Vehicle Detection and Logging

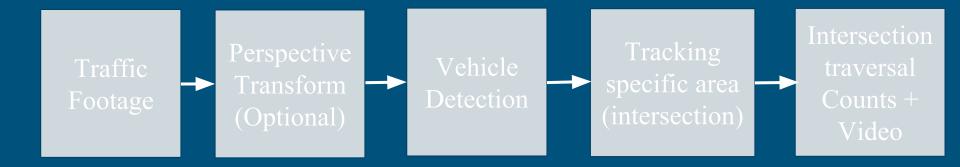
Shane Ickes, Arash Behpour, Jake Pan

Commercial Future

Honda Thinks Smarter
 Intersections Can Reduce Auto
 Accidents And Fatalities

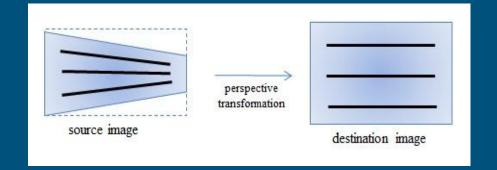


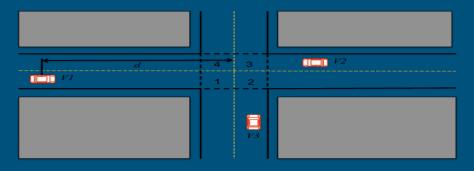
Project Overview



Perspective Transform (Optional)

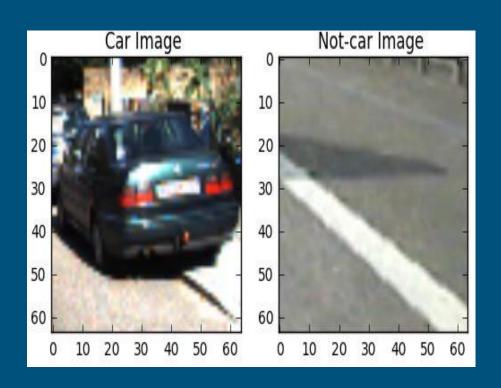
- Our traffic camera viewpoint can be changed to top-down
- Better output visualization





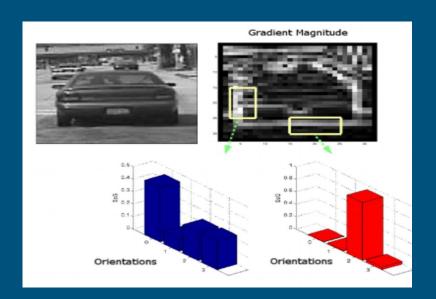
Vehicle Detection

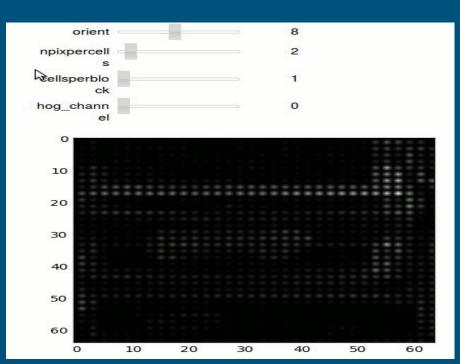
- Two options considered for distinguishing between objects that are vehicles and non-vehicles
- Both require datasets of training images
- Our detection will be angled from a traffic camera position



HOG Approach

Histogram of Oriented Gradients
 (HOG) with Sliding window





CNN Approach

- Train a Neural Network
- Collect training images from Google Earth, Google street views
 - The quality of images
 - Sample Requirements
 - Extracting poor features



Expected Inputs and Outputs

- Input: Video of Traffic Intersection
- Outputs:
 - 1) Vehicle object
 detection/tracking within an
 intersection
 - 2) Log number of vehicles traveling through intersection



Work Cited

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