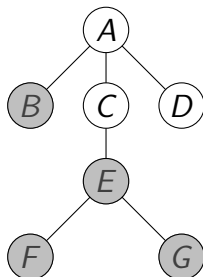
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

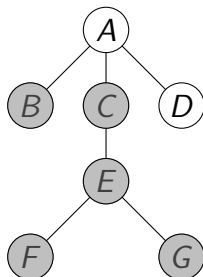
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

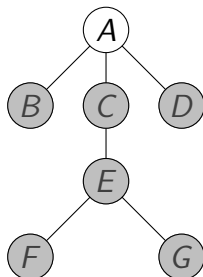
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Postorder Traversal on Trees

Postorder traversal: visit the node after visiting its children.

Algorithm: Postorder(v)

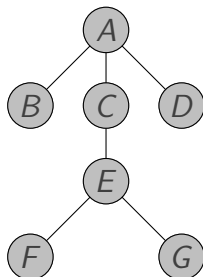
for v 's each child u **do**

 | Postorder(u);

end

visit node v ;

Postorder(A): B, F, G, E, C, D, A



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

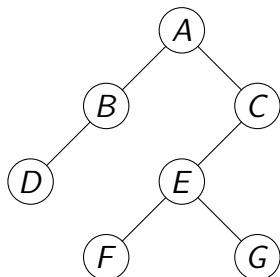
Algorithm: Inorder(v)

Inorder(u' left child);

visit node v ;

Inorder(u' right child);

Inorder(A): D, B, A, F, E, G, C



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

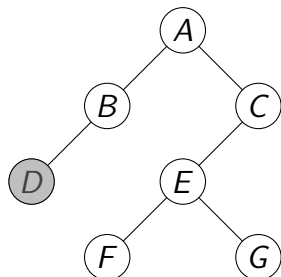
Algorithm: Inorder(v)

Inorder(u' left child);

visit node v ;

Inorder(u' right child);

Inorder(A): D, B, A, F, E, G, C



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

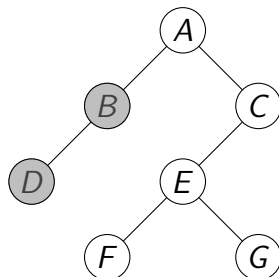
Algorithm: Inorder(v)

Inorder(u' left child);

visit node v ;

Inorder(u' right child);

Inorder(A): D, B, A, F, E, G, C



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

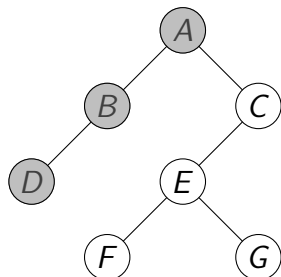
Algorithm: Inorder(v)

Inorder(u' left child);

visit node v ;

Inorder(u' right child);

Inorder(A): D, B, A, F, E, G, C



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

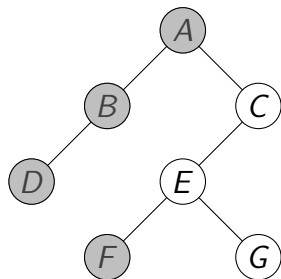
Algorithm: $\text{Inorder}(v)$

$\text{Inorder}(u' \text{ left child});$

visit node v ;

$\text{Inorder}(u' \text{ right child});$

$\text{Inorder}(A): D, B, A, F, E, G, C$



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

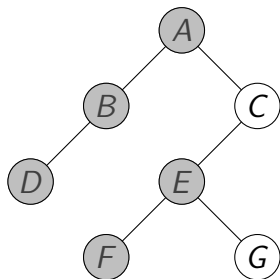
Algorithm: Inorder(v)

Inorder(u' left child);

visit node v ;

Inorder(u' right child);

Inorder(A): D, B, A, F, E, G, C



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

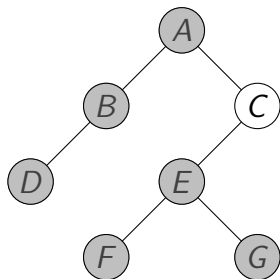
Algorithm: Inorder(v)

Inorder(u' left child);

visit node v ;

Inorder(u' right child);

Inorder(A): D, B, A, F, E, G, C



Inorder Traversal on Binary Trees

Inorder traversal: visit the node between the visiting of the left child and the right child.

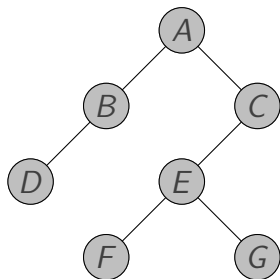
Algorithm: Inorder(v)

Inorder(u' left child);

visit node v ;

Inorder(u' right child);

Inorder(A): D, B, A, F, E, G, C

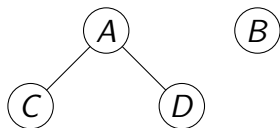


Connectivity

Connected graph: all nodes can be visited through the traversal.

Traversal on graph?

For each node v in $V = [A, B, C, D]$



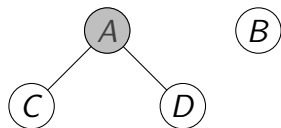
- If v is not visited
 - Traversal starting at v

Connectivity

Connected graph: all nodes can be visited through the traversal.

Traversal on graph?

For each node v in $V = [A, B, C, D]$



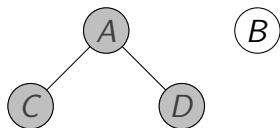
- If v is not visited
 - Traversal starting at v

Connectivity

Connected graph: all nodes can be visited through the traversal.

Traversal on graph?

For each node v in $V = [A, B, C, D]$



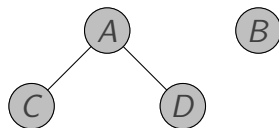
- If v is not visited
 - Traversal starting at v

Connectivity

Connected graph: all nodes can be visited through the traversal.

Traversal on graph?

For each node v in $V = [A, B, C, D]$



- If v is not visited
 - Traversal starting at v

Forest and Tree

Forest: the graph containing no cycle.

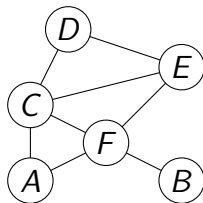
Tree: the **connected** graph containing no cycle.

Shortest Path

Path

Path: a sequence consecutively linked nodes.

- A path: $[A, C, E, F]$
- Not a path: $[A, C, E, B]$
 - E is not linked to B .



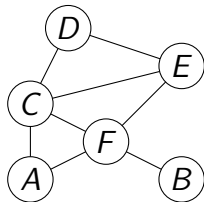
Length: number of the edges in a path.

Shortest Path

Connected graph: for any pair of nodes u and v , there is a path from u to v .

