

**Department of Physics and Astronomy**  
**University of Heidelberg**

Bachelor Thesis in Physics  
submitted by

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born in Aalen, Germany

handed in on  
**March 28, 2016**

# **Characterization of a multispecies imaging system**

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**Institute for Theoretical Physics in Heidelberg**  
under the supervision of  
**Prof. Dr. Matthias Weidemüller**

# Characterization of a multispecies imaging system

Robin Eberhard

**Abstract** Lorem ipsum dolor sit amet, consectetur adipiscing elit. Ut purus elit, vestibulum ut, placerat ac, adipiscing vitae, felis. Curabitur dictum gravida mauris. Nam arcu libero, nonummy eget, consectetur id, vulputate a, magna. Donec vehicula augue eu neque. Pellentesque habitant morbi tristique senectus et netus et malesuada fames ac turpis egestas. Mauris ut leo. Cras viverra metus rhoncus sem. Nulla et lectus vestibulum urna fringilla ultrices. Phasellus eu tellus sit amet tortor gravida placerat. Integer sapien est, iaculis in, pretium quis, viverra ac, nunc. Praesent eget sem vel leo ultrices bibendum. Aenean faucibus. Morbi dolor nulla, malesuada eu, pulvinar at, mollis ac, nulla. Curabitur auctor semper nulla. Donec varius orci eget risus. Duis nibh mi, congue eu, accumsan eleifend, sagittis quis, diam. Duis eget orci sit amet orci dignissim rutrum.

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# 1. Introduction

## 1.1. Stuff

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## 1.2. More stuff

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### 1.3. Interesting stuff

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## 2. Setup for high resolution imaging

### 2.1. Experimental requirements

### 2.2. Camera for double species imaging

#### 2.2.1. Comparison with the present setup

#### 2.2.2. Dark current

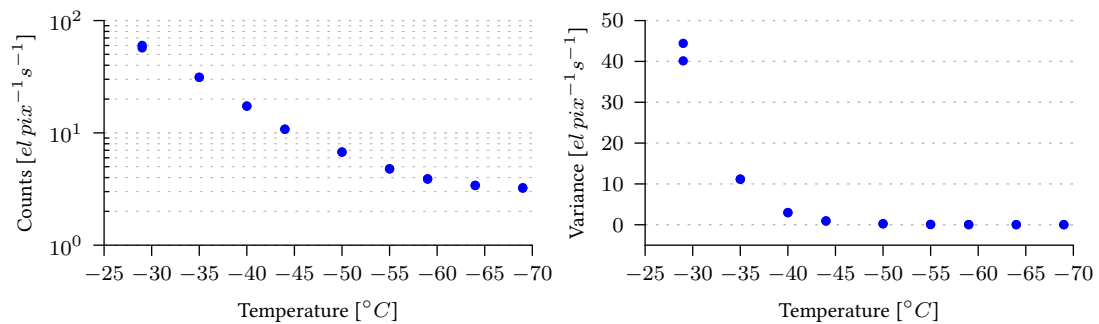


Figure 2.1.: **Dark noise** The dark noise follows a power law dependency. Since these measurements were taken without water cooling installed, deviations are visible as the temperature reaches  $-70^{\circ}\text{C}$ . The convergence to zero on the counts and their variance indicates accurate imaging when low temperatures are used. Gain in this measurement was minimal and the exposure time set to 100s, such that dark current was the dominant noise source.

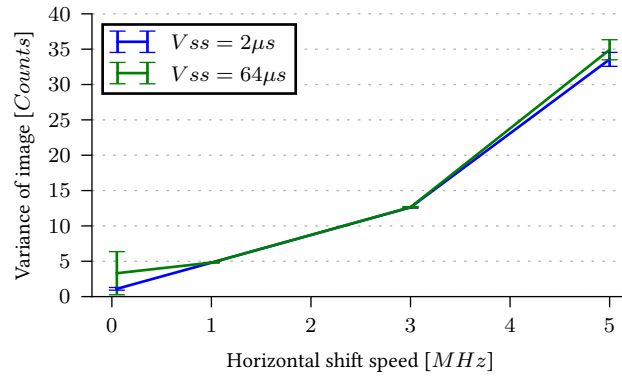


Figure 2.2.: **Readout noise** The pixels are shifted row-wise into the readout register, depending on the vertical shift speed ( $v_{ss}$ ) and then moved pixel-by-pixel with the horizontal shift speed into the analog to digital converter. Since noise reduction is important, minimal horizontal shift speeds will be used, while the vertical shift speed does not seem to affect the variance. To make the readout the dominant noise source, temperature was set to  $-69^{\circ}\text{C}$  and exposure to 10 ms

### 2.2.3. Readout noise

### 2.2.4. Quantum efficiency

### 2.2.5. Pixel correlations

## 2.3. Mechanical shutter



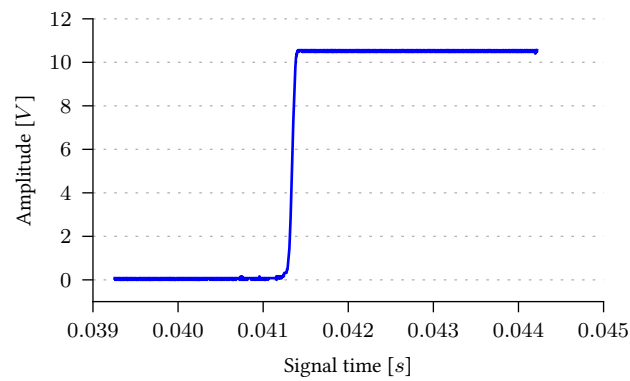


Figure 2.3.: **Shutter characterization** The dynamics of the shutter were measured using a laser with a variable horizontal offset, which is fixed in this plot, and a photodiode measuring the laser intensity. For various offsets, error functions were fitted yielding the time until the shutter opens to this offset.

