## Zixuan Liu

### zx-liu21@mails.tsinghua.edu.cn

#### Research Interests

### Reinforcement Learning in Real-World Scenarios

Focusing on dynamics adaptation and safety constraints in real-world scenarios, such as robotics and smart grid.

#### Education

Tsinghua University M.E. Degree in Electronic and Information Engineering; GPA: 3.80/4.00	2021.09 – Present Beijing, China
Harbin Institute of Technology B.E. Degree in Mechatronics Engineering; GPA: 94.6/100.0; R: 5/125	2016.09 – 2021.06 Harbin, Heilongjiang, China

### Research Experience

### General Robotic Manipulation with Foundation Models

2023.09 - Present

Singapore

NUS School of Computing, Robot Learning and Intelligent System Lab

- · Designing network architecture for the foundation model
- · Ongoing work

### Reinforcement Learning with Hard Safety Constraints

2022.10 - 2023.09

Tencent, AI Lab

Shenzhen, Guangdong, China

- Combining optimization with policy networks
- · Combining optimization with simulators

### Adversarial Imitation Learning with Dynamics Adaptation

2022.01 - 2022.06

Tencent, AI Lab

Shenzhen, Guangdong, China

- Proposing a method to deal with dynamics shift between source and target domains
- Providing a theoretical guarantee for the method

### Other Experience

### The 4th Power Dispatching AI Application Competition 2022

2022.09 - 2022.09

China Southern Power Grid

Guangzhou, Guangdong, China

- Ranking: 12/24
- Introducing graph neural networks to predict powerflow
- Designing an action filter to optimize unsafe actions

### New Power System Artificial Intelligence Application Competition

2022.07 - 2022.09

China Electricity Council

Beijing, China

- Ranking: 13/34
- Introducing grid safety constraints to reinforcement learning through regularization
- Alternatively using traditional optimization to output safe actions

## Revisiting Plasticity in Visual Reinforcement Learning: Data, Modules and Training Stages (Accepted to ICLR 2024) [OpenReview]

Guozheng Ma, Lu Li, Sen Zhang, Zixuan Liu, Zhen Wang, Yixin Chen, Li Shen, Xueqian Wang, Dacheng Tao

# UniContact: A Basic Model for Robotic Manipulation of Contact Synthesis on Rigid and Articulated Rigid Bodies with Arbitrary Manipulators (Under review for ICLR)

Gang Yang, Zhixuan Xu, Zixuan Liu, Jichen Sun, Hanwei Fan, Xinghao Zhu, Lin Shao

## Differentiable Frank-Wolfe Optimization Layer (Accepted to Tiny Papers @ ICLR 2024) [OpenReview][GitHub]

Zixuan Liu, Liu Liu, Xueqian Wang, Peilin Zhao

### Dynamics Adapted Imitation Learning (Published in TMLR) [OpenReview][GitHub]

Zixuan Liu, Liu Liu, Bingzhe Wu, Lanqing Li, Xueqian Wang, Bo Yuan, Peilin Zhao

## NN-Based Reinforcement Learning Optimal Control for Inequality-Constrained Nonlinear Discrete-Time Systems With Disturbances (Published in TNNLS) [IEEE]

Shu Li, Liang Ding, Miao Zheng, Zixuan Liu, Xinyu Li, Huaiguang Yang, Haibo Gao, Zongquan Deng

### **Patents**

## Power Grid Dispatching Method, Device, Equipment and Storage Medium [GooglePatent] Liu Liu, Peilin Zhao, Zixuan Liu. Guangdong: CN116960997A

## Neural Network Training Method and Device for Industrial System Control [GooglePatent] Liu Liu, Peilin Zhao, Zixuan Liu. Guangdong: CN116956995A

# Training Method, Training Device, Training Equipment, Training Medium and Training Program Product for Strategy Generator [GooglePatent]

Liu Liu, Zixuan Liu, Peilin Zhao. Guangdong: CN116956018A

# Method and Apparatus for Generating Controlstrategy for Industrial System [GooglePatent] Liu Liu, Zixuan Liu, Peilin Zhao. Guangdong: CN116954162A

### Awards & Honors

President Graduate Fellowship Naitional University of Singapore	2024
Outstanding Research Scholarship Tsinghua University	2023
Outstanding Graduates Harbin Institute of Technology	2021
National Scholarship Ministry of Education of the People's Republic of China	2019
Provincial Merit Students Heilongjiang Provincial Education Department	2019

### Specialized Skills

Programming Languages: Python Deep Learning Framework: PyTorch English: TOEFL (107), GRE (322)