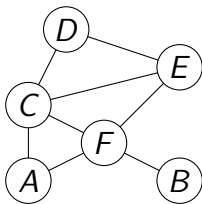
Given two nodes u and v , find the path of minimum length, that connects u and v .

- A to E
 - A, C, E
 - A, F, E
- D to B
 - D, C, F, B
 - D, E, F, B



Shortest Path

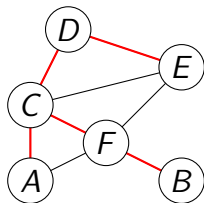
Find the length of the shortest path from D to B .



Shortest Path

Find the length of the shortest path from D to B .

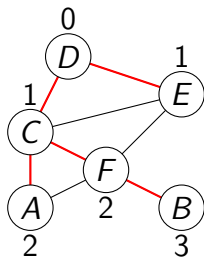
- Perform BFS on the graph, starting at D .



Shortest Path

Find the length of the shortest path from D to B .

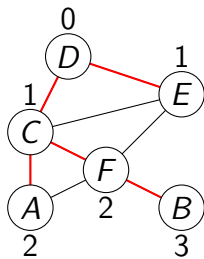
- Perform BFS on the graph, starting at D .
- **Layer** of node v : $1 +$ layer of the node that add v to the explored list.



Shortest Path

Find the length of the shortest path from D to B .

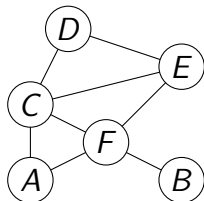
- Perform BFS on the graph, starting at D .
- **Layer** of node v : $1 +$ layer of the node that add v to the explored list.
- Layer of node B = length of the shortest path from D to B .



Weighted Edges

A weight function w maps each edge to a real number.

$$w(v, u) \rightarrow \mathbb{R}^+$$



Weighted Edges

A weight function w maps each edge to a real number.

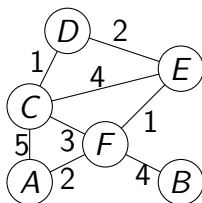
$$w(v, u) \rightarrow \mathbb{R}^+$$

$$w(A, C) = 5; w(A, F) = 2$$

$$w(C, D) = 1; w(C, E) = 4$$

$$w(C, F) = 3; w(D, E) = 2$$

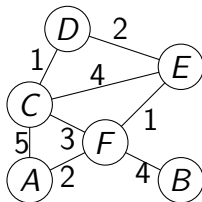
$$w(E, F) = 1; w(B, F) = 4$$



Weighted Path

Given the weight of each edge, the (weighted) length of a path is the sum of the weights of the edges in the path.

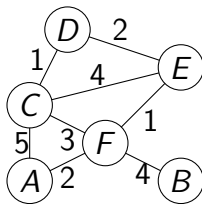
Shortest path: Given a weighted graph and a pair of nodes v and u , find the path of minimum (weighted) length, that connects v and u .



Weighted Path

Shortest path: Given a weighted graph and a pair of nodes v and u , find the path of minimum (weighted) length, that connects v and u .

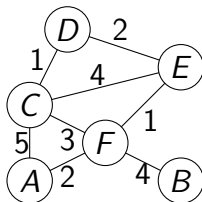
Path $[A, F, E]$ has length $2 + 1 = 3$.



Shortest Path

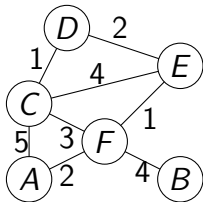
Idea: To calculate the length of the shortest path from s to v , consider an edge (u, v) ,

- $d(s, v) \leq d(s, u) + w(u, v)$
- $d(s, u)?$



Shortest Path

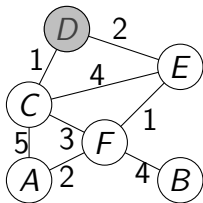
Find the length of the shortest path from D to B .



Shortest Path

Find the length of the shortest path from D to B .

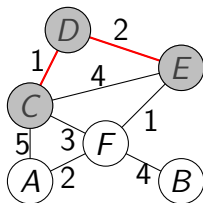
- Initially, we know $d(D, D) = 0$



Shortest Path

Find the length of the shortest path from D to B .

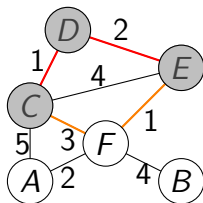
- **Initially**, we know $d(D, D) = 0$
- among all the nodes that $d(D, v)$ is not known
 - $d(D, C) = d(D, D) + w(D, C)$
 - $d(D, E) = d(D, D) + w(D, E)$



Shortest Path

Find the length of the shortest path from D to B .

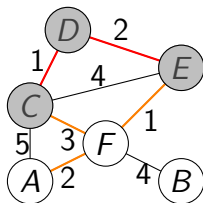
- **Initially**, we know $d(D, D) = 0$
- among all the nodes that $d(D, v)$ is not known
 - $d(D, C) = d(D, D) + w(D, C)$
 - $d(D, E) = d(D, D) + w(D, E)$
- $d(D, F)$
 - $d(D, C) + w(C, F)$
 - $d(D, E) + w(E, F)$
 - $d(D, D) + ?$



Shortest Path

Find the length of the shortest path from D to B .

- **Initially**, we know $d(D, D) = 0$
- among all the nodes that $d(D, v)$ is not known
 - $d(D, C) = d(D, D) + w(D, C)$
 - $d(D, E) = d(D, D) + w(D, E)$
- $d(D, F)$
 - $d(D, C) + w(C, F)$
 - $d(D, E) + w(E, F)$
 - $d(D, D) + ?$
 - $d(D, A) + w(A, F)?$



Dijkstra's Algorithm

$d(s, v)$ length of the shortest path from s to v .

$\delta(s, v)$ length of the shortest path from s to v , **through** S .

To calculate $d(s, v)$ for all nodes $v \in V$.

Dijkstra's Algorithm

$d(s, v)$ length of the shortest path from s to v .

$\delta(s, v)$ length of the shortest path from s to v , **through** S .

To calculate $d(s, v)$ for all nodes $v \in V$.

- Let S be the nodes, s.t.
 - $d(s, u)$ is known, for all $u \in S$
 - $d(s, v)$ for all $v \in V$ are known if $S = V$

Dijkstra's Algorithm

$d(s, v)$ length of the shortest path from s to v .

$\delta(s, v)$ length of the shortest path from s to v , **through** S .

To calculate $d(s, v)$ for all nodes $v \in V$.

- Let S be the nodes, s.t.
 - $d(s, u)$ is known, for all $u \in S$
 - $d(s, v)$ for all $v \in V$ are known if $S = V$
- **initially**, $S = \{s\}$
 - $d(s, s) = 0$
 - $\delta(s, v) = w(s, v)$ if $(s, v) \in E$
 - $\delta(s, v) = \infty$ if $(s, v) \notin E$

Dijkstra's Algorithm

$d(s, v)$ length of the shortest path from s to v .

$\delta(s, v)$ length of the shortest path from s to v , **through** S .

To calculate $d(s, v)$ for all nodes $v \in V$.

- Let S be the nodes, s.t.
 - $d(s, u)$ is known, for all $u \in S$
 - $d(s, v)$ for all $v \in V$ are known if $S = V$
- **initially**, $S = \{s\}$
 - $d(s, s) = 0$
 - $\delta(s, v) = w(s, v)$ if $(s, v) \in E$
 - $\delta(s, v) = \infty$ if $(s, v) \notin E$
- **while** $S \neq V$
 - $u := \arg \min_{u \in V \setminus S} \delta(s, u)$
 - $d(s, u) = \delta(s, u)$

Dijkstra's Algorithm

$$u := \arg \min_{u \in V \setminus S} \delta(s, u) \Rightarrow d(s, u) = \delta(s, u)$$

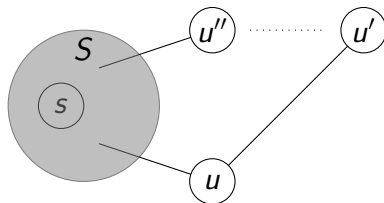
Proof: Assume that $d(s, u) < \delta(s, u)$.

Dijkstra's Algorithm

$$u := \arg \min_{u \in V \setminus S} \delta(s, u) \Rightarrow d(s, u) = \delta(s, u)$$

Proof: Assume that $d(s, u) < \delta(s, u)$.

- $\exists u' \in V \setminus S, d(s, u') + w(u', u) < \delta(s, u)$

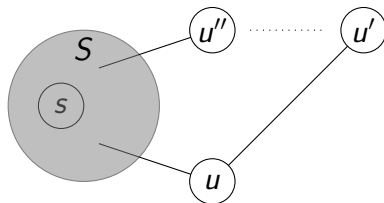


Dijkstra's Algorithm

$$u := \arg \min_{u \in V \setminus S} \delta(s, u) \Rightarrow d(s, u) = \delta(s, u)$$

Proof: Assume that $d(s, u) < \delta(s, u)$.

- $\exists u' \in V \setminus S, d(s, u') + w(u', u) < \delta(s, u)$



- $\delta(s, u'') = d(s, u'') \leq d(s, u') < \delta(s, u)$
- **Contradiction!**

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V;$

$S = \emptyset;$

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0;$

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u);$

$d(s, u) = \delta(s, u);$

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

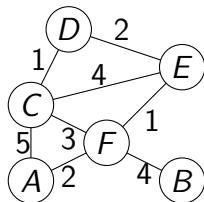
then

$\delta(s, v) = d(s, u) + w(u, v);$

end

end

end



$\delta(D, D) = 0$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

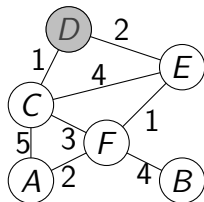
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$d(D, D) = 0$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

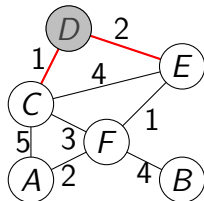
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$\delta(D, C) = 1$

$\delta(D, E) = 2$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

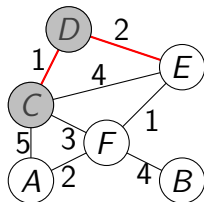
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$d(D, C) = 1$$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

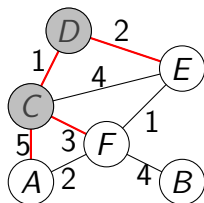
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$\delta(D, E) = 2$$

$$\delta(D, A) = 6$$

$$\delta(D, F) = 4$$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

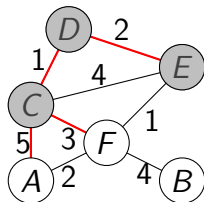
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$d(D, E) = 2$$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

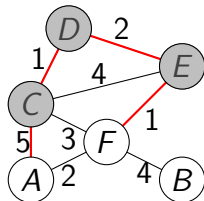
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$\delta(D, A) = 6$

$\delta(D, F) = 3$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

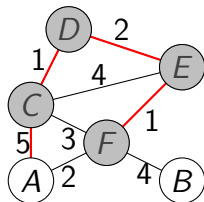
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$d(D, F) = 3$$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

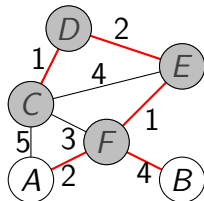
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$\delta(D, A) = 5$$

$$\delta(D, B) = 7$$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

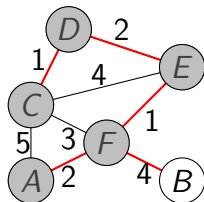
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$d(D, A) = 5$$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

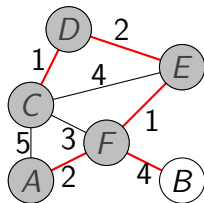
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$\delta(D, B) = 7$$

Dijkstra's Algorithm

Algorithm: Dijkstra(G, s)

$d(s, v) = \infty, \forall v \in V$;

$S = \emptyset$;

$\delta(s, v) = \infty, \forall v \neq s, \delta(s, s) = 0$;

while $S \neq V$ **do**

$u = \arg \min_{u \in V \setminus S} \delta(s, u)$;

$d(s, u) = \delta(s, u)$;

 add u to S ;

for $v \in V \setminus S$ with $(u, v) \in E$ **do**

if $d(s, u) + w(u, v) < \delta(s, v)$

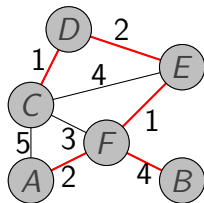
then

$\delta(s, v) = d(s, u) + w(u, v)$;

end

end

end



$$d(D, B) = 7$$

Min-Priority Queue

How to find $u = \arg \min_{u \in V \setminus S} \delta(s, u)$?

Priority: $p(v) \rightarrow \mathbb{R}^+$

- is the queue empty: $O(1)$
- add/remove: $O(\log |V|)$
- get the minimum element: $O(1)$

Implementation: binary heap.

Dijkstra's Algorithm

Keep $\delta(s, v)$ in min-priority queue.

- update $\delta(s, v)$: $O(\log |V|)$
- pop the smallest: $O(\log |V|)$

Complexity: $O((|V| + |E|) \log |V|)$

- $O(|V| \log |V|)$: For each node v , $\delta(s, v)$ is popped for at most 1 time.
- $O(|E| \log |V|)$: For each edges (u, v) , when u is added to S at first, $\delta(s, v)$ is updated.

All Pairs Shortest Path

Problem: Given a graph $G = (V, E)$, calculate the length of shortest path between all pairs of nodes u and v .

$$T = O(|V|) \cdot O((|V| + |E|) \log |V|)$$

- for each node $s \in V$,
 - find $d(s, v)$ for all $v \in V$

$$T = O(|V|^3 \log |V|), \text{ if } |E| = \Omega(|V|^2)$$

Floyd-Warshall Algorithm

Index the n nodes in V

$$v_0, v_1, v_2, \dots, v_{n-1}$$

Dynamic programming: let $d_{i,j}^k$ be the length of the shortest path from v_i to v_j , through $\{v_0, v_1, \dots, v_{k-1}\}$

$$d_{i,j}^k = \begin{cases} w(v_i, v_j) & \text{if } k = 0 \\ \min\{d_{i,j}^{k-1}, d_{i,k-1}^{k-1} + d_{k-1,j}^{k-1}\} & \text{if } k \geq 1 \end{cases}$$

$$O(|V|^3)$$

Negative Weighted Edge: Bellman-Ford Algorithm

Calculate $d(s, v)$ for all $v \in V$, with

$$w(u, v) \rightarrow \mathbb{R}$$

$d_{s,v}^l$: the length of the shortest path from s to v , through at most l nodes.

$$d_{s,v}^l = \begin{cases} w(s, v) & \text{if } l = 0 \\ \min\{d_{s,v}^{l-1}, \min_{(u,v) \in E} \{d_{s,u}^{l-1} + w(u, v)\}\} & \text{if } l \geq 1 \end{cases}$$

Negative weighted cycle: $d_{s,v}^{n-1} < d_{s,v}^{n-2}$ for some v .

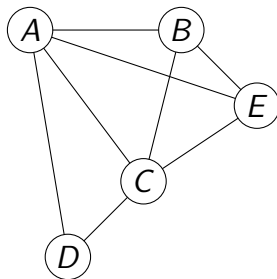
$O(|V||E|)$.

Minimum Spanning Tree

Graph and Spanning Tree

Graph. $G = (V, E)$

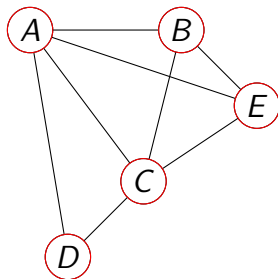
- V : vertices
- E : edges



Graph and Spanning Tree

Graph. $G = (V, E)$

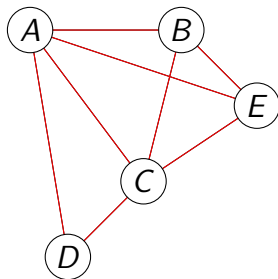
- V : vertices
- E : edges



Graph and Spanning Tree

Graph. $G = (V, E)$

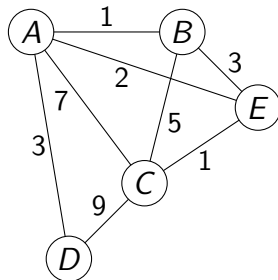
- V : vertices
- E : edges



Graph and Spanning Tree

Graph. $G = (V, E)$

- V : vertices
- E : edges
- W : weights



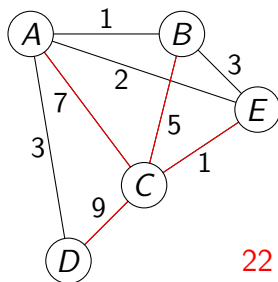
Graph and Spanning Tree

Graph. $G = (V, E)$

- V : vertices
- E : edges
- W : weights

Spanning Tree

- $|V| - 1$ edges
- connect V



Graph and Spanning Tree

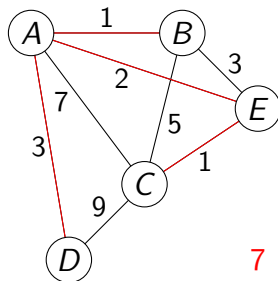
Graph. $G = (V, E)$

- V : vertices
- E : edges
- W : weights

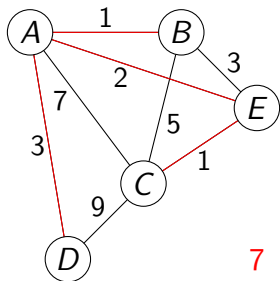
Spanning Tree

- $|V| - 1$ edges
- connect V

Problem: find the spanning tree of the minimum weight (MST).

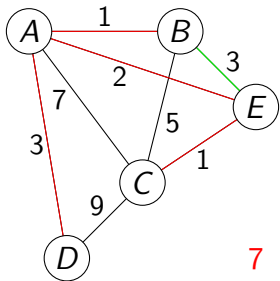


Minimum Spanning Tree: Cycle Property



Minimum Spanning Tree

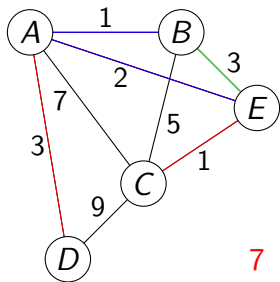
Minimum Spanning Tree: Cycle Property



Minimum Spanning Tree

add one **edge** to MST

Minimum Spanning Tree: Cycle Property

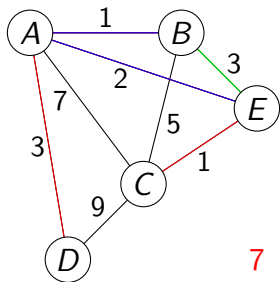


Minimum Spanning Tree

add one **edge** to MST

get a **cycle**

Minimum Spanning Tree: Cycle Property



Minimum Spanning Tree

add one **edge** to MST

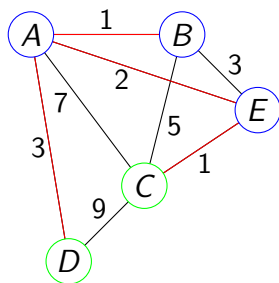
get a **cycle**

edge has the max weight

Minimum Spanning Tree: Smallest Link

Divide V into two parts

- V_1 : A, B, E
- V_2 : C, D



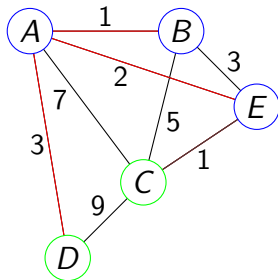
Minimum Spanning Tree: Smallest Link

Divide V into two parts

- V_1 : A, B, E
- V_2 : C, D

Let e be the smallest-weighted edge between V_1 and V_2

- $e = (C, E)$: weight 1
- for any MST, it must contain an edge e' , such that
 - e' links V_1 and V_2
 - $w(e') = w(e)$

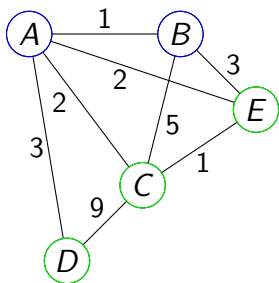


Minimum Spanning Tree: Replacement

Theorem: Given $G = (V, E)$ and w , divide V into two parts V_1 and $V_2 = V \setminus V_1$. Let $e = (u, v)$ be the smallest-weighted edge between V_1 and V_2 . Then for any MST T that does not include e , we can construct MST T' that includes e .

Minimum Spanning Tree: Replacement

Theorem: Given $G = (V, E)$ and w , divide V into two parts V_1 and $V_2 = V \setminus V_1$. Let $e = (u, v)$ be the smallest-weighted edge between V_1 and V_2 . Then for any MST T that does not include e , we can construct MST T' that includes e .

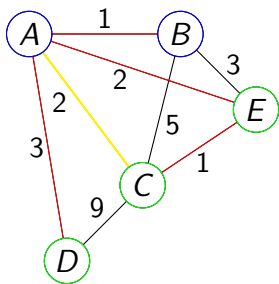


$$V_1 = [A, B]$$

$$V_2 = [C, D, E]$$

Minimum Spanning Tree: Replacement

Theorem: Given $G = (V, E)$ and w , divide V into two parts V_1 and $V_2 = V \setminus V_1$. Let $e = (u, v)$ be the smallest-weighted edge between V_1 and V_2 . Then for any MST T that does not include e , we can construct MST T' that includes e .



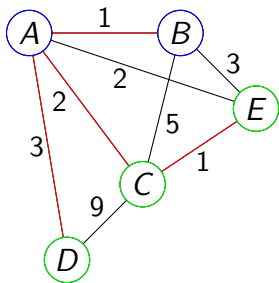
$$V_1 = [A, B]$$

$$V_2 = [C, D, E]$$

cycle: A, C, E

Minimum Spanning Tree: Replacement

Theorem: Given $G = (V, E)$ and w , divide V into two parts V_1 and $V_2 = V \setminus V_1$. Let $e = (u, v)$ be the smallest-weighted edge between V_1 and V_2 . Then for any MST T that does not include e , we can construct MST T' that includes e .



$$V_1 = [A, B]$$

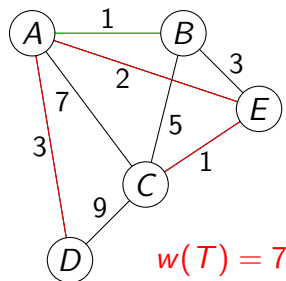
$$V_2 = [C, D, E]$$

cycle: A, C, E

$$w(A, C) \leq w(A, E)$$

Minimum Spanning Tree: Optimal Structure

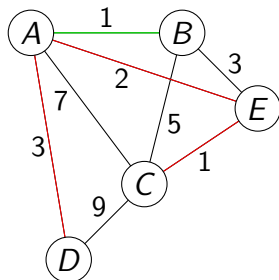
Remove one edge from T



Minimum Spanning Tree: Optimal Structure

Remove one edge from T

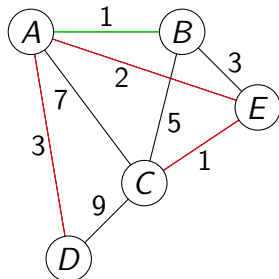
- $T_1 : B$
- $T_2 : (A, E), (A, D), (C, E)$



Minimum Spanning Tree: Optimal Structure

Remove one edge from T

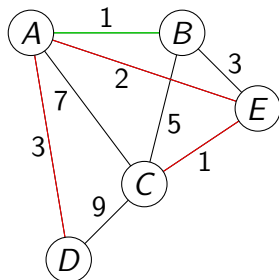
- $T_1 : B$
- $T_2 : (A, E), (A, D), (C, E)$
- T_1 is MST of B



Minimum Spanning Tree: Optimal Structure

Remove one edge from T

- $T_1 : B$
- $T_2 : (A, E), (A, D), (C, E)$
- T_1 is MST of B
- T_2 is MST of $[A, C, D, E]$



Minimum Spanning Tree: Optimal Structure

Theorem: Let T_1 and T_2 be the subtrees derived by removing one edge from the MST T .

- $G_1 = (V_1, E_1)$
 - V_1 : the vertices in T_1
 - E_1 : edges between V_1
- $G_2 = (V_2, E_2)$
 - V_2 : the vertices in T_2
 - E_2 : edges between V_2

Then, T_1 is MST of G_1 , and T_2 is MST of G_2 .

Minimum Spanning Tree: Optimal Structure

T_1 is MST of G_1 , and T_2 is MST of G_2 .

Proof: Let $e = (u, v)$ be the removed edge.

$$w(T) = w(e) + w(T_1) + w(T_2)$$

Minimum Spanning Tree: Optimal Structure

T_1 is MST of G_1 , and T_2 is MST of G_2 .

Proof: Let $e = (u, v)$ be the removed edge.

$$w(T) = w(e) + w(T_1) + w(T_2)$$

- Assume that there is MST T'_1 for G_1 , with

$$w(T'_1) < w(T_1)$$

Minimum Spanning Tree: Optimal Structure

T_1 is MST of G_1 , and T_2 is MST of G_2 .

Proof: Let $e = (u, v)$ be the removed edge.

$$w(T) = w(e) + w(T_1) + w(T_2)$$

- Assume that there is MST T'_1 for G_1 , with

$$w(T'_1) < w(T_1)$$

- Then $T' = \{e\} \cup T'_1 \cup T_2$ is a spanning tree, and

$$w(T') = w(e) + w(T'_1) + w(T_2) < w(T)$$

Minimum Spanning Tree: Optimal Structure

T_1 is MST of G_1 , and T_2 is MST of G_2 .

Proof: Let $e = (u, v)$ be the removed edge.

$$w(T) = w(e) + w(T_1) + w(T_2)$$

- Assume that there is MST T'_1 for G_1 , with

$$w(T'_1) < w(T_1)$$

- Then $T' = \{e\} \cup T'_1 \cup T_2$ is a spanning tree, and

$$w(T') = w(e) + w(T'_1) + w(T_2) < w(T)$$

- **Contradiction** to the fact that T is MST.

Finding MST: Greedy

Matroid $M(S, \mathcal{I})$ for finding MST of $G = (V, E)$: $S = E$.

Finding MST: Greedy

Matroid $M(S, \mathcal{I})$ for finding MST of $G = (V, E)$: $S = E$.

Kruskal's algorithm

- \mathcal{I} : the edge subsets that forms no cycle

Finding MST: Greedy

Matroid $M(S, \mathcal{I})$ for finding MST of $G = (V, E)$: $S = E$.

Kruskal's algorithm

- \mathcal{I} : the edge subsets that forms no cycle
- **hereditary**: A has no cycle, then $A' \subseteq A$ has no cycle.

Finding MST: Greedy

Matroid $M(S, \mathcal{I})$ for finding MST of $G = (V, E)$: $S = E$.

Kruskal's algorithm

- \mathcal{I} : the edge subsets that forms no cycle
- **hereditary**: A has no cycle, then $A' \subseteq A$ has no cycle.
- **exchange**: $|A| < |B| \in \mathcal{I} \Rightarrow$
 - find $(u, v) \in B$, such that $A \cup \{(u, v)\}$ has no cycle
 - if for all $(u, v) \in B$, $A \cup \{(u, v)\}$ has a cycle, then B has a cycle.
 - repeat: add an edge of B to A , and remove an edge (of A) in the cycle.

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

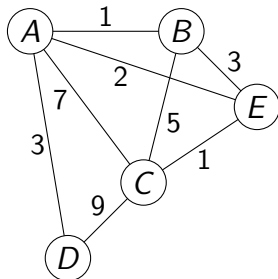
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

 | **if** $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$$

$$w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$$

$$w(A, C) = 7, w(C, D) = 9$$

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

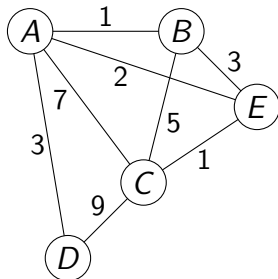
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

 | **if** $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(A, B): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

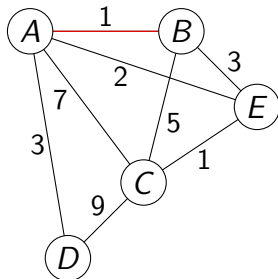
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

if $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(A, B): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

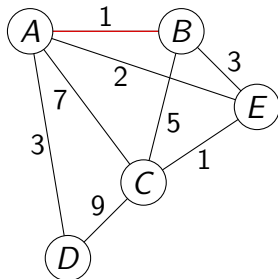
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

 | **if** $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(C, E): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

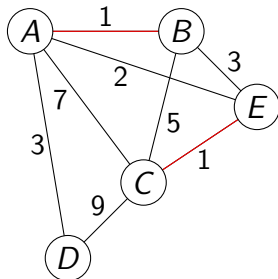
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

if $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(C, E): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

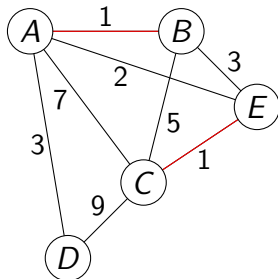
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

if $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(A, E): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

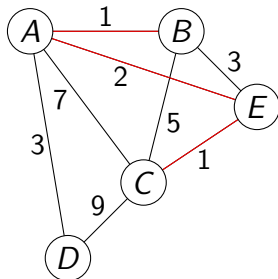
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

if $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(A, E): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

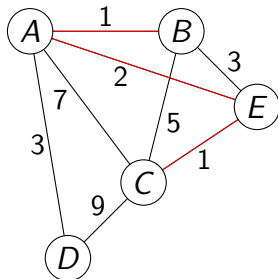
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

 | **if** $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(B, E): **create a cycle**

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

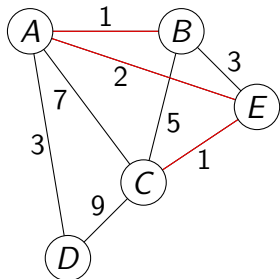
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

if $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(A, D): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

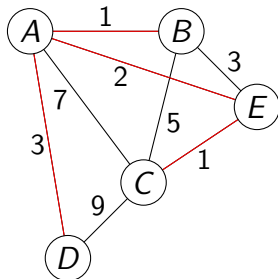
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

 | **if** $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$w(A, B) = 1, w(C, E) = 1, w(A, E) = 2$
 $w(B, E) = 3, w(A, D) = 3, w(B, C) = 5$
 $w(A, C) = 7, w(C, D) = 9$

(A, D): create no cycle

Finding MST: Greedy

Algorithm: Kruskal(G, w)

$M = \emptyset$;

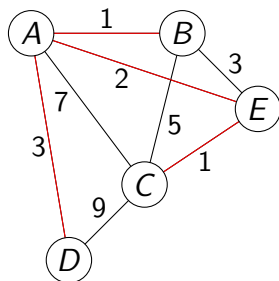
Sort E in the **increasing** order of $w[e]$;

for $i = 0$ **to** $|E| - 1$ **do**

 | **if** $A \cup \{E[i]\}$ *has no cycle* **then** add $E[i]$ to M ;

end

Return M ;



$$\begin{aligned}w(A, B) &= 1, w(C, E) = 1, w(A, E) = 2 \\w(B, E) &= 3, w(A, D) = 3, w(B, C) = 5 \\w(A, C) &= 7, w(C, D) = 9\end{aligned}$$

$$w(M) = 7$$

Finding MST: Greedy

Theorem: Kruskal's algorithm returns a MST.

For each edge $e = (u, v)$ added into M .

- let T be the tree connected to v according to underlying M .
- e is the smallest-weighted edge between $V(T)$ and $V \setminus V(T)$

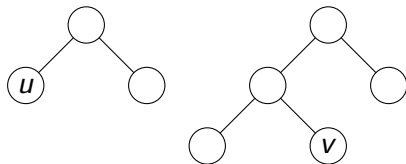
For any MST M' other than M , we can: replace the edges in M' by edges in M without losing any weight.

Finding MST: Greedy

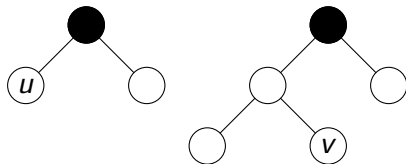
Time Complexity: $O(|E| \log |V|)$

- Sort the edges: $O(|E| \log |E|) = O(|E| \log |V|)$
- Consider the edges one by one : $O(E)$
 - Cycle check: $O(\log |V|)$
 - How?

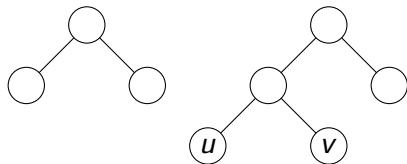
Finding MST: Union of Disjoint Sets



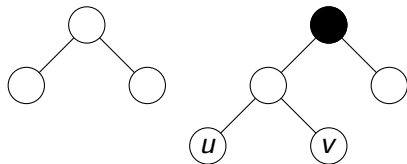
Finding MST: Union of Disjoint Sets



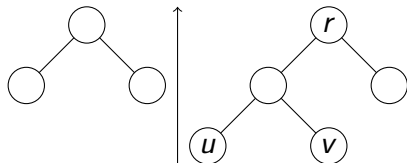
Finding MST: Union of Disjoint Sets



Finding MST: Union of Disjoint Sets

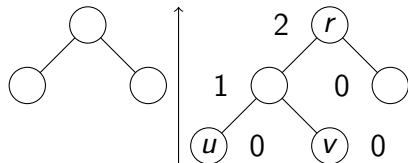


Finding MST: Union of Disjoint Sets



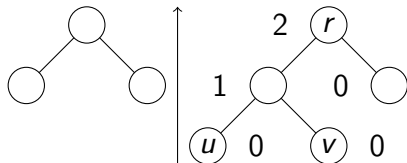
- $\text{Rank}(r)$: the height of the subtree rooted at r .

Finding MST: Union of Disjoint Sets



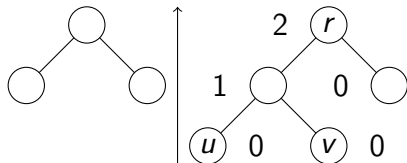
- $\text{Rank}(r)$: the height of the subtree rooted at r .

Finding MST: Union of Disjoint Sets



- Rank(r): the height of the subtree rooted at r .
- **Claim:** $R(r) = O(\log n)$.

Finding MST: Union of Disjoint Sets



- $\text{Rank}(r)$: the height of the subtree rooted at r .
- **Claim:** $R(r) = O(\log n)$.
- It is sufficient to prove the subtree rooted at r has at least $2^{\text{Rank}(r)}$ nodes.

Finding MST: Union of Disjoint Sets

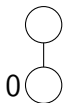
Rank 0 0 0 0 0 0



- Initially, every node has rank 0.

Finding MST: Union of Disjoint Sets

Rank **1**



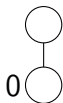
0 0 0 0



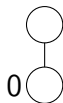
- Initially, every node has rank 0.
- Union:** point the root of the lower rank to the root of the higher rank.

Finding MST: Union of Disjoint Sets

Rank 1



1



0



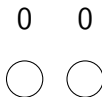
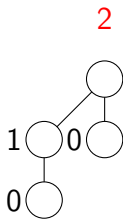
0



- Initially, every node has rank 0.
- Union:** point the root of the lower rank to the root of the higher rank.

Finding MST: Union of Disjoint Sets

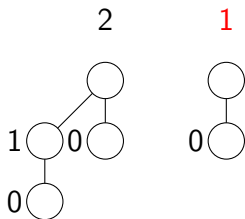
Rank



- Initially, every node has rank 0.
- Union:** point the root of the lower rank to the root of the higher rank.

Finding MST: Union of Disjoint Sets

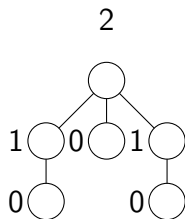
Rank



- Initially, every node has rank 0.
- Union:** point the root of the lower rank to the root of the higher rank.

Finding MST: Union of Disjoint Sets

Rank



- Initially, every node has rank 0.
- Union:** point the root of the lower rank to the root of the higher rank.

Finding MST: Union of Disjoint Sets

Subtree at node v has at least $2^{\text{Rank}(v)}$ nodes.

Proof: Induction on rank k .

Finding MST: Union of Disjoint Sets

Subtree at node v has at least $2^{\text{Rank}(v)}$ nodes.

Proof: Induction on rank k .

- **Base case:** for root of rank 0, the tree has $1 \geq 2^0$ nodes.

Finding MST: Union of Disjoint Sets

Subtree at node v has at least $2^{\text{Rank}(v)}$ nodes.

Proof: Induction on rank k .

- **Base case:** for root of rank 0, the tree has $1 \geq 2^0$ nodes.
- **Assume:** for root of rank $k - 1$, the tree has $\geq 2^{k-1}$ nodes.

Finding MST: Union of Disjoint Sets

Subtree at node v has at least $2^{\text{Rank}(v)}$ nodes.

Proof: Induction on rank k .

- **Base case:** for root of rank 0, the tree has $1 \geq 2^0$ nodes.
- **Assume:** for root of rank $k - 1$, the tree has $\geq 2^{k-1}$ nodes.
- **Consider** a root of rank k .

Finding MST: Union of Disjoint Sets

Subtree at node v has at least $2^{\text{Rank}(v)}$ nodes.

Proof: Induction on rank k .

- **Base case:** for root of rank 0, the tree has $1 \geq 2^0$ nodes.
- **Assume:** for root of rank $k - 1$, the tree has $\geq 2^{k-1}$ nodes.
- **Consider** a root of rank k .
 - rank $k - 1$ to rank k : point a root of rank $k - 1$ to another root of rank $k - 1$.

Finding MST: Union of Disjoint Sets

Subtree at node v has at least $2^{\text{Rank}(v)}$ nodes.

Proof: Induction on rank k .

- **Base case:** for root of rank 0, the tree has $1 \geq 2^0$ nodes.
- **Assume:** for root of rank $k - 1$, the tree has $\geq 2^{k-1}$ nodes.
- **Consider** a root of rank k .
 - rank $k - 1$ to rank k : point a root of rank $k - 1$ to another root of rank $k - 1$.
 - # nodes: $\geq 2 \cdot 2^{k-1} = 2^k$.

Finding MST: Another Greedy Idea

Algorithm: Prim(G, w)

$M = \emptyset$;

while $|M| < |V| - 1$ **do**

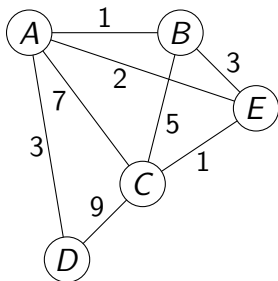
 let e be the smallest-weighted edge between $V(E)$

 and $V \setminus V(E)$;

 add e to M ;

end

Return M ;



Finding MST: Another Greedy Idea

Algorithm: Prim(G, w)

$M = \emptyset;$

while $|M| < |V| - 1$ **do**

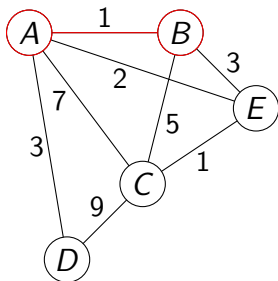
 let e be the smallest-weighted edge between $V(E)$

 and $V \setminus V(E);$

 add e to $M;$

end

Return $M;$



$$w(A, B) = 1$$

Finding MST: Another Greedy Idea

Algorithm: Prim(G, w)

$M = \emptyset$;

while $|M| < |V| - 1$ **do**

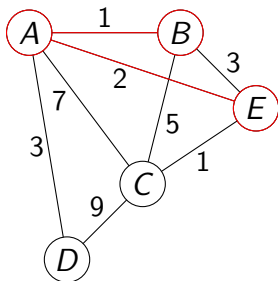
 let e be the smallest-weighted edge between $V(E)$

 and $V \setminus V(E)$;

 add e to M ;

end

Return M ;



$$w(A, E) = 2$$

Finding MST: Another Greedy Idea

Algorithm: Prim(G, w)

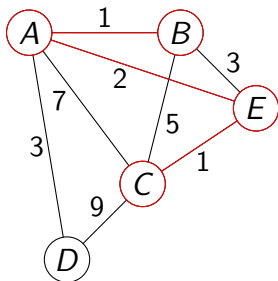
$M = \emptyset$;

while $|M| < |V| - 1$ **do**

 let e be the smallest-weighted edge between $V(E)$
 and $V \setminus V(E)$;
 add e to M ;

end

Return M ;



$$w(C, E) = 1$$

Finding MST: Another Greedy Idea

Algorithm: Prim(G, w)

$M = \emptyset$;

while $|M| < |V| - 1$ **do**

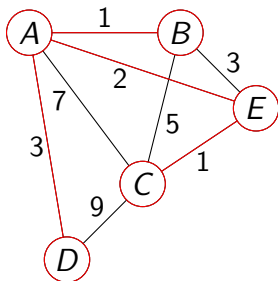
 let e be the smallest-weighted edge between $V(E)$

 and $V \setminus V(E)$;

 add e to M ;

end

Return M ;



$$w(A, D) = 3$$

Finding MST: Another Greedy Idea

Algorithm: Prim(G, w)

$M = \emptyset;$

while $|M| < |V| - 1$ **do**

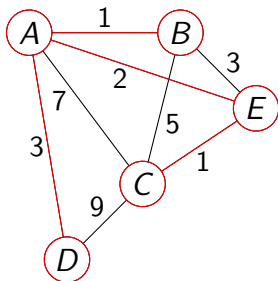
 let e be the smallest-weighted edge between $V(E)$

 and $V \setminus V(E);$

 add e to $M;$

end

Return $M;$



$$w(M) = 7$$

Finding MST: Prim

Theorem: Prim's algorithm returns a MST.

For each edge $e = (u, v)$ added into M .

- M is a tree.
- e is the smallest-weighted edge between $V(M)$ and $V \setminus V(M)$

For any MST M' other than M , we can: replace the edges in M' by edges in M without losing any weight.

Finding MST: Prim

Time Complexity: $O(|E| \log |V|)$

- How to find the smallest edge which extends M ?
- **min-priority queue**
- Thus
 - Maintain the priorities of all edges between $V(M)$ and $V \setminus V(M)$
 - Take the one of the minimum priority, and add it to M .
 - Update the edges between $V(M)$ and $V \setminus V(M)$.

Finding MST: Prim

Algorithm: Prim(G, w)

$M = \emptyset$;

$B = []$; # min-priority queue of nodes between $V(M)$ and $V \setminus V(M)$

while $|M| < |V| - 1$ **do**

 let e be the min edge in B ;

 let v be e 's endpoint outside M ;

 add e to M ;

for each $u \in V \setminus V(M)$ and $(v, u) \in E$ **do**

 | add **or** update the priority of u ;

end

while endpoints of the min edge are all in M **do**

 | remove the min edge from B ;

end

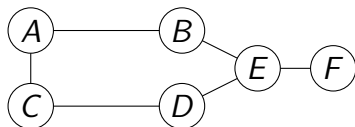
end

Return M ;

Independent Set

Independent Set

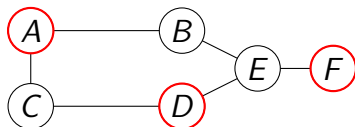
Given a graph $G = (V, E)$, an independent set is a subset of V , such that there are no edges between them.



Independent Set

Given a graph $G = (V, E)$, an independent set is a subset of V , such that there are no edges between them.

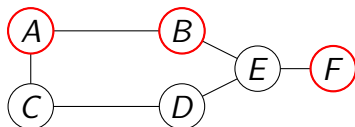
- $\{A, D, F\}$ is an independent set



Independent Set

Given a graph $G = (V, E)$, an independent set is a subset of V , such that there are no edges between them.

- $\{A, D, F\}$ is an independent set
- $\{A, B, F\}$ is not an independent set



Largest Independent Set

Problem: Given a graph $G = (V, E)$, find the largest independent set.

It is believed to be **intractable**, for the general cases.

What about the **trees**?

Largest Independent Set

Problem: Given a tree rooted at node r , find the largest independent set.

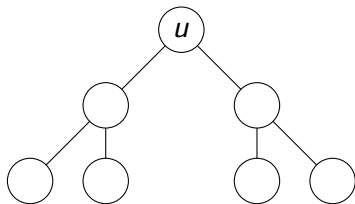
$I(u)$ = size of the largest independent set of subtree rooted at node u .

Solution: $I(r)$.

Calculate $I(u)$

Assume that $I(v)$ is known for all the children v (of node u).

$I(u)$



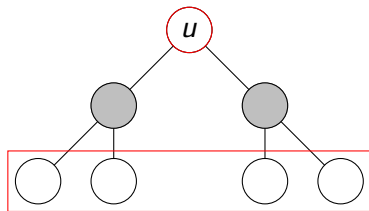
Calculate $I(u)$

Assume that $I(v)$ is known for all the children v (of node u).

$I(u)$

- if u is included

$$I(u) = 1 + \sum_{\text{grandchild } v} I(v)$$



Calculate $I(u)$

Assume that $I(v)$ is known for all the children v (of node u).

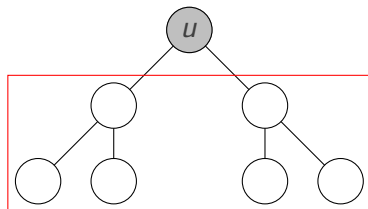
$I(u)$

- if u is included

$$I(u) = 1 + \sum_{\text{grandchild } v} I(v)$$

- if u is not included

$$I(u) = \sum_{\text{child } v} I(v)$$



THANK YOU



中国科学院深圳先进技术研究院
SHENZHEN INSTITUTES OF ADVANCED TECHNOLOGY
CHINESE ACADEMY OF SCIENCES