### 2.3.1. Electronic setup

### 2.3.2. Dynamical properties

## 2.4. Mask for the CCD sensor

### 2.4.1. Fast kinetics mode

### 2.4.2. Frequency response of an imaging system

### 2.4.3. Optimization of the masking setup

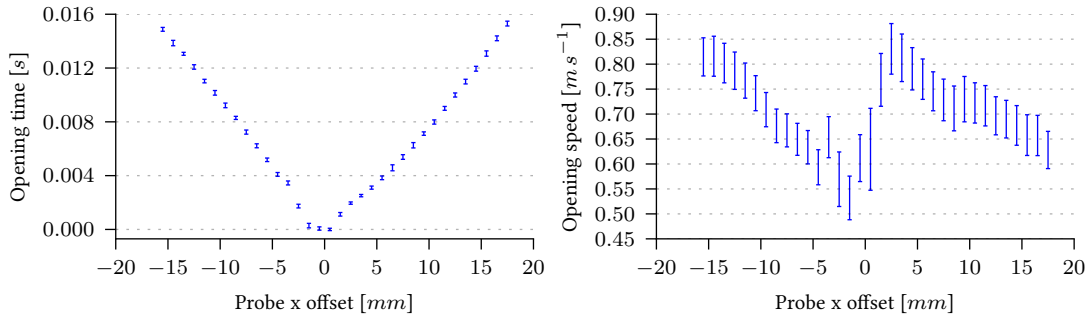


Figure 2.4.: **Sample dynamics** Opening velocity was measured using the beam diameter and the time the shutter needed to transverse it. It is noticable, that the opening velocity on the right side is faster at first than on the left side. This is due to the structure of the shutter, as can be seen in [Appendix image of shutter]. The overall opening speed on the other hand is not affected by this and seems to be linear with the offset.

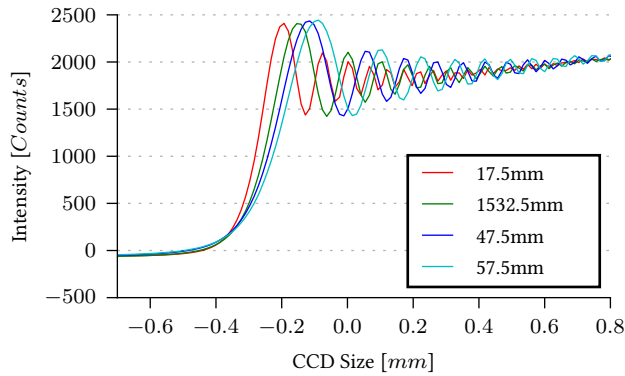


Figure 2.5.: **Distance dependant diffraction** A slit was placed on a moving platform and diffraction was measured for various offsets. The diffraction frequency rises as the distance gets closer to the CCD. As soon as the frequency is of the order of one pixel, the diffraction is unnoticable, therefore higher frequencies, or closer slit positions are preferred.

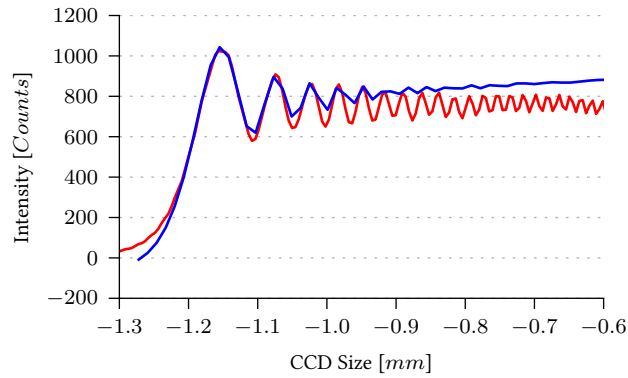


Figure 2.6.: **Diffraction measurement** In order to characterize the diffraction on the CCD, a slit was placed as close as possible. The parameters were then measured as distance  $d = 10.9$  mm, opening  $a = 2.5$  mm using a ruler and wavelength  $\lambda = 852$  nm from the laser specifications. The blue curve is the experimental data, while the red curve was fitted, leaving distance and opening free. They were found to be  $d' = (11.0 \pm 0.3)$  mm and  $a' = (2.470 \pm 0.013)$  mm, which is in close agreement.

### **3. Testing the camera: Superfluids**

## **4. Conclusion and outlook**

## **A. Acquisition sequence**

## **B. Testing software**